

CS221 Assembly Language

Lab 01: Introduction to Assembly Language

Objectives

- Learn the basic template of a MASM assembly code.
- Use the IA-32 general-purpose registers.
- Use and understand **mov**.
- Understand how to use binary, octal, decimal, and hexadecimal values in MASM.
- Use **add**, **sub**, **inc**, and **dec**.
- Use the debugger to inspect the registers during execution.

Practice

The basic 32-bit MASM template is

```
.686
.model flat, stdcall
.stack 4096
ExitProcess proto, dwExitCode:dword
.data
    ; declare variables here
.code
main proc
    ; write your code here
    invoke ExitProcess, 0
main endp
    ; write additional procedures here
end main
```

Write the following assembly instructions inside the main procedure **main proc**. Then, use the debugger to check the content of each register after executing each line. Note that all the destination operands for the instructions in this example are registers. Figure 1 lists the IA-32 registers.

```
mov eax, 0
mov eax, 43707
mov ebx, 255

; swapping values
mov ecx, eax
mov eax, ebx
mov ebx, ecx

; immediate hexadecimal values use the h suffix.
```

```

mov edx, 0FFh
mov ebp, 0AABBh           ; Delete the leading zero. What happens?

; immediate binary values have the suffix b or y.
mov esi, 11111111b
mov edi, 101010101011011b

; immediate octal values have the suffix o or q.
mov eax, 377o
mov ebx, 125273o

; character constants (ASCII values).
mov eax, "5"
mov ebx, 5      ; observe the different values in eax and ebx.
mov eax, "ZA"   ; 32-bit register can hold 4 ASCII characters, try it yourself.

```

IA-32 instructions have the following format:

[label:] mnemonic [operands] [;comment]

Remember, when the mnemonic requires two operands, the first is the destination and the second is the source. For example:

mov eax, ebx

In the previous instruction, the source is **ebx** register and the destination is the **eax** register.

Exercises

Use the mnemonics in Table 1 to answer the questions in this section.

Table 1

Mnemonic	# of Operands	Function
mov	2	Stores the value of the source in the destination.
add	2	Adds the value of the source to the destination. The value is stored in the destination.
sub	2	Subtracts the value of the source from the destination. The value is stored in the destination.
inc	1	Increment the operand by 1.
dec	1	Decrement the operand by 1.

1. Initialize all the general-purpose registers with random values.
2. Add the values of all the general-purpose registers shown in Figure 1 into the **eax** register.
3. Find the minimum and maximum values that can be stored in 32-bit registers. Examine the values using the debugger.

4. Use the general-purpose registers shown in Figure 1 to calculate the following expression:

$$X = (A - B) + (C + D - E) - 19$$

Where:

$$A = 100, B = 55, C = 15, D = 200, \text{ and } E = 123$$

5. Printing the result: you can use the procedure **WriteDec** provided by the Irvine32 library to print decimal (unsigned) values. The **WriteDec** procedure requires the value to be printed in **eax**. Move the result of task 3 into **eax**. Then, call the procedure using the following x86 instruction:

call WriteDec

Did you get an error after assembling the instructions? What is missing? Try adding “**include irvine32.inc**” before “.686” and try again. Why is there a warning after adding **include irvine32.inc**?

6. Call the procedure “**DumpRegs**”. What does it do?

32-bit General-Purpose Registers

EAX	EBP
EBX	ESP
ECX	ESI
EDX	EDI

Figure 1