

The Practical QR Algorithm

The Unsymmetric Eigenvalue Problem

The efficiency of the *QR* Iteration for computing the eigenvalues of an $n \times n$ matrix A is significantly improved by first reducing A to a Hessenberg matrix H , so that only $O(n^2)$ operations per iteration are required, instead of $O(n^3)$. However, the iteration can still converge very slowly, so additional modifications are needed to make the *QR* Iteration a practical algorithm for computing the eigenvalues of a general matrix.

In general, the p th subdiagonal entry of H converges to zero at the rate

$$\left| \frac{\lambda_{p+1}}{\lambda_p} \right|,$$

where λ_p is the p th largest eigenvalue of A in magnitude. It follows that convergence can be particularly slow if eigenvalues are very close to one another in magnitude. Suppose that we *shift* H by a scalar μ , meaning that we compute the *QR* factorization of $H - \mu I$ instead of H , and then update H to obtain a new Hessenberg \tilde{H} by multiplying the *QR* factors in reverse order as before, but then adding μI . Then, we have

$$\begin{aligned}\tilde{H} &= RQ + \mu I \\ &= Q^T(H - \mu I)Q + \mu I \\ &= Q^THQ - \mu Q^TQ + \mu I \\ &= Q^THQ - \mu I + \mu I \\ &= Q^THQ.\end{aligned}$$

So, we are still performing an orthogonal similarity transformation of H , but with a different Q . Then, the convergence rate becomes $|\lambda_{p+1} - \mu|/|\lambda_p - \mu|$. Then, if μ is close to an eigenvalue, convergence of a particular subdiagonal entry will be much more rapid.

In fact, suppose H is *unreduced*, and that μ happens to be an eigenvalue of H . When we compute the *QR* factorization of $H - \mu I$, which is now *singular*, then, because the first $n - 1$ columns of $H - \mu I$ must be linearly independent, it follows that the first $n - 1$ columns of R must be linearly independent as well, and therefore the last row of R must be zero. Then, when we compute RQ , which involves rotating columns of R , it follows that the last row of RQ must also be zero. We then add μI , but as this only changes the diagonal elements, we can conclude that

$\tilde{h}_{n,n-1} = 0$. In other words, \tilde{H} is not an unreduced Hessenberg matrix, and *deflation has occurred in one step*.

If μ is not an eigenvalue of H , but is still close to an eigenvalue, then $H - \mu I$ is nearly singular, which means that its columns are nearly linearly dependent. It follows that r_{nn} is small, and it can be shown that $\tilde{h}_{n,n-1}$ is also small, and $\tilde{h}_{nn} \approx \mu$. Therefore, the problem is nearly decoupled, and μ is revealed by the structure of \tilde{H} as an approximate eigenvalue of H . This suggests using h_{nn} as the shift μ during each iteration, because if $h_{n,n-1}$ is small compare to h_{nn} , then this choice of shift will drive $h_{n,n-1}$ toward zero. In fact, it can be shown that this strategy generally causes $h_{n,n-1}$ to converge to zero *quadratically*, meaning that only a few similarity transformations are needed to achieve decoupling. This improvement over the linear convergence rate reported earlier is due to the changing of the shift during each step.

Example If

$$H = \begin{bmatrix} 0.6324 & 0.2785 \\ 0.0975 & 0.5469 \end{bmatrix},$$

then the value of h_{21} after each of the first three *QR* steps is 0.1575, -0.0037 , and 0.000021 . It can be seen that h_{21} is quadratically converging to zero, as the number of leading zeros in its decimal expansion is doubling with each iteration. \square

This shifting strategy is called the *single shift strategy*. Unfortunately, it is not very effective if H has complex eigenvalues. An alternative is the *double shift strategy*, which is used if the two eigenvalues, μ_1 and μ_2 , of the lower-right 2×2 block of H are complex. Then, these two eigenvalues are used as shifts in consecutive iterations to achieve quadratic convergence in the complex case as well. That is, we compute

$$\begin{aligned} H - \mu_1 I &= U_1 R_1 \\ H_1 &= R_1 U_1 + \mu_1 I \\ H_1 - \mu_2 I &= U_2 R_2 \\ H_2 &= R_2 U_2 + \mu_2 I. \end{aligned}$$

To avoid complex arithmetic when using complex shifts, the *double implicit shift strategy* is used. We first note that

$$\begin{aligned} U_1 U_2 R_2 R_1 &= U_1 (H_1 - \mu_2 I) R_1 \\ &= U_1 H_1 R_1 - \mu_2 U_1 R_1 \\ &= U_1 (R_1 U_1 + \mu_1 I) R_1 - \mu_2 (H - \mu_1 I) \\ &= U_1 R_1 U_1 R_1 + \mu_1 U_1 R_1 - \mu_2 (H - \mu_1 I) \\ &= (H - \mu_1 I)^2 + \mu_1 (H - \mu_1 I) - \mu_2 (H - \mu_1 I) \\ &= H^2 - 2\mu_1 H + \mu_1^2 I + \mu_1 H - \mu_1^2 I - \mu_2 H + \mu_1 \mu_2 I \\ &= H^2 - (\mu_1 + \mu_2) H + \mu_1 \mu_2 I. \end{aligned}$$

Since $\mu_1 = a + bi$ and $\mu_2 = a - bi$ are a complex-conjugate pair, it follows that $\mu_1 + \mu_2 = ab$ and $\mu_1\mu_2 = a^2 + b^2$ are real. Therefore, $U_1U_2R_2R_1 = (U_1U_2)(R_2R_1)$ represents the *QR* factorization of a real matrix.

Furthermore,

$$\begin{aligned}
H_2 &= R_2U_2 + \mu_2I \\
&= U_2^T U_2 R_2 U_2 + \mu_2 U_2^T U_2 \\
&= U_2^T (U_2 R_2 + \mu_2 I) U_2 \\
&= U_2^T H_1 U_2 \\
&= U_2^T (R_1 U_1 + \mu_1 I) U_2 \\
&= U_2^T (U_1^T U_1 R_1 U_1 + \mu_1 U_1^T U_1) U_2 \\
&= U_2^T U_1^T (U_1 R_1 + \mu_1 I) U_1 U_2 \\
&= U_2^T U_1^T H U_1 U_2.
\end{aligned}$$

That is, U_1U_2 is the orthogonal matrix that implements the similarity transformation of H to obtain H_2 . Therefore, we could use exclusively real arithmetic by forming $M = H^2 - (\mu_1 + \mu_2)H + \mu_1\mu_2I$, compute its *QR* factorization to obtain $M = ZR$, and then compute $H_2 = Z^THZ$, since $Z = U_1U_2$, in view of the uniqueness of the *QR* decomposition. However, M is computed by squaring H , which requires $O(n^3)$ operations. Therefore, this is not a practical approach.

We can work around this difficulty using the Implicit Q Theorem. Instead of forming M in its entirety, we only form its first column, which, being a second-degree polynomial of a Hessenberg matrix, has only three nonzero entries. We compute a Householder transformation P_0 that makes this first column a multiple of \mathbf{e}_1 . Then, we compute P_0HP_0 , which is no longer Hessenberg, because it operates on the first three rows and columns of H . Finally, we apply a series of Householder reflections P_1, P_2, \dots, P_{n-2} that restore Hessenberg form. Because these reflections are not applied to the first row or column, it follows that if we define $\tilde{Z} = P_0P_1P_2 \cdots P_{n-2}$, then Z and \tilde{Z} have the same first column. Since both matrices implement similarity transformations that preserve the Hessenberg form of H , it follows from the Implicit Q Theorem that Z and \tilde{Z} are essentially equal, and that they essentially produce the same updated matrix H_2 . This variation of a Hessenberg *QR* step is called a *Francis QR step*.

A Francis *QR* step requires $10n^2$ operations, with an additional $10n^2$ operations if orthogonal transformations are being accumulated to obtain the entire real Schur decomposition. Generally, the entire *QR* algorithm, including the initial reduction to Hessenberg form, requires about $10n^3$ operations, with an additional $15n^3$ operations to compute the orthogonal matrix Q such that $A = QTQ^T$ is the real Schur decomposition of A .

The Symmetric Eigenvalue Problem

In the symmetric case, there is no need for a double-shift strategy, because the eigenvalues are real. However, the Implicit Q Theorem can be used for a different purpose: computing the similarity

transformation to be used during each iteration without explicitly computing $T - \mu I$, where T is the tridiagonal matrix that is to be reduced to diagonal form. Instead, the first column of $T - \mu I$ can be computed, and then a Householder transformation to make it a multiple of \mathbf{e}_1 . This can then be applied directly to T , followed by a series of Givens rotations to restore tridiagonal form. By the Implicit Q Theorem, this accomplishes the same effect as computing the QR factorization $UR = T - \mu I$ and then computing $\tilde{T} = RU + \mu I$.

While the shift $\mu = t_{nn}$ can always be used, it is actually more effective to use the *Wilkinson shift*, which is given by

$$\mu = t_{nn} + d - \text{sign}(d)\sqrt{d^2 + t_{n,n-1}^2}, \quad d = \frac{t_{n-1,n-1} - t_{nn}}{2}.$$

This expression yields the eigenvalue of the lower 2×2 block of T that is closer to t_{nn} . It can be shown that this choice of shift leads to *cubic* convergence of $t_{n,n-1}$ to zero.

The symmetric QR algorithm is much faster than the unsymmetric QR algorithm. A single QR step requires about $30n$ operations, because it operates on a tridiagonal matrix rather than a Hessenberg matrix, with an additional $6n^2$ operations for accumulating orthogonal transformations. The overall symmetric QR algorithm requires $4n^3/3$ operations to compute only the eigenvalues, and approximately $8n^3$ additional operations to accumulate transformations. Because a symmetric matrix is unitarily diagonalizable, then the columns of the orthogonal matrix Q such that $Q^T A Q$ is diagonal contains the eigenvectors of A .