Nonlinear Vibration ODE

$$mu'' + b|u'|u' + s(u) = F(t) \tag{1}$$

where both m and b are positive constants. s(u) is possibly a nonlinear function of u, and F(t) is a given function.

(a) System of two first order ODEs

We introduce v = u':

$$v' = \frac{1}{m} \left(F(t) - bv|v| - s(u) \right)$$

$$u' = v$$
(2)

We discretize the system with Crank-Nicolson and use arithmetic mean on linear terms and a geometric mean on the quadratic term:

$$\frac{v^{n+1} - v^n}{\Delta t} = \left[\frac{1}{m} (F^n - b|v|v - s(u)) \right]^{n+\frac{1}{2}}
= \frac{1}{m} (F^{n+\frac{1}{2}} - b|v^{n+\frac{1}{2}}|v^{n+\frac{1}{2}} - s(u)^{n+\frac{1}{2}})
\approx \frac{1}{m} \left(\frac{1}{2} (F^{n+1} + F^n) - b|v^{n+\frac{1}{2}}|v^{n+\frac{1}{2}} - \frac{1}{2} (s(u^{n+1}) + s(u^n)) \right)
\approx \frac{1}{m} \left(\frac{1}{2} (F^{n+1} + F^n) - bv^{n+1}|v^n| - \frac{1}{2} (s(u^{n+1}) + s(u^n)) \right)$$
(3)

$$\frac{u^{n+1} - u^n}{\Delta t} = \frac{1}{2}(v^{n+1} + v^n) \tag{4}$$

(b) Picard Iteration

We start by denoting $v^n = v_1$, $u^n = u_1$, $u^{n+1} = u$, $v^{n+1} = v$ and the unknown in the nonlinear terms u^- . We insert this into (3) and (4) and solv with respect to the unknowns v and u

$$v = v_1 + \frac{\Delta t}{m} \left(\frac{1}{2} (F^{n+1} + F^n) - bv |v_1| - \frac{1}{2} (s(u_1) + s(u^-)) \right)$$

$$= v_1 + \left(\frac{\Delta t}{2m} \right) \frac{F^{n+1} + F^n - s(u_1) - s(u^-)}{1 + \frac{dt}{m} b |v_1|}$$
(5)

$$u = u_1 + \frac{\Delta t}{2}(v + v_1) \tag{6}$$

We start our iteration by guessing that $v^- = v_1$ and $u^- = u_1$. We solve the equations for v and u. We then set $v^- = v$ and $u^- = u$, and solve for v and u. The iteration continues until the desired precision or max number of iterations is reached.

Newtons Method

We denote our unknown values v^{n+1} and u^{n+1} as v and u. The values at the previous timestep is written as v_1 and u_1 .

$$G_1(v,u) = v - v_1 - \frac{dt}{m} \left(\frac{1}{2} (F^{n+1} + F^n) - \frac{1}{2} (s(u) + s(u_1)) - v|v_1| \right) = 0$$
 (7)

$$G_2(v,u) = u - u^1 - \frac{dt}{2}(v+v_1) = 0$$
 (8)

We denote $\mathbf{G}(\mathbf{u}) = \begin{pmatrix} G_1(v,u) \\ G_2(v,u) \end{pmatrix}$. We linearize \mathbf{G} by a Taylor expansion around a known value \mathbf{u}^-

$$\hat{\mathbf{G}}(\mathbf{u}) = \mathbf{G}(\mathbf{u}^{-}) + J(\mathbf{u}^{-})(\mathbf{u} - \mathbf{u}^{-}) = \mathbf{G}(\mathbf{u}^{-}) + J(\mathbf{u}^{-})\delta\mathbf{u} = 0$$
(9)

Where the Jacobian, J, is a 2×2 matrix with entries:

$$J_{i,j} = \frac{\partial G_i}{\partial x_i} \tag{10}$$

where $x_1 = v$ and $x_2 = u$.

$$J_{1,1} = \frac{\partial G_1}{\partial v} = 1 - \frac{dt}{m}v^1$$

$$J_{1,2} = \frac{\partial G_1}{\partial u} = \frac{dt}{2m}s'(u)$$

$$J_{2,1} = \frac{\partial G_2}{\partial v} = -\frac{dt}{2}$$

$$J_{2,2} = \frac{\partial G_2}{\partial u} = 1$$

$$(11)$$

We can now make an initial guess for \mathbf{u}^- and iterate until we reach desired precision:

solve
$$J\delta \mathbf{u} = -\mathbf{G}(\mathbf{u}^{-})$$
 wrt $\delta \mathbf{u}$

 $\mathbf{update} \ \ \mathbf{u} = \mathbf{u}^- + \delta \mathbf{u}$

 $new \; guess \; u^- \leftarrow u$

check precision How close is $\mathbf{G}(\mathbf{u})$ to 0 or how large is $\delta \mathbf{u}$