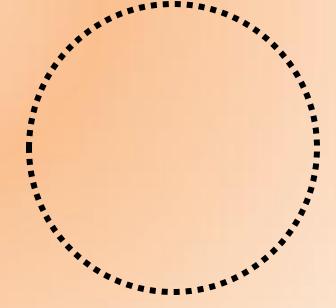
Computer Graphics Lecture 4

By
Kareem Ahmed

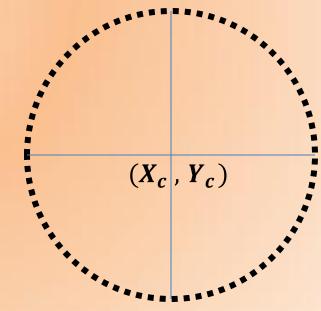
- A circle is defined as a set of points that are all have the same distance from a given center (X_c, Y_c) .
- This distance relationship is expressed by the pythagorean theorem in Cartesian coordinates as

$$(x - x_c)^2 + (y - y_c)^2 = r^2$$

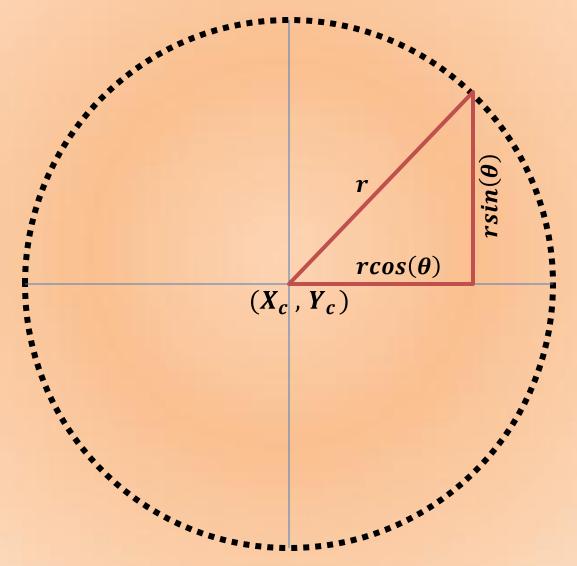


We could use this equation to calculate the points on the circle circumference by stepping along x-axis in unit steps from $x_c - r$ to $x_c + r$ and calculate the corresponding y values at each position from

$$y = y_c \pm \sqrt{r^2 - (x_c - x)^2}$$



- Drawbacks:
 - Considerable amount of computation
 - Spacing between plotted pixels is not uniform

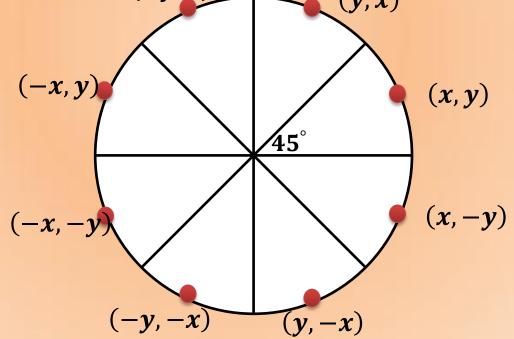


• We could use polar coordinates r and θ ,

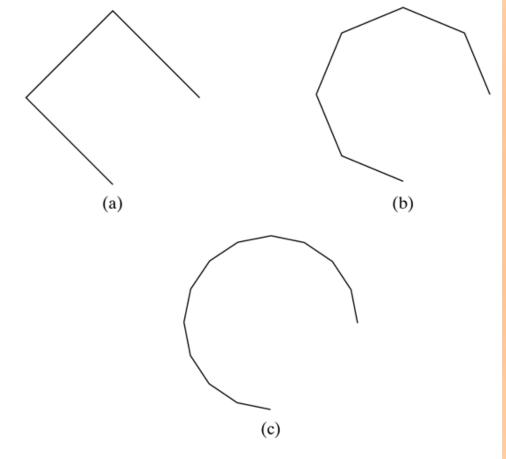
$$x = x_c + r\cos(\theta)$$
$$y = y_c + \sin(\theta)$$

- A fixed angular step size can be used to plot equally spaced points along the circumference
- A step size of 1/r can be used to set pixel positions to approximately 1 unit apart for a continuous boundary

• But, note that circle sections in adjacent octants within one quadrant are symmetric with respect to the 45° line dividing the two octants.



- Symmetry of a circle. Calculation of a circle point (x, y) in one octant yields the circle points shown for the other seven octants
- Thus we can generate all pixel positions around a circle by calculating just the points within the sector from x=0 to x=y
- But This method is still computationally expensive



A circular arc approximated with (a) three straight-line segments, (b) six line segments, and (c) twelve line segments.

- Determining pixel positions along a circle circumference using Cartesian or polar coordinates equations still requires a good deal of computation time.
- The Cartesian equation involves multiplications and square-root calculations, while the parametric equations contain multiplications and trigonometric calculations.
- More efficient circle algorithms are based on incremental calculation of decision parameters, as in the Bresenham line algorithm, which involves only simple integer operations.

 Bresenham's line algorithm for raster displays is adapted to circle generation by setting up decision parameters for finding the closest pixel to the circumference at each sampling step.

- A method for direct distance comparison is to test the halfway position between two pixels to determine if this midpoint is inside or outside the circle boundary.
- This method is more easily applied to other conics; and for an integer circle radius, the midpoint approach generates the same pixel positions as the Bresenham circle algorithm.
- Also, the error involved in locating pixel positions along any conic section using the midpoint test is limited to one-half the pixel separation.

- Bresenham requires explicit equation
 - Not always convenient (many equations are implicit)
 - Based on implicit equations: Midpoint Algorithm (circle, ellipse, etc.)
 - Implicit equations have the form F(x,y)=0.

 We will first calculate pixel positions for a circle centered around the origin (0,0). Then, each calculated position (x,y) is moved to its proper screen position by adding xc to x and yc to y

- Note that along the circle section from x=0 to x=y in the first octant, the slope of the curve varies from 0 to 1.
- Circle function around the origin is given by

$$f_{\text{circle}}(x, y) = x^2 + y^2 - r^2$$

 Any point (x,y) on the boundary of the circle satisfies the equation and circle function is zero

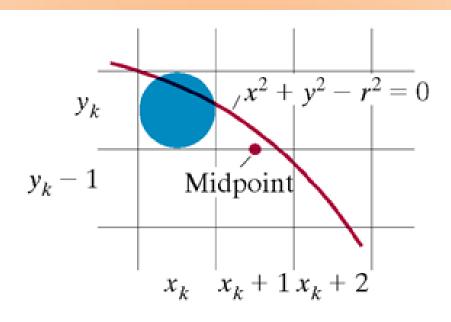
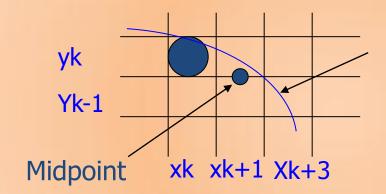


Figure 3-19

Midpoint between candidate pixels at sampling position $x_k + 1$ along a circular path.

- For a point in the interior of the circle, the circle function is negative and for a point outside the circle, the function is positive
- Thus,
 - $-f_{\text{circle}}(x,y) < 0$ if (x,y) is inside the circle boundary
 - $-f_{\text{circle}}(x,y) = 0 \text{ if } (x,y) \text{ is on the circle boundary}$
 - $-f_{\text{circle}}(x,y) > 0$ if (x,y) is outside the circle boundary



$$x^2 + y^2 - r^2$$

Midpoint between candidate pixels at sampling position x_k+1 along a circular path

• Assuming we have just plotted the pixel at (x_k, y_k) , we next need to decide which one of the following two pixels is closer to the circle:

$$(x_{k+1}, y_k)$$
 or (x_{k+1}, y_{k-1})

 Our decision parameter is the circle function evaluated at the midpoint between these two pixels

$$P_{k} = f_{\text{circle}} \left(x_{k} + 1, y_{k} - \frac{1}{2} \right)$$

$$P_{k} = (x_{k} + 1)^{2} + \left(y_{k} - \frac{1}{2} \right)^{2} - r^{2}$$

- If $P_k < 0$, this midpoint is inside the circle and the pixel on the scan line y_k is closer to the circle boundary.
- Otherwise, the mid position is outside or on the circle boundary, and we select the pixel on the scan line $y_k \, \, 1$

 Successive decision parameters are obtained using incremental calculations

$$P_{k+1} = f_{\text{circle}} \left(x_{k+1} + 1, y_{k+1} - \frac{1}{2} \right)$$

$$P_{k+1} = (x_{k+1} + 1)^2 + \left(y_{k+1} - \frac{1}{2} \right)^2 - r^2$$

$$P_{k+1} = P_k + 2(x_k + 1) + (y_{k+1}^2 - y_k^2) - (y_{k+1} - y_k) + 1$$

$$P_{k+1} = P_k + 2(x_k + 1) + (y_{k+1}^2 - y_k^2) - (y_{k+1} - y_k) + 1$$

If
$$P_k < 0$$

$$Y_{k+1} = Y_k$$

$$P_{k+1} = P_k + 2(x_k + 1) + (y_k^2 - y_k^2) - (y_k - y_k) + 1$$

$$P_{k+1} = P_k + 2(x_k + 1) + 1$$

$$P_{k+1} = P_k + 2x_{k+1} + 1$$

$$P_{k+1} = P_k + 2(x_k + 1) + (y_{k+1}^2 - y_k^2) - (y_{k+1} - y_k) + 1$$

If
$$P_k \geq 0$$

$$Y_{k+1} = Y_k - 1$$

$$P_{k+1} = P_k + 2(x_k + 1) + ((y_k - 1)^2 - y_k^2) - (y_k - 1 - y_k) + 1$$

$$P_{k+1} = P_k + 2(x_k + 1) + (-2y_k + 1) + 1 + 1$$

$$P_{k+1} = P_k + 2(x_k + 1) - 2y_k + 2 + 1$$

$$P_{k+1} = P_k + 2(x_k + 1) - 2(y_k - 1) + 1$$

$$P_{k+1} = P_k + 2x_{k+1} - 2y_{k+1} + 1$$

- Where y_{k+1} is either y_k or y_{k-1} , depending on the sign of P_k .
- Increments for obtaining P_{k+1} :

$$2X_{k+1} + 1$$
 if P_k is negative

$$2X_{k+1} + 1 - 2Y_{k+1}$$
 otherwise

 Note that following can also be done incrementally:

$$2X_{k+1} = 2X_k + 2$$
$$2Y_{k+1} = 2Y_k - 2$$

Midpoint Circle Algorithm

1. Input radius r and circle center (x_c, y_c) , and obtain the first point on the circumference of a circle centered on the origin as

$$(x_0, y_0) = (0, r)$$

2. Calculate the initial value of the decision parameter as

$$p_0=\frac{5}{4}-r$$

$$p_0 = f_{\text{circle}}\left(1, r - \frac{1}{2}\right)$$
$$= 1 + \left(r - \frac{1}{2}\right)^2 - r^2$$

or

$$p_0=\frac{5}{4}-r$$

If the radius r is specified as an integer, we can simply round p_0 to

$$p_0 = 1 - r$$
 (for r an integer)

since all increments are integers.

3. At each x_k position, starting at k = 0, perform the following test: If $p_k < 0$, the next point along the circle centered on (0, 0) is (x_{k+1}, y_k) and

$$p_{k+1} = p_k + 2x_{k+1} + 1$$

Otherwise, the next point along the circle is $(x_k + 1, y_k - 1)$ and

$$p_{k+1} = p_k + 2x_{k+1} + 1 - 2y_{k+1}$$

where $2x_{k+1} = 2x_k + 2$ and $2y_{k+1} = 2y_k - 2$.

- 4. Determine symmetry points in the other seven octants.
- 5. Move each calculated pixel position (x, y) onto the circular path centered on (x_c, y_c) and plot the coordinate values:

$$x = x + x_c, \quad y = y + y_c$$

6. Repeat steps 3 through 5 until $x \ge y$.

Example 3-2 Midpoint Circle-Drawing

Given a circle radius r = 10, we demonstrate the midpoint circle algorithm by determining positions along the circle octant in the first quadrant from x = 0 to x = y. The initial value of the decision parameter is

$$p_0 = 1 - r = -9$$

For the circle centered on the coordinate origin, the initial point is $(x_0, y_0) = (0, 10)$, and initial increment terms for calculating the decision parameters are

$$2x_0 = 0$$
, $2y_0 = 20$

Successive decision parameter values and positions along the circle path are calculated using the midpoint method as

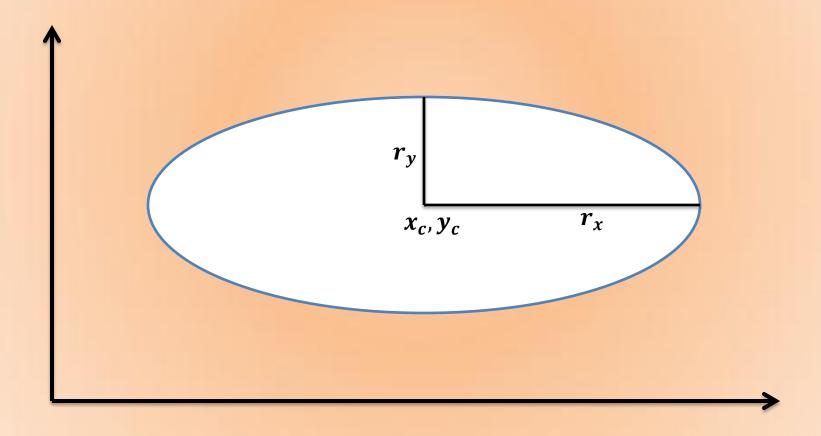
k	p_k	(x_{k+1}, y_{k+1})	$2x_{k+1}$	$2y_{k+1}$
0	-9	(1, 10)	2	20
1	-6	(2, 10)	4	20
2	-1	(3, 10)	6	20
3	6	(4, 9)	8	18
4	-3	(5, 9)	10	18
5	8	(6, 8)	12	16
6	5	(7, 7)	14	14

MidDaint Circle Algerithm

```
#include *device.h*
void circleMidpoint (int xCenter, int yCenter, int radius)
  int x = 0:
  int y = radius;
  int p = 1 - radius;
  void circlePlotPoints (int, int, int, int);
  /* Plot first set of points */
  circlePlotPoints (xCenter, yCenter, x, y);
  while (x < y) (
    x++;
    if (p < 0)
     p += 2 * x + 1;
    else {
      y--;
      p += 2 * (x - y) + 1;
    circlePlotPoints (xCenter, yCenter, x, y);
```

```
void circlePlotPoints (int xCenter, int yCenter, int x, int y)
  setPixel (xCenter + x, yCenter + y);
  setPixel (xCenter - x, yCenter + y);
  setPixel (xCenter + x, yCenter - y);
  setPixel (xCenter - x, yCenter - y);
  setPixel (xCenter + y, yCenter + x);
  setPixel (xCenter - y, yCenter + x);
  setPixel (xCenter + y, yCenter - x);
  setPixel (xCenter - y, yCenter - x);
```

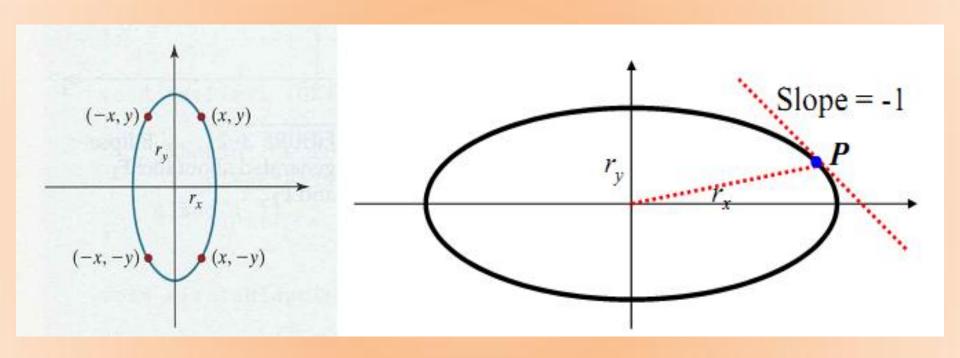
Last update on 11-3-2014



- Use symmetry of ellipse
- Divide the quadrant into two regions
 - the boundary of two regions is the point at which the curve has a slope of -1.
 - Process by taking unit steps in the x direction to the point P, then taking unit steps in the y direction

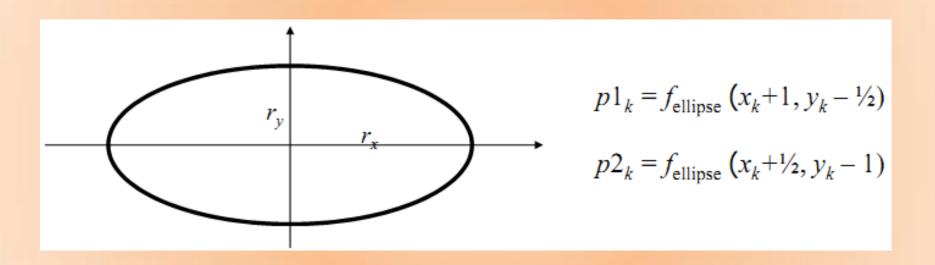
35

Apply midpoint algorithm.



$$\left(\frac{x - x_c}{r_x}\right)^2 + \left(\frac{y - y_c}{r_y}\right)^2 = 1$$

$$f_{\text{ellipse}}(x,y) = r_y^2 x^2 + r_x^2 y^2 - r_x^2 r_y^2$$
< 0 inside the ellipse boundary
$$= 0 \text{ on the ellipse boundary}$$
> 0 outside the ellipse boundary



1. Input r_x , r_y and ellipse center (x_c, y_c) and obtain the first point on an ellipse centered on the origin as

$$(x_0, y_0) = (0, r_y)$$

2. Calculate the initial value of the decision parameter in region 1 as

$$P1_0 = r_y^2 - r_x^2 r_y + \frac{1}{4} r_x^2$$

3. At each x_k position in region 1, starting at k=0 perform the following test:

If
$$P1_k < 0$$
,

- The next point along the ellipse centered on (0,0) is $(x_k + 1, y_k)$ and

$$P1_{k+1} = P1_k + 2r_y^2 x_{k+1} + r_y^2$$

Else

- The next point along the ellipse centered on (0,0) is $(x_k + 1, y_k - 1)$ and

$$P1_{k+1} = P1_k + 2r_y^2 x_{k+1} - 2r_x^2 y_{k+1} + r_y^2$$

where

$$2r_y^2 x_{k+1} = 2r_y^2 x_k + 2r_y^2$$

$$2r_x^2y_{k+1} = 2r_x^2y_k - 2r_x^2$$

And continue until

$$2r_y^2x \geq 2r_x^2y$$

4. Calculate the initial value of the decision parameter in region 2 using the last point (x_0, y_0) calculated in region 1 as

$$P2_0 = r_y^2 \left(x_0 + \frac{1}{2}\right)^2 + r_x^2 (y_0 - 1)^2 - r_x^2 r_y^2$$

5. At each y_k position in region 2, starting at k=0 perform the following test until y = 0:

If
$$P2_k > 0$$
,

- The next point along the ellipse centered on (0, 0) is $(x_k, y_k - 1)$ and

$$P2_{k+1} = P2_k - 2r_x^2 y_{k+1} + r_x^2$$

Else

- The next point along the ellipse centered on (0,0) is $(x_k + 1, y_k - 1)$ and

$$P2_{k+1} = P2_k + 2r_y^2 x_{k+1} - 2r_x^2 y_{k+1} + r_x^2$$

- 6. Determine symmetry points in the other three quadrants.
- 7. Move each calculated pixel position (x, y) onto the elliptical path centered on (x_c, y_c) and plot the coordinate values:

$$x = x + x_c$$
$$y = y + y_c$$