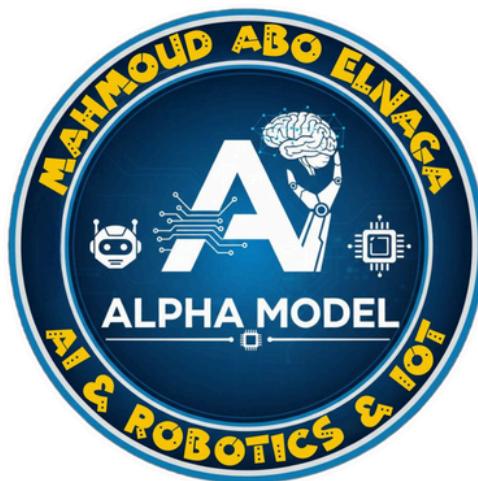


Roadma p

A simple path from basics in math and programming to AI, Computer Vision, and Robotics — ending with real projects like drones and smart cars.



Prepared by:Mahmoud Ayman
Faculty of Artificial Intelligence – Robotics and
Artificial Intelligence Major
Kafr El-Sheikh University

Week	Topics
Week 1 - Programming Basics for Robotics	<ul style="list-style-type: none"> - Introduction to Programming - What is Coding? - Programming Languages (High, Low, Machine) - IDE & Syntax - Editor vs Compiler vs Interpreter - Data Types & Conditional Statements - How to choose a laptop for programming
Week 2 - Arduino Basics & First Project	<ul style="list-style-type: none"> - Introduction to Arduino - Arduino IDE Overview - Code Structure (setup & loop) - Digital & Analog Pins - First Project: LED Blinking
Week 3 - Sensors & Inputs with Arduino	<ul style="list-style-type: none"> - What are Sensors? - Types of Sensors (Ultrasonic, IR, LDR, etc.) - Reading sensor values - Serial Monitor & Debugging - Mini Project: Distance Measurement
Week 4 - Linear Algebra for Robotics	<p>Vectors & Matrices</p> <ul style="list-style-type: none"> - Matrix Operations - Applications in Robot Kinematics - Python with NumPy Examples
Week 5 - Actuators & Motion	<ul style="list-style-type: none"> - What are Actuators? - DC Motors, Servos, Relays - L298N Motor Driver - PWM & Speed Control - Mini Project: Motor Test

Week	Topics
Week 6 - Mid Evaluation & Quiz	<ul style="list-style-type: none"> - Review of Weeks 1-4 - Short Quiz - Small Team Challenge
Week 7 - Obstacle Avoidance Basics	<ul style="list-style-type: none"> - Obstacle Detection Concept - Ultrasonic Sensor Logic - Decision Making with if-else - Mini Project: Obstacle Detection
Week 8 - Motors + Ultrasonic Integration	<ul style="list-style-type: none"> - Combining Sensors & Motors - Distance Calibration - Mini Project: Stop Before Collision
Week 9 - Full Obstacle Avoiding Robot	<ul style="list-style-type: none"> - Full Robot Assembly - Integration & Testing - Troubleshooting & Optimization
Week 10 - Advanced Project: Line Follower	<ul style="list-style-type: none"> - Concept of Line Following - IR Sensors for Path Detection - Logic Implementation - Build & Test Line Follower
Week 11 - Final Project & Closing	<ul style="list-style-type: none"> - Final Project Presentation - Real-world Robotics Applications - Feedback
Week 12 - Graduation Project	<ul style="list-style-type: none"> - Final Practical Project - Teamwork & Presentation - Evaluation & Closing Ceremony