# Introduction to Online Learning Algorithms

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#### **Outline**

Halving Algorithm

Hedge Algorithm

Perceptron

Laplace law of succession

expert1

expert2

expert3

expert4

expert5

expert6

expert7

expert8

alg.

```
expert1
```

expert2

expert3

expert4

expert5

expert6

expert7

expert8

alg.

outcome

```
t = 1
expert1
expert2
expert3
expert4
expert5
expert6
expert7
expert8
alg.
```

alg. outcome Halving Algorithm

```
t = 1
expert1
expert2
expert3
expert4
expert5
expert6
expert7
expert8
alg.
outcome
```

```
t = 1
expert1
expert2
expert3
expert4
expert5
expert6
expert7
expert8
alg.
outcome
```

```
t = 1 t = 2
expert1
expert2
expert3
expert4
expert5
expert6
expert7
expert8
alg.
outcome
```

	t = 1	<i>t</i> = 2
expert1	1	1
expert2	1	0
expert3	0	-
expert4	1	0
expert5	1	0
expert6	0	-
expert7	1	1
expert8	1	1
alg.	1	0
outcome	1	

	t = 1	<i>t</i> = 2
expert1	1	1
expert2	1	0
expert3	0	-
expert4	1	0
expert5	1	0
expert6	0	-
expert7	1	1
expert8	1	1
alg.	1	0
outcome	1	1

```
t = 1 t = 2 t = 3
expert1
expert2
expert3
expert4
expert5
expert6
expert7
expert8
alg.
outcome
```

	t = 1	<i>t</i> = 2	<i>t</i> = 3
expert1	1	1	1
expert2	1	0	-
expert3	0	-	-
expert4	1	0	-
expert5	1	0	-
expert6	0	-	-
expert7	1	1	1
expert8	1	1	1
alg.	1	0	1
outcome	1	1	

	t = 1	t = 2	t = 3
expert1	1	1	1
expert2	1	0	-
expert3	0	-	-
expert4	1	0	-
expert5	1	0	-
expert6	0	-	-
expert7	1	1	1
expert8	1	1	1
alg.	1	0	1
outcome	1	1	1

	t = 1	<i>t</i> = 2	t = 3	t = 4
expert1	1	1	1	1
expert2	1	0	-	-
expert3	0	-	-	-
expert4	1	0	-	-
expert5	1	0	-	-
expert6	0	-	-	-
expert7	1	1	1	1
expert8	1	1	1	0
alg.	1	0	1	
outcome	1	1	1	

	t = 1	<i>t</i> = 2	t = 3	t = 4
expert1	1	1	1	1
expert2	1	0	-	-
expert3	0	-	-	-
expert4	1	0	-	-
expert5	1	0	-	-
expert6	0	-	-	-
expert7	1	1	1	1
expert8	1	1	1	0
alg.	1	0	1	1
outcome	1	1	1	

	t = 1	<i>t</i> = 2	t = 3	t = 4
expert1	1	1	1	1
expert2	1	0	-	-
expert3	0	-	-	-
expert4	1	0	-	-
expert5	1	0	-	-
expert6	0	-	-	-
expert7	1	1	1	1
expert8	1	1	1	0
alg.	1	0	1	1
outcome	1	1	1	0

	t = 1	t = 2	t = 3	t = 4	<i>t</i> = 5
expert1	1	1	1	1	-
expert2	1	0	-	-	-
expert3	0	-	-	-	-
expert4	1	0	-	-	-
expert5	1	0	-	-	-
expert6	0	-	-	-	-
expert7	1	1	1	1	0
expert8	1	1	1	0	-
alg.	1	0	1	1	
outcome	1	1	1	0	

	t = 1	<i>t</i> = 2	t = 3	t = 4	<i>t</i> = 5
expert1	1	1	1	1	-
expert2	1	0	-	-	-
expert3	0	-	-	-	-
expert4	1	0	-	-	-
expert5	1	0	-	-	-
expert6	0	-	-	-	-
expert7	1	1	1	1	0
expert8	1	1	1	0	-
alg.	1	0	1	1	0
outcome	1	1	1	0	

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expert1	1	1	1	1	-
expert2	1	0	-	-	-
expert3	0	-	-	-	-
expert4	1	0	-	-	-
expert5	1	0	-	-	-
expert6	0	-	-	-	-
expert7	1	1	1	1	0
expert8	1	1	1	0	-
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- Number of mistakes is at most log<sub>2</sub> N.

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- ▶ If  $N = 2^k$  then  $k^* = k$ , otherwise  $k^* < \log N$
- k\* is the Min-Max number of mistakes: algorithm never makes more than k\* mistakes, adversary can force k\* mistakes.

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- Fits nicely in game theory

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- Modified Goal:
   minimize REGRET =
   expected total loss
   minus
   minimal total loss of repeating one action.

Consider action i at time t

Total loss:

$$L_i^t = \sum_{s=1}^{t-1} \ell_i^s$$

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Weight:

$$W_i^t = e^{-\eta L_i^t}$$

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▶  $\eta > 0$  is the learning rate parameter. Halving:  $\eta = \infty$ 

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Weight:

$$W_i^t = e^{-\eta L_i^t}$$

- ▶  $\eta > 0$  is the learning rate parameter. Halving:  $\eta = \infty$
- Probability:

$$P_i^t = \frac{W_i^t}{\sum_{i=1}^N W_i^t}$$

$$\eta = 1$$

```
\eta = 1
```

expert1 expert3 expert4 expert5 expert6 expert7 expert8

alg.

alg.

```
\eta = 1
                     \vec{W}^1
expert1
expert2
expert3
expert4
expert5
expert6
expert7
expert8
```

$\eta=1$		
•	$ec{W}^1$	$L^1$
expert1	1	.1
expert2	1	.8
expert3	1	.3
expert4	1	.1
expert5	1	.9
expert6	1	0
expert7	1	1
expert8	1	.8

alg.

$\eta = 1$			
,	$ec{W}^1$	<i>L</i> <sup>1</sup>	
expert1	1	.1	
expert2	1	.8	
expert3	1	.3	
expert4	1	.1	
expert5	1	.9	
expert6	1	0	
expert7	1	1	
expert8	1	.8	
ala.		.5	

$\eta = 1$			
·	$ec{W}^1$	<i>L</i> <sup>1</sup>	$\vec{W}^2$
expert1	1	.1	.90
expert2	1	.8	.45
expert3	1	.3	.74
expert4	1	.1	.90
expert5	1	.9	.41
expert6	1	0	1
expert7	1	1	.37
expert8	1	.8	.45
alg.		.5	

$\eta=1$				
,	$\vec{W}^1$	$L^1$	$\vec{W}^2$	$L^2$
expert1	1	.1	.90	.1
expert2	1	.8	.45	.5
expert3	1	.3	.74	.2
expert4	1	.1	.90	.7
expert5	1	.9	.41	1
expert6	1	0	1	.1
expert7	1	1	.37	.5
expert8	1	.8	.45	.2
alg.		.5		

,
2
6

$\eta=1$					
	$ec{W}^1$	$L^1$	$\vec{W}^2$	$L^2$	$\vec{W}^3$
expert1	1	.1	.90	.1	0.82
expert2	1	.8	.45	.5	0.27
expert3	1	.3	.74	.2	0.61
expert4	1	.1	.90	.7	0.45
expert5	1	.9	.41	1	0.15
expert6	1	0	1	.1	0.91
expert7	1	1	.37	.5	0.22
expert8	1	.8	.45	.2	0.37
alg.		.5		.36	

$\eta=1$						
	$ec{W}^1$	$L^1$	$\vec{W}^2$	$L^2$	$\vec{W}^3$	$L^3$
expert1	1	.1	.90	.1	0.82	0
expert2	1	.8	.45	.5	0.27	.2
expert3	1	.3	.74	.2	0.61	.2
expert4	1	.1	.90	.7	0.45	.8
expert5	1	.9	.41	1	0.15	.8
expert6	1	0	1	.1	0.91	.2
expert7	1	1	.37	.5	0.22	.4
expert8	1	.8	.45	.2	0.37	.6
alg.		.5		.36		

$\eta=1$						
•	$ec{W}^1$	<i>L</i> <sup>1</sup>	$\vec{W}^2$	$L^2$	$\vec{W}^3$	$L^3$
expert1	1	.1	.90	.1	0.82	0
expert2	1	.8	.45	.5	0.27	.2
expert3	1	.3	.74	.2	0.61	.2
expert4	1	.1	.90	.7	0.45	.8
expert5	1	.9	.41	1	0.15	.8
expert6	1	0	1	.1	0.91	.2
expert7	1	1	.37	.5	0.22	.4
expert8	1	.8	.45	.2	0.37	.6
alg.		.5		.36		.30

$\eta=1$							
·	$ec{W}^1$	<i>L</i> <sup>1</sup>	$\vec{W}^2$	$L^2$	$\vec{W}^3$	$L^3$	total
expert1	1	.1	.90	.1	0.82	0	.2
expert2	1	.8	.45	.5	0.27	.2	1.5
expert3	1	.3	.74	.2	0.61	.2	.7
expert4	1	.1	.90	.7	0.45	.8	1.6
expert5	1	.9	.41	1	0.15	.8	2.7
expert6	1	0	1	.1	0.91	.2	.3
expert7	1	1	.37	.5	0.22	.4	1.9
expert8	1	.8	.45	.2	0.37	.6	1.6
alg.		.5		.36		.30	

$\eta=$ 1							
,	$\vec{W}^1$	<i>L</i> <sup>1</sup>	$\vec{W}^2$	$L^2$	$\vec{W}^3$	$L^3$	total
expert1	1	.1	.90	.1	0.82	0	.2
expert2	1	.8	.45	.5	0.27	.2	1.5
expert3	1	.3	.74	.2	0.61	.2	.7
expert4	1	.1	.90	.7	0.45	.8	1.6
expert5	1	.9	.41	1	0.15	.8	2.7
expert6	1	0	1	.1	0.91	.2	.3
expert7	1	1	.37	.5	0.22	.4	1.9
expert8	1	.8	.45	.2	0.37	.6	1.6
ala.		.5		.36		.30	1.16

► L<sup>t</sup><sub>Hedge</sub>: Expected total loss of Hedge algorithm for time 1, 2, . . . , t

▶  $L_{\text{Hedge}}^t$ : Expected total loss of Hedge algorithm for time 1, 2, . . . , t

$$\forall t, i, \quad L_{\mathsf{Hedge}} \leq \frac{\mathsf{In}\, \mathsf{N} + \eta L_i^t}{1 - e^{-\eta}}$$

► L<sup>t</sup><sub>Hedge</sub>: Expected total loss of Hedge algorithm for time 1.2....*t* 

$$\forall t, i, \quad L_{\mathsf{Hedge}} \leq \frac{\mathsf{In}\, N + \eta L_i^t}{1 - e^{-\eta}}$$

Which implies

$$\forall t, \quad L_{\mathsf{Hedge}} \leq \min_{i} \left( \frac{\ln N + \eta L_{i}^{t}}{1 - e^{-\eta}} \right)$$

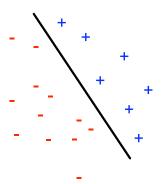
► L<sup>t</sup><sub>Hedge</sub>: Expected total loss of Hedge algorithm for time 1,2,...,t

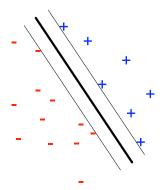
$$\forall t, i, \quad L_{\mathsf{Hedge}} \leq \frac{\ln N + \eta L_i^t}{1 - e^{-\eta}}$$

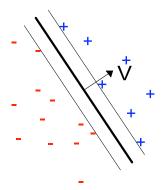
Which implies

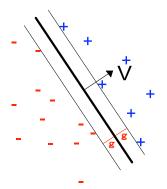
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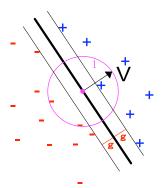
▶ Proof and choice of  $\eta$ : next class.

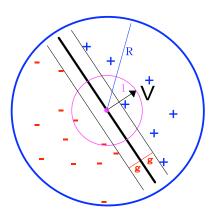


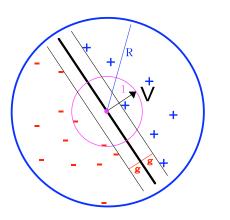




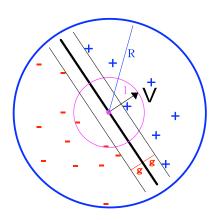




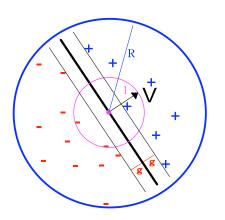




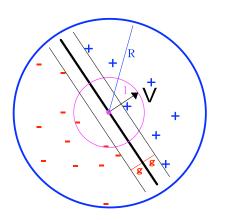
$$||\vec{V}|| = 1$$



- ▶  $\|\vec{V}\| = 1$
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- $\blacktriangleright \ \forall \vec{X}, \ \|\vec{X}\| \leq R.$



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- ► Example =  $(\vec{X}, y)$ ,  $y \in \{-1, +1\}.$
- $\blacktriangleright \ \forall \vec{X}, \ \|\vec{X}\| \leq R.$
- $\forall (\vec{X}, y), \\ y(\vec{X} \cdot \vec{V}) \geq g$

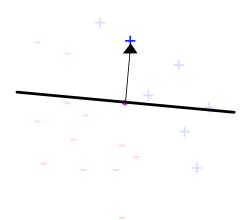
► An online algorithm. Examples presented one by one.

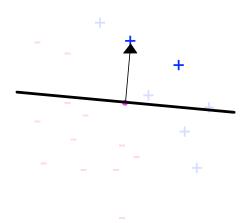
- ► An online algorithm. Examples presented one by one.
- start with  $\vec{W}_0 = \vec{0}$ .

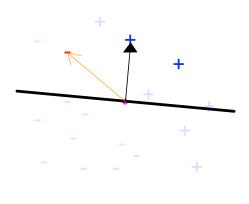
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- If mistake:  $(\vec{W}_i \cdot \vec{X}_i)y_i \leq 0$

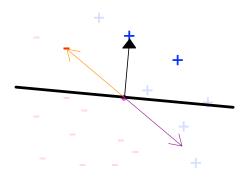
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- start with  $\vec{W}_0 = \vec{0}$ .
- ▶ If mistake:  $(\vec{W}_i \cdot \vec{X}_i)y_i \leq 0$ 
  - Update  $\vec{W}_{i+1} = \vec{W}_i + y_i X_i$ .

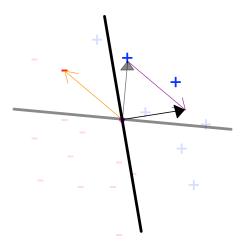












#### Bound on number of mistakes

The number of mistakes that the perceptron algorithm can make is at most  $\left(\frac{R}{g}\right)^2$ .

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- The number of mistakes that the perceptron algorithm can make is at most  $\left(\frac{R}{g}\right)^2$ .
- ▶ Proof by combining upper and lower bounds on  $\|\vec{W}\|$ .

### Pythagorian Lemma

If  $(\vec{W}_i \cdot X_i)y < 0$  then

### Pythagorian Lemma

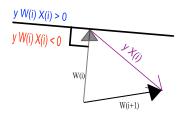
If 
$$(\vec{W}_i \cdot X_i)y < 0$$
 then

$$\|\vec{W}_{i+1}\|^2 = \|\vec{W}_i + y_i \vec{X}_i\|^2 \le \|\vec{W}_i\|^2 + \|\vec{X}_i\|^2$$

### Pythagorian Lemma

If 
$$(\vec{W}_i \cdot X_i)y < 0$$
 then

$$\|\vec{W}_{i+1}\|^2 = \|\vec{W}_i + y_i \vec{X}_i\|^2 \le \|\vec{W}_i\|^2 + \|\vec{X}_i\|^2$$



# Upper bound on $\|\vec{W}_i\|$

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#### Proof by induction

- ► Claim:  $\|\vec{W}_i\|^2 < iR^2$
- ► Base: i = 0,  $\|\vec{W}_0\|^2 = 0$
- ▶ Induction step (assume for i and prove for i + 1):

$$\|\vec{W}_{i+1}\|^2 \le \|\vec{W}_i\|^2 + \|\vec{X}_i\|^2 \le \|\vec{W}_i\|^2 + R^2 \le (i+1)R^2$$

$$\leq \|\vec{W}_i\|^2 + R^2 \leq (i+1)R^2$$

$$\|\vec{W}_i\| \ge \vec{W}_i \cdot \vec{V}$$
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- Induction step (assume for i and prove for i+1):  $\vec{W}_{i+1} \cdot \vec{V} = (\vec{W}_i + \vec{X}_i y_i) \vec{V} = \vec{W}_i \cdot \vec{V} + y_i \vec{X}_i \cdot \vec{V}$

$$\geq ig + g = (i + 1)g$$

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$$(\textit{ig})^2 \leq \|\vec{W}_i\|^2 \leq \textit{iR}^2$$

Thus:

$$i \leq \left(\frac{R}{g}\right)^2$$

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## Estimating the bias of a coin

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# Estimating the bias of a coin

- We observe n coin flips: H,T,T,H,H,T,H,T,T
- We want to estimate the probability that the next flip will be Head.
- Natural Answer:

$$\frac{\#\mathbf{H}}{n} = \frac{4}{9}$$

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- $\triangleright$  For  $p_1$ ?
- Laplace Law of succession

$$\frac{\# \mathbf{H} + 1}{n+2}$$

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- ▶ What would be a good value for  $p_0$ ?
- For p₁?
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Turns out that a better rule is

$$\frac{\# \mathbf{H} + 1/2}{n+1}$$

Krichevsky and Trofimov, 1981

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Why?

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- ► Why?
- What does "better" mean?

#### Next time

Analysis of the Hedge Algorithm.

▶ slides in talk1.handout.pdf on:

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- See you on Thursday!