

"Digital Signal"

* Section 2 *

Signal

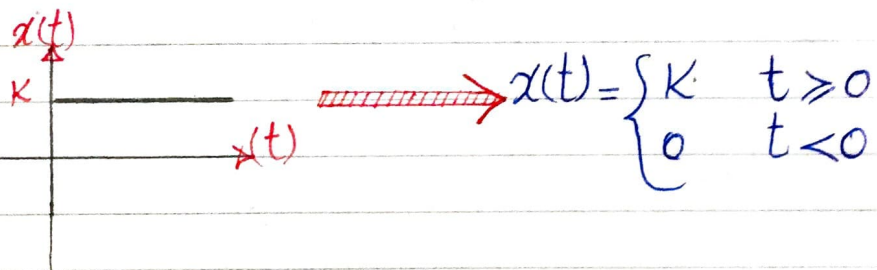


System: interconnection between more than device «Component».

1) Continuous Signal: -

1. Step Signal:

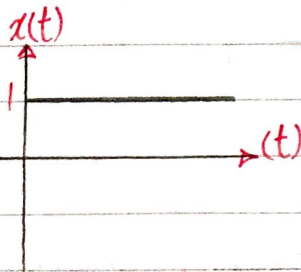
graph:



$$x(t) = \begin{cases} K & t \geq 0 \\ 0 & t < 0 \end{cases}$$

- Unit Step Signal:

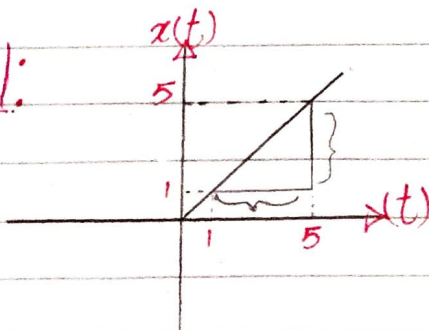
graph:



$$x(t) = \begin{cases} 1 & t \geq 0 \\ 0 & t < 0 \end{cases}$$

2. Ramp Signal:

graph:

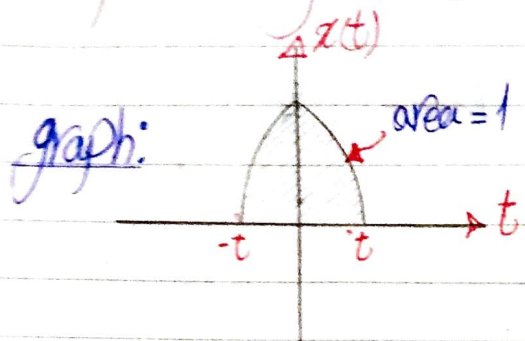


$$\text{slope} = \frac{x(t_2) - x(t_1)}{t_2 - t_1} = 1$$

$$x(t) = \begin{cases} t & t \geq 0 \\ 0 & t < 0 \end{cases}$$

if slope $\neq 1$, $\therefore x(t) = \begin{cases} k \cdot t & t \geq 0 \\ 0 & t < 0 \end{cases}$

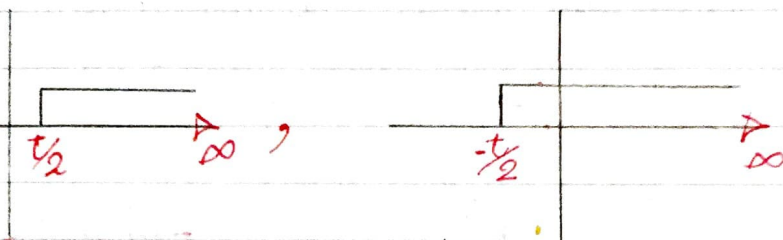
3. Impulse Signal: $\delta(t)$



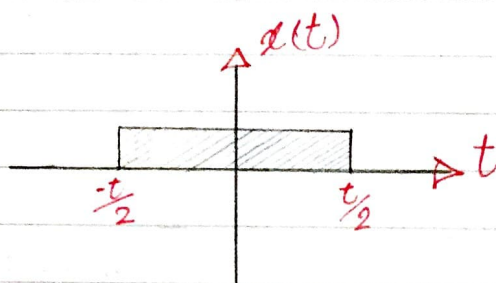
$\delta(t) = 0$, at $t \neq 0$
 $\int_{-t}^t \delta(t) dt = 1$
 $\int_{-t}^{t_1+t} \delta(t-t_1) f(t_1) dt = f(t)$

4. Pulse Signal:

- Consists of 2 signals:



graph:



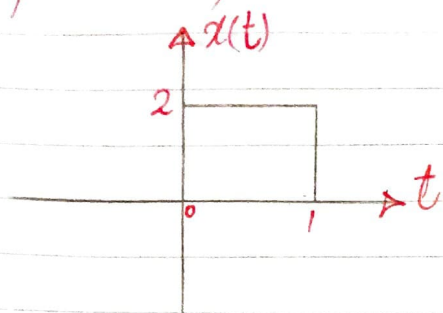
5. Periodic Signal:

$x(t) \rightarrow x(t+T)$ period.

- example: $x(t) = \sin(\omega t + \theta)$
 $= \sin(\omega t + \theta + 2\pi)$
 $= \sin\left[\omega\left(t + \frac{2\pi}{\omega}\right) + \theta\right]$
 $= x(t) + 2\pi$

* operations on Continuous Signal:-

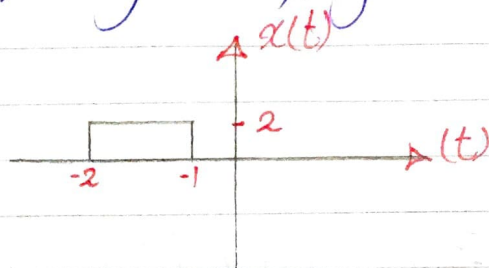
1) Phase Shift: For Time $\langle 0, 1 \rangle$ Not magnitude



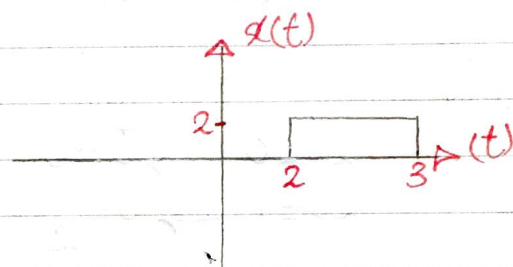
$x(t+2)$ positive shift left

$x(t-2)$ negative shift right

- positive shift left: $t+2=0 \rightarrow t=-2$
 $t+2=1 \rightarrow t=-1$

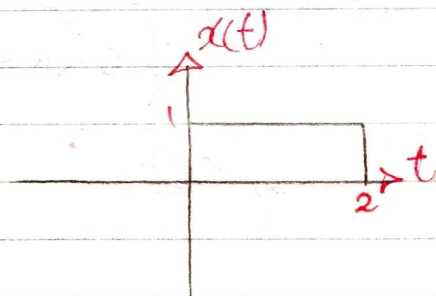
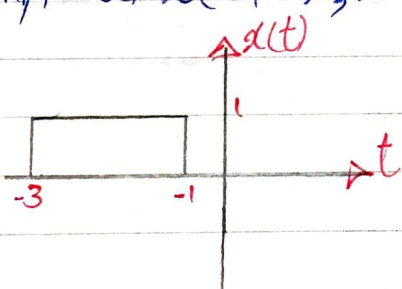


- negative shift right: $t-2=0 \rightarrow t=2$
 $t-2=1 \rightarrow t=3$

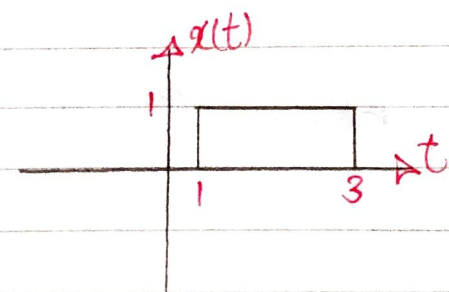


- Example: Find phase shift at $x(t+3)$, $x(t-1)$

$\Rightarrow t+3=0 \rightarrow t=-3$
 $t+3=2 \rightarrow t=-1$



$\Rightarrow t-1=0 \rightarrow t=1$
 $t-1=2 \rightarrow t=3$

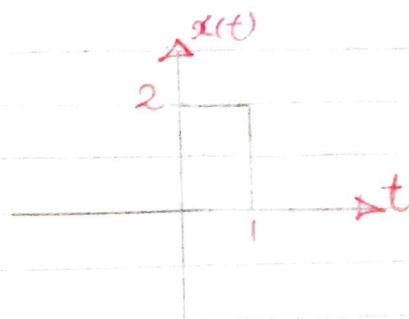
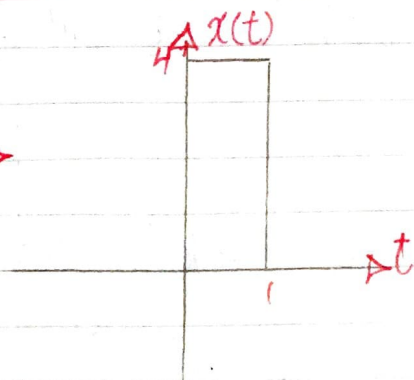


2) Scaling: "For magnitude and time"

1. magnitude:

- Form: $\text{Const. } x(t)$

ex: Find $2x(t)$

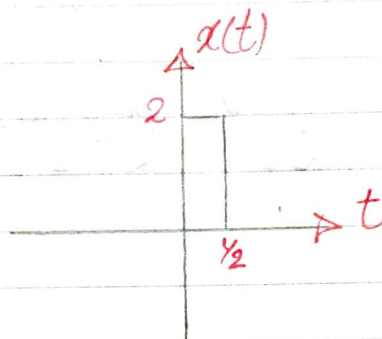


2. time:

- Form: $x(\text{Const. } t)$

ex: Find $x(2t)$

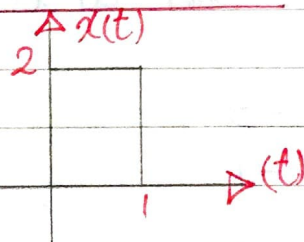
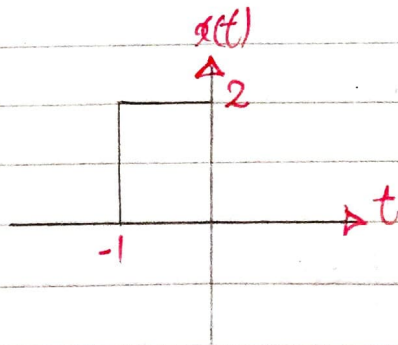
$$\begin{aligned} \Rightarrow 2t=0 &\rightarrow t=0 \\ 2t=1 &\rightarrow t=\frac{1}{2} \end{aligned}$$



* at time scaling, if $K > 1 \rightarrow$ compression
if $0 < K < 1 \rightarrow$ stretching

3) mirror reflection: " $x(-t)$ "

$$\begin{aligned} \Rightarrow -t=0 &\rightarrow t=0 \\ -t=1 &\rightarrow t=-1 \end{aligned}$$

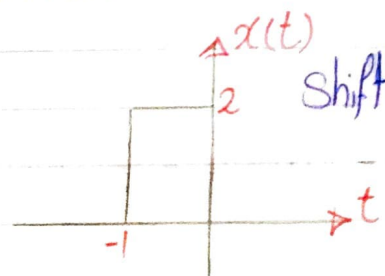


* General Example:

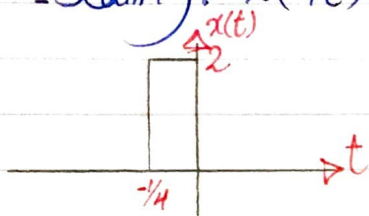
- Find: 1) $x(-4t+1)$
2) $3x(-2t+3)$

- We have to solve by order: Shift then scaling then mirror.

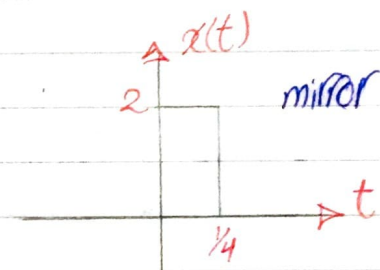
⇒ 1) - Shift: $x(t+1)$ $t+1=0 \rightarrow t=-1$
 $t+1=1 \rightarrow t=0$



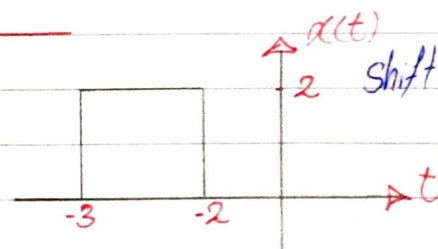
- Scaling: $x(4t)$ $4t=-1 \rightarrow t=-1/4$
 $4t=0 \rightarrow t=0$



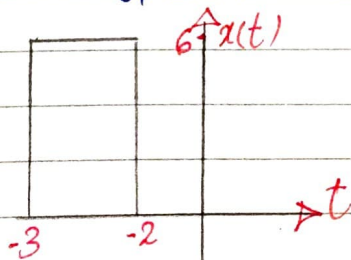
- mirror: $x(-t)$ $-t=-1/4 \rightarrow t=1/4$
 $-t=0 \rightarrow t=0$



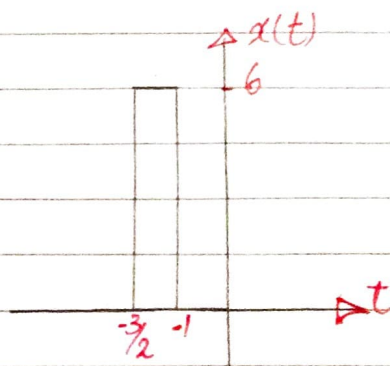
⇒ 2) - Shift: $x(t+3)$ $t+3=0 \rightarrow t=-3$
 $t+3=1 \rightarrow t=-2$



- mag. scaling: $3x(t)$



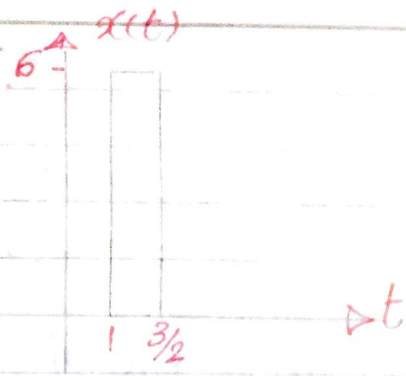
- time scaling: $x(2t)$ $2t=-2 \rightarrow t=-1$
 $2t=-3 \rightarrow t=-3/2$



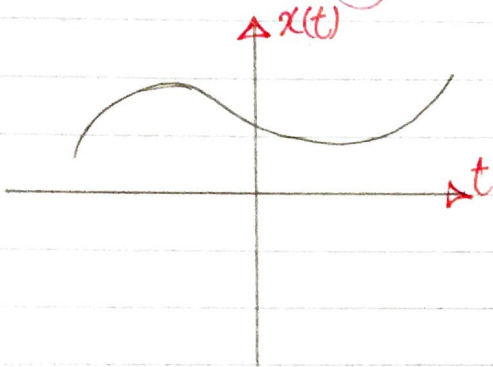
- mirror: $x(-t)$

$$-t = -1 \rightarrow t = 1$$

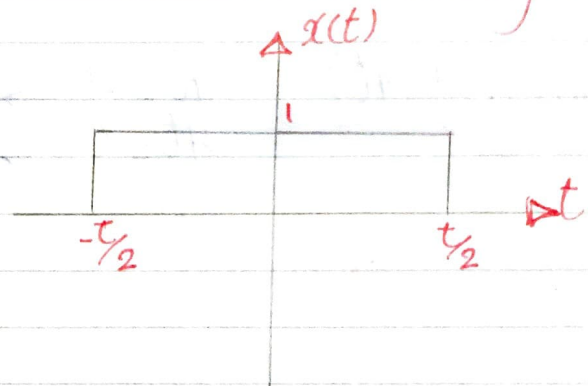
$$-t = -\frac{3}{2} \rightarrow t = \frac{3}{2}$$



- Continuous Signal



- Piecewise Continuous Signal



- There is low change in signal values.

- There is sudden change in signal values.