



COMPUTER GRAPHICS SECTION

MidPoint Ellipse Drawing Algorithm



Agenda

- MidPoint Ellipse definitions.
- Mid Point Ellipse Algorithm.
- Algorithm steps.
- Code.

Mid Point Ellipse Algorithm

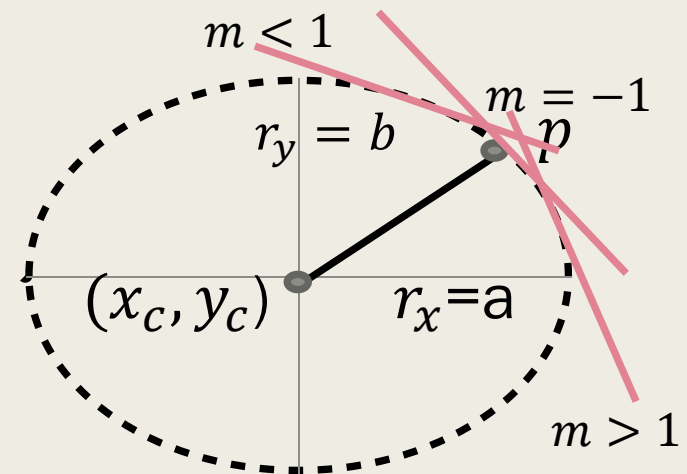
- With respect to Circle drawing function
 - $x^2 + y^2 - r^2 = 0$
- Suppose the initial point is x_0, y_0

$$\left(\frac{x - x_c}{r_x} \right)^2 + \left(\frac{y - y_c}{r_y} \right)^2 = 1$$

- Setting the initial point of ellipse $x_0 = 0$ and $y_0 = 0$.

- $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$

- $x^2 b^2 + y^2 a^2 - a^2 b^2 = 0$



Mid Point Ellipse Algorithm Cont...

- Where slope $m = \frac{dy}{dx}$
- So we will calculate partial derivative with respect to $x = 2xb^2$
- So we will calculate partial derivative with respect to $y = 2ya^2$
- So $m = \frac{dy}{dx} = \frac{2xb^2}{2ya^2}$
- So to remove from octant one to octant two we will stop at this condition :-
 - $2xb^2 > 2ya^2$

Mid Point Ellipse Algorithm Cont...

- For $m < 1$:

- $X \rightarrow \text{unit interval}$
- $y_{K+1} = y_K / y_{K-1}$
- $(x_{K+1}, y_K) \quad , \quad (x_{K+1}, y_{K-1})$

- Mid point = $(x_{K+1}, y_K - \frac{1}{2})$

- Where $x^2 r_y^2 + y^2 r_x^2 - r_x^2 r_y^2 = 0$

- So $p_{1K} = (x_k + 1)^2 r_y^2 + (y_k - \frac{1}{2})^2 r_x^2 - r_x^2 r_y^2 = 0$
- So $p_{1K+1} = (x_{k+1} + 1)^2 r_y^2 + (y_{k+1} - \frac{1}{2})^2 r_x^2 - r_x^2 r_y^2 = 0$

Mid Point Ellipse Algorithm Cont...

$$\text{So } p_{1K} = (x_k+1)^2 r_y^2 + (y_k - \frac{1}{2})^2 r_x^2 - r_x^2 r_y^2 = 0$$

$$\text{So } p_{1K+1} = (x_{k+1}+1)^2 r_y^2 + (y_{k+1} - \frac{1}{2})^2 r_x^2 - r_x^2 r_y^2 = 0$$

- $p_{1K+1} - p_{1K} = \cancel{(x_{k+1})^2 r_y^2 + r_y^2 + 2(x_{k+1})r_y^2 + (y_{k+1})^2 r_x^2 + \frac{1}{4} r_x^2} - \cancel{(y_{k+1})r_x^2 - r_x^2 r_y^2 - (x_k+1)^2 r_y^2 - y_k^2 r_x^2 - \frac{1}{4} r_x^2 + y_k r_x^2 + r_x^2 r_y^2}$
- $p_{1K+1} = p_{1K} + r_y^2 + 2(x_{k+1})r_y^2 + r_x^2 [(y_{k+1}^2) - y_k^2] - r_x^2 [y_{k+1} - y_k]$

Mid Point Ellipse Algorithm Cont...

$$\text{So } p_{1K} = (x_k + 1)^2 r_y^2 + (y_k - \frac{1}{2})^2 r_x^2 - r_x^2 r_y^2 = 0$$

■ For the initial parameter

- $(0, r_y)$.

- $p_{1k} = (0 + 1)^2 r_x^2 + (r_y - \frac{1}{2})^2 r_x^2 - r_x^2 r_y^2 = 0$

- $p_{1k} = r_y^2 + \frac{r_x^2}{4} - r_y r_x^2$

Mid Point Ellipse Algorithm Cont...

- For $p_{1k} < 0$
 - $(x_k + 1, y_k)$
 - $p_{1k+1} = p_{1k} + 2r_y^2 x_{k+1} + r_y^2$
- For $p_{1k} \geq 0$
 - $(x_k + 1, y_{k-1})$
 - $p_{1k+1} = p_{1k} + 2r_y^2 x_{k+1} - 2r_x^2 y_{k+1} + r_y^2$
- Loop until
 - $2r_y^2 x \geq 2r_x^2 y$

Mid Point Ellipse Algorithm Cont...

- For $m > 1$:
 - $y \rightarrow \text{unit interval}$
 - $x_{K+1} = x_K / x_{K+1}$
 - $(x_K, y_{K-1}) \quad , \quad (x_{K+1}, y_{K-1})$
- Mid point = $(x_{K+\frac{1}{2}}, y_K - 1)$
- Where $x^2 r_y^2 + y^2 r_x^2 - r_x^2 r_y^2 = 0$
 - So $p_{2K} = (x_k + \frac{1}{2})^2 r_y^2 + (y_k - 1)^2 r_x^2 - r_x^2 r_y^2 = 0$
 - So $p_{2K+1} = (x_{k+\frac{1}{2}} + 1)^2 r_y^2 + (y_{k+1} - 1)^2 r_x^2 - r_x^2 r_y^2 = 0$
- $p_{2K+1} = p_{2K} + r_x^2 - 2(y_{k-1})r_x^2 + r_y^2[(x_{k+1}) - x_k] + r_y^2[x_{k+1} - x_k]$

Mid Point Ellipse Algorithm Cont...

- For $p_{2k} \geq 0$
 - (x_k, y_{k-1})
 - $p_{2k+1} = p_{2k} - 2r_x^2 y_{k+1} + r_x^2$
- For $p_{2k} < 0$
 - $(x_k + 1, y_{k-1})$
 - $p_{2k+1} = p_{2k} + 2r_y^2 x_{k+1} - 2r_x^2 y_{k+1} + r_x^2$
- Loop until
 - $2r_y^2 x_{k+1} \geq 2r_x^2 y_{k+1}$

Algorithm steps

1. Input r_x , r_y and ellipse center x_c , y_c and obtain the first point on an ellipse centered on the origin as x_0 , $y_0 = 0$, r_y .

2. Calculate the initial value of the decision parameter in region 1 as

$$1. \quad p_{1k} = r_y^2 + \frac{r_x^2}{4} - r_y r_x^2$$

3. At each x_k position in region 1, starting at $k=0$ perform the following test:

If $p_{1k} < 0$, The next point along the ellipse centered on 0,0 is x_{k+1} , y_k and

$$p_{1k+1} = p_{1k} + 2r_y^2 x_{k+1} + r_y^2$$

Else

$$p_{1k+1} = p_{1k} + 2r_y^2 x_k + 1 - 2r_x^2 y_{k+1} + r_y^2$$

Algorithm steps Cont...

where

$$2r_y^2 x_{k+1} = 2r_y^2 x_k + 2r_y^2$$

$$2r_x^2 y_{k+1} = 2r_x^2 y_k - 2r_x^2$$

And continue until

$$2r_y^2 x \geq 2r_x^2 y$$

Algorithm steps Cont...

- Calculate the initial value of the decision parameter in region 2 using the last point x_0, y_0 calculated in region 1 as

$$P2_0 = r_y^2 \left(x_0 + \frac{1}{2} \right)^2 + r_x^2 (y_0 - 1)^2 - r_x^2 r_y^2$$

Algorithm steps Cont...

- At each y_k position in region 2, starting at $k=0$ perform the following test until $y = 0$: If $P_{2k} > 0$,

$$- p_{2k+1} = p_{2k} - 2r_x^2 y_{k+1} + r_x^2$$

Else

The next point along the ellipse centered on 0, 0 is x_{k+1} and y_{k+1} and

$$p_{2k+1} = p_{2k} + 2r_y^2 x_{k+1} - 2r_x^2 y_{k+1} + r_x^2$$

Algorithm steps Cont...

- Determine symmetry points in the other three quadrants.
- Move each calculated pixel position x, y onto the elliptical path centered on x_c, y_c and plot the coordinate values: $x = x + x_c, y = y + y_c$

```

#include<GL\include\GL\freeglut.h>
#include<Windows.h>
#include<stdio.h>
void midptellipse(int rx, int ry,
int xc, int yc)
{
float dx, dy, d1, d2, x, y;
x = 0;
y = ry;

// Initial decision parameter of region 1
d1 = (ry * ry) - (rx * rx * ry) +
(0.25 * rx * rx);
dx = 2 * ry * ry * x;
dy = 2 * rx * rx * y;
glClearColor(1.0, 1.0, 1.0, 1.0);
glClear(GL_COLOR_BUFFER_BIT);
glColor3f(1.0, 0.0, 0.0);
glPointSize(1.0);
glBegin(GL_POINTS);
// For region 1
while (dx < dy)
{

```

```

// Print points based on 4-way symmetry
glVertex2i(x + xc, y + yc);
glVertex2i(-x + xc, y + yc);
glVertex2i(x + xc, -y + yc);
glVertex2i(-x + xc, -y + yc);

// Checking and updating value of
// decision parameter based on algorithm
if (d1 < 0)
{
x++;
dx = dx + (2 * ry * ry);
d1 = d1 + dx + (ry * ry);
}
else
{
x++;
y--;
dx = dx + (2 * ry * ry);
dy = dy - (2 * rx * rx);
d1 = d1 + dx - dy + (ry * ry);
}
}

```



```

// Decision parameter of region 2
d2 = ((ry * ry) * ((x + 0.5) * (x + 0.5))) +
((rx * rx) * ((y - 1) * (y - 1))) -
(rx * rx * ry * ry);

// Plotting points of region 2
while (y >= 0)
{
    // Print points based on 4-way symmetry
    glVertex2i(x + xc, y + yc);
    glVertex2i(-x + xc, y + yc);
    glVertex2i(x + xc, -y + yc);
    glVertex2i(-x + xc, -y + yc);
    // Checking and updating parameter
    // value based on algorithm
    if (d2 > 0)
    {
        y--;
        dy = dy - (2 * rx * rx);
        d2 = d2 + (rx * rx) - dy;
    }
    else
    {

```

```

        y--;
        x++;
        dx = dx + (2 * ry * ry);
        dy = dy - (2 * rx * rx);
        d2 = d2 + dx - dy + (rx * rx);
    }
}
glEnd();
glFlush();
}

void display()
{
    midptellipse(80, 60, 0, 0);
}

int main(int argc, char** argv)
{
    glutInit(&argc, argv);
    glutInitDisplayMode(GLUT_SINGLE | GLUT_RGB);
    glutInitWindowPosition(300, 300);
    glutInitWindowSize(600, 600);
    glutCreateWindow("Mid Point Circle Algorithm");
    gluOrtho2D(-600, 600, -600, 600);
    glutDisplayFunc(display);
    glutMainLoop();
    return 0;
}

```

Sheet_3

- Using Mid point ellipse Algorithm to define ellipse pixels in four quarters using $x_c=50$ and $y_c=150$:
 - With $R_x = 6$ and $R_y = 9$



THE END