Abrar Anwar

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Education

University of Texas at Austin

Austin, TX

Bachelor of Science, Computer Science, GPA: 3.66

May 2021

Relevant Coursework: Machine Learning (G), Geometric Foundations of Data Science, Computer Vision, Autonomous Robotics I/II, Wireless Networks, Quantum Computing, Predictive Analytics, Compilers

National University of Singapore

Singapore

Exchange Program funded by Gilman Scholarship

Fall 2019

Relevant Coursework: AI and Decision Making (G), Natural Language Processing

(G) = Graduate course

Interests

- Neural networks
- Robotics
- Evolutionary optimization
- Computer vision
- Neuromorphic computing
- Human-robot interaction

Academic Works

- [1] A. Anwar, C. Vineyard, W. Severa, S. Musuvathy, S. Cardwell. "Evolving Spiking Circuit Motifs using Weight Agnostic Networks". *Computer Science Research Institute Summer Proceedings*. Technical Report, Sandia National Laboratories. 2020. (in progress)
- [2] A. Anwar et al. "Evolving Spiking Circuit Motifs using Weight Agnostic Neural Networks." Poster presented at the *International Conference on Neuromorphic Systems*; July 2020.
- [3] F. Wang, J. B. Aimone, A. Anwar, and S. Musuvathy. "BrainSLAM: Robust autonomous navigation in sensor-deprived contexts". Technical Report SAND2019-11302R, 2019.
- [4] A. Anwar, B. Holman., C. Sheehan, J. Huang. "Using Human-Inspired Signals to Disambiguate Navigational Intentions." Poster presented at the *UT Undergraduate Research Forum*; April 2020.
- [5] A. Anwar, B. Holman, M. Shaposhnikov. "Bounding Box SLAM: A Fast, Selective SLAM." Poster presented at the *UT Undergraduate Research Forum*; April 2019.

Talks

- [1] **A. Anwar.** "Weight-Agnostic Neural Networks and Neural Architecture Search." Talk for the *NERL Summer Seminar Series* at Sandia National Laboratories. June 2019.
- [2] **A. Anwar** "Grover's Algorithm: An Introduction to Quantum Algorithms." Presentation session for *Spring Directed Reading Program Symposium* at UT Austin. May 2019.

Research Experience

Sandia National Laboratories

Research Intern

May 2020 - Present Albuquerque, NM

Neural Exploration and Research Lab

PI: Craig Vineyard

- Developed and optimized evolutionary method to evolve spiking-like neural network circuits for low-power, edge computing cases, specifically neuromorphic computing
- Assessed my approach on various tasks ranging from classification and continuous control, to playing Atari using a ResNet feature extractor
- Implemented parallel, asynchronous evolutionary training to speed up training process by 2x on HPC systems using OpenMPI
- Working on extensions for low-power neural network-hardware co-design

Computational Visualization Center

April 2020 - Present Austin, TX

Undergraduate Researcher

PI: Chandrajit Bajaj

- Develop a novel unsupervised optical flow estimation neural network by reconstructing the Helmholtz-Hodge Decomposition
- Use a deep reinforcement learning module to selectively refine residual patches in a course-to-fine manner

Building Wide Intelligence Lab

January 2020 - Present

Undergraduate Researcher

Austin, TX

PI: Peter Stone. Supervisor: Justin Hart.

- Managed and lead several projects, mentoring students in research
- Using eye tracking and 3D depth tracking to model the navigational intent of humans interacting with robots
- Created a word embedding model to shelve groceries in a human-like manner with a training process that allows for predicting generalizable human-like object placement. Designed Amazon MTurk expirements to collect data.
- Designed experiments to quantify humans' ability to interpret the gaze of virtual/physical agents

Sandia National Laboratories

May - July 2019

Autonomy Intern

Albuquerque, NM

Neural Exploration and Research Lab

PI: Brad Aimone

- Developed brain-inspired localization network for a hypersonic glide vehicle
- Designed rotation-invariant representations of images using Monte Carlo-like partial pixel estimation to develop a lightweight, circular feature
- Trained a rotation-invariant feature extraction autoencoder to reduce storage requirements of place recognition maps. Explored hierarchical, dense coding approaches to allow for sub-linear growth in map storage

Building Wide Intelligence Lab

July 2018 - May 2019

Undergraduate Researcher/Summer Research Fellow

Austin, TX

PI: Peter Stone. Supervisor: Justin Hart.

- \bullet Combined semantic info from object detection with visual SLAM to increase SLAM accuracy by 60% in dynamic environments by reducing drift
- Implemented active facial recognition system for RoboCup@Home competition
- Developed motion planning and simulation models for UR5 robot arm

Projects

Gaussian Processes for Detecting Cocontraction

May 2020

• Implemented Gaussian processes (GP) from scratch to detect muscle cocontraction from shifts in the hyperparameters of sliding windows of the non-parametric GP models using 3D motion capture data

Teaching Experience

Autonomous Robots I/II

January 2019 - Present

Teaching Assistant/Peer Mentor

Austin, TX

- Taught freshman CS students how to conduct robotics research for the BWI Lab
- Mentored students on numerous projects such as facial detection and frontier exploration

UTCS Robotics Camp

July 2018

Residential Advisor

Austin, TX

- Designed curriculum for an all-encompassing robotics summer camp for high school students
- Created hands-on activities ranging from soldering to Arduino programming

High School Research Initiative

September 2017 - May 2018

Student Intern

Austin, TX

- Facilitated students to explore biology research with UT faculty
- Led discussions on student projects to encourage inquiry

UTeach Natural Sciences

August 2017 - May 2018

Student Teacher

Austin, TX

• Taught elementary, then later middle school students computer science at underprivileged schools to facilitate interest in the field

Awards & Honors

- Princeton Pathways to Graduate School Admitted Participant
- Benjamin A. Gilman International Scholarship, Fall 2019
- FRI Summer Research Fellowship, Summer 2018
- Horatio Alger Honeywell Scholar, 2018
- University Honors, Spring 2018 Spring 2020

Skills

 $\label{languages: Languages: C/C++, Python, MATLAB, Java, R, I&T_EX \\ \textbf{Technologies: } PyTorch, Tensorflow, ROS, OpenMPI, scikit-learn, OpenCV$