

# **Lecture 21**

## **Sparse Matrix Algorithms**

MIT 18.335J / 6.337J

Introduction to Numerical Methods

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November 28, 2006

# Sparse vs. Dense Matrices

- A *sparse matrix* is a matrix with enough zeros that it is worth taking advantage of them [Wilkinson]

$$\begin{bmatrix} \bullet & & \bullet & \bullet & \bullet \\ & \bullet & & & \\ \bullet & & \bullet & & \\ \bullet & & & \bullet & \\ & & & & \bullet \end{bmatrix}$$

- A *structured matrix* has enough structure that it is worthwhile to use it (e.g. Toeplitz)

$$\begin{bmatrix} a & b & c & d & e \\ b & a & b & c & d \\ c & b & a & b & c \\ d & c & b & a & b \\ e & d & c & b & a \end{bmatrix}$$

- A *dense matrix* is neither sparse nor structured

$$\begin{bmatrix} \bullet & \bullet & \bullet & \bullet & \bullet \\ \bullet & \bullet & \bullet & \bullet & \bullet \\ \bullet & \bullet & \bullet & \bullet & \bullet \\ \bullet & \bullet & \bullet & \bullet & \bullet \\ \bullet & \bullet & \bullet & \bullet & \bullet \end{bmatrix}$$

# MATLAB Sparse Matrices: Design Principles

- Most operations should give the same results for sparse and full matrices
- Sparse matrices are never created automatically, but once created they propagate
- Performance is important – but usability, simplicity, completeness, and robustness are more important
- Storage for a sparse matrix should be  $O(\text{nonzeros})$
- Time for a sparse operation should be close to  $O(\text{flops})$

# Data Structures for Matrices

## Full:

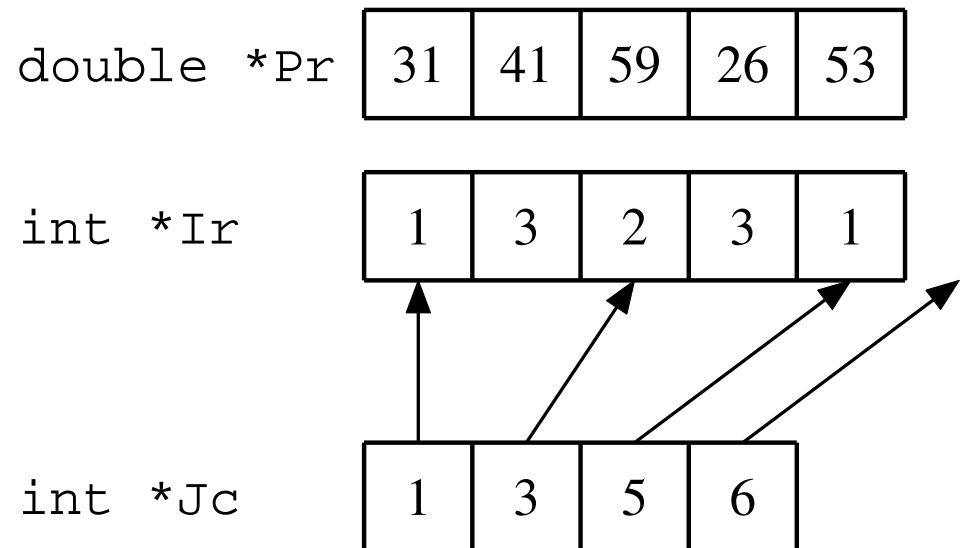
- Storage: Array of real (or complex) numbers
- Memory:  $\text{nrows} * \text{ncols}$

31	0	53
0	59	0
41	26	0

double \*A

## Sparse:

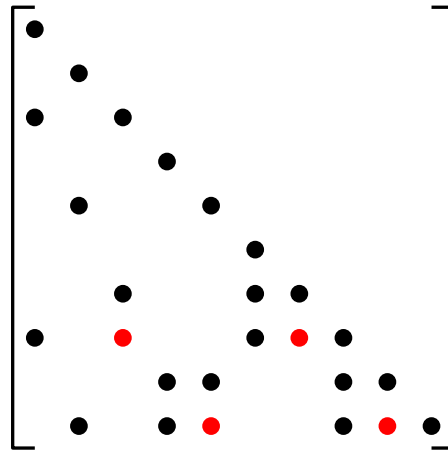
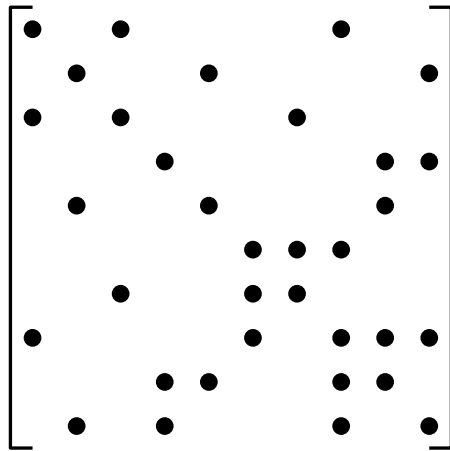
- Compressed column storage
- Memory: About  $1.5 * \text{nnz} + .5 * \text{ncols}$



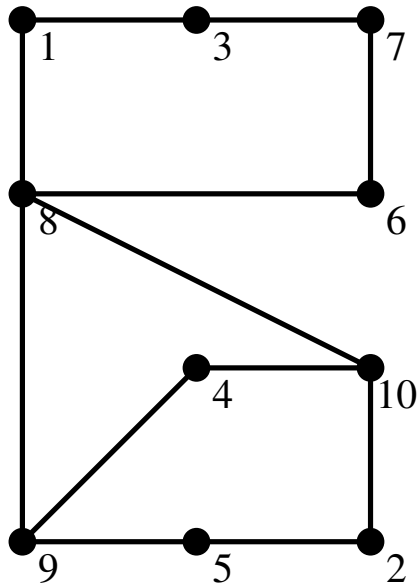
# Compressed Column Format - Observations

- Element look-up:  $O(\log \text{ \#elements in column})$  time
- Insertion of new nonzero very expensive
- Sparse vector = Column vector (not Row vector)

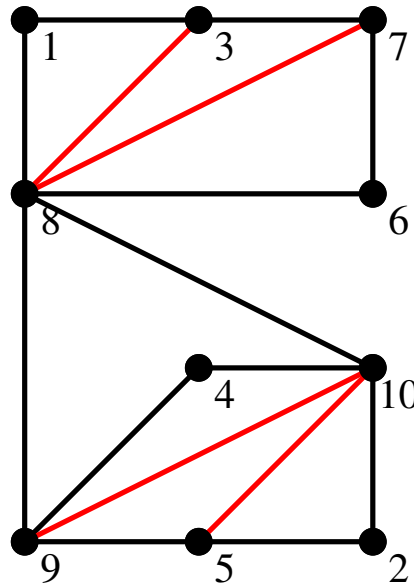
# Graphs and Sparsity: Cholesky Factorization



**Fill:** New nonzeros in factor



$G(A)$



$G^+(A)$

Symmetric Gaussian

Elimination:

**for**  $j = 1$  **to**  $N$

Add edges between  $j$ 's  
higher-numbered neighbors

# Permutations of the 2-D Model Problem

- 2-D Model Problem: Poisson's Equation on  $n \times n$  finite difference grid
- Total number of unknowns  $n^2 = N$
- Theoretical results for the fill-in:
  - With natural permutation:  $O(N^{3/2})$  fill
  - With any permutation:  $\Omega(N \log N)$  fill
  - With a *nested dissection* permutation:  $O(N \log N)$  fill

# Nested Dissection Ordering

- A *separator* in a graph  $G$  is a set  $S$  of vertices whose removal leaves at least two connected components
- A *nested dissection* ordering for an  $N$ -vertex graph  $G$  numbers its vertices from 1 to  $N$  as follows:
  - Find a separator  $S$ , whose removal leaves connected components  $T_1, T_2, \dots, T_k$
  - Number the vertices of  $S$  from  $N - |S| + 1$  to  $N$
  - Recursively, number the vertices of each component:  $T_1$  from 1 to  $|T_1|$ ,  $T_2$  from  $|T_1| + 1$  to  $|T_1| + |T_2|$ , etc
  - If a component is small enough, number it arbitrarily
- It all boils down to finding good separators!



# Heuristic Fill-Reducing Matrix Permutations

- Banded orderings (Reverse Cuthill-McKee, Sloan, etc):
  - Try to keep all nonzeros close to the diagonal
  - Theory, practice: Often wins for “long, thin” problems
- Minimum degree:
  - Eliminate row/col with fewest nonzeros, add fill, repeat
  - Hard to implement efficiently – current champion is “Approximate Minimum Degree” [Amestoy, Davis, Duff]
  - Theory: Can be suboptimal even on 2-D model problem
  - Practice: Often wins for medium-sized problems

# Heuristic Fill-Reducing Matrix Permutations


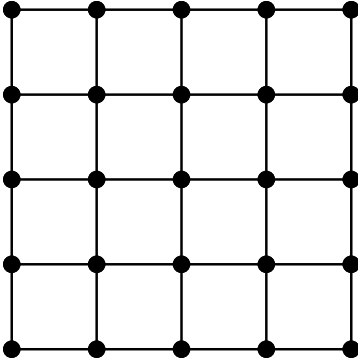
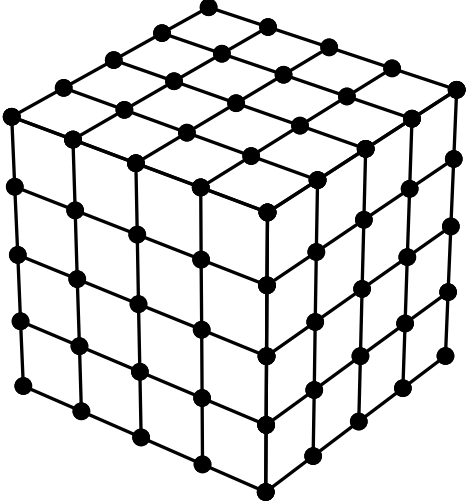
- Nested dissection:
  - Find a separator, number it *last*, proceed recursively
  - Theory: Approximately optimal separators  $\implies$  approximately optimal fill and flop count
  - Practice: Often wins for very large problems
- The best modern general-purpose orderings are ND/MD hybrids

# Fill-Reducing Permutations in Matlab

- Reverse Cuthill-McKee:
  - `p=symrcm(A)` ;
  - Symmetric permutation:  $A(p, p)$  often has smaller bandwidth than  $A$
- Symmetric approximate minimum degree:
  - `p=symamd(A)` ;
  - Symmetric permutation:  $\text{chol}(A(p, p))$  sparser than  $\text{chol}(A)$
- Nonsymmetric approximate minimum degree:
  - `p=colamd(A)` ;
  - Column permutation:  $\text{lu}(A(:, p))$  sparser than  $\text{lu}(A)$
- Symmetric nested dissection:
  - Not built into MATLAB, several versions in the MESHPART toolbox

# Complexity of Direct Methods

- Time and space to solve any problem on any well-shaped finite element mesh with  $N$  nodes:

			
	1-D	2-D	3-D
Space (fill):	$O(N)$	$O(N \log N)$	$O(N^{4/3})$
Time (flops):	$O(N)$	$O(N^{3/2})$	$O(N^2)$