

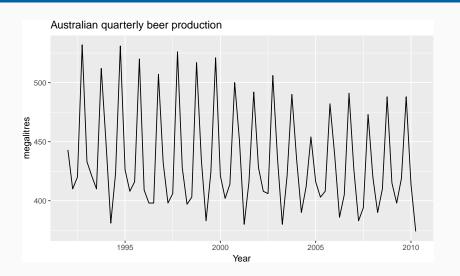
# Forecasting: principles and practice

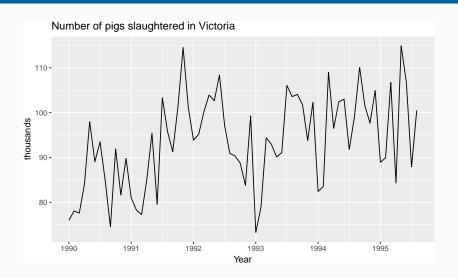
Rob J Hyndman

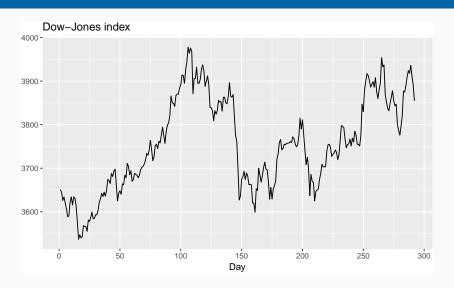
1.3 Forecast evaluation

#### **Outline**

- 1 Benchmark methods
- **2** Forecasting residuals
- 3 Lab session 3
- 4 Evaluating forecast accuracy
- 5 Lab session 4







#### Average method

- Forecast of all future values is equal to mean of historical data  $\{y_1, \dots, y_T\}$ .
- Forecasts:  $\hat{y}_{T+h|T} = \bar{y} = (y_1 + \cdots + y_T)/T$

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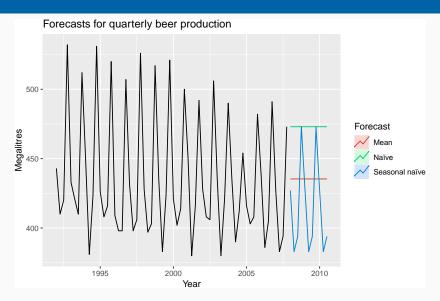
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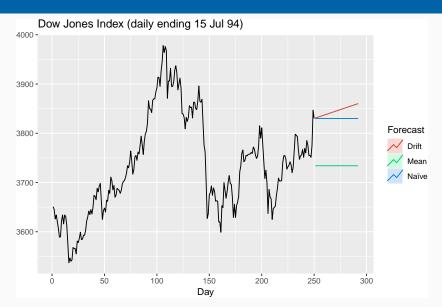
#### Seasonal naïve method

- Forecasts equal to last value from same season.
- Forecasts:  $\hat{y}_{T+h|T} = y_{T+h-km}$  where m = seasonal period and k is integer part of (h-1)/m.

#### **Drift method**

- Forecasts equal to last value plus average change.
- Forecasts:  $\hat{y}_{T+h|T} = y_T + \frac{h}{T-1} \sum_{t=2}^{T} (y_t y_{t-1})$ =  $y_T + \frac{h}{T-1} (y_T - y_1)$ .
- Equivalent to extrapolating a line drawn between first and last observations.





- Mean: meanf(y, h=20)
- Naïve: naive(y, h=20)
- Seasonal naïve: snaive(y, h=20)
- Drift: rwf(y, drift=TRUE, h=20)

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#### **Fitted values**

- $\hat{y}_{t|t-1}$  is the forecast of  $y_t$  based on observations  $y_1, \dots, y_t$ .
- We call these "fitted values".
- Sometimes drop the subscript:  $\hat{y}_t \equiv \hat{y}_{t|t-1}$ .
- Often not true forecasts since parameters are estimated on all data.

#### For example:

- $\hat{y}_t = \bar{y}$  for average method.
- $\hat{y}_t = y_{t-1} + (y_T y_1)/(T 1)$  for drift method.

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- $\{e_t\}$  have mean zero. If they don't, then forecasts are biased.

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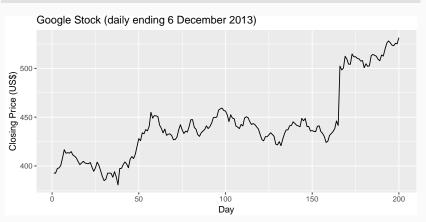
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#### **Useful properties** (for prediction intervals)

- $\{e_t\}$  have constant variance.
- $\{e_t\}$  are normally distributed.

```
autoplot(goog200) +
  xlab("Day") + ylab("Closing Price (US$)") +
  ggtitle("Google Stock (daily ending 6 December 2013)")
```



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$$\hat{\mathsf{y}}_{t|t-1} = \mathsf{y}_{t-1}$$

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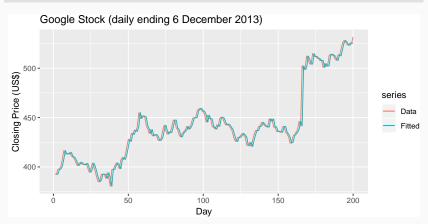
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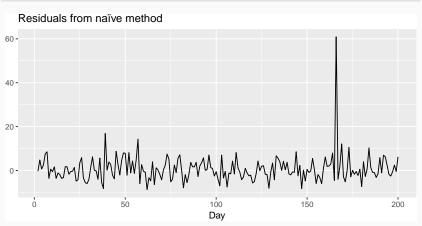
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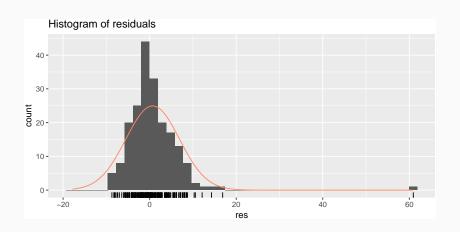
Note:  $e_t$  are one-step-forecast residuals

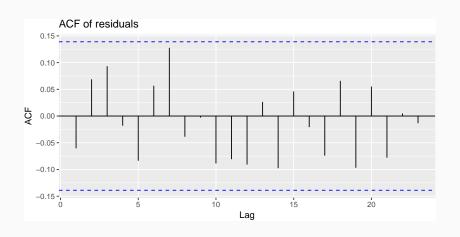
```
fits <- fitted(naive(goog200))
autoplot(goog200, series="Data") +
  autolayer(fits, series="Fitted") +
  xlab("Day") + ylab("Closing Price (US$)") +
  ggtitle("Google Stock (daily ending 6 December 2013)")</pre>
```



```
res <- residuals(naive(goog200))
autoplot(res) + xlab("Day") + ylab("") +
   ggtitle("Residuals from naïve method")</pre>
```







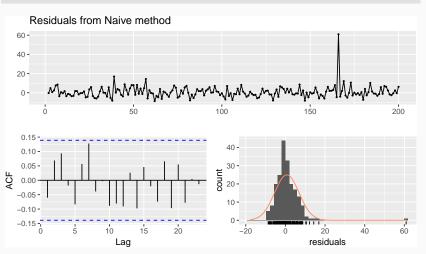
#### **ACF of residuals**

- We assume that the residuals are white noise (uncorrelated, mean zero, constant variance). If they aren't, then there is information left in the residuals that should be used in computing forecasts.
- So a standard residual diagnostic is to check the ACF of the residuals of a forecasting method.
- We *expect* these to look like white noise.

#### checkresiduals function

##

#### checkresiduals(naive(goog200))



#### **Portmanteau tests**

Test whether set of  $r_k$  values are significantly different from a zero set.

#### Ljung-Box test

$$Q^* = T(T+2) \sum_{k=0}^{h} (T-k)^{-1} r_k^2$$

where *h* is max lag being considered and *T* is number of observations.

- My preferences: h = 10 for non-seasonal data,
   h = 2m for seasonal data.
- If each  $r_k$  close to zero, Q will be **small**.
- p-value measures probability of results if residuals are WN.

#### checkresiduals function

#### checkresiduals(naive(goog200))

```
##
## Ljung-Box test
##
## data: Residuals from Naive method
## Q* = 11.088, df = 10, p-value = 0.3507
## Model df: 0. Total lags used: 10
```

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# **Lab Session 3**

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# **Training and test sets**



- A model which fits the training data well will not necessarily forecast well.
- A perfect fit can always be obtained by using a model with enough parameters.
- Over-fitting a model to data is just as bad as failing to identify a systematic pattern in the data.
- The test set must not be used for *any* aspect of model development or calculation of forecasts.
- Forecast accuracy is based only on the test set.

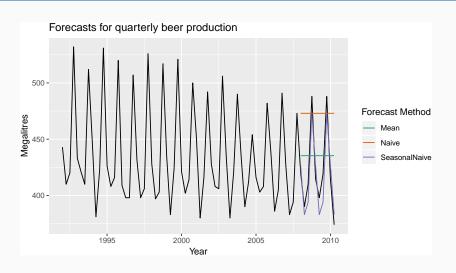
#### **Forecast errors**

Forecast "error": the difference between an observed value and its forecast.

$$e_{T+h} = y_{T+h} - \hat{y}_{T+h|T},$$

where the training data is given by  $\{y_1, \ldots, y_T\}$ 

- Unlike residuals, forecast errors on the test set involve multi-step forecasts.
- These are *true* forecast errors as the test data is not used in computing  $\hat{y}_{T+h|T}$ .



```
y_{T+h} = (T+h)th observation, h = 1, ..., H

\hat{y}_{T+h|T} = its forecast based on data up to time T.

e_{T+h} = y_{T+h} - \hat{y}_{T+h|T}
```

```
MAE = mean(|e_{T+h}|)

MSE = mean(e_{T+h}^2) RMSE = \sqrt{\text{mean}(e_{T+h}^2)}

MAPE = 100mean(|e_{T+h}|/|y_{T+h}|)
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- MAE, MSE, RMSE are all scale dependent.
- MAPE is scale independent but is only sensible if  $y_t \gg 0$  for all t, and y has a natural zero.

#### **Mean Absolute Scaled Error**

MASE = 
$$T^{-1} \sum_{t=1}^{T} |y_t - \hat{y}_{t|t-1}|/Q$$

where Q is a stable measure of the scale of the time series  $\{y_t\}$ .

Proposed by Hyndman and Koehler (IJF, 2006).

For non-seasonal time series,

$$Q = (T - 1)^{-1} \sum_{t=2}^{T} |y_t - y_{t-1}|$$

works well. Then MASE is equivalent to MAE relative to a naïve method.

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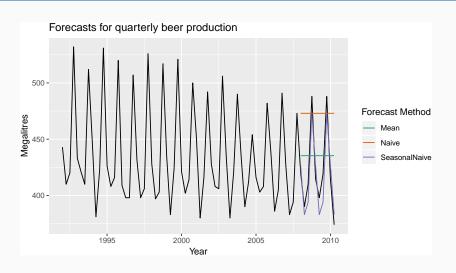
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For seasonal time series,

$$Q = (T - m)^{-1} \sum_{t=1}^{T} |y_t - y_{t-m}|$$

works well. Then MASE is equivalent to MAE relative to a seasonal naïve method.



```
beer2 <- window(ausbeer, start=1992, end=c(2007,4))
beer3 <- window(ausbeer, start=2008)
beerfit1 <- meanf(beer2, h=10)
beerfit2 <- rwf(beer2, h=10)
beerfit3 <- snaive(beer2, h=10)
accuracy(beerfit1, beer3)
accuracy(beerfit2, beer3)
accuracy(beerfit3, beer3)</pre>
```

	RMSE	MAE	MAPE	MASE
Mean method	38.45	34.83	8.28	2.44
Naïve method	62.69	57.40	14.18	4.01
Seasonal naïve method	14.31	13.40	3.17	0.94

#### Poll: true or false?

- Good forecast methods should have normally distributed residuals.
- A model with small residuals will give good forecasts.
- The best measure of forecast accuracy is MAPE.
- If your model doesn't forecast well, you should make it more complicated.
- Always choose the model with the best forecast accuracy as measured on the test set.

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# **Lab Session 4**