MedXact-Arm

Executive Summary



MedXact Robotic Arm

is a low-cost, compact, and userfriendly robotic system designed to enhance surgical and ophthalmic procedures with high precision, remote speed. and control capabilities. It features a 3D-printed, eco-friendly robotic arm controlled by an ESP32 sensor glove that tracks hand and finger gestures in real-time. The system includes servo-driven joints for accuracy, an ESP32-CAM for object detection and live video feedback, and a memory module for learning from AI-based past procedures. MedXact addresses the limitations of current surgical robotics by making advanced robotic surgery accessible, affordable, and more efficient.

problem Statement



The Medxact robotic arm addresses critica challenges in global healthcare:

- Surgeon Shortage: Limited access to skilled surgeons especially in rural or underserved areas.
- High Cost of Robotic Systems: Most surgical robots are too expensive for widespread use in developing
- Human Error: Fatigue and inconsistency in manual surgery highlight the need for precise, reliable tools
- Training Limitations: Safe, repeatable practice environments are scarce, impacting surgical learning
- Emergency & Remote Access: Many settings lack advanced surgical tools or specialist support.
- Infection Control: Surgical environments demand tools that minimize infection risk and are easy to sterilize.

Solution

The MedXact Robotic Arm offers a compact cost-effective, and intuitive alternative to current robotic surgical systems that are often expensive, bulky, and complex. Designed for precisionbased medical procedures, it uses a 3D-printed arm with servo-driven joints, controlled by an ESP32-based glove equipped with sensors for real-time hand gesture control. Integrated with an ESP32-CAM for computer vision, it provides live video feedback and object detection during surgery to enhance accuracy. A memory unit stores surgical data for AI-based learning, enabling the arm to eventually perform repetitive procedures autonomously. MedXact makes advanced robotic surgery accessible to under-resourced healthcare centers and serves as a valuable tool for medical education and training—aligning with global goals to deliver safe, efficient, and affordable healthcare.

Operational Plan



The MedXact Robotic Arm will be developed, manufactured, and deployed

as a compact, cost-effective, and intelligent solution for surgical assistance and training.

Applications:

- Medical Procedures: Precision surgeries, especially in ophthalmology and minimally invasive fields.
- Medical Education: Hands-on training using gesturebased robotic control.
- Resource-Limited Facilities: Affordable alternative for clinics and hospitals with budget constraints.

Technology Stack:

- 3D-Printed Robotic Arm: Servo-controlled, modular, and durable.
- Wearable Control Glove: Equipped with LDRs, LEDs, and a gyroscope for real-time gesture tracking.
- ESP32-CAM Module: Provides live video feedback and object detection.
- Al Memory Unit: Stores surgical data for machine learning and future autonomous task execution.

(ev Advantages:

- Cost Efficiency: LDR-based glove costs <100 pounds compared to ~1,250 pounds for flex sensors.
- Compact & Modular: Easy to deploy, maintain, and adapt to different procedures.
- Remote Operation & AI: Enables tele-surgery and selflearning capabilities.

Goal-Oriented Design:

- Solves the cost, complexity, and size issues seen in systems like the da Vinci robot.
- Increases access to robotic surgery in underserved regions and enhances medical training worldwide.

Initial Costs



2810-2945 Hardware Software Development 7500 Miscellaneous 1800 ≈12,110 - 12,245 EG **Grand Total**

Target Market



Competitive Advantage

MedXact stands out with its cost-effective and innovative control system. By using LDR sensors and LEDs for finger movement detection instead of traditional flex sensors, the glove-based control system achieves precise gesture tracking at a fraction of the cost. While a full set of flex sensors can cost around 1,250 pounds, the LDR-based system for all five finger costs less than 100 pounds. This significant reduction in hardware cost makes MedXact a highly affordable solution without compromising functionality—giving it a strong edge in markets with limited resources. Combined with its compact design, modular structure, and AI learning capabilities, MedXact delivers highperformance robotic surgery at a disruptive price point.

Risks and Challenges

Material Durability Challenge

During development of the Medxact robotic arm, certain 3D-printed plastic components—especially joints and motor mounts—showed poor durability under mechanical stress. These areas experienced cracking and deformation, affecting performance and reliability.

The plastic materials used lacked the strength to withstand operational loads at high-stress points, leading to structural failure over time. Risks:

- System failure from damaged critical parts
- Increased maintenance and repair costs
- Reduced customer confidence
- Limited scalability for industrial applications

Mitigation:

We are shifting to high-strength composites and reinforced polymers, supported by advanced stress simulations to redesign and strengthen key

Marketing Plan

The Medxact Robotic Arm operates on a business model focused on delivering affordable, precise, and compact surgical robotics to hospitals, training institutions, and remote clinics. Revenue is generated through direct sales, leasing options, software licensing, and ongoing support and training services. By partnering with medical universities, NGOs, and health agencies, Medxact ensures wide accessibility and trust. Its core activities include product development, clinical validation, and customer support, while maintaining a lean cost structure centered on R&D, manufacturing, and distribution.