

PhD Macroeconomics – DSGE methods
Summer 2013
Examination

Willi Mutschler*

*Institute for Econometrics and Economic Statistics,
University of Münster, Germany*

Due date: August 31, 2013

- Answer **all** of the following three exercises.
- Hand in your solutions before August 31, 2012.
- Please e-mail the solutions to `willi.mutschler@uni-muenster.de`
- The solution files should contain your Dynare code and all additional files (preferably **pdf**, not **doc** or **docx**).
- **Important:** Please indicate if you are a Master student or a PhD student. If you are a Master student, please also give your registration number.
- All students must work on their own.
- If there are any questions, contact Willi Mutschler in room 305 or via e-mail.

GOOD LUCK!

*Electronic address: `willi.mutschler@uni-muenster.de`

1 Dynare

Consider the Clarida-Gali-Gertler model from the lecture. (Hint: Use the `cggexam.mod` as starting point for your analysis)

1. Replace the time series representation of a_t with

$$a_t = \rho a_{t-1} + \varepsilon_t^a$$

Consider the response of the economy to a technology shock ε_t^a . Does the economy over- or under-respond to the shock relative to its *natural* response? How does this compare to the unit root case? Give also economic intuition for the response. Hint: Use the Matlab function `plots.m` to get some prettier plots (put everything in one folder and write plots as the last command of your mod-file).

2. Now assume that agents have advance information (news) about the future realization of the technology shock, i.e.

$$a_t = \rho a_{t-1} + \xi_t^0 + \xi_{t-1}^1$$

where ξ_t^0 and ξ_t^1 are both iid. In economic terms agents see ξ_t^0 at time t and they see ξ_{t-1}^1 at time $t-1$. Introduce this into your code and consider a news shock to ξ_t^1 . What happens with inflation and the output gap? Provide intuition behind this apparently contradictory result.

3. What happens with the response of the economy due to a news shock relative to its natural response, if the natural rate of interest is introduced into the policy rule, i.e.

$$r_t = r_t^* + \alpha(r_{t-1} - r_{t-1}^*) + (1 - \alpha)[\phi_\pi \pi_t + \phi_x x_t]$$

2 Solution methods

Consider a simplified Asset-Pricing Model given by

$$\begin{aligned} u'(d_t) \cdot p_t &= \beta E_t [u'(d_{t+1}) \cdot (p_{t+1} + d_{t+1})] \\ d_{t+1} &= \rho d_t + e_{t+1}, \quad e_{t+1} \sim N(0, \sigma_e^2) \end{aligned}$$

in which $u'(d_t)$ denotes the first order derivative of the utility function $u(d_t)$, β the discount factor, ρ a time persistence parameter, p_t the price and d_t the dividend of a single asset in the environment with steady states \bar{p} and \bar{d} . e_t is a gaussian random variable with zero mean and standard deviation σ_e .

1. In the notation of the lecture, which variable is the state (x_t) and which the control (y_t) variable?
2. Derive the decision rule for the state variable in the form of

$$x_{t+1} = \bar{x} + h(x_t, \sigma) + \sigma \varepsilon_{t+1}$$

How would you set σ in this case?

3. The decision rule for the control variable up to second order is of the form

$$y_{t+1} = \bar{y} + [g_x](x_t - \bar{x}) + [g_\sigma]\sigma + \frac{1}{2}[g_{xx}](x_t - \bar{x})^2 + \frac{1}{2}[g_{x\sigma}](x_t - \bar{x})\sigma + \frac{1}{2}[g_{\sigma x}]\sigma(x_t - \bar{x}) + \frac{1}{2}[g_{\sigma\sigma}]\sigma^2$$

Derive the expressions for $\bar{y}, [g_x], [g_{xx}], [g_{x\sigma}], [g_{\sigma x}]$ analytically (you don't have to do it for $g_{\sigma\sigma}$).

Hints:

- Set up $F(x_t, \sigma) = 0$ and differentiate with respect to x_t and σ twice, THEN take expectation of $F_x = 0, F_\sigma = 0, F_{xx} = 0$ and evaluate at $(x_t, \sigma) = (\bar{x}, 0)$.
- For g_x and g_{xx} you should get:

$$\begin{aligned} g_x &= \frac{-u''(\bar{d}) \cdot \bar{y} + \beta \rho u''(\bar{d}) \cdot (\bar{y} + \bar{x}) + \beta \rho u'(\bar{d})}{u'(\bar{d}) \cdot (1 - \rho\beta)}, \\ g_{xx} &= \frac{-u'''(\bar{d}) \cdot \bar{y} - 2u''(\bar{d}) \cdot g_x + \beta \rho^2 u'''(\bar{d}) \cdot (\bar{y} + \bar{x}) + 2\beta \rho^2 u''(\bar{d}) \cdot (\bar{y} + 1)}{u'(\bar{d})(1 - \beta \rho^2)} \end{aligned}$$

3 Estimation methods

Consider the following simplified RBC-model (social planner problem);

$$\begin{aligned} \max_{\{c_{t+j}, l_{t+j}, k_{t+j}\}_{j=0}^{\infty}} W_t &= \sum_{j=0}^{\infty} \beta^j u(c_{t+j}, l_{t+j}) \\ \text{s.t. } y_t &= c_t + i_t, & A_t &= Ae^{a_t}, \\ y_t &= A_t f(k_{t-1}, l_t), & a_t &= \rho a_{t-1} + \varepsilon_t, \\ k_t &= i_t + (1 - \delta)k_{t-1}, & \varepsilon_t &\sim N(0, \sigma_\varepsilon^2), \end{aligned}$$

where preferences and technology follow:

$$u(c_t, l_t) = \frac{[c_t^\theta (1 - l_t)^{1-\theta}]^{1-\tau}}{1 - \tau}, \quad f(k_{t-1}, l_t) = [\alpha k_{t-1}^\psi + (1 - \alpha)l_t^\psi]^{1/\psi}.$$

Optimality is given by:

$$\begin{aligned} u_c(c_t, l_t) - \beta E_t \{u_c(c_{t+1}, l_{t+1}) [A_{t+1} f_k(k_t, l_{t+1}) + 1 - \delta]\} &= 0, \\ -\frac{u_l(c_t, l_t)}{u_c(c_t, l_t)} - A_t f_l(k_{t-1}, l_t) &= 0, \\ c_t + k_t - A_t f(k_{t-1}, l_t) - (1 - \delta)k_{t-1} &= 0. \end{aligned}$$

See `rbcestim.mod` for this model and the Bayesian estimation we did in the lecture. **RUN IT ONCE TO GET SIMULATED DATA AND ESTIMATION.**

Now we will use the same dataset to estimate the parameters of a misspecified model. We will use the same model, however, with a small difference, i.e. technology follows a Cobb-Douglas production function. See `rbexam.mod` for the new model equations and steady-state block.

1. Define priors for α, θ and τ . How many observable variables do you need? Choose an appropriate number of observables.
2. Estimate the posterior mode using the `estimation` command and a limited sample with 200 observations. Check the posterior mode using `mode_check`. If you get errors due to a non-positive definite Hessian, try a different optimization algorithm or change the initial values.
3. If you are satisfied with the posterior mode, approximate the posterior distribution using the Metropolis-Hastings-Algorithm with 3×5000 iterations. How large is your acceptance rate (change `jh_scale` if you're not satisfied). Provide also the diagnostic plots. If the algorithm does not converge to the (ergodic) posterior-distribution, repeat the algorithm with 1000 more iterations without discarding the previous draws.
4. Take a stand on your Bayesian estimation. What is good, what can be improved and how? Compare the estimation of the common parameters of the true model with the misspecified model.
5. Calculate the *posterior-odds* and the *posterior-model-probabilities* weighting each model by 0.5 a prior. Hint: Write a mod-file with the following code and execute it:

```
model_comparison rbcestim(0.5) rbexam(0.5);
```