## EE24BTECH11019 - DWARAK A

**Question:** Find the value of x such that the four points with position vectors  $\mathbf{A}(3\hat{i} + 2\hat{j} + \hat{k})$ ,  $\mathbf{B}(4\hat{i} + x\hat{j} + 5\hat{k})$ ,  $\mathbf{C}(4\hat{i} + 2\hat{j} - 2\hat{k})$ , and  $\mathbf{D}(6\hat{i} + 5\hat{j} - \hat{k})$  are coplanar. **Solution:** 

Symbol	Description	Value
A	Coordinates of Point A	$\begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}$
В	Coordinates of Point B	$\begin{pmatrix} 4 \\ x \\ 5 \end{pmatrix}$
C	Coordinates of Point C	$\begin{pmatrix} 4 \\ 2 \\ -2 \end{pmatrix}$
D	Coordinates of Point <b>D</b>	$\begin{pmatrix} 6 \\ 5 \\ -1 \end{pmatrix}$

TABLE 0: Variables Used

Plane Equation,

$$\mathbf{n}^{\mathsf{T}}x = 1\tag{0.1}$$

1

If A, C, D are coplanar

$$\begin{pmatrix} A & C & D \end{pmatrix}^{\mathsf{T}} \mathbf{n} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \tag{0.2}$$

$$\begin{pmatrix} 3 & 2 & 1 \\ 4 & 2 & -2 \\ 6 & 5 & -1 \end{pmatrix} \mathbf{n} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$
 (0.3)

Augmented Matrix,

$$\begin{pmatrix} 3 & 2 & 1 & 1 \\ 4 & 2 & -2 & 1 \\ 6 & 5 & -1 & 1 \end{pmatrix} \xrightarrow{R_1 \to \frac{1}{3}R_1} \begin{pmatrix} 1 & \frac{2}{3} & \frac{1}{3} & \frac{1}{3} \\ 4 & 2 & -2 & 1 \\ 6 & 5 & -1 & 1 \end{pmatrix}$$
(0.4)

$$\xrightarrow{R_3 \to R_3 - 6R_1} \begin{pmatrix} 1 & \frac{2}{3} & \frac{1}{3} & \frac{1}{3} \\ 4 & 2 & -2 & 1 \\ 0 & 1 & -3 & -1 \end{pmatrix}$$
 (0.5)

(0.18)

$$\frac{R_2 \to R_2 - 4R_1}{0} \xrightarrow{\frac{2}{3}} \begin{pmatrix} 1 & \frac{2}{3} & \frac{1}{3} & \frac{1}{3} \\ 0 & -\frac{2}{3} & -\frac{10}{3} & -\frac{1}{3} \\ 0 & 1 & -3 & -1 \end{pmatrix} \qquad (0.6)$$

$$\frac{R_2 \to -\frac{3R_2}{2}}{0} \xrightarrow{\frac{1}{3}} \begin{pmatrix} 1 & \frac{2}{3} & \frac{1}{3} & \frac{1}{3} \\ 0 & 1 & 5 & \frac{1}{2} \\ 0 & 1 & -3 & -1 \end{pmatrix} \qquad (0.7)$$

$$\frac{R_3 \to R_3 - R_2}{0} \xrightarrow{\frac{2}{3}} \begin{pmatrix} 1 & \frac{2}{3} & \frac{1}{3} & \frac{1}{3} \\ 0 & 1 & 5 & \frac{1}{2} \\ 0 & 0 & -8 & -\frac{3}{2} \end{pmatrix} \qquad (0.8)$$

$$\frac{R_1 \to R_1 - \frac{2R_2}{3}}{0} \xrightarrow{\frac{1}{3}} \begin{pmatrix} 1 & 0 & -3 & 0 \\ 0 & 1 & 5 & \frac{1}{2} \\ 0 & 0 & -8 & -\frac{3}{2} \end{pmatrix} \qquad (0.9)$$

$$\frac{R_3 \to -\frac{R_3}{8}}{0} \xrightarrow{\frac{1}{3}} \begin{pmatrix} 1 & 0 & -3 & 0 \\ 0 & 1 & 5 & \frac{1}{2} \\ 0 & 0 & 1 & \frac{3}{16} \end{pmatrix} \qquad (0.10)$$

$$\frac{R_1 \to R_1 + 3R_3}{0} \xrightarrow{\frac{1}{3}} \begin{pmatrix} 1 & 0 & 0 & \frac{9}{16} \\ 0 & 0 & 1 & \frac{3}{16} \end{pmatrix} \qquad (0.11)$$

$$\frac{R_2 \to R_2 - 5R_3}{0} \xrightarrow{\frac{1}{3}} \begin{pmatrix} 1 & 0 & 0 & \frac{9}{16} \\ 0 & 1 & 0 & -\frac{7}{16} \\ 0 & 0 & 1 & \frac{3}{16} \end{pmatrix} \qquad (0.12)$$

$$\begin{array}{c|ccccc}
\hline
 & O & 1 & 3 & \frac{7}{2} \\
\hline
 & O & 0 & 1 & \frac{3}{16}
\end{array}$$

$$\xrightarrow{R_2 \to R_2 - 5R_3} \begin{pmatrix} 1 & 0 & 0 & \frac{9}{16} \\ 0 & 1 & 0 & -\frac{7}{16} \\ 0 & 0 & 1 & \frac{3}{16}
\end{pmatrix}$$

$$\begin{pmatrix} \frac{9}{16} \\ 1 \\ \frac{9}{16} \\ \frac{9}$$

$$\mathbf{n} = \begin{pmatrix} \frac{9}{16} \\ -\frac{7}{16} \\ \frac{3}{16} \end{pmatrix}$$

$$\mathbf{n}^{\mathsf{T}}B = 1$$
(0.13)

$$\mathbf{n}^{\mathsf{T}}B = 1 \tag{0.14}$$

$$(9 \quad -7 \quad 3) \begin{pmatrix} 4 \\ x \\ 5 \end{pmatrix} = 16 \tag{0.15}$$

$$36 - 7x + 15 = 16 \tag{0.16}$$

$$7x = 35 \tag{0.17}$$

x = 5

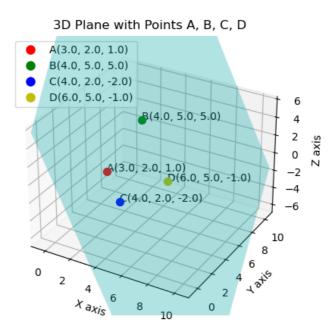


Fig. 0.1: Plot of the plane with points A, B, C and D