" Modhs II,

* Lecture 4*

* Linear Iransformations *

Definition if u, v are two vectorspaces on the Same field, then the mapping I.V. u is Called a Linear transformation if it satisfies the following Conditions:

1) - 1(a+y) = 1(a) + T(y) , Y x, y \(\var{v} \) = \(\alpha \) | \(\alpha \) \(\var{v} \) \(\var

heaven: if u, v are two vectorspaces on the same field, then the mapping it iv _ u is called a linear transformation if . I (ax by) = area + b (y)

* Note: $\rightarrow \Gamma(0) = 0$ $\rightarrow \Gamma(-\alpha) = -\Gamma(\alpha)$

Example: Determine wheather the following mappings

i) $T(\alpha, y, z) = (\alpha, y, 0)$ ii) $T(\alpha, y) = \alpha y$ $\Rightarrow 0$ $\Rightarrow 1$ $\Rightarrow 1$

Let u= (d, J, Z), V=(2, J, Z)

 $au + bv = (ax_{1+}bx_{2}, ay_{1+}by_{2}, az_{1+}bz_{2})$

, 1(au + bx) = (ax + bx, cy+bx, 0) -> L.H.S

T(U)=T(a, y,, Z,)=(x,,y,,0)

 $T(V) = T(\chi_2, \chi_2, \chi_2) = (\chi_2, \chi_2, 0)$

aT(W+ bT(V) = (ax,+bx, ay,+b/2,0) -> R.H.S : L.H.S = R.H.S , L.T.

ii) T: R-R

let u= (d., J.), v= (de J2)

au+bv = (ax+bx2, ay+by2)

T(au+bv) = (au+ba2)(ay+b)= a2J, +ab2+ab22, +b22, -> LHS

T(u) = 2y, , T(v) = 2xy,

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, a I (W+b I (V) = ad J, + bd J, - R. H.s
- L.H. 8 + R.H. 8, Not 2.1.
Exi Let T: R R be alinear transformation such that:
 Find T(a,b) and then find T(3,4).
 \Rightarrow (a,b) = \alpha_1(1,1) + \alpha_2(0,1)
   a=d, b=d,+d2 = d2 = b-a.
   , I(a,b) = dil(1,1)+da T(0,1)
       = 3d_1 - 2d_2
      = 3a - 2(b - a)
       = 3a - 2b + 2a
    1 (a,b) = 5a - 2b
     1 (3, 4) = 5x3 - 2x4 = 7
-EX2: Let T: R2 R2 a. L.T Such that:
    \rightarrow T(1,1) = (0,2) , T(3,1) = (2,-4).
    Then find T(a,b), T(T,4)
  (a,b) = d_1(1,1) + d_2(3,1)
    a=d1+3d2, b=d1+d2 = = b-d1
  : D1 = Q - B D2
    d, = a - 3(b-a)
    di= a-3b+3a,
    2d1 = 3b - a
  - d1 = 3b - d2 , d2 = b- 3b + a
  =1(a,b)=d,1(1,1)+d_2(3,1)
            =\frac{3b}{2}-\frac{a}{2}(0,2)+b-\frac{3b}{2}+\frac{a}{2}(2,-H)
            =(0,3b-a)+(2b-3b+a,-4b+6b-2a)
   T(a,b) = (a-b, 5b-3a)

T(7.4) = (7-4, 5x4-3x7) = (3,-1)
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* Definition. The Kernal of e.L.T. 1:U , V is the Collection of vectors whose image under Tis Q, and denoted by "Ker (1)" The domain of T is the space u and denoted by dom (1) = u n
The Range of T is the collection of all images of all vectors of u under T
and denoted by a Rang (1) = v ». Note: - $f(\alpha) = \alpha^2$, f: R = RLy dom(f) = R, G = dom(f) = R, range = $Eo, \infty E$ Ex: Find Ker (1), ILW for the following L.T: i) T(d,, d2, d3) = (d, d2, d2 do) 11) T(2, 22, 23) = (2, de, 2, 25) > 1) T: R3 R2 Let u= (x, x2, x3) ER 3 T(U) = Q , 1(d, de, ds) = (0,0) : (A, A2, A2, A3) = (0,0) : d1-d2=0 , d2-23=0 : X1 = X2 = X3 : Ker (T) = } (d, de, ds) ER3: d=de = ds} : Ker(T) = { (1,1,1), (2,2,2), (3,3,3), ---} ii) T: R'_ R' Let u = (d, de, ds) ER 9 I(U) = 0 , T(d, de, d3) = (0,0,0) : (d+d2, d2, d3) = (0,0,0) · 1+ de =0 , le=0 , de=0 = 2 = 23 = 0 : Ker (T) = } (d, de, de) ER: d = 2= 2= 0} Ker(1) = (0,0,0) * Theorem: Let Ti, to: U-v be Two L.T, then (Ti+T2), (ITi) are L.T. too.