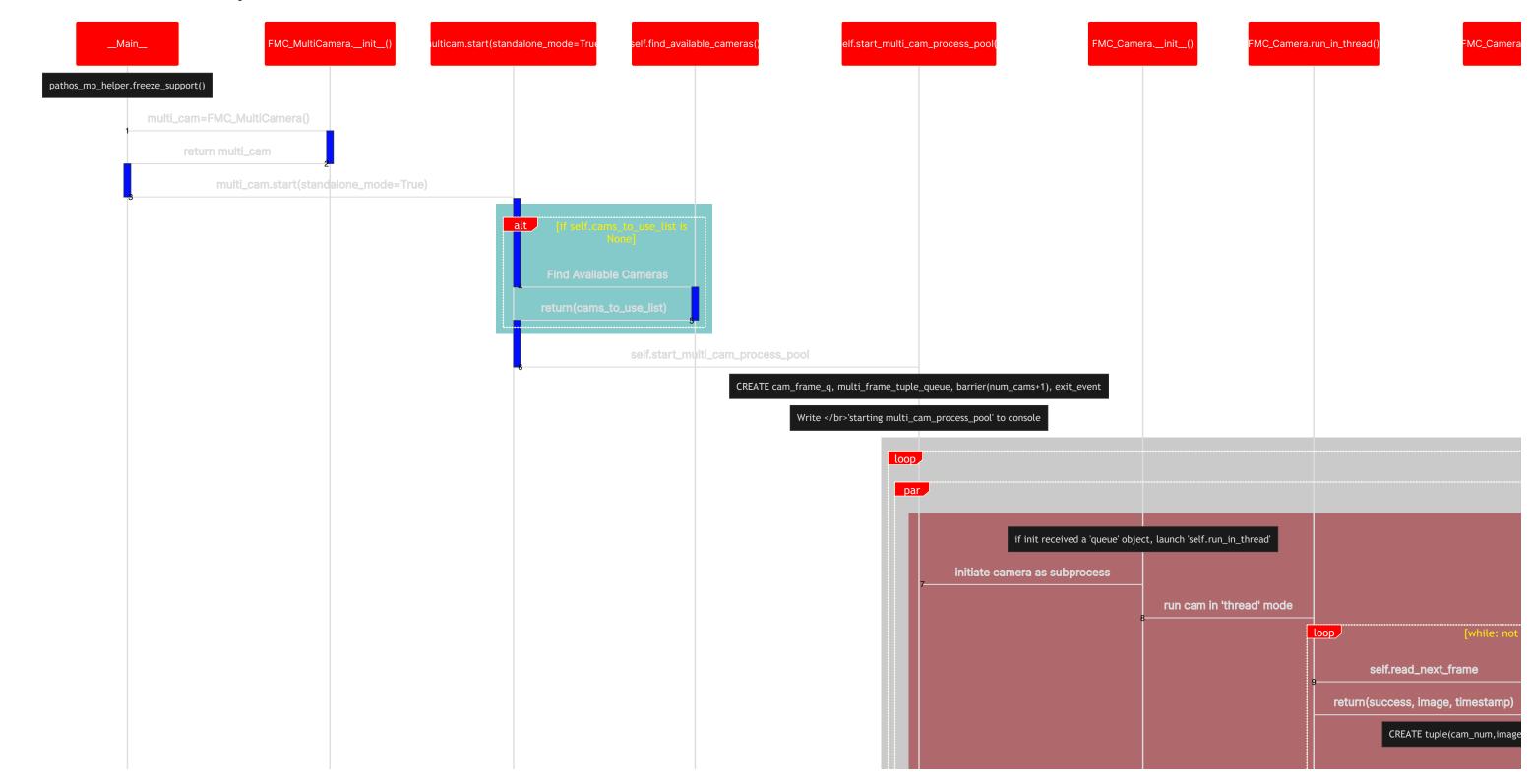
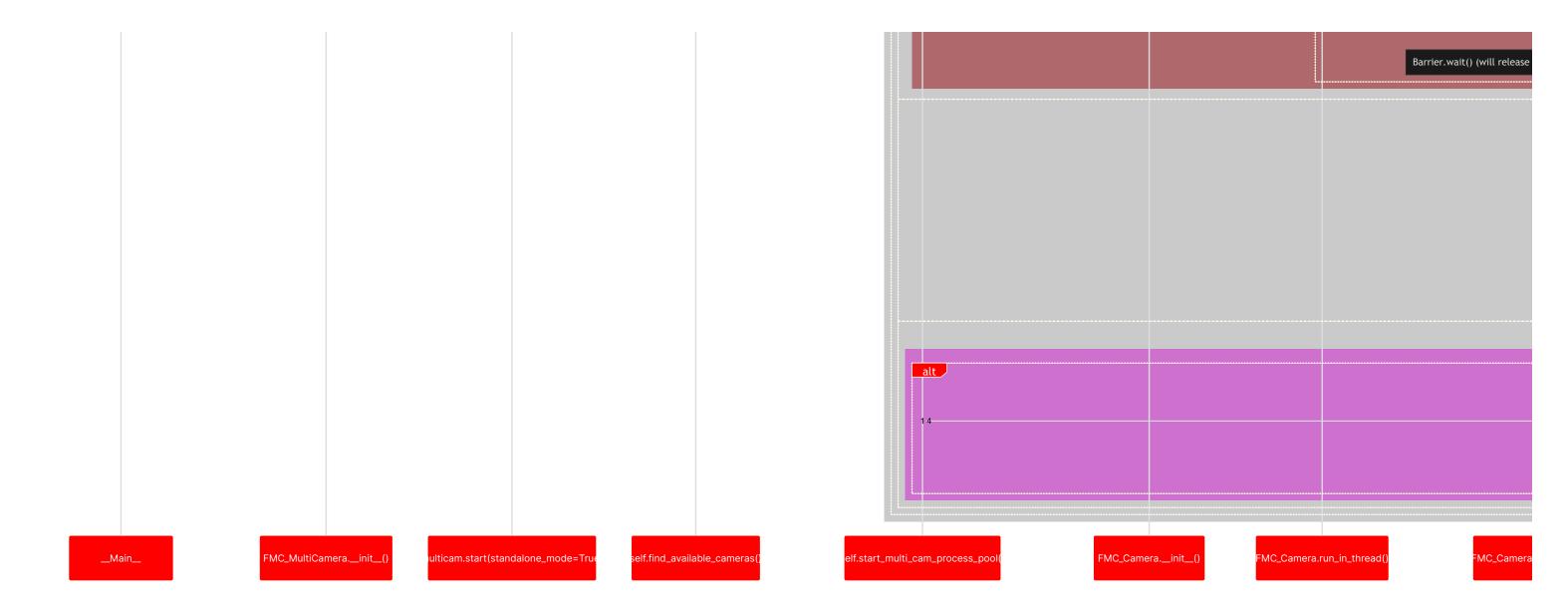
## FMC\_MultiCamera

A class to launch a 'multi\_camera' which acts like a single camera but pulls synchronized images from multiple USB webcams

## **Class definition and contents**

## Run as Main file - Code sequence chart





## FMC\_MultiCamera

```
self,
+[str] rec_name = None,
+[pathlib.Path] save_path = None,
[int] num_cams = 0,
[list<int>]cams_to_use_list = None,
[list<str>]rotation_codes_list = None,
[bool] show_multi_cam_stream = True,
[bool] save_to_mp4 = True,
[bool] save_to_h5 = False,
[bool] save_log_file = False
 __init__()
start(self, standalone_mode=False)
find_available_cameras(self)
start_multi_cam_process_pool(self)
grab_incoming_cam_tuples(self)
stitch_multicam_image(self, multi_cam_tuple)
show_multi_cam_opencv(self)
initialize_video(self, multi_cam_image)
create_diagnostic_images(self)
```

\_\_enter\_\_() \_\_exit\_\_()