

Forecasting: principles and practice

Rob J Hyndman

2.4 Non-seasonal ARIMA models

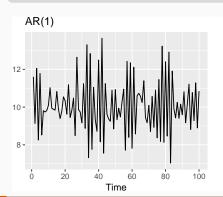
Outline

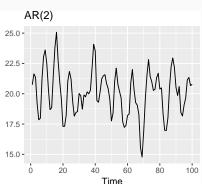
- 1 Autoregressive models
- 2 Moving Average models
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- 4 Estimation and order selection
- 5 ARIMA modelling in R
- 6 Lab session 15

Autoregressive models

Autoregressive (AR) models:

 $y_t = c + \phi_1 y_{t-1} + \phi_2 y_{t-2} + \cdots + \phi_p y_{t-p} + \varepsilon_t$, where ε_t is white noise. This is a multiple regression with **lagged values** of y_t as predictors.

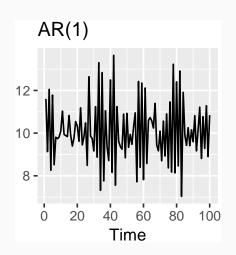




AR(1) model

$$y_t = 2 - 0.8y_{t-1} + \varepsilon_t$$

 $\varepsilon_t \sim N(0, 1)$, T = 100.



AR(1) model

$$y_t = c + \phi_1 y_{t-1} + \varepsilon_t$$

- When ϕ_1 = 0, y_t is **equivalent to WN**
- When ϕ_1 = 1 and c = 0, y_t is **equivalent to a RW**
- When ϕ_1 = 1 and $c \neq 0$, y_t is **equivalent to a RW** with drift
- When ϕ_1 < 0, y_t tends to oscillate between positive and negative values.

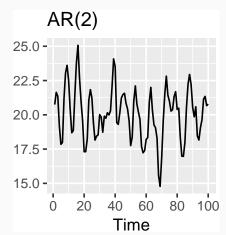
5

AR(2) model

$$y_t = 8 + 1.3y_{t-1} - 0.7y_{t-2} + \varepsilon_t$$

 $arepsilon_t \sim$ N(0, 1),

T = 100.



Stationarity conditions

We normally restrict autoregressive models to stationary data, and then some constraints on the values of the parameters are required.

General condition for stationarity

Complex roots of $1 - \phi_1 z - \phi_2 z^2 - \cdots - \phi_p z^p$ lie outside the unit circle on the complex plane.

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We normally restrict autoregressive models to stationary data, and then some constraints on the values of the parameters are required.

General condition for stationarity

Complex roots of $1 - \phi_1 z - \phi_2 z^2 - \cdots - \phi_p z^p$ lie outside the unit circle on the complex plane.

- For p = 1: $-1 < \phi_1 < 1$.
- For p = 2:

$$-1 < \phi_2 < 1$$
 $\phi_2 + \phi_1 < 1$ $\phi_2 - \phi_1 < 1$.

■ More complicated conditions hold for $p \ge 3$.

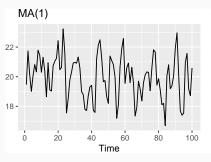
Outline

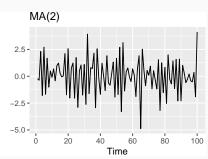
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Moving Average (MA) models

Moving Average (MA) models:

 $y_t = c + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \theta_2 \varepsilon_{t-2} + \cdots + \theta_q \varepsilon_{t-q}$, where ε_t is white noise. This is a multiple regression with **past errors** as predictors. Don't confuse this with moving average smoothing!

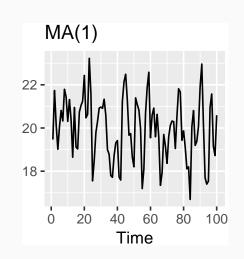




MA(1) model

$$y_t = 20 + \varepsilon_t + 0.8\varepsilon_{t-1}$$

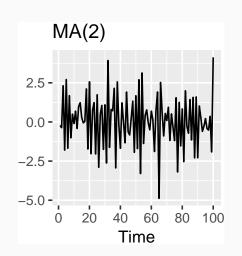
 $\varepsilon_t \sim N(0, 1)$, T = 100.



MA(2) model

$$y_t = \varepsilon_t - \varepsilon_{t-1} + 0.8\varepsilon_{t-2}$$

 $\varepsilon_t \sim N(0, 1)$, T = 100.



Invertibility

 Invertible models have property that distant past has negligible effect on forecasts. Requires consraints on MA parameters.

General condition for invertibility

Complex roots of $1 + \theta_1 z + \theta_2 z^2 + \cdots + \theta_q z^q$ lie outside the unit circle on the complex plane.

Invertibility

 Invertible models have property that distant past has negligible effect on forecasts. Requires consraints on MA parameters.

General condition for invertibility

Complex roots of $1 + \theta_1 z + \theta_2 z^2 + \cdots + \theta_q z^q$ lie outside the unit circle on the complex plane.

- For $q = 1: -1 < \theta_1 < 1$.
- For q = 2:

$$-1 < \theta_2 < 1$$
 $\theta_2 + \theta_1 > -1$ $\theta_1 - \theta_2 < 1$.

■ More complicated conditions hold for $q \ge 3$.

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Autoregressive Moving Average models:

$$y_t = c + \phi_1 y_{t-1} + \dots + \phi_p y_{t-p} + \theta_1 e_{t-1} + \dots + \theta_q e_{t-q} + e_t.$$

Autoregressive Moving Average models:

$$y_t = c + \phi_1 y_{t-1} + \dots + \phi_p y_{t-p} + \theta_1 e_{t-1} + \dots + \theta_a e_{t-a} + e_t.$$

- Predictors include both lagged values of y_t and lagged errors.
- Conditions on coefficients ensure stationarity.
- Conditions on coefficients ensure invertibility.

Autoregressive Moving Average models:

$$y_t = c + \phi_1 y_{t-1} + \dots + \phi_p y_{t-p} + \theta_1 e_{t-1} + \dots + \theta_q e_{t-q} + e_t.$$

- Predictors include both lagged values of y_t and lagged errors.
- Conditions on coefficients ensure stationarity.
- Conditions on coefficients ensure invertibility.

Autoregressive Integrated Moving Average models

- Combine ARMA model with **differencing**.
- $(1-B)^d y_t$ follows an ARMA model.

Autoregressive Integrated Moving Average models

ARIMA(p, d, q) model

- AR: p = order of the autoregressive part
 - I: d =degree of first differencing involved
- MA: q =order of the moving average part.
 - White noise model: ARIMA(0,0,0)
 - Random walk: ARIMA(0,1,0) with no constant
 - Random walk with drift: ARIMA(0,1,0) with const.
 - \blacksquare AR(p): ARIMA(p,0,0)
 - \blacksquare MA(q): ARIMA(0,0,q)

Backshift notation for ARIMA

ARMA model:

$$\begin{aligned} \mathbf{y}_t &= \mathbf{c} + \phi_1 \mathbf{B} \mathbf{y}_t + \dots + \phi_p \mathbf{B}^p \mathbf{y}_t + \varepsilon_t + \theta_1 \mathbf{B} \varepsilon_t + \dots + \theta_q \mathbf{B}^q \varepsilon_t \\ \text{or} \quad & (1 - \phi_1 \mathbf{B} - \dots - \phi_p \mathbf{B}^p) \mathbf{y}_t = \mathbf{c} + (1 + \theta_1 \mathbf{B} + \dots + \theta_q \mathbf{B}^q) \varepsilon_t \end{aligned}$$

ARIMA(1,1,1) model:

$$(1 - \phi_1 B)$$
 $(1 - B)y_t = c + (1 + \theta_1 B)\varepsilon_t$
 \uparrow \uparrow \uparrow
AR(1) First MA(1)
difference

Backshift notation for ARIMA

ARMA model:

$$\begin{aligned} \mathbf{y}_t &= \mathbf{c} + \phi_1 \mathbf{B} \mathbf{y}_t + \dots + \phi_p \mathbf{B}^p \mathbf{y}_t + \varepsilon_t + \theta_1 \mathbf{B} \varepsilon_t + \dots + \theta_q \mathbf{B}^q \varepsilon_t \\ \text{or} \quad & (\mathbf{1} - \phi_1 \mathbf{B} - \dots - \phi_p \mathbf{B}^p) \mathbf{y}_t = \mathbf{c} + (\mathbf{1} + \theta_1 \mathbf{B} + \dots + \theta_q \mathbf{B}^q) \varepsilon_t \end{aligned}$$

ARIMA(1,1,1) model:

$$(1 - \phi_1 B)$$
 $(1 - B)y_t = c + (1 + \theta_1 B)\varepsilon_t$
 \uparrow \uparrow \uparrow \uparrow
AR(1) First MA(1)
difference

Written out:

$$y_t = c + y_{t-1} + \phi_1 y_{t-1} - \phi_1 y_{t-2} + \theta_1 \varepsilon_{t-1} + \varepsilon_t$$

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R model

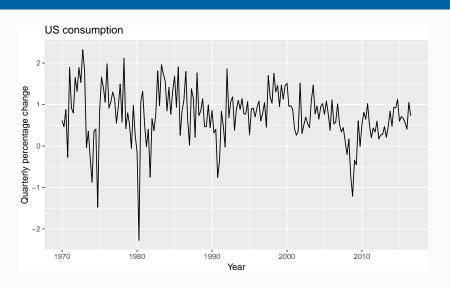
Intercept form

$$(1 - \phi_1 B - \dots - \phi_p B^p) y_t' = c + (1 + \theta_1 B + \dots + \theta_q B^q) \varepsilon_t$$

Mean form

$$(1 - \phi_1 B - \dots - \phi_p B^p)(y_t' - \mu) = (1 + \theta_1 B + \dots + \theta_q B^q)\varepsilon_t$$

- $y'_t = (1 B)^d y_t$
- \blacksquare μ is the mean of \mathbf{y}_t' .
- $c = \mu(1 \phi_1 \cdots \phi_p).$
- R uses mean form.



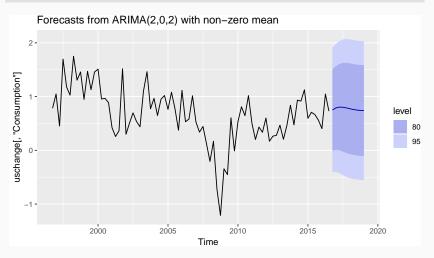
```
(fit <- auto.arima(uschange[,"Consumption"]))</pre>
## Series: uschange[, "Consumption"]
## ARIMA(2,0,2) with non-zero mean
##
## Coefficients:
##
           ar1
                   ar2
                            ma1
                                   ma2
                                          mean
##
        1.3908 -0.5813 -1.1800
                                0.5584 0.7463
## s.e. 0.2553 0.2078 0.2381
                                 0.1403 0.0845
##
## sigma^2 estimated as 0.3511: log likelihood=-165.14
## AIC=342.28 AICc=342.75 BIC=361.67
```

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```

ARIMA(2,0,2) model:

```
y_t = c + 1.391y_{t-1} - 0.581y_{t-2} - 1.180\varepsilon_{t-1} + 0.558\varepsilon_{t-2} + \varepsilon_t,
where c = 0.746 \times (1 - 1.391 + 0.581) = 0.142 and \varepsilon_t \sim N(0, 0.351).
```





Understanding ARIMA models

Long-term forecasts

```
zero c = 0, d = 0

non-zero constant c = 0, d = 1 c \neq 0, d = 0

linear c = 0, d = 2 c \neq 0, d = 1

quadratic c = 0, d = 3 c \neq 0, d = 2
```

Forecast variance and d

- The higher the value of *d*, the more rapidly the prediction intervals increase in size.
- For d = 0, the long-term forecast standard deviation will go to the standard deviation of the historical data.

Understanding ARIMA models

Cyclic behaviour

- For cyclic forecasts, $p \ge 2$ and some restrictions on coefficients are required.
- If p = 2, we need $\phi_1^2 + 4\phi_2 < 0$. Then average cycle of length

$$(2\pi)/\left[\arccos(-\phi_1(1-\phi_2)/(4\phi_2))\right]$$
.

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Maximum likelihood estimation

Having identified the model order, we need to estimate the parameters $c, \phi_1, \ldots, \phi_p, \theta_1, \ldots, \theta_q$.

Maximum likelihood estimation

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 MLE is very similar to least squares estimation obtained by minimizing

$$\sum_{t=1}^{T} e_t^2$$

- The Arima() command allows CLS or MLE estimation.
- Non-linear optimization must be used in either case.
- Different software will give different estimates.

Akaike's Information Criterion (AIC):

$$AIC = -2 \log(L) + 2(p + q + k + 1),$$

where *L* is the likelihood of the data,

$$k = 1 \text{ if } c \neq 0 \text{ and } k = 0 \text{ if } c = 0.$$

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Corrected AIC:

AICc = AIC +
$$\frac{2(p+q+k+1)(p+q+k+2)}{T-p-q-k-2}$$

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$$\frac{2(p+q+k+1)(p+q+k+2)}{T-p-q-k-2}$$

Bayesian Information Criterion:

$$BIC = AIC + \log(T)(p + q + k - 1).$$

Good models are obtained by minimizing either the AIC, AICc or BIC. My preference is to use the AICc.

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How does auto.arima() work?

A non-seasonal ARIMA process

$$\phi(B)(1-B)^d y_t = c + \theta(B)\varepsilon_t$$

Need to select appropriate orders: p, q, d

Hyndman and Khandakar (JSS, 2008) algorithm:

- Select no. differences d and D via KPSS test and seasonal strength measure.
- Select p, q by minimising AICc.
- Use stepwise search to traverse model space.

How does auto.arima() work?

Step 1: Select values of *d* and *D*.

Step 2: Select current model (with smallest AICc) from:

ARIMA(2, d, 2)

ARIMA(0, d, 0)

ARIMA(1, d, 0)

ARIMA(0, d, 1)

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Step 1: Select values of *d* and *D*.

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ARIMA(1, d, 0)

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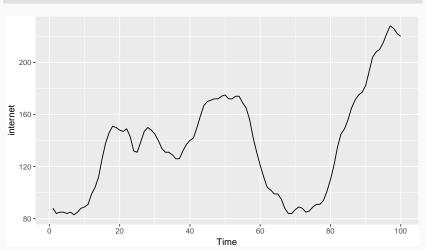
Step 3: Consider variations of current model:

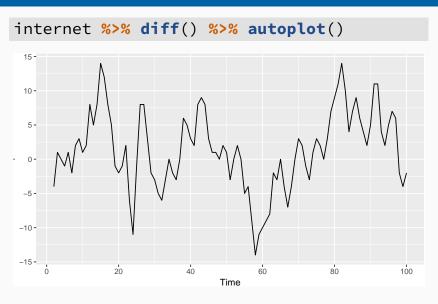
- vary one of p, q, from current model by ± 1 ;
- p, q both vary from current model by ± 1 ;
- Include/exclude c from current model.

Model with lowest AICc becomes current model.

Repeat Step 3 until no lower AICc can be found.

autoplot(internet)





(fit <- auto.arima(internet))</pre>

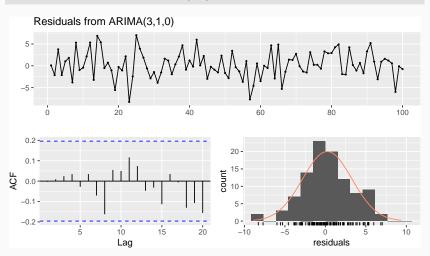
```
## Series: internet
## ARIMA(1,1,1)
##
## Coefficients:
##
           arl mal
##
       0.6504 0.5256
## s.e. 0.0842 0.0896
##
## sigma^2 estimated as 9.995: log likelihood=-
254.15
## ATC=514.3 ATCc=514.55 BTC=522.08
```

```
(fit <- auto.arima(internet, stepwise=FALSE,
    approximation=FALSE))</pre>
```

```
## Series: internet
## ARIMA(3,1,0)
##
## Coefficients:
##
           ar1 ar2 ar3
## 1.1513 -0.6612 0.3407
## s.e. 0.0950 0.1353 0.0941
##
## sigma^2 estimated as 9.656: log likelihood=-
252
## ATC=511.99 ATCc=512.42 BTC=522.37
```

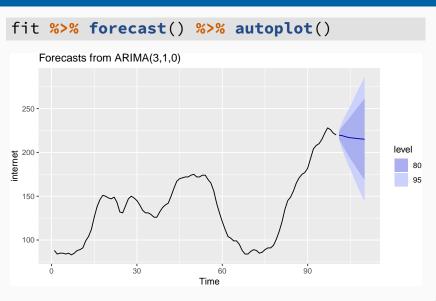
##

checkresiduals(fit, plot=TRUE)



checkresiduals(fit, plot=FALSE)

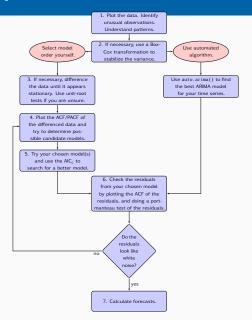
```
##
## Ljung-Box test
##
## data: Residuals from ARIMA(3,1,0)
## Q* = 4.4913, df = 7, p-value = 0.7218
##
## Model df: 3. Total lags used: 10
```



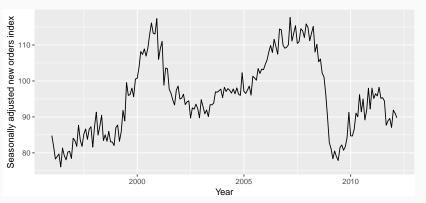
Modelling procedure with auto.arima

- Plot the data. Identify any unusual observations.
- If necessary, transform the data (using a Box-Cox transformation) to stabilize the variance.
- Use auto.arima to select a model.
- Check the residuals from your chosen model by plotting the ACF of the residuals, and doing a portmanteau test of the residuals. If they do not look like white noise, try a modified model.
- Once the residuals look like white noise, calculate forecasts.

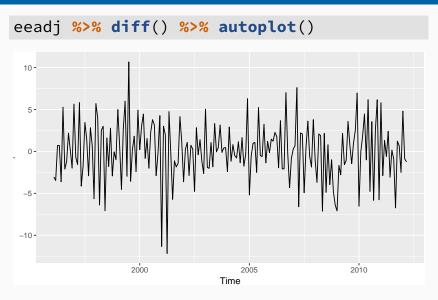
Modelling procedure



```
eeadj <- seasadj(stl(elecequip, s.window="periodic"
autoplot(eeadj) + xlab("Year") +
  ylab("Seasonally adjusted new orders index")</pre>
```



- Time plot shows sudden changes, particularly big drop in 2008/2009 due to global economic environment. Otherwise nothing unusual and no need for data adjustments.
- No evidence of changing variance, so no Box-Cox transformation.
- Data are clearly non-stationary, so we take first differences.



fit <- auto.arima(eeadj, stepwise=FALSE, approximation=FALSE)</pre> summary(fit)

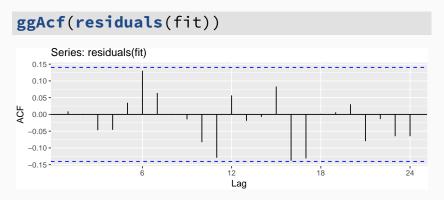
```
## Series: eeadj
## ARIMA(3,1,1)
##
## Coefficients:
##
          ar1 ar2 ar3 ma1
        0.0044 0.0916 0.3698 -0.3921
##
## s.e. 0.2201 0.0984 0.0669 0.2426
##
## sigma^2 estimated as 9.577: log likelihood=-492.69
  AIC=995.38 AICc=995.7 BIC=1011.72
##
  Training set error measures:
##
                     MF
                            RMSE
                                     MAF
                                                  MPF
## Training set 0.0328818 3.054718 2.357169 -0.006470086 2.481603
                     ACF1
```

##

MAPF

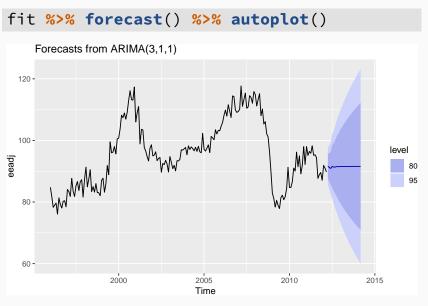
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ACF plot of residuals from ARIMA(3,1,1) model look like white noise.



checkresiduals(fit, plot=FALSE)

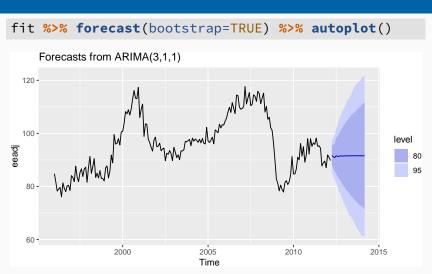
```
##
## Ljung-Box test
##
## data: Residuals from ARIMA(3,1,1)
## Q* = 24.034, df = 20, p-value = 0.2409
##
## Model df: 4. Total lags used: 24
```



Prediction intervals

- Prediction intervals increase in size with forecast horizon.
- Calculations assume residuals are uncorrelated and normally distributed.
- Prediction intervals tend to be too narrow.
 - the uncertainty in the parameter estimates has not been accounted for.
 - the ARIMA model assumes historical patterns will not change during the forecast period.
 - the ARIMA model assumes uncorrelated future errors

Bootstrapped prediction intervals



No assumption of normally distributed residuals.

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Lab Session 15