#### LAB NO 09: HASHING

### Overview

- Introduction
- Advantages
- Hash Function
- Hash Table
- Collision Resolution Techniques
- Separate Chaining
- Linear Chaining
- Quadratic Probing
- Double Hashing
- Application
- Reference

- Hashing is a technique that is used to uniquely identify a specific object from a group of similar objects.
- Some examples of how hashing is used in our lives include:
- In universities, each student is assigned a unique roll number that can be used to retrieve information about them.
- In libraries, each book is assigned a unique number that can be used to determine information about the book, such as its exact position in the library or the users it has been issued to etc.
- In both these examples the students and books were hashed to a unique number.

Assume that you have an object and you want to assign a key to it to make searching easy.

To store the key/value pair, you can use a simple array like a data structure where keys (integers) can be used directly as an index to store values. However, in cases where the keys are large and cannot be used directly as an index, you should use hashing.

- In hashing, large keys are converted into small keys by using hash functions.
- The values are then stored in a data structure called hash table.
- The idea of hashing is to distribute entries (key/value pairs) uniformly across an array.
- Each element is assigned a key (converted key).
- By using that key you can access the element in O(1) time. Using the key, the algorithm (hash function) computes an index that suggests where an entry can be found or inserted.

- Hashing is implemented in two steps:
- An element is converted into an integer by using a hash function. This element can be used as an index to store the original element, which falls into the hash table.
- The element is stored in the hash table where it can be quickly retrieved using hashed key.
- hash = hashfunc(key)index = hash % array size

# Advantages

- The main advantage of hash tables over other table data structures is speed.
- This advantage is more apparent when the number of entries is large (thousands or more).
- Hash tables are particularly efficient when the maximum number of entries can be predicted in advance, so that the bucket array can be allocated once with the optimum size and never resized.

## Hash function

- A hash function is any function that can be used to map a data set of an arbitrary size to a data set of a fixed size, which falls into the hash table.
- The values returned by a hash function are called hash values, hash codes, hash sums, or simply hashes.

## Hash function

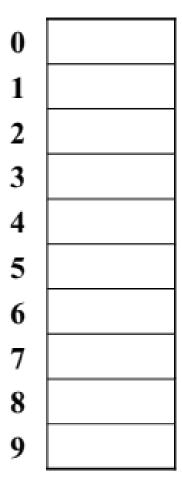
- To achieve a good hashing mechanism, It is important to have a good hash function with the following basic requirements:
- Easy to compute
- Uniform distribution
- Less Collision

### Hash Table

- A hash table is a data structure that is used to store keys/value pairs. It uses a hash function to compute an index into an array in which an element will be inserted or searched.
- By using a good hash function, hashing can work well. Under reasonable assumptions, the average time required to search for an element in a hash table is O(1).

## Hash Table

- key space = integers
- TableSize = 10
- h(K) = K mod 10
- Insert: 7, 18, 41, 94



## Hash Table

Data Item	Value % No. of Slots	Hash Value
26	26 % 10 = 6	6
70	70 % 10 = 0	0
18	18 % 10 = 8	8
31	31 % 10 = 1	1
54	54 % 10 = 4	4
93	93 % 10 = 3	3

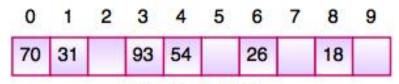
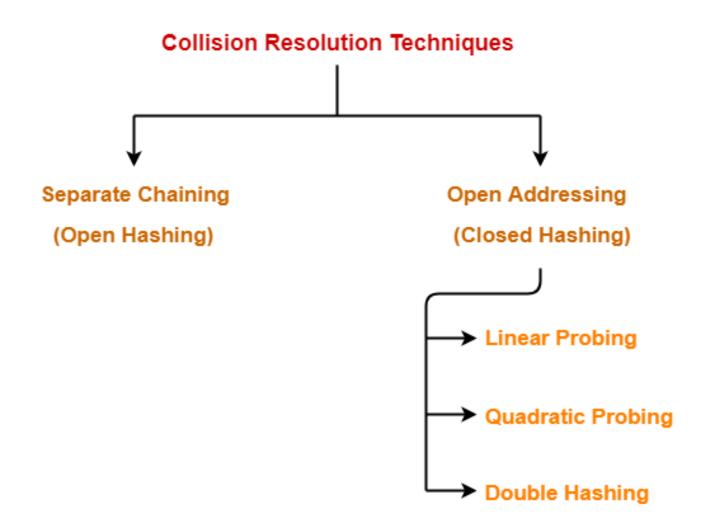


Fig. Hash Table

# Collision resolution techniques

- If  $x_1$  and  $x_2$  are two different keys, it is possible that  $h(x_1) = h(x_2)$ . This is called a collision. Collision resolution is the most important issue in hash table implementations.
- Choosing a hash function that minimizes the number of collisions and also hashes uniformly is another critical issue.
- Separate chaining (open hashing)
- Linear probing (open addressing or closed hashing)
- Quadratic Probing
- Double hashing

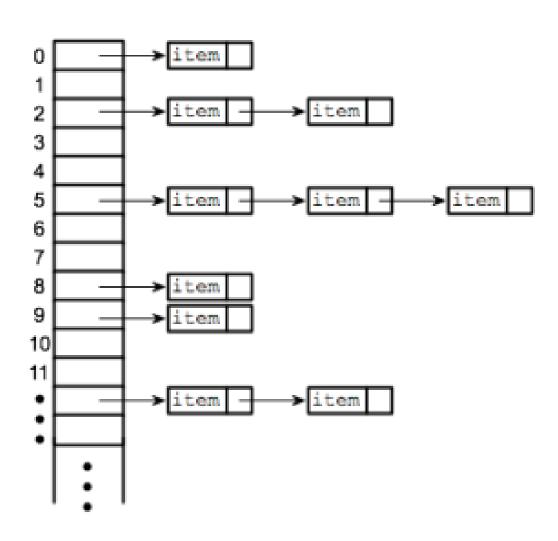
## Collision resolution techniques



# Separate Chaining (Open Hashing)

- Separate chaining is one of the most commonly used collision resolution techniques.
- It is usually implemented using linked lists. In separate chaining, each element of the hash table is a linked list.
- To store an element in the hash table you must insert it into a specific linked list.
- If there is any collision (i.e. two different elements have same hash value) then store both the elements in the same linked list.

# Separate Chaining (Open Hashing)



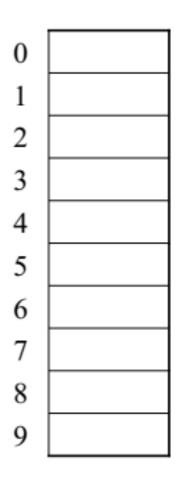
- In open addressing, instead of in linked lists, all entry records are stored in the array itself.
- When a new entry has to be inserted, the hash index of the hashed value is computed and then the array is examined (starting with the hashed index).
- If the slot at the hashed index is unoccupied, then the entry record is inserted in slot at the hashed index else it proceeds in some probe sequence until it finds an unoccupied slot.

- The probe sequence is the sequence that is followed while traversing through entries. In different probe sequences, you can have different intervals between successive entry slots or probes.
- When searching for an entry, the array is scanned in the same sequence until either the target element is found or an unused slot is found. This indicates that there is no such key in the table. The name "open addressing" refers to the fact that the location or address of the item is not determined by its hash value.

• Linear probing is when the interval between successive probes is fixed (usually to 1). Let's assume that the hashed index for a particular entry is index. The probing sequence for linear probing will be:

index = index % hashTableSize
index = (index + 1) % hashTableSize
index = (index + 2) % hashTableSize

index = (index + 3) % hashTableSize



#### Insert:

### Linear Probing:

after checking spot h(k), try spot h(k)+1, if that is full, try h(k)+2, then h(k)+3, etc.

- Quadratic probing is similar to linear probing and the only difference is the interval between successive probes or entry slots.
- Here, when the slot at a hashed index for an entry record is already occupied, you must start traversing until you find an unoccupied slot.
- The interval between slots is computed by adding the successive value of an arbitrary polynomial in the original hashed index.

• Let us assume that the hashed index for an entry is index and at index there is an occupied slot. The probe sequence will be as follows:

index = index % hashTableSize

index =  $(index + 1^2)$  % hashTableSize

index =  $(index + 2^2)$  % hashTableSize

index =  $(index + 3^2)$  % hashTableSize

```
f(i) = i²
Probe sequence:
Oth probe = h(k) mod TableSize
1th probe = (h(k) + 1) mod TableSize
2th probe = (h(k) + 4) mod TableSize
3th probe = (h(k) + 9) mod TableSize
...
ith probe = (h(k) + i²) mod TableSize
```

0	
1	
2	
3	
4	
3 4 5 6 7	
6	
7	
8	
9	

#### Insert:

## Double hashing

- Double hashing is similar to linear probing and the only difference is the interval between successive probes. Here, the interval between probes is computed by using two hash functions.
- Let us say that the hashed index for an entry record is an index that is computed by one hashing function and the slot at that index is already occupied. You must start traversing in a specific probing sequence to look for an unoccupied slot. The probing sequence will be:

# Double hashing

```
index = (index + 1 * indexH) % hashTableSize;
index = (index + 2 * indexH) % hashTableSize;
```

# Double Hashing

```
f(i) = i * g(k)
where g is a second hash function
• Probe sequence:
Oth probe = h(k) mod TableSize
1th probe = (h(k) + g(k)) mod TableSize
2th probe = (h(k) + 2*g(k)) mod TableSize
3th probe = (h(k) + 3*g(k)) mod TableSize
ith probe = (h(k) + i*g(k)) mod TableSize
h(k) = k \mod 7 \text{ and } g(k) = 5 - (k \mod 5)
```

# Separate Chaining Vs Open Addressing

Separate Chaining	Open Addressing
Keys are stored inside the hash table as well as outside the hash table.	All the keys are stored only inside the hash table. No key is present outside the hash table.
The number of keys to be stored in the hash table can even exceed the size of the hash table.	The number of keys to be stored in the hash table can never exceed the size of the hash table.
Deletion is easier.	Deletion is difficult.

# Separate Chaining Vs Open Addressing

Extra space is required for the pointers to No extra space is store the keys outside required. the hash table. Cache performance is Cache performance is poor. This is because of better. linked lists which store This is because here no linked lists are used. the keys outside the hash table. Some buckets of the Buckets may be used hash table are never even if no key maps to used which leads to those particular buckets. wastage of space.

## Summary

#### Which is the Preferred Technique?

The performance of both the techniques depend on the kind of operations that are required to be performed on the keys stored in the hash table-

## Summary

#### **Separate Chaining-**

Separate Chaining is advantageous when it is required to perform all the following operations on the keys stored in the hash table-

- Insertion Operation
- Deletion Operation
- Searching Operation

#### NOTE-

- •Deletion is easier in separate chaining.
- •This is because deleting a key from the hash table does not affect the other keys stored in the hash table.

## Summary

#### **Open Addressing-**

Open addressing is advantageous when it is required to perform only the following operations on the keys stored in the hash table-

- Insertion Operation
- Searching Operation

#### NOTE-

- Deletion is difficult in open addressing.
- •This is because deleting a key from the hash table requires some extra efforts.
- •After deleting a key, certain keys have to be rearranged.

```
#include <iostream>
#include<list>
using namespace std;
class hashclass
 int bucket; //no of buckets you want
 list<int>*hashtable;//container
 public:
 hashclass(int a)//constructor
   bucket=a;
   hashtable=new list<int>[bucket];
```

```
void insert_element(int key)//function used to insert elements to the hashtable
{
    //to get the hash index of key
    int indexkey=hashFunction(key);
    hashtable[indexkey].push_back(key);
}
```

```
void delete_element(int key)//function used to delete elements from the hashtable
   int indexkey=hashFunction(key);
   list<int>::iterator i=hashtable[indexkey].begin();
   for(;i!=hashtable[indexkey].end();i++)
      if(*i==key)
        break;
if(i!=hashtable[indexkey].end())
      hashtable[indexkey].erase(i);
```

```
int hashFunction(int a)//function used to map
values to key
{
    return (a%bucket);
}
```

```
void display_table()//used to display hashtable values
    for(int i=0;i<bucket;i++)</pre>
       cout<<i;
       list<int>::iterator j=hashtable[i].begin();
    for(;j!=hashtable[i].end();j++)
         cout<<"--->"<<*j;
       cout<<endl;
```

```
void search_element(int key)//used to search
element
                                          if(a==1)
    int a=0;//will be 1 if element exist
otherwise 0
                                                   cout<<"The element you wanted to
    int indexkey=hashFunction(key);
                                          search is present in the hashtable."<<endl;
         list<int>::iterator
i=hashtable[indexkey].begin();
                                                 else
    for(;i!=hashtable[indexkey].end();i++)
                                                   cout<<"Element not present"<<endl;
      if(*i==key)
        a=1;
         break;
```

```
~hashclass()//destructor
{
    delete[]hashtable;
};
```

```
int main()
{
int bucketn,ch,element;

cout<<"enter the no of buckets"<<endl;
cin>>bucketn;
hashclass hashelement(bucketn);
```

```
while(1)
{
  cout<<"1.insert element to the hashtable"<<endl;
  cout<<"2.search element from the hashtable"<<endl;
  cout<<"3.delete element from the hashtable"<<endl;
  cout<<"4.display elements of the hashtable"<<endl;
  cout<<"5.exit"<<endl;
  cout<<"enter your choice"<<endl;
  cin>>ch;
```

```
switch(ch)
   case 1:cout<<"enter the element"<<endl;
   cin>>element;
   hashelement.insert_element(element);
   break;
   case 2:cout<<"enter the element you want to search"<<endl;
   cin>>element;
   hashelement.search element(element);
   break;
   case 3:cout<<"enter the element to be deleted"<<endl;
   cin>>element;
   hashelement.delete_element(element);
   break;
```

```
case 4:hashelement.display_table();
    break;
    case 5:return 0;
    default:cout<<"enter a valid value"<<endl;
}
return 0;
}</pre>
```

enter the no of buckets 1.insert element to the hashtable 2.search element from the hashtable 3.delete element from the hashtable 4. display elements of the hashtable 5.exit enter your choice enter the element 13

1.insert element to the hashtable
2.search element from the hashtable
3.delete element from the hashtable
4.display elements of the hashtable
5.exit
enter your choice
1
enter the element
16

```
1.insert element to the hashtable
2.search element from the hashtable
3.delete element from the hashtable
4.display elements of the hashtable
5.exit
enter your choice
1
enter the element
20
```

```
1.insert element to the hashtable
2.search element from the hashtable
3.delete element from the hashtable
4. display elements of the hashtable
5.exit
enter your choice
0---->16---->20
1---->13
3
```

```
1.insert element to the hashtable
2.search element from the hashtable
3.delete element from the hashtable
4.display elements of the hashtable
5.exit
enter your choice
enter the element you want to search
20
```

The element you wanted to search is present in the hashtable.

```
1.insert element to the hashtable
2.search element from the hashtable
3.delete element from the hashtable
4.display elements of the hashtable
5.exit
enter your choice
3
enter the element to be deleted
20
```

1.insert element to the hashtable
2.search element from the hashtable
3.delete element from the hashtable
4.display elements of the hashtable
5.exit
enter your choice
4
0---->16
1---->13