```
from google.colab import drive
drive.mount('/content/drive')

    Mounted at /content/drive

from future import print function
import numpy as np
from sklearn.model_selection import train_test_split
from sklearn.metrics import classification report
from time import time
#np.random.seed(1337) # for reproducibility
from keras.preprocessing import sequence
from keras.models import Sequential
from keras.layers.core import Dense, Dropout, Activation, Flatten
from keras.layers.normalization import BatchNormalization
from keras.layers.convolutional import Convolution1D, MaxPooling1D
from keras.utils import np_utils
from keras.callbacks import TensorBoard
# set parameters:
test dim = 499
maxlen = 100
nb filter = 512
filter_length_1 = 10
filter length 2 = 5
hidden dims = 750
nb_epoch = 12
nb classes = 2
split_ratio = 0.15
print('Loading data...')
```

X = np.load('/content/drive/My Drive/Colab Notebooks/data/numpy\_vectors/x\_test\_mfcc\_500\_50:50\_samples\_sliced\_out.npy')

```
y = np.load('/content/drive/My Drive/Colab Notebooks/data/numpy_vectors/y_label_500_50:50_samples_sliced_out.npy')
print(X.shape)
print(y.shape)
    Loading data...
                                                Traceback (most recent call last)
     FileNotFoundError
     <ipython-input-6-4680f96d35c4> in <module>()
          29 print('Loading data...')
          30
     ---> 31 X = np.load('/content/drive/My Drive/Colab Notebooks/data/numpy_vectors/x_test_mfcc_500_50:50_samples_sliced_
          32 y = np.load('/content/drive/My Drive/Colab Notebooks/data/numpy vectors/y label 500 50:50 samples sliced out.
          33 print(X.shape)
     /usr/local/lib/python3.6/dist-packages/numpy/lib/npyio.py in load(file, mmap mode, allow pickle, fix imports, encodin
                     own fid = False
         426
         427
                 else:
                     fid = open(os_fspath(file), "rb")
     --> 428
                     own fid = True
         429
         430
     FileNotFoundError: [Errno 2] No such file or directory: '/content/drive/My Drive/Colab Notebooks/data/numpy_vectors/x
      SEARCH STACK OVERFLOW
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=split_ratio)
xts = X train.shape
\#X_{train} = np.reshape(X_{train}, (xts[0], xts[1], 1))
xtss = X_test.shape
\#X_{\text{test}} = \text{np.reshape}(X_{\text{test}}, (xtss[0], xtss[1], 1))
yts = y_train.shape
#y_train = np.reshape(y_train, (yts[0], 1))
ytss = y_test.shape
#y_test = np.reshape(y_test, (ytss[0], 1))
```

```
print(len(X_test), 'test sequences')
Y_train = np_utils.to_categorical(y_train, nb_classes)
Y test = np utils.to categorical(y test, nb classes)
# print('Pad sequences (samples x time)')
# X train = sequence.pad sequences(X train, maxlen=maxlen)
# X_test = sequence.pad_sequences(X_test, maxlen=maxlen)
# print('X_train shape:', X_train.shape)
# print('X_test shape:', X_test.shape)
 225 test sequences
for batch_size in range(10, 11, 5):
    print('Build model...')
    model = Sequential()
    # we start off with an efficient embedding layer which maps
    # our vocab indices into embedding_dims dimensions
    # model.add(Embedding(max_features, embedding_dims, input_length=maxlen))
    # model.add(Dropout(0.25))
    # we add a Convolution1D, which will learn nb_filter
    # word group filters of size filter_length:
    model.add(Convolution1D(nb filter=nb filter,
                           filter_length=filter_length_1,
                           input_shape=(test_dim, 13),
                           border mode='valid',
                           activation='relu'
                            ))
    # we use standard max pooling (halving the output of the previous layer):
    model.add(BatchNormalization())
    model.add(Convolution1D(nb filter=nb filter.
```

https://colab.research.google.com/drive/1Z5vq1eRU3zCskrlTc2kp1y9xzUx8P9H8?authuser=2#scrollTo=9yKzDEqVroJf&printMode=true

```
filter_length=5,
                        border_mode='valid',
                        activation='relu'
                        ))
model.add(BatchNormalization())
model.add(MaxPooling1D(pool_length=2))
model.add(Convolution1D(nb_filter=nb_filter,
                        filter_length=25,
                        border mode='same',
                        activation='relu'
                        ))
model.add(BatchNormalization())
model.add(MaxPooling1D(pool_length=2))
model.add(Convolution1D(nb_filter=nb_filter,
                        filter_length=50,
                        border_mode='same',
                        activation='relu'
                        ))
model.add(BatchNormalization())
model.add(MaxPooling1D(pool_length=2))
model.add(Convolution1D(nb_filter=nb_filter,
                        filter_length=2,
                        border_mode='same',
                        activation='relu'
                        ))
model.add(BatchNormalization())
```

```
model.add(maxPoolinglD(pool_tengtn=2))
# We flatten the output of the conv layer,
# so that we can add a vanilla dense layer:
model.add(Flatten())
# We add a vanilla hidden layer:
# model.add(Dense(hidden dims))
model.add(Dropout(0.25))
# model.add(Activation('relu'))
model.add(Dense(1000))
model.add(Activation('relu'))
model.add(Dense(750))
model.add(Activation('relu'))
model.add(Dense(50))
model.add(Activation('relu'))
# We project onto a single unit output layer, and squash it with a sigmoid:
model.add(Dense(nb classes))
model.add(Activation('softmax'))
model.compile(loss='binary crossentropy',
            optimizer='adam', metrics=['accuracy'])
print("model/split = {} <> batchsize = {}".format(split_ratio, batch_size))
tensorboard = TensorBoard(log_dir="logs/split_{}_batchsize_{}".format(split_ratio, batch_size))
model.fit(X_train, Y_train, batch_size=batch_size,
        nb_epoch=12, verbose=1, callbacks=[tensorboard] )
# model.save('model_hin_tel_38_samples.h5')
y_preds = model.predict(X_test)
for i in range(len(y_preds)):
    print(y_preds[i], y_test[i])
score = model.evaluate(X_test, Y_test, verbose=1)
print(score)
```

print("\n\*
# print(classification\_report(Y\_test, Y\_preds))

```
Build model...
/usr/local/lib/python3.6/dist-packages/ipykernel_launcher.py:17: UserWarning: Update your `Conv1D` call to the Keras
/usr/local/lib/python3.6/dist-packages/ipykernel_launcher.py:25: UserWarning: Update your `Conv1D` call to the Keras
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/usr/local/lib/python3.6/dist-packages/ipykernel launcher.py:35: UserWarning: Update your `Conv1D` call to the Keras
/usr/local/lib/python3.6/dist-packages/ipykernel launcher.py:40: UserWarning: Update your `MaxPooling1D` call to the
/usr/local/lib/python3.6/dist-packages/ipykernel_launcher.py:45: UserWarning: Update your `Conv1D` call to the Keras
/usr/local/lib/python3.6/dist-packages/ipykernel launcher.py:50: UserWarning: Update your `MaxPooling1D` call to the
/usr/local/lib/python3.6/dist-packages/ipykernel launcher.py:55: UserWarning: Update your `Conv1D` call to the Keras
/usr/local/lib/python3.6/dist-packages/ipykernel launcher.py:60: UserWarning: Update your `MaxPooling1D` call to the
model/split = 0.15 <> batchsize = 10
/usr/local/lib/python3.6/dist-packages/ipykernel launcher.py:88: UserWarning: The `nb epoch` argument in `fit` has be
Epoch 1/12
Epoch 2/12
Epoch 3/12
Epoch 4/12
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Epoch 11/12
Epoch 12/12
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