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OPERATING SYSTEMS

Lift Simulator - Report

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1 Mutual Exclusion and Shared Resources

1.1 Threads

Mutual exclusion is done using pthread mutexes the queue struct contains a mutex that is used to protect the data inside the queue, this mutex must be acquired before manipulating queue data to ensure mutual exclusion, this queue is shared between the scheduler thread and the 3 lift threads, and if any of them wish to mutate the queue in any way (removing or adding) they must first acquire mutex.

2 conditions are also used to allow some basic communication between threads, the conditions are when the queue is empty or full, if the queue is empty the lift threads wait until the scheduler adds something to the queue, and signals the condition waking up a sleeping thread to reacquire the mutex and to process the data, and in the case of the queue been full.

```
1 ...
2 pthread_mutex_lock(&l->queue->mutex);
3 ...
4
5 while(l->queue->empty && !l->queue->finished) {
6     pthread_cond_wait(&l->queue->cond_empty, &l->queue->mutex);
7 }
8
9 if(!l->queue->empty) {
10    request_t *r = queue_remove(l->queue);
11    pthread_cond_signal(&l->queue->cond_full);
12    pthread_mutex_unlock(&l->queue->mutex);
13 }
```

The scheduler waits on a full condition which is signaled by any of the 3 lift threads when they remove something from the queue, letting the scheduler know that there is space now and it can wake up an reacquire the mutex to add more into the queue.

```
1 ...
2 pthread_mutex_lock(&s->queue->mutex);
3
4 while(s->queue->full) {
5     pthread_cond_wait(&s->queue->cond_full, &s->queue->mutex);
6 }
7
8 request_t *r = file_read_line(s->input);
9 if(r) {
10    queue_add(s->queue, r);
11    ...
12    pthread_mutex_unlock(&s->queue->mutex);
13 }
```

1.2 Processes

A logic similar to threads exists in processes but requires the use of shared memory and semaphores since processes do not share memory mappings the way threads do.

I used POSIX shared memory and semaphores in order to implement shared resources and mutual exclusion. The bounded buffer problem can be solved through the use of 3 semaphores, one acting as a signal for full, another as a signal for empty, and the final used as a mutex to protect the shared memory (I also had another to protected accesses to the output file). The semaphores are initialised to different values.

```
1 sem_init(&ptr->semaphore.empty, 1, m);
2 sem_init(&ptr->semaphore.full, 1, 0);
3 sem_init(&ptr->semaphore.mutex, 1, 1);
4 sem_init(&ptr->semaphore.file, 1, 1);
```

The empty semaphore marks how many empty locations are in the buffer, the full semaphore marks how many are full, the mutex is used as a binary semaphore to protect the shared memory and same for the file semaphore to protect the file IO.

The scheduler must wait on the empty mutex to be available in order to add something into the shared memory, and once it has added something the scheduler posts the full mutex to allow a lift process to wake up and take one from the queue, once the lift is done it posts another empty, which will allow the scheduler back on if the queue was completely full prior.

The mutex semaphore is used to protect the shared memory by enforcing mutual exclusion by only allowing a single process to modify the data in the shared memory.

In terms of the shared resources, there was an array of requests which was used as a circular queue, and the semaphores were also shared, along with some statistics that need to be printed such as total requests and the movement counts of each individual lift.

These resources were shared through the use of the POSIX shared memory API, this API required you to open a shared memory object with a name, use `ftruncate` to set the size of the shared memory object, and to use `mmap` to map the memory object into the address space of the current process. This was done once to create the shared memory by the main, and then each process mapped the same block of shared memory into their own address space.

Once the processes have been waited on, the shared memory is unmapped and the memory objects are unlinked.

The output `FILE` isn't included in the shared memory since according to the manual page for `fork`, the open file descriptors are shared across child processes, therefore the parent simply opens it, and each child will close it when they're done, and same for the parent.

2 Testing

2.1 Processes

2.1.1 Example 1

Testing with a buffer size larger than the number of threads, and relatively small sleep time to see if the program behaves as expected. Through manual inspection of the output, it can be surmised that the program works as expected.

Command `./lift_sim_B 4 2 test/inputs/test2.txt`

Input `test/inputs/test2.txt`

Output `examples/process/test2.out`

2.1.2 Example 2

Testing with a significantly larger buffer size but with a sleep time of 0 to see if mutual exclusion still exists in the case of the “work” being done quickly. Manual inspection reveals the expected output, and since there was a final output, it means there was no deadlock while acquiring resources.

Command `./lift_sim_B 10 0 test/inputs/test7.txt`

Input `test/inputs/test7.txt`

Output `examples/process/test7.out`

2.1.3 Example 3

A very large buffer size with a long sleep time to demonstrate another possible situation where the program works as expected.

Command `./lift_sim_B 20 5 test/inputs/test21.txt`

Input `test/inputs/test21.txt`

Output `examples/process/test21.out`

2.2 Threads

Each test file is a different size between the allowed values of 50 and 100.

2.2.1 Example 1

A buffer size equal to to the number of worker threads with a relatively short “working” time.

Command ./lift_sim_A 3 1 test/inputs/test34.txt

Input test/inputs/test34.txt

Output examples/threads/test34.out

2.2.2 Example 2

Larger buffer with the same time.

Command ./lift_sim_A 5 1 test/inputs/test1.txt

Input test/inputs/test1.txt

Output examples/threads/test1.out

2.2.3 Example 3

Even larger buffer with a zero time to ensure mutual exclusion happens even without the threads sleeping.

Command ./lift_sim_A 10 0 test/inputs/test10.txt

Input test/inputs/test10.txt

Output examples/threads/test10.out

A Source Code

A.1 README.md

```
1 # Lift Simulator
2
3 #### Anurag Singh
4
5 ## Introduction
6
7 Lift Simulator is a solution to the Operating Systems (COMP2006) assignment
8 → in Semester 1 2020.
9
10 ## Purpose
11
12 To demonstrate multi-threading, and inter process/thread communication, and
13 → solving the critical section problem.
14
15 ## Building
16
17 Running `make` will build 2 executables, `lift_sim_A` and `lift_sim_B` which
18 → refer to threads and processes implementations respectively.
19
20 ## Usage
21
22 Both lift_sim_A, and lift_sim_B are used the same way, the program will write
23 → to the sim_out file as it runs.
24
25
26
27 Various test files are included in the `test/inputs` directory, with some
28 → sample outputs available in the `examples` directory.
29
30 Python scripts in the testing directory are for testing the program through
31 → the input files quickly.
```

A.2 Common

A.2.1 common.h

```
1 #ifndef COMMON_H
2 #define COMMON_H
3 /**
4  * Some common definitions between
5  * threads and processes implementation
6  */
7 #define OUTPUT_FILENAME          "sim_out"
8 #define TOTAL_THREADS            4
9 #define TOTAL_LIFTS              3
10 #define MAX_FLOOR                20
11 #define MIN_FLOOR                1
12 #define MIN_INPUT                50
13 #define MAX_INPUT               100
14
15 #endif
```

A.2.2 file_io

```
1 #ifndef FILE_IO_H
2 #define FILE_IO_H
3 #include <stdio.h>
4 #include <stdbool.h>
5
6 #include "request.h"
7
8 request_t* file_read_line(FILE *file);
9 bool file_validate(FILE *file);
10 #endif
```

```
1 /**
2  * @file file_io.c
3  * @author Anurag Singh (18944183)
4  *
5  * @date 24-04-20
6  *
7  */
8
9 #include <stdio.h>
10 #include <stdlib.h>
11 #include <stdbool.h>
12
13 #include "common.h"
```

```

14 #include "file_io.h"
15 #include "request.h"
16
17 /**
18 * This function reads a line
19 * from the input file, parses it
20 * in the format specified, and
21 * does a simple sanity check to
22 * ensure that its valid, before
23 * malloc'ing a struct and returning
24 * it containing the values read.
25 *
26 * @param file to read the line from
27 * @return malloc'd request_t* containing the values
28 */
29 request_t* file_read_line(FILE *file)
30 {
31     int src, dest;
32     char buffer[BUFSIZ] = {0};
33
34     if(!fgets(buffer, BUFSIZ, file)) {
35         return NULL;
36     }
37
38     int ret = sscanf(buffer, "%d %d", &src, &dest);
39     if(ret != 2) {
40         // incase 2 values weren't read from the line
41         return NULL;
42     }
43
44     // bounds check the input
45     if(src > MAX_FLOOR || dest > MAX_FLOOR || src < MIN_FLOOR || dest <
46     ↪ MIN_FLOOR) {
47         return NULL;
48     }
49
50     request_t *req = malloc(sizeof(request_t));
51     req->src = src;
52     req->dest = dest;
53
54     return req;
55 }
56
57 /**
58 * Validates that the input file has
59 * only valid lift locations and
60 * has a valid size between the min and

```

```

60 * max inclusive
61 *
62 * @param file to be validated
63 * @return true if the file is valid
64 * @return false if the file is invalid
65 */
66 bool file_validate(FILE *file)
67 {
68     request_t *req;
69     int count = 0;
70
71     while((req = file_read_line(file))) {
72         count++;
73         free(req);
74     }
75
76     // If we didn't reach eof
77     // it means there was an invalid line
78     if(!feof(file)) {
79         return false;
80     }
81
82     // If the overall count is less than or more than
83     // its also invalid
84     if(count > MAX_INPUT || count < MIN_INPUT) {
85         return false;
86     }
87
88     rewind(file);
89
90     return true;
91 }
```

A.2.3 request.h

```

1 #ifndef REQUEST_H
2 #define REQUEST_H
3
4 /**
5  * Each request is stored as a struct
6  */
7 typedef struct request {
8     int src;
9     int dest;
10} request_t;
```

```
12 #endif
```

A.3 Processes

A.3.1 cqueue

```
1 #ifndef CQUEUE_H
2 #define CQUEUE_H
3 #include "memory.h"
4
5 void sm_cqueue_add(struct shared_memory *sm, request_t r);
6 request_t sm_cqueue_remove(struct shared_memory *sm);
7 #endif
```

```
1 /**
2  * @file cqueue.c
3  * @author Anurag Singh (18944183)
4  *
5  * @date 24-04-20
6  *
7  * A simple circular queue "implementation"
8  *
9  */
10
11 #include <common/request.h>
12
13 #include "memory.h"
14
15 /**
16  * Add a request to the queue stored in
17  * the shared memory param
18  *
19  * @param sm shared memory struct
20  * @param r request to add to queue
21  */
22 void sm_cqueue_add(struct shared_memory *sm, request_t r)
23 {
24     if(sm->head == -1) {
25         sm->head = 0;
26         sm->tail = 0;
27     } else {
28         if(sm->tail == sm->max - 1) {
29             sm->tail = 0;
30         } else {
31             sm->tail++;
```

```

32         }
33     }

34     sm->current++;
35     if(sm->current == sm->max) {
36         sm->full = true;
37     }
38     sm->empty = false;
39     sm->requests[sm->tail] = r;
40 }
41 }

42 /**
43 * Remove a request from the queue
44 *
45 * @param sm memory to remove from
46 * @return request_t
47 */
48
49 request_t sm_cqueue_remove(struct shared_memory *sm)
{
50     request_t r = sm->requests[sm->head];

51     if(sm->head == sm->tail) {
52         sm->head = -1;
53         sm->tail = -1;
54     } else {
55         if(sm->head == sm->max - 1) {
56             sm->head = 0;
57         } else {
58             sm->head++;
59         }
60     }
61 }

62     sm->current--;
63     if(sm->current == 0) {
64         sm->empty = true;
65     }
66     sm->full = false;

67
68     return r;
69 }
70 }

```

A.3.2 lift_main

```

1 #ifndef LIFT_MAIN_H
2 #define LIFT_MAIN_H
3 #include <stdio.h>

```

```

4 int lift_main(int lift_num, int sleep_time, FILE *output);
5
6 #endif

```

```

1 /**
2  * @file lift_main.c
3  * @author Anurag Singh (18944183)
4  *
5  * @date 24-04-20
6  *
7  * The function called when a lift process needs
8  * to be created. Effectively the "main" of the lift.
9  *
10 */
11
12 #include <stdio.h>
13 #include <stdlib.h>
14 #include <unistd.h>
15 #include <sys/types.h>
16 #include <sys/wait.h>
17 #include <sys/mman.h>
18 #include <sys/stat.h>
19 #include <fcntl.h>
20
21 #include "memory.h"
22 #include "cqueue.h"
23 #include "lift_main.h"
24
25 int lift_main(int lift_num, int sleep_time, FILE *output)
26 {
27     int previous_floor = 1;
28     int current_floor = 1;
29     int request_num = 0;
30     // Get access to the shared memory
31     int shm_fd = shm_open(SHARED_MEMORY_NAME, O_RDWR, 0666);
32     int req_fd = shm_open(SHARED_MEMORY_REQUESTS, O_RDWR, 0666);
33     struct shared_memory *sm = mmap(0, sizeof(struct shared_memory),
34         PROT_READ | PROT_WRITE, MAP_SHARED, shm_fd, 0);
35     sm->requests = mmap(0, sizeof(request_t) * sm->max, PROT_READ |
36         PROT_WRITE, MAP_SHARED, req_fd, 0);
37
38     while(1) {
39         sem_wait(&sm->semaphore.mutex);
40         if(sm->empty && sm->finished) {
41             sem_post(&sm->semaphore.full);
42             sem_post(&sm->semaphore.mutex);
43             break;
44         }
45     }
46 }

```

```

42 }
43 sem_post(&sm->semaphore.mutex);
44 // we release the mutex after checking
45 // if the process should die, because
46 // to solve the bounded buffer problem
47 // we need to wait on the full semaphore
48 // which will be posted by the producer
49 // waiting while keeping holding the
50 // "mutex" will prevent progress, and likely deadlock
51
52
53 sem_wait(&sm->semaphore.full);
54 sem_wait(&sm->semaphore.mutex);
55
56 if(!sm->empty) {
57     request_t r = sm_cqueue_remove(sm);
58     sem_wait(&sm->semaphore.file);
59     request_num++;
60     previous_floor = current_floor;
61     current_floor = r.dest;
62     int r_movement = abs(previous_floor - r.src) + abs(r.src -
63     ↪ current_floor);
64     sm->lift_movements[lift_num - 1] += r_movement;
65
66     fprintf(output, "Lift-%d Operation\n"
67             "Previous Floor: %d\n"
68             "Request: Floor %d to %d\n"
69             "Details: \n"
70             "\tGo from Floor %d to %d\n"
71             "\tGo from Floor %d to %d\n"
72             "\t# Movements: %d\n"
73             "\tRequest No: %d\n"
74             "\tTotal # Movement: %d\n"
75             "Current Position: Floor %d\n\n",
76             lift_num, previous_floor, r.src, r.dest,
77             previous_floor, r.src, r.src, current_floor,
78             r_movement, request_num,
79             ↪ sm->lift_movements[lift_num - 1],
80             current_floor);
81     fflush(output);
82
83     sem_post(&sm->semaphore.file);
84     sem_post(&sm->semaphore.mutex);
85     sem_post(&sm->semaphore.empty);
86
87     // release the mutex since the critical section
88     // doesn't involve the work we do (in this case)

```

```

87         // pretend to work
88         sleep(sleep_time);
89     } else {
90         sem_post(&sm->semaphore.mutex);
91         sem_post(&sm->semaphore.empty);
92     }
93 }
94
95
96     fclose(output);
97
98     return 0;
}

```

A.3.3 memory

```

1 #ifndef MEMORY_H
2 #define MEMORY_H
3 #include <stdbool.h>
4 #include <semaphore.h>
5
6 #include <common/request.h>
7 #include <common/common.h>
8
9 #define SHARED_MEMORY_NAME           "shared_mem"
10 #define SHARED_MEMORY_REQUESTS      "requests_list"
11
12 /**
13  * kinda like the stack of
14  * memory that'll be shared
15  * across processes, also contains
16  * the shared semaphores in a separate struct
17  */
18 struct shared_memory {
19     request_t *requests;
20     int max;
21     int current;
22     int head;
23     int tail;
24
25     int total_requests;
26     int lift_movements[TOTAL_LIFTS];
27
28     bool finished;
29     bool empty;
30     bool full;
31

```

```

32     struct {
33         sem_t full;
34         sem_t empty;
35         sem_t mutex;
36         sem_t file;
37     } semaphore;
38 };
39
40 struct shared_memory* shared_mem_create(int m);
41 void shared_memory_destroy(struct shared_memory *sm, int m);
42
43 #endif

```

```

1 /**
2  * @file memory.c
3  * @author Anurag Singh (18944183)
4  *
5  * @date 24-04-20
6  *
7  * Handles allocating and freeing shared memory
8  *
9  */
10
11 // ftruncate
12 #define _POSIX_C_SOURCE 200112L
13 #include <unistd.h>
14 #include <sys/types.h>
15 #include <sys/wait.h>
16 #include <sys/mman.h>
17 #include <sys/stat.h>
18 #include <fcntl.h>
19
20 #include <common/request.h>
21 #include <common/common.h>
22
23 #include "memory.h"
24
25 /**
26  * Create the shared memory
27  * initialising all fields to sane defaults
28  * Uses the POSIX shared memory API
29  *
30  * @param m buffer size
31  * @return struct shared_memory*
32  */
33 struct shared_memory* shared_mem_create(int m)
34 {

```

```

35     int shm_fd = shm_open(SHARED_MEMORY_NAME, O_CREAT | O_RDWR, 0666);
36     ftruncate(shm_fd, sizeof(struct shared_memory));
37     struct shared_memory *ptr = mmap(0, sizeof(struct shared_memory),
38                                     PROT_WRITE, MAP_SHARED, shm_fd, 0);
39
39     int req_list_fd = shm_open(SHARED_MEMORY_REQUESTS, O_CREAT | O_RDWR,
40                                0666);
41     ftruncate(req_list_fd, sizeof(request_t) * m);
42     ptr->requests = mmap(0, sizeof(request_t) * m, PROT_WRITE, MAP_SHARED,
43                           req_list_fd, 0);
44
44     // i think the memory is zero'd out
45     // but just incase, we need sane defaults
46     ptr->current = 0;
47     ptr->max = m;
48     ptr->finished = false;
49     ptr->empty = true;
50     ptr->full = false;
51     ptr->head = -1;
52     ptr->tail = -1;
53     ptr->total_requests = 0;
54     for(int i = 0; i < TOTAL_LIFTS; i++) {
55         ptr->lift_movements[i] = 0;
56     }
57
58     sem_init(&ptr->semaphore.empty, 1, m);
59     sem_init(&ptr->semaphore.full, 1, 0);
60     sem_init(&ptr->semaphore.mutex, 1, 1);
61     sem_init(&ptr->semaphore.file, 1, 1);
62
62     return ptr;
63 }
64
65 /**
66 * Unlinks and unmaps all of the shared memory
67 *
68 * @param sm shared memory block
69 * @param m buffer size (munmap needs this)
70 */
71 void shared_memory_destroy(struct shared_memory *sm, int m)
72 {
73     sem_destroy(&sm->semaphore.mutex);
74     sem_destroy(&sm->semaphore.empty);
75     sem_destroy(&sm->semaphore.full);
76     sem_destroy(&sm->semaphore.file);
77
78     munmap(sm->requests, sizeof(request_t) * m);

```

```

79     munmap(sm, sizeof(struct shared_memory));
80
81     shm_unlink(SHARED_MEMORY_REQUESTS);
82     shm_unlink(SHARED_MEMORY_NAME);
83 }
```

A.3.4 scheduler_main

```

1 #ifndef SCHEDULER_MAIN_H
2 #define SCHEDULER_MAIN_H
3 #include <stdio.h>
4 int scheduler_main(const char *filename, FILE *output);
5 #endif
```

```

1 /**
2  * @file scheduler_main.c
3  * @author Anurag Singh (18944183)
4  *
5  * @date 24-04-20
6  *
7  * the function called after fork to create a scheduler child
8  *
9  */
10
11 #include <stdio.h>
12 #include <stdlib.h>
13 #include <unistd.h>
14 #include <sys/types.h>
15 #include <sys/wait.h>
16 #include <sys/mman.h>
17 #include <sys/stat.h>
18 #include <fcntl.h>
19
20 #include <common/file_io.h>
21
22 #include "memory.h"
23 #include "cqueue.h"
24 #include "scheduler_main.h"
25
26 int scheduler_main(const char *filename, FILE *output)
27 {
28     bool finished = false;
29     int shm_fd = shm_open(SHARED_MEMORY_NAME, O_RDWR, 0666);
30     int req_fd = shm_open(SHARED_MEMORY_REQUESTS, O_RDWR, 0666);
31     struct shared_memory *sm = mmap(0, sizeof(struct shared_memory),
32         PROT_READ | PROT_WRITE, MAP_SHARED, shm_fd, 0);
```

```

32     sm->requests = mmap(0, sizeof(request_t) * sm->max, PROT_READ |
33                           PROT_WRITE, MAP_SHARED, req_fd, 0);
34
35 // Make sure we can actually open the input file
36 // Else we mark as finished, and post the full mutex
37 // to allow each process to wake up and die
38 FILE *fp = fopen(filename, "r");
39 if(!fp) {
40     sem_wait(&sm->semaphore.mutex);
41     sm->finished = true;
42     sm->empty = true;
43     sem_post(&sm->semaphore.mutex);
44     sem_post(&sm->semaphore.full);
45     perror("input file");
46     fclose(output);
47     return EXIT_FAILURE;
48 }
49
50 while(!finished) {
51     request_t *r = file_read_line(fp);
52     if(r) {
53         sem_wait(&sm->semaphore.empty);
54         sem_wait(&sm->semaphore.mutex);
55         sm->total_requests++;
56         sm_cqueue_add(sm, *r);
57
58         sem_wait(&sm->semaphore.file);
59         fprintf(output, "-----\n"
60                 "New Lift Request from %d to %d\n"
61                 "Request No: %d\n"
62                 "-----\n\n", r->src,
63                               r->dest, sm->total_requests);
64         fflush(output);
65         sem_post(&sm->semaphore.file);
66
67         sem_post(&sm->semaphore.mutex);
68         sem_post(&sm->semaphore.full);
69
70         free(r);
71     } else {
72         sm->finished = true;
73         finished = true;
74         // wake up anything sleeping before i die
75         sem_post(&sm->semaphore.full);
76     }
77 }

```

```

77
78     fclose(fp);
79     fclose(output);
80
81     return 0;
82 }
```

A.3.5 lift_sim_B

```

1 /**
2  * @file lift_sim_B.c
3  * @author Anurag Singh (18944183)
4  *
5  * @date 24-04-20
6  *
7  * The actual main of the process part
8  * Loads up shared memory, and setups up
9  * to fork and create child processes,
10 * while also waiting for them to
11 * die so we can clean up afterwards
12 *
13 */
14
15 #include <stdio.h>
16 #include <stdlib.h>
17 #include <unistd.h>
18 #include <string.h>
19 #include <stdbool.h>
20 #include <sys/types.h>
21 #include <sys/wait.h>
22
23 #include <common/request.h>
24 #include <common/file_io.h>
25 #include <common/common.h>
26
27 #include "memory.h"
28 #include "lift_main.h"
29 #include "scheduler_main.h"
30
31 int main(int argc, const char *argv[])
32 {
33     if(argc < 4) {
34         fprintf(stderr, "usage: %s [buffer size] [time] [filename]\n",
35             argv[0]);
36         return EXIT_FAILURE;
37     }
38 }
```

```

37
38     int m = atoi(argv[1]);
39     int lift_time = atoi(argv[2]);
40
41     if(m <= 0 && lift_time < 0) {
42         fprintf(stderr, "buffer size > 0, time >= 0\n");
43         return EXIT_FAILURE;
44     }
45
46     FILE *output = fopen(OUTPUT_FILENAME, "w");
47     if(!output) {
48         perror("output file");
49         return EXIT_FAILURE;
50     }
51
52     FILE *input = fopen(argv[3], "r");
53     if(!input) {
54         perror("input file");
55         return EXIT_FAILURE;
56     }
57
58     bool valid = file_validate(input);
59     fclose(input);
60
61     if(!valid) {
62         fclose(output);
63
64         fprintf(stderr, "invalid input file: %s\n", argv[3]);
65         return EXIT_FAILURE;
66     }
67
68 // Shared Memory
69 struct shared_memory *sm = shared_mem_create(m);
70
71 pid_t lifts[TOTAL_LIFTS];
72 pid_t scheduler;
73 int total_children = 0;
74
75 // TODO: Add error checking to fork()
76 for(int i = 0; i < TOTAL_LIFTS; i++) {
77     if((lifts[i] = fork()) == 0) {
78         // Child
79         // Each child will immediately exit main by returning
80         total_children++;
81         return lift_main(i + 1, lift_time, output);
82     } else if(lifts[i] < 0) {
83         // Signal to end all processes that might have started

```

```

84     sem_wait(&sm->semaphore.mutex);
85     sm->empty = true;
86     sm->finished = true;
87     sem_post(&sm->semaphore.mutex);
88
89     // Wait to prevent zombies
90     for(int j = 0; j < total_children; j++) {
91         waitpid(lifts[j], NULL, 0);
92     }
93
94     perror("fork");
95     // Clean up
96     fclose(output);
97     shared_memory_destroy(sm, m);
98     return EXIT_FAILURE;
99 }
100 }
101
102 // Create scheduler
103 if((scheduler = fork()) == 0) {
104     // Child
105     return scheduler_main(argv[3], output);
106 } else if(scheduler < 0) {
107     sem_wait(&sm->semaphore.mutex);
108     sm->empty = true;
109     sm->finished = true;
110     sem_post(&sm->semaphore.mutex);
111 }
112
113 // Parent
114 for(int i = 0; i < TOTAL_LIFTS; i++) {
115     waitpid(lifts[i], NULL, 0);
116 }
117
118 // If the scheduler fork worked
119 if(scheduler > 0) {
120     waitpid(scheduler, NULL, 0);
121
122     fprintf(output, "Total Number of Requests: %d\n"
123             "Total Number of Movements: %d\n",
124             sm->total_requests, sm->lift_movements[0]
125                         + sm->lift_movements[1]
126                         + sm->lift_movements[2]);
127
128 }
129
130 fclose(output);

```

```

131     shared_memory_destroy(sm, m);
132
133     return 0;
134 }
```

A.4 Threads

A.4.1 lift

```

1 #ifndef LIFT_H
2 #define LIFT_H
3
4 #include "queue.h"
5 #include "log.h"
6
7 struct lift {
8     int id;
9     int lift_time;
10    int total_movements;
11    struct queue *queue;
12    struct log *logger;
13 };
14
15 struct lift* lift_init(struct queue *queue, int lift_time, struct log
16    ↵ *logger, int id);
17 void lift_free(struct lift *l);
18 void *lift(void *ptr);
#endif
```

```

1 /**
2  * @file lift.c
3  * @author Anurag Singh (18944183)
4  *
5  * @date 09-05-20
6  *
7  * Handles lift struct and the lift
8  * function itself
9  *
10 */
11
12 #include <stdio.h>
13 #include <pthread.h>
14 #include <unistd.h>
15 #include <stdlib.h>
16
17 #include <common/request.h>
```

```

18
19 #include "lift.h"
20 #include "queue.h"
21 #include "log.h"
22
23 /**
24 * Creates a lift struct with
25 * fields initialised to import params
26 *
27 * @param queue
28 * @param lift_time
29 * @param logger
30 * @param id
31 * @return struct lift*
32 */
33 struct lift* lift_init(struct queue *queue, int lift_time, struct log
34 ↵ *logger, int id)
35 {
36     struct lift *l = malloc(sizeof(struct lift));
37     l->total_movements = 0;
38     l->logger = logger;
39     l->queue = queue;
40     l->lift_time = lift_time;
41     l->id = id;
42
43     return l;
44 }
45
46 /**
47 * Frees lift struct pointed to by l
48 *
49 * @param l lift struct to be free'd
50 */
51 void lift_free(struct lift *l)
52 {
53     free(l);
54 }
55
56 /**
57 * Lift function passed to pthread_create
58 * Handles all mutual exclusion and simulates
59 * work by sleeping
60 *
61 * @param ptr points to the lift struct
62 * @return void*
63 */
64 void* lift(void *ptr)

```

```

64  {
65      struct lift *l = (struct lift*)ptr;
66      // Each lift starts at the first floor
67      int current_floor = 1;
68      int previous_floor = 1;
69      int request_no = 0;
70
71      while(1) {
72          pthread_mutex_lock(&l->queue->mutex);
73
74          if(l->queue->empty && l->queue->finished) {
75              // let everyone know that the queue is empty
76              pthread_cond_broadcast(&l->queue->cond_empty);
77              pthread_mutex_unlock(&l->queue->mutex);
78              break;
79          }
80
81          while(l->queue->empty && !l->queue->finished) {
82              pthread_cond_wait(&l->queue->cond_empty, &l->queue->mutex);
83          }
84
85          if(!l->queue->empty) {
86              request_t *r = queue_remove(l->queue);
87              // need to let scheduler thread know that there's space now in
88              // the queue
89              pthread_cond_signal(&l->queue->cond_full);
90              pthread_mutex_unlock(&l->queue->mutex);
91
92              request_no++;
93              previous_floor = current_floor;
94              current_floor = r->dest;
95              int r_movement = abs(previous_floor - r->src) + abs(r->src -
96              // current_floor);
97              l->total_movements += r_movement;
98
99              log_printf(l->logger, "Lift-%d Operation\n"
100                         "Previous Floor: %d\n"
101                         "Request: Floor %d to %d\n"
102                         "Details: \n"
103                         "\tGo from Floor %d to %d\n"
104                         "\tGo from Floor %d to %d\n"
105                         "\t# Movements: %d\n"
106                         "\tRequest No: %d\n"
107                         "\tTotal # Movement: %d\n"
108                         "Current Position: Floor %d\n",
109                         l->id, previous_floor, r->src, r->dest,

```

```

108                     previous_floor, r->src, r->src,
109                     ↵ current_floor,
110                     r_movement, request_no, l->total_movements,
111                     current_floor);
112
113             sleep(l->lift_time);
114             free(r);
115             // Simulate work by putting the thread to sleep
116         } else {
117             pthread_mutex_unlock(&l->queue->mutex);
118         }
119
120     return NULL;
121 }
```

A.4.2 log

```

1 #ifndef LOG_H
2 #define LOG_H
3 #include <stdio.h>
4 #include <pthread.h>
5
6 struct log {
7     pthread_mutex_t mutex;
8     FILE *fp;
9 };
10
11 struct log* log_init(FILE *fp);
12 void log_free(struct log *l);
13 void log_printf(struct log *l, const char *s, ...);
14
15 #endif
```

```

1 /**
2 * @file log.c
3 * @author Anurag Singh (18944183)
4 *
5 * @date 09-05-20
6 *
7 * Handles log struct creation
8 * and mutual exclusion for logging
9 * to file
10 *
11 */
```

```

13 #include <stdio.h>
14 #include <stdlib.h>
15 #include <stdarg.h>
16
17 #include "log.h"
18
19 /**
20 * Creates a log struct with
21 * file pointer fp, initialises
22 * the mutex used to protect FILE io
23 *
24 * @param fp
25 * @return struct log*
26 */
27 struct log* log_init(FILE *fp)
28 {
29     struct log *l = malloc(sizeof(struct log));
30
31     l->fp = fp;
32     pthread_mutex_init(&l->mutex, NULL);
33
34     return l;
35 }
36
37 /**
38 * Frees the log struct, and destroys the mutex
39 *
40 * @param l log struct to be freed
41 */
42 void log_free(struct log *l)
43 {
44     // File will be closed by whoever opened it
45     // eg. the main thread in this case
46     pthread_mutex_destroy(&l->mutex);
47     free(l);
48 }
49
50 /**
51 * printf like function that allows printing
52 * to the FILE in the log struct, while utilising
53 * the mutex to protect it
54 *
55 * @param l
56 * @param s
57 * @param ...
58 */
59 void log_printf(struct log *l, const char *s, ...)

```

```

60  {
61      va_list args;
62      va_start(args, s);
63
64      pthread_mutex_lock(&l->mutex);
65      vfprintf(l->fp, s, args);
66      pthread_mutex_unlock(&l->mutex);
67
68      va_end(args);
69  }

```

A.4.3 queue

```

1  #ifndef QUEUE_H
2  #define QUEUE_H
3  #include <stdbool.h>
4  #include <pthread.h>
5
6  #include <common/request.h>
7
8  struct node {
9      struct node *next;
10     request_t *data;
11 };
12
13 /// Queue backed by a List
14 struct queue {
15     pthread_mutex_t mutex;
16     pthread_cond_t cond_empty;
17     pthread_cond_t cond_full;
18
19     struct node *head;
20     struct node *tail;
21
22     bool full;
23     bool empty;
24
25     bool finished;
26
27     int max;
28     int count;
29 };
30
31 struct queue* queue_init(int m);
32 void queue_add(struct queue *queue, request_t *node);
33 request_t* queue_remove(struct queue *queue);

```

```

34 void queue_free(struct queue *queue);
35
36 #endif

```

```

1 /**
2  * @file queue.c
3  * @author Anurag Singh (18944183)
4  *
5  * @date 09-05-20
6  *
7  * Queue implementation, backed by a list
8  *
9 */
10
11 #include <stdlib.h>
12
13 #include <common/request.h>
14 #include "queue.h"
15
16 /**
17  * Initialises a queue struct with
18  * a maximum size of m
19  *
20  * @param m max size
21  * @return struct queue*
22 */
23 struct queue* queue_init(int m)
24 {
25     struct queue *queue = malloc(sizeof(struct queue));
26     queue->max = m;
27     queue->count = 0;
28     queue->head = NULL;
29     queue->tail = NULL;
30     queue->empty = true;
31     queue->full = false;
32     queue->finished = false;
33
34     pthread_mutex_init(&queue->mutex, NULL);
35     pthread_cond_init(&queue->cond_empty, NULL);
36     pthread_cond_init(&queue->cond_full, NULL);
37
38     return queue;
39 }
40
41 /**
42  * Creates a node containing the data
43 */

```

```

44 * @param data data to put in the node
45 * @return struct node*
46 */
47 static struct node* node_init(request_t *data)
48 {
49     struct node *node = malloc(sizeof(struct node));
50     node->next = NULL;
51     node->data = data;
52
53     return node;
54 }
55
56 /**
57 * Adds to the end of the list
58 * to allow FIFO behaviour
59 *
60 * @param queue queue to add to
61 * @param ptr data to add
62 */
63 void queue_add(struct queue *queue, request_t *ptr)
64 {
65     if(queue->count == queue->max) {
66         return;
67     }
68
69     struct node *node = node_init(ptr);
70
71     if(queue->tail == NULL) {
72         queue->head = node;
73         queue->tail = node;
74     } else {
75         queue->tail->next = node;
76         queue->tail = node;
77     }
78
79     queue->count++;
80     if(queue->count == queue->max) {
81         queue->full = true;
82     }
83
84     queue->empty = false;
85 }
86
87 /**
88 * Removes from the front of the queue
89 *
90 * @param queue

```

```

91     * @return request_t*
92     */
93 request_t* queue_remove(struct queue *queue)
94 {
95     struct node *node = queue->head;
96
97     if(!node) {
98         return NULL;
99     }
100
101    void *data = queue->head->data;
102
103    if(queue->head && queue->head->next) {
104        queue->head = queue->head->next;
105    } else if(!queue->head->next) {
106        queue->head = NULL;
107        queue->tail = NULL;
108        queue->empty = true;
109    }
110
111    queue->full = false;
112    queue->count--;
113    free(node);
114
115    return data;
116}
117
118 /**
119 * Frees a node
120 *
121 * @param node
122 */
123 static void node_free(struct node *node)
124 {
125     free(node->data);
126     free(node);
127 }
128
129 /**
130 * Frees the entire queue including
131 * the struct and any mutexes
132 *
133 * @param queue
134 */
135 void queue_free(struct queue *queue)
136 {
137     struct node *current = queue->head;

```

```

138
139     while(current) {
140         struct node *next = current->next;
141
142         node_free(current);
143
144         current = next;
145     }
146
147     pthread_mutex_destroy(&queue->mutex);
148     pthread_cond_destroy(&queue->cond_empty);
149     pthread_cond_destroy(&queue->cond_full);
150     free(queue);
151 }
```

A.4.4 scheduler

```

1 #ifndef SCHEDULER_H
2 #define SCHEDULER_H
3
4 #include <stdio.h>
5 #include <pthread.h>
6
7 #include "queue.h"
8 #include "log.h"
9
10 struct scheduler {
11     int total_requests;
12     FILE *input;
13     struct queue *queue;
14     struct log *logger;
15 };
16
17 struct scheduler* scheduler_init(FILE *input, struct queue *queue, struct log
18 → *logger);
19 void scheduler_free(struct scheduler *s);
20 void* scheduler(void *ptr);
21
#endif
```

```

1 /**
2 * @file scheduler.c
3 * @author Anurag Singh (18944183)
4 *
5 * @date 09-05-20
6 *
```

```

7  * Handles all scheduler based actions
8  * including allocating the structure
9  * and the function passed to pthread_create
10 *
11 */
12
13 #include <stdlib.h>
14 #include <string.h>
15 #include <pthread.h>
16
17 #include <common/file_io.h>
18 #include <common/request.h>
19
20 #include "scheduler.h"
21
22 /**
23 * Create a scheduler struct, initialising struct
24 * fields to imported variables
25 *
26 * @param input
27 * @param queue
28 * @param logger
29 * @return struct scheduler*
30 */
31 struct scheduler* scheduler_init(FILE *input, struct queue *queue, struct log
32 → *logger)
33 {
34     struct scheduler *s = malloc(sizeof(struct scheduler));
35     s->total_requests = 0;
36     s->input = input;
37     s->logger = logger;
38     s->queue = queue;
39
40     return s;
41 }
42 /**
43 * Frees a scheduler struct
44 *
45 * @param s
46 */
47 void scheduler_free(struct scheduler *s)
48 {
49     free(s);
50 }
51 /**
52 */

```

```

53 * Function passed to pthread_create
54 * in order to create a scheduler struct
55 * Contains all mutual exclusion required
56 *
57 * @param ptr scheduler struct
58 * @return void*
59 */
60 void* scheduler(void *ptr)
61 {
62     struct scheduler *s = (struct scheduler *)ptr;
63     bool finished = false;
64
65     while(!finished) {
66         pthread_mutex_lock(&s->queue->mutex);
67
68         while(s->queue->full) {
69             // if queue at max capacity, wait for someone to dequeue
70             pthread_cond_wait(&s->queue->cond_full, &s->queue->mutex);
71         }
72
73         request_t *r = file_read_line(s->input);
74         if(r) {
75             queue_add(s->queue, r);
76             s->total_requests++;
77             log_printf(s->logger, "-----\n"
78                         "New Lift Request from %d to %d\n"
79                         "Request No: %d\n"
80                         "-----\n\n",
81                         r->src, r->dest, s->total_requests);
82             pthread_cond_signal(&s->queue->cond_empty);
83         } else {
84             // let everyone know we got nothing to put in
85             // for anyone waiting for something to be added
86             pthread_cond_broadcast(&s->queue->cond_empty);
87             s->queue->finished = true;
88             finished = true;
89         }
90
91         pthread_mutex_unlock(&s->queue->mutex);
92     }
93
94     return NULL;
}

```

A.4.5 lift_sim_A

```
1  /**
2  * @file lift_sim_A.c
3  * @author Anurag Singh (18944183)
4  *
5  * @date 09-05-20
6  *
7  * The main of the threads part, handles
8  * logging, queue and creation and
9  * destruction of threads.
10 *
11 */
12
13 #include <stdio.h>
14 #include <stdlib.h>
15
16 #include <common/request.h>
17 #include <common/file_io.h>
18 #include <common/common.h>
19
20 #include "queue.h"
21 #include "scheduler.h"
22 #include "lift.h"
23 #include "log.h"
24
25 int main(int argc, const char *argv[])
26 {
27     if(argc < 4) {
28         fprintf(stderr, "usage: %s [buffer size] [time] [filename]\n",
29                 argv[0]);
30         return EXIT_FAILURE;
31     }
32
33     int m = atoi(argv[1]);
34     int lift_time = atoi(argv[2]);
35
36     if(m <= 0 && lift_time < 0) {
37         fprintf(stderr, "buffer size > 0, time >= 0\n");
38         return EXIT_FAILURE;
39     }
40
41     FILE *input = fopen(argv[3], "r");
42     if(!input) {
43         perror("input file");
44         return EXIT_FAILURE;
45     }
```

```

45
46     FILE *output = fopen(OUTPUT_FILENAME, "w");
47     if(!output) {
48         fclose(input);
49         perror("output file");
50         return EXIT_FAILURE;
51     }
52
53     bool valid = file_validate(input);
54     if(!valid) {
55         fclose(input);
56         fclose(output);
57
58         fprintf(stderr, "invalid input file: %s\n", argv[3]);
59         return EXIT_FAILURE;
60     }
61
62     pthread_t threads[TOTAL_THREADS];
63     struct lift *lifts[TOTAL_LIFTS];
64
65     struct queue *queue = queue_init(m);
66     struct log *logger = log_init(output);
67
68     // thread 0 is task scheduler
69     // thread 1 - TOTAL_THREADS are lift threads
70     for(int i = 0; i < TOTAL_LIFTS; i++) {
71         lifts[i] = lift_init(queue, lift_time, logger, i + 1);
72         pthread_create(&threads[i + 1], NULL, lift, lifts[i]);
73     }
74
75     struct scheduler *s = scheduler_init(input, queue, logger);
76     pthread_create(&threads[0], NULL, scheduler, s);
77
78     // Clean up
79     // join all threads
80     for(int i = 0; i < TOTAL_THREADS; i++) {
81         pthread_join(threads[i], NULL);
82     }
83
84     // Log the final stuff once the threads are dead
85     log_printf(logger, "Total Number of Requests: %d\n"
86                 "Total Number of Movements: %d\n",
87                 s->total_requests, lifts[0]->total_movements
88                             + lifts[1]->total_movements
89                             + lifts[2]->total_movements);
90
91     for(int i = 0; i < TOTAL_LIFTS; i++) {

```

```
92     lift_free(lifts[i]);
93 }
94
95 fclose(input);
96 fclose(output);
97
98 log_free(logger);
99 queue_free(queue);
100 scheduler_free(s);
101
102 return EXIT_SUCCESS;
103 }
```