

Affine spaces

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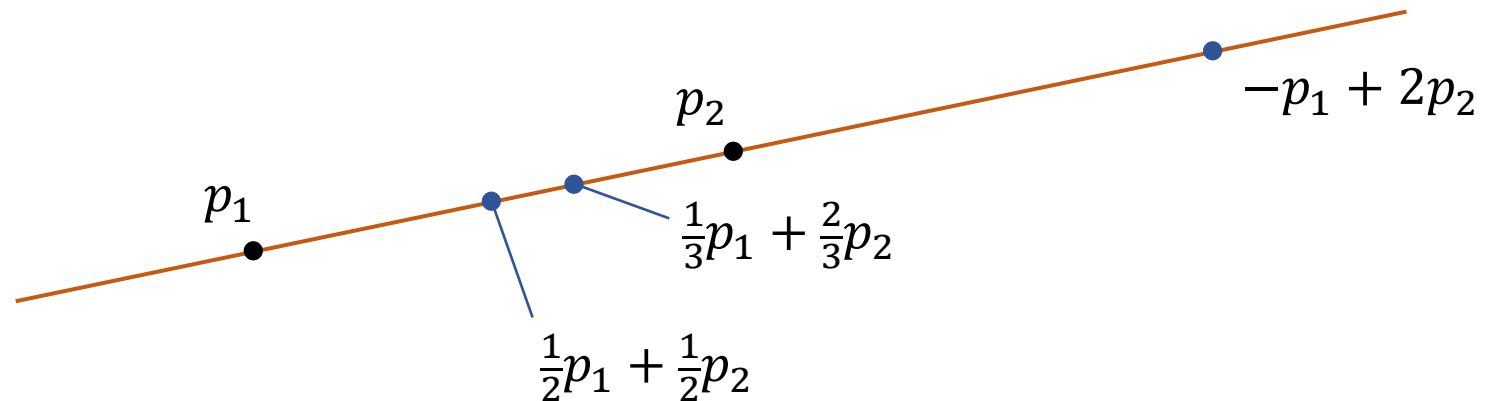
Affine combination of points

$$p_1, \dots, p_k \in \mathbb{R}^d$$

$$w = \alpha_1 p_1 + \dots + \alpha_k p_k \quad \text{where } \alpha_1 + \dots + \alpha_k = 1$$

w is an **Affine Combination** (AC) of p_1, \dots, p_k

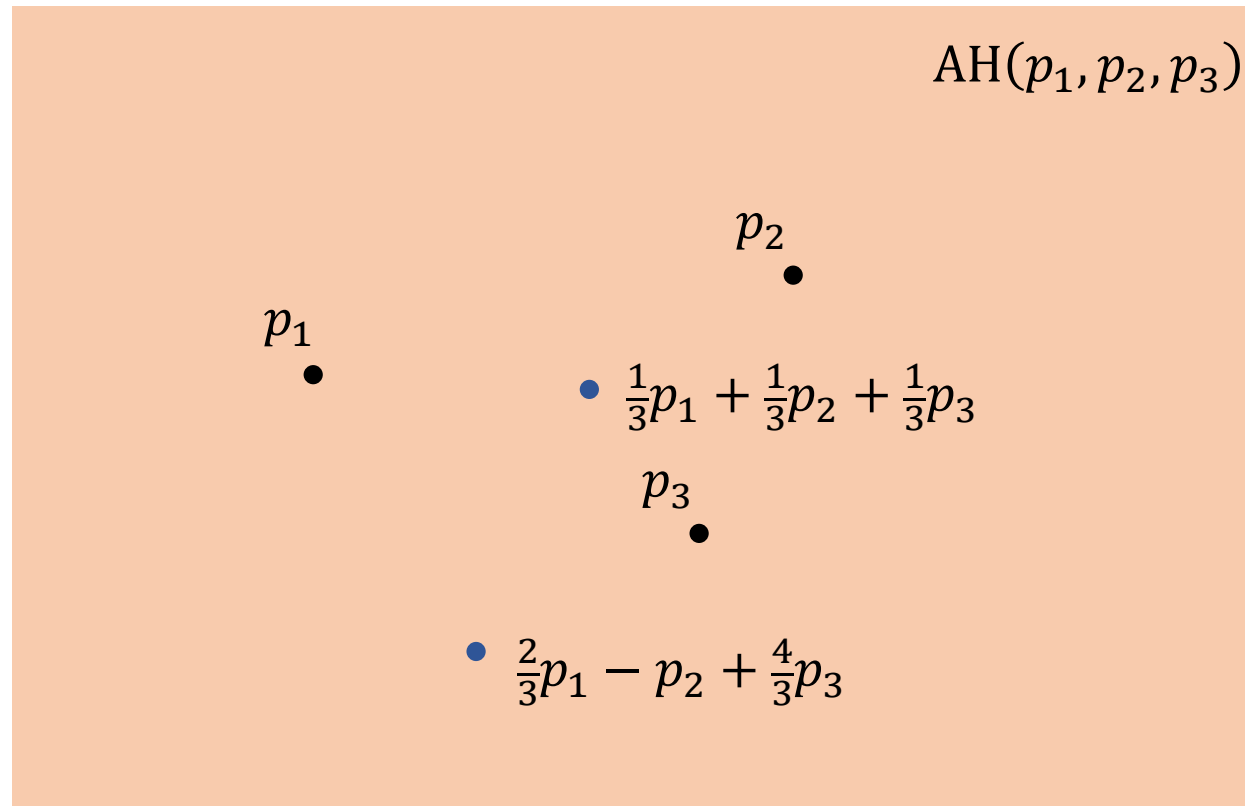
Examples:



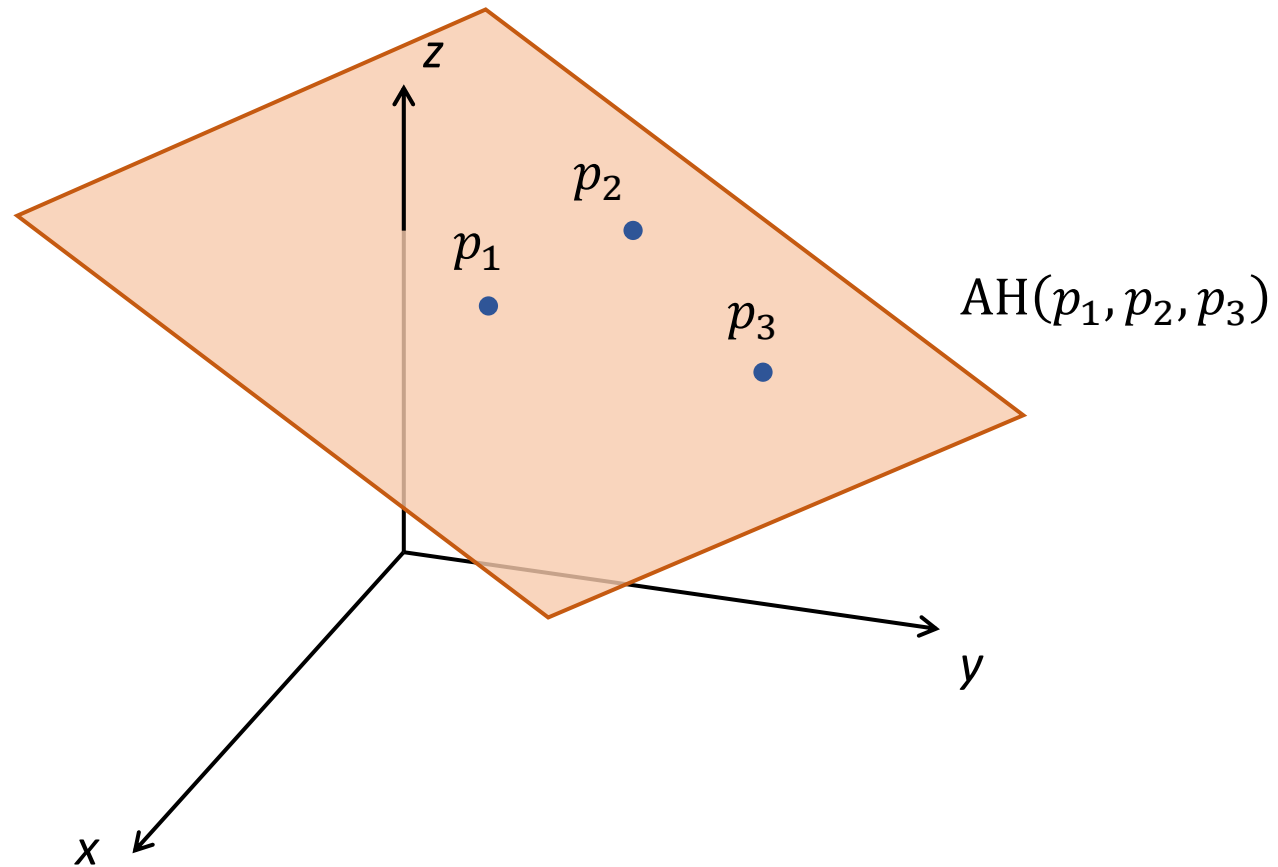
Affine Hull (AH) (or **affine span**): Set of all affine combinations

Affine combination of points

Examples:



Affine combination of points



Affinely Dependent points

Definition 1: Points p_1, \dots, p_k are Affinely Dependent if one of them is an AC of the others.

Example:

p_1, p_2, p_3

$$p_2 = 4p_1 - 3p_3$$

p_2 is an AC of p_1, p_3

p_1, p_2, p_3 are AD

Definition 2: Points p_1, \dots, p_k are Affinely Dependent if there exist scalars $\alpha_1, \dots, \alpha_k$, not all zero, such that

$$\alpha_1 p_1 + \dots + \alpha_k p_k = \vec{0}$$

$$\alpha_1 + \dots + \alpha_k = 0$$

$$4p_1 - p_2 - 3p_3 = \vec{0}$$

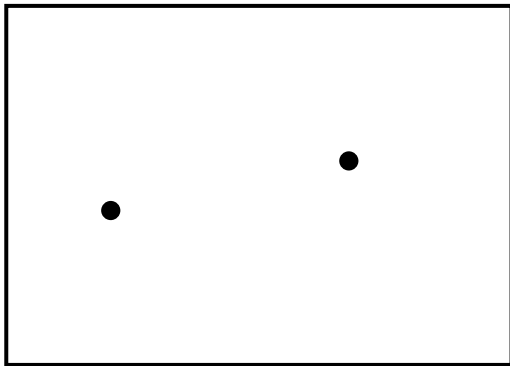
Affinely Dependent points

In other words, points p_1, \dots, p_k are Affinely Independent if the only solution to the homogeneous system

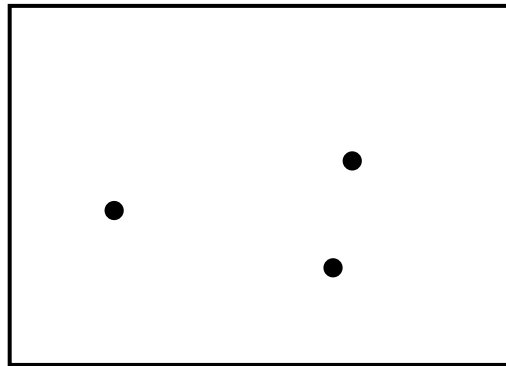
$$\alpha_1 p_1 + \dots + \alpha_k p_k = \vec{0}$$

$$\alpha_1 + \dots + \alpha_k = 0 \quad \text{is the trivial one } \alpha_1 = \dots = \alpha_k = 0$$

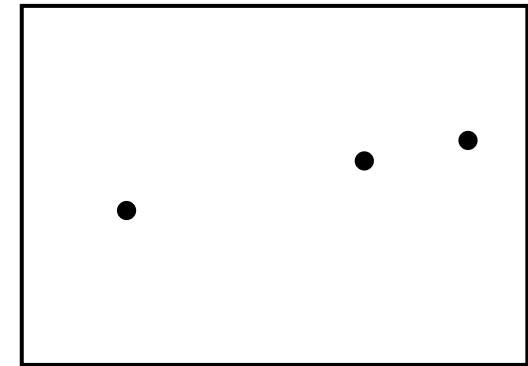
Examples in the plane:



AI



AI



AD

Exercise 1: Prove that the two definitions of AD are equivalent



Affine Combination: $\sum \alpha_i = 1$

Affinely Dependent: $\sum \alpha_i = 0$

Recall from Linear Algebra: $d + 1$ vectors in \mathbb{R}^d are always LD.

Exercise 2: Use this to prove that $d + 2$ points in \mathbb{R}^d are always AD.

Exercise 3: Prove that Affinely Dependent points are “unnecessary” for Affine Combinations:

If $q \in \mathbb{R}^d$ is an AC of $p_1, \dots, p_k \in \mathbb{R}^d$, and p_1 is an AC of p_2, \dots, p_k , then q is an AC of p_2, \dots, p_k

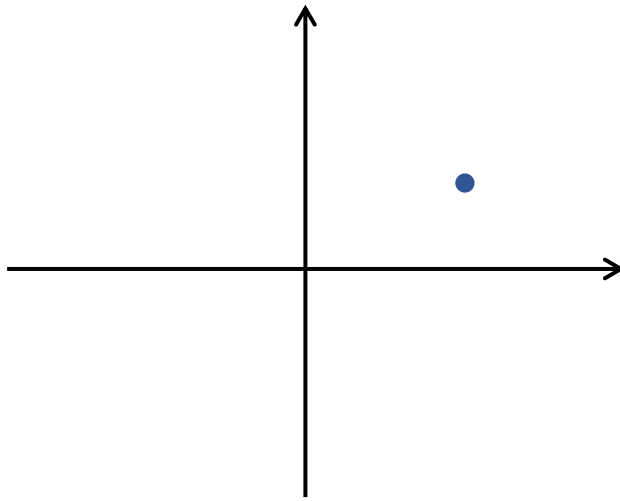
(Just like with LD and LC in Linear Algebra)

Affinely closed sets

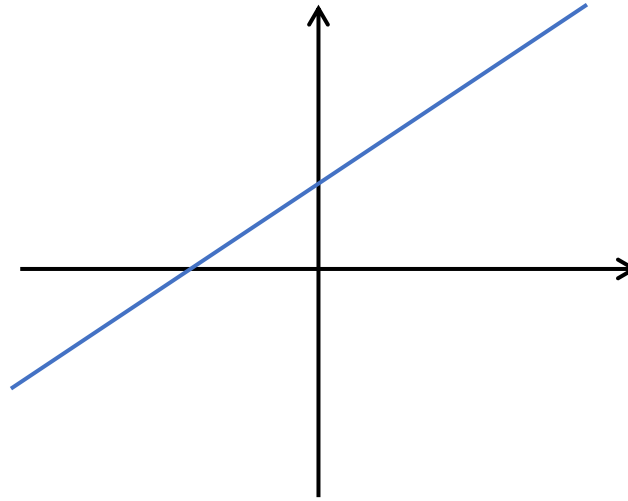
Definition: A subset $F \subseteq \mathbb{R}^d$ is ***affinely closed*** if every AC of finitely many points of F is also in F

up to $d + 1$ is enough

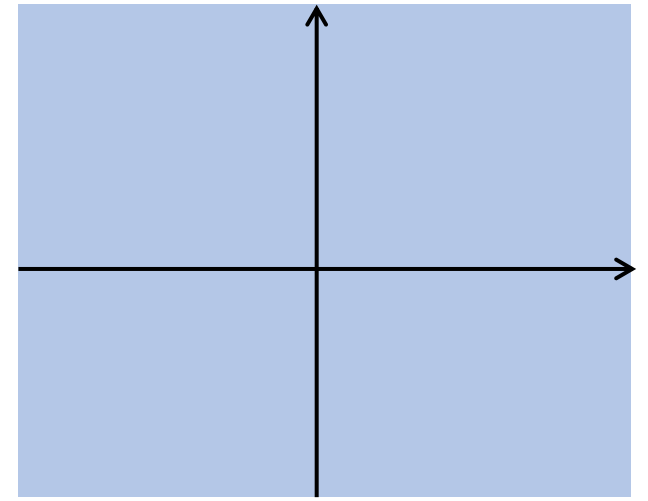
Affinely closed subsets of the plane:



points



lines



the whole plane

Affinely closed sets

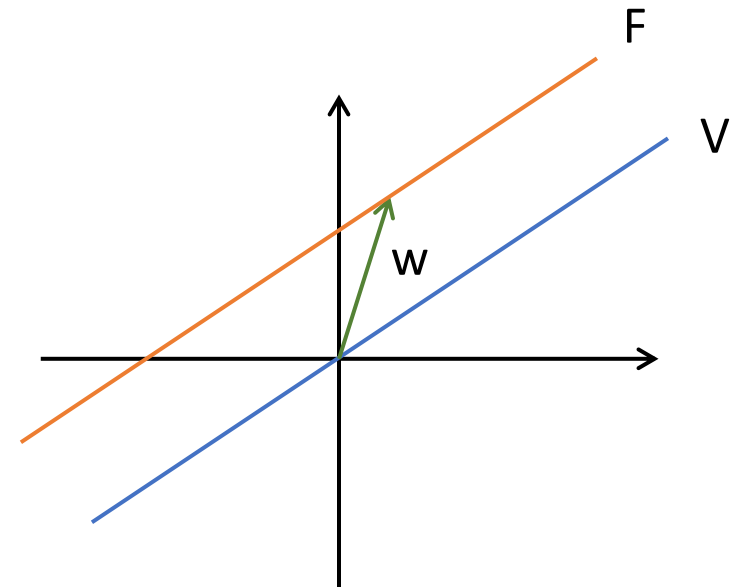
Affinely closed subsets of three-dimensional space:

- points
- lines
- planes
- the whole space

Affine subspaces

Definition: An *affine subspace* is a translated linear subspace:

$$F = \{v + w \mid v \in V\} \quad V \text{ linear subspace}$$

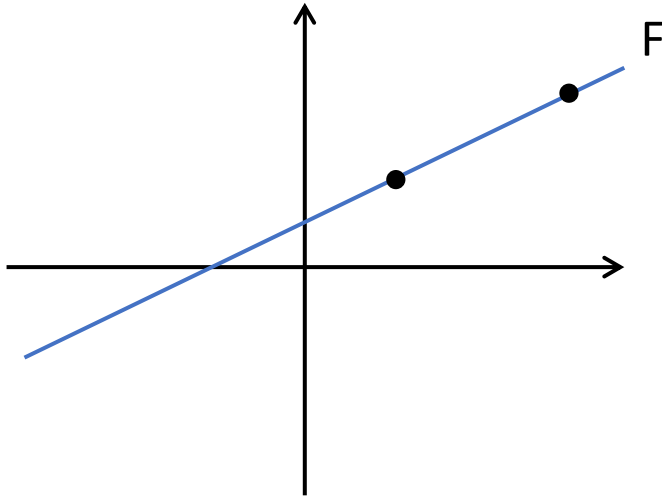


Exercise 4: Prove that the above two notions are equivalent:
A subset of \mathbb{R}^d is affinely closed if and only if it is an affine subspace.

Representation of affine subspaces

There are two ways to represent affine subspaces:

- With points
- With equations



affine subspace = “*flat*”

k-dimensional affine subspace = “*k-flat*”

$$F = \text{AH}((1, 1), (3, 2))$$

two points

$$F = \{(x, y) \in \mathbb{R}^2 \mid x - 2y = -1\}$$

one equation

A k -flat in \mathbb{R}^d can be represented by

- $k + 1$ points
- $d - k$ equations

Hyperplanes

A $(d - 1)$ -dimensional flat in \mathbb{R}^d is called a ***hyperplane***

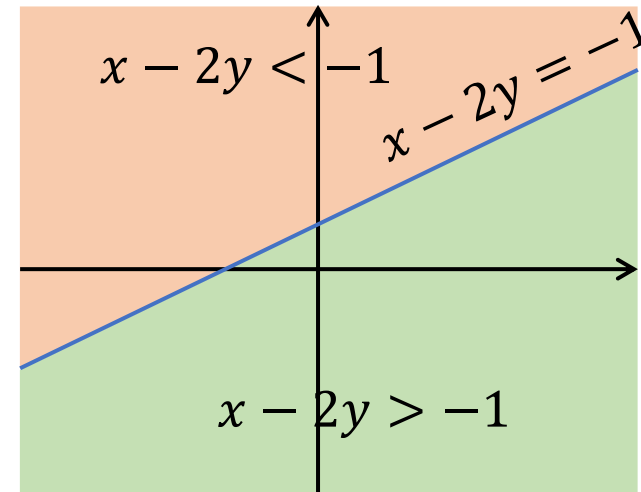
- Line in the plane
- Plane in space
- ...

A hyperplane is defined by a single equation

It partitions \mathbb{R}^d into two ***half-spaces***

$$x - 2y < -1 \quad \text{open half-space}$$

$$x - 2y \leq -1 \quad \text{closed half-space}$$



Affine transformation

An **affine transformation** is a linear transformation plus a translation

$$f: \mathbb{R}^d \rightarrow \mathbb{R}^k \quad \text{given by} \quad f(v) = Av + b$$

\uparrow \uparrow
 $k \times d$ matrix vector of size k

Example in the plane:

