

Example for Kroneckerproduct:

$$\underbrace{\begin{pmatrix} 1 & 3 & 2 \\ 1 & 0 & 0 \\ 1 & 2 & 2 \end{pmatrix}}_{3 \times 3} \otimes \underbrace{\begin{pmatrix} 0 & 5 \\ 5 & 0 \\ 1 & 1 \end{pmatrix}}_{3 \times 2} = \underbrace{\begin{pmatrix} 1 \cdot \begin{pmatrix} 0 & 5 \\ 5 & 0 \end{pmatrix} & 3 \cdot \begin{pmatrix} 0 & 5 \\ 5 & 0 \end{pmatrix} & 2 \cdot \begin{pmatrix} 0 & 5 \\ 5 & 0 \end{pmatrix} \\ 1 \cdot \begin{pmatrix} 0 & 5 \\ 5 & 0 \end{pmatrix} & 0 \cdot \begin{pmatrix} 0 & 5 \\ 5 & 0 \end{pmatrix} & 0 \cdot \begin{pmatrix} 0 & 5 \\ 5 & 0 \end{pmatrix} \\ 1 \cdot \begin{pmatrix} 0 & 5 \\ 5 & 0 \end{pmatrix} & 2 \cdot \begin{pmatrix} 0 & 5 \\ 5 & 0 \end{pmatrix} & 2 \cdot \begin{pmatrix} 0 & 5 \\ 5 & 0 \end{pmatrix} \end{pmatrix}}_{9 \times 6}$$

Consider the matrices A: $m \times n$, B: $n \times p$ and C: $p \times k$. Show that $\text{vec}(ABC) = (C' \otimes A) \text{vec}(B)$.

$$\begin{aligned} ABC &= A \begin{pmatrix} b_1 & b_2 & \dots & b_p \end{pmatrix} \begin{pmatrix} c_{11} & c_{12} & \dots & c_{1k} \\ c_{21} & c_{22} & \dots & c_{2k} \\ \vdots & \vdots & \vdots & \vdots \\ c_{p1} & c_{p2} & \dots & c_{pk} \end{pmatrix} \\ &= A \underbrace{\begin{pmatrix} b_1 c_{11} + b_2 c_{21} + \dots + b_p c_{p1}, & b_1 c_{12} + b_2 c_{22} + \dots + b_p c_{p2}, & \dots, & b_1 c_{1k} + b_2 c_{2k} + \dots + b_p c_{pk} \end{pmatrix}}_{n \times k} \\ \text{vec}(ABC) &= \begin{pmatrix} c_{11}Ab_1 + c_{21}Ab_2 + \dots + c_{p1}Ab_p \\ c_{12}Ab_1 + c_{22}Ab_2 + \dots + c_{p2}Ab_p \\ \vdots \\ c_{1k}Ab_1 + c_{2k}Ab_2 + \dots + c_{pk}Ab_p \end{pmatrix} = \begin{pmatrix} c_{11}A & c_{21}A & \dots & c_{p1}A \\ c_{12}A & c_{22}A & \dots & c_{p2}A \\ \vdots & \vdots & \vdots & \vdots \\ c_{1k}A & c_{2k}A & \dots & c_{pk}A \end{pmatrix} \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_p \end{pmatrix} = (C' \otimes A) \text{vec}(B) \end{aligned}$$

Exercise 5

Derivation of optimality-conditions:

- $u_c(c_t, l_t) = \theta [c_t^\theta (1 - l_t)^{1-\theta}]^{1-\tau} c_t^{-1}$
- $u_l(c_t, l_t) = -(1 - \theta) [c_t^\theta (1 - l_t)^{1-\theta}]^{1-\tau} (1 - l_t)^{-1}$
- $f_k = \alpha \left[\alpha k_{t-1}^\psi + (1 - \alpha) l_t^\psi \right]^{\frac{1-\psi}{\psi}} k_{t-1}^{\psi-1} = \alpha \left(\frac{f_t}{k_{t-1}} \right)^{1-\psi} = \alpha \left[\alpha + (1 - \alpha) \left(\frac{l_t}{k_{t-1}} \right)^\psi \right]^{\frac{1-\psi}{\psi}}$
- $f_l = (1 - \alpha) \left[\alpha k_{t-1}^\psi + (1 - \alpha) l_t^\psi \right]^{\frac{1-\psi}{\psi}} l_t^{\psi-1} = (1 - \alpha) \left(\frac{f_t}{l_t} \right)^{1-\psi} = (1 - \alpha) \left[\alpha \left(\frac{k_{t-1}}{l_t} \right)^\psi + (1 - \alpha) \right]^{\frac{1-\psi}{\psi}}$
- Euler:

$$\begin{aligned} [c_t^\theta (1 - l_t)^{1-\theta}]^{1-\tau} c_t^{-1} &= \beta E_t [c_{t+1}^\theta (1 - l_{t+1})^{1-\theta}]^{1-\tau} c_{t+1}^{-1} \cdot \left[A_{t+1} \alpha \left(\frac{f_{t+1}}{k_t} \right)^{1-\psi} + 1 - \delta \right] \\ &= \beta E_t [c_{t+1}^\theta (1 - l_{t+1})^{1-\theta}]^{1-\tau} c_{t+1}^{-1} \cdot \left[\alpha A_{t+1}^\psi \left(\frac{y_{t+1}}{k_t} \right)^{1-\psi} + 1 - \delta \right] \end{aligned}$$

- Consumption-Leisure:

$$\frac{1-\theta}{\theta} \frac{c_t}{1-l_t} = A_t(1-\alpha) \left(\frac{f_t}{l_t} \right)^{1-\psi} = A_t^\psi (1-\alpha) \left(\frac{y_t}{l_t} \right)^{1-\psi}$$

- Resource-constraint:

$$y_t = c_t + k_t - (1-\delta)k_{t-1}$$

- Stochastic process: $A_t = e^{a_t}$ and $a_t = \rho a_{t-1} + \sigma \varepsilon_t$ with $\varepsilon_t \sim N(0,1)$.

Derivation of steady-state:

1. $A = A^{ss}$

2. From Euler:

$$\begin{aligned} \frac{1}{\beta} &= A^\psi \alpha \left(\frac{y}{k} \right)^{1-\psi} + 1 - \delta \\ \Leftrightarrow \frac{y}{k} &= \left(\frac{\beta^{-1} - 1 + \delta}{\alpha A^\psi} \right)^{\frac{1}{1-\psi}} \end{aligned}$$

3. From resource-constraint:

$$\frac{c}{k} = \frac{y}{k} - \delta$$

4. Definition of Production-function:

$$\begin{aligned} \frac{y}{k} &= A \left[\alpha + (1-\alpha) \left(\frac{l}{k} \right)^\psi \right]^{\frac{1}{\psi}} = \left(\frac{\beta^{-1} - 1 + \delta}{\alpha A^\psi} \right)^{\frac{1}{1-\psi}} = \frac{y}{k} \\ \Leftrightarrow \frac{l}{k} &= \left[\left(\left(\frac{y/k}{A} \right)^\psi - \alpha \right) (1-\alpha)^{-1} \right]^{\frac{1}{\psi}} \end{aligned}$$

5. Identity:

$$\frac{y}{l} = \frac{y}{k} \frac{k}{l}$$

6. Identity:

$$\frac{c}{l} = \frac{c}{k} \frac{k}{l}$$

7. From the consumption-leisure decision:

$$\begin{aligned} l \frac{c}{l} &= (1-l) \frac{\theta}{1-\theta} A^\psi (1-\alpha) \left(\frac{y}{l} \right)^{1-\psi} \\ \Leftrightarrow l &= \left(1 + \frac{\frac{c}{l}}{\frac{\theta(1-\alpha)}{1-\theta} A^\psi \left(\frac{y}{l} \right)^{1-\psi}} \right)^{-1} \end{aligned}$$

8. Identities:

$$c = \frac{c}{l}l, \quad k = \frac{l}{l/k}, \quad y = \frac{y}{k}k.$$

How to calibrate?

- We have a CES-production-function. One can show that the capital-share in steady-state is equal to

$$\begin{aligned} s(l, k) &= \frac{\alpha k^\psi}{\alpha k^\psi + (1 - \alpha)l^\psi} = \frac{\alpha k^\psi}{\left[\alpha + (1 - \alpha) \left(\frac{l}{k} \right)^\psi \right] k^\psi} = \frac{\alpha}{\left(\frac{y}{Ak} \right)^\psi} \\ &= \frac{\alpha A^\psi}{\left(\frac{\beta^{-1} - 1 + \delta}{\alpha} \right)^{\frac{\psi}{1-\psi}}} = \frac{\alpha^{\frac{1}{1-\psi}} A^\psi}{(\beta^{-1} - 1 + \delta)^{\frac{\psi}{1-\psi}}} \end{aligned}$$

- So, choose parameters such that this expression is close to 0.2-0.3.