GDSiMS: Gene Drive Simulator of Mosquito Spread

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Namespace Index

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---------------	------

Here is a list of all namespaces with brief descriptions:	
constants	

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Hierarchical Index

2.1 Class Hierarchy

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Class Index

3.1 Class List

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Namespace Documentation

5.1 constants Namespace Reference

Variables

```
• const int max_dev = 20
```

• const int num_gen = 6

5.1.1 Variable Documentation

5.1.1.1 max_dev

const int constants::max_dev = 20

5.1.1.2 num_gen

const int constants::num_gen = 6

Class Documentation

6.1 Aestivation Class Reference

#include <Aestivation.h>

Collaboration diagram for Aestivation:

Aestivation - psi - mu_aes - t_hide1 - t_hide2 - t_wake1 - t_wake2 - aes_F + Aestivation() + hide() + wake() + is_hide_time() + is_wake_time()

Public Member Functions

- Aestivation (AestivationParams *params, int sites_size)
- void hide (std::vector< Patch * > &sites)
- void wake (int day, std::vector< Patch * > &sites)
- bool is_hide_time (int day)
- bool is_wake_time (int day)

Private Attributes

- double psi
- double mu_aes
- int t_hide1
- int t_hide2
- int t_wake1
- int t_wake2
- std::vector< std::array< std::array< long long int, num_gen >, num_gen > > aes_F

6.1.1 Constructor & Destructor Documentation

6.1.1.1 Aestivation()

6.1.2 Member Function Documentation

6.1.2.1 hide()

```
void Aestivation::hide ( {\tt std::vector} < {\tt Patch} \ * \ > \& \ sites \ )
```

Here is the call graph for this function:



Here is the caller graph for this function:



6.1.2.2 is_hide_time()

Here is the caller graph for this function:



6.1.2.3 is_wake_time()

Here is the caller graph for this function:



6.1.2.4 wake()

Here is the call graph for this function:



Here is the caller graph for this function:



6.1.3 Member Data Documentation

6.1.3.1 aes_F

```
std::vector < std::array < std::array < long int, \\ num_gen>, \\ num_gen>> \\ Aestivation::aes\_ \leftarrow \\ F \ [private]
```

6.1.3.2 mu_aes

```
double Aestivation::mu_aes [private]
```

6.1.3.3 psi

```
double Aestivation::psi [private]
```

6.1.3.4 t_hide1

```
int Aestivation::t_hide1 [private]
```

6.1.3.5 t_hide2

```
int Aestivation::t_hide2 [private]
```

6.1.3.6 t_wake1

```
int Aestivation::t_wake1 [private]
```

6.1.3.7 t_wake2

```
int Aestivation::t_wake2 [private]
```

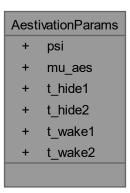
The documentation for this class was generated from the following files:

- · Aestivation.h
- · Aestivation.cpp

6.2 AestivationParams Struct Reference

```
#include <Params.h>
```

Collaboration diagram for AestivationParams:



Public Attributes

```
• double psi = 0.0
```

• double mu_aes = 0.0

• int t_hide1 = 0

• int t_hide2 = 0

• int t_wake1 = 0

• int t_wake2 = 0

6.2.1 Member Data Documentation

6.2.1.1 mu_aes

double AestivationParams::mu_aes = 0.0

6.2.1.2 psi

double AestivationParams::psi = 0.0

6.2.1.3 t_hide1

int AestivationParams::t_hide1 = 0

6.2.1.4 t_hide2

```
int AestivationParams::t_hide2 = 0
```

6.2.1.5 t_wake1

```
int AestivationParams::t_wake1 = 0
```

6.2.1.6 t_wake2

```
int AestivationParams::t_wake2 = 0
```

The documentation for this struct was generated from the following file:

· Params.h

6.3 AreaParams Struct Reference

```
#include <Params.h>
```

Collaboration diagram for AreaParams:



Public Attributes

- int num_pat = 50
- double side = 1.0

6.3.1 Member Data Documentation

6.3.1.1 num_pat

```
int AreaParams::num_pat = 50
```

6.3.1.2 side

double AreaParams::side = 1.0

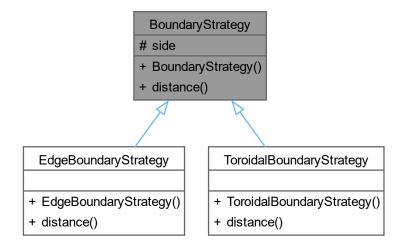
The documentation for this struct was generated from the following file:

· Params.h

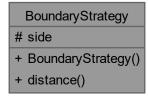
6.4 BoundaryStrategy Class Reference

#include <BoundaryStrategy.h>

Inheritance diagram for BoundaryStrategy:



Collaboration diagram for BoundaryStrategy:



Public Member Functions

- BoundaryStrategy (double side)
- virtual double distance (const Point &p1, const Point &p2)=0

Protected Attributes

· double side

6.4.1 Constructor & Destructor Documentation

6.4.1.1 BoundaryStrategy()

6.4.2 Member Function Documentation

6.4.2.1 distance()

```
virtual double BoundaryStrategy::distance ( const Point & p1, const Point & p2 ) [pure virtual]
```

Implemented in ToroidalBoundaryStrategy, and EdgeBoundaryStrategy.

Here is the caller graph for this function:



6.4.3 Member Data Documentation

6.4.3.1 side

```
double BoundaryStrategy::side [protected]
```

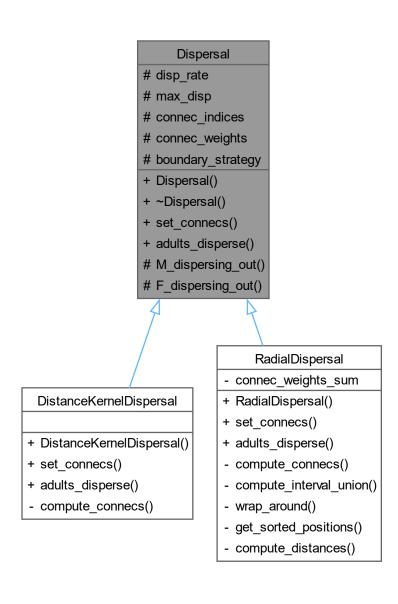
The documentation for this class was generated from the following file:

· BoundaryStrategy.h

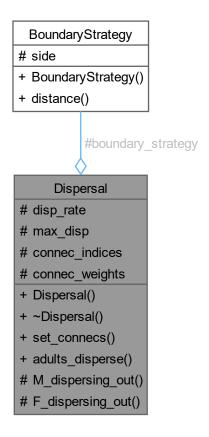
6.5 Dispersal Class Reference

#include <Dispersal.h>

Inheritance diagram for Dispersal:



Collaboration diagram for Dispersal:



Public Member Functions

- Dispersal (DispersalParams *params, BoundaryType boundary, double side)
- ∼Dispersal ()
- virtual void set_connecs (std::vector< Patch * > &sites)=0
- virtual void adults_disperse (std::vector< Patch * > &sites)=0

Protected Member Functions

- $\bullet \ \, \text{std::vector} < \text{std::array} < \text{long long int, } \ \, \text{num_gen} > > \text{M_dispersing_out} \ \, \text{(const std::vector} < \text{Patch} \ \, * > \& \text{sites)}$

Protected Attributes

- · double disp_rate
- double max_disp
- std::vector< std::vector< int > > connec_indices
- std::vector< std::vector< double >> connec_weights
- BoundaryStrategy * boundary_strategy

6.5.1 Constructor & Destructor Documentation

6.5.1.1 Dispersal()

6.5.1.2 \sim Dispersal()

```
Dispersal::~Dispersal ( )
```

6.5.2 Member Function Documentation

6.5.2.1 adults_disperse()

Implemented in DistanceKernelDispersal, and RadialDispersal.

Here is the caller graph for this function:



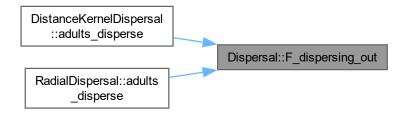
6.5.2.2 F_dispersing_out()

```
\label{long_const_std::rector} $$ std::array< std::array< long_long_int, num_gen >, num_gen >> Dispersal::F_{\leftarrow} $$ dispersing_out ( $$ const_std::vector< Patch *> & sites ) [protected]
```

Here is the call graph for this function:



Here is the caller graph for this function:



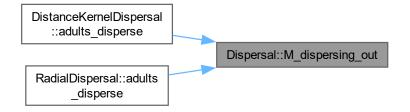
6.5.2.3 M_dispersing_out()

```
\label{long_const_std} $$ std::vector< std::array< long_long_int, num_gen >> Dispersal::M_dispersing_out ( const_std::vector< Patch *> & sites ) [protected]
```

Here is the call graph for this function:



Here is the caller graph for this function:



6.5.2.4 set_connecs()

```
virtual void Dispersal::set_connecs ( std::vector < \ Patch \ * > \& \ sites \ ) \quad [pure \ virtual]
```

Implemented in DistanceKernelDispersal, and RadialDispersal.

Here is the caller graph for this function:



6.5.3 Member Data Documentation

6.5.3.1 boundary_strategy

```
BoundaryStrategy* Dispersal::boundary_strategy [protected]
```

6.5.3.2 connec_indices

```
std::vector<std::vector<int> > Dispersal::connec_indices [protected]
```

6.5.3.3 connec_weights

```
std::vector<std::vector<double> > Dispersal::connec_weights [protected]
```

6.5.3.4 disp_rate

```
double Dispersal::disp_rate [protected]
```

6.5.3.5 max_disp

```
double Dispersal::max_disp [protected]
```

The documentation for this class was generated from the following files:

- Dispersal.h
- Dispersal.cpp

6.6 DispersalParams Struct Reference

#include <Params.h>

Collaboration diagram for DispersalParams:

DispersalParams
+ disp_rate
+ max_disp

Public Attributes

- double disp_rate = 0.01
- double max_disp = 0.2

6.6.1 Member Data Documentation

6.6.1.1 disp_rate

double DispersalParams::disp_rate = 0.01

6.6.1.2 max_disp

double DispersalParams::max_disp = 0.2

The documentation for this struct was generated from the following file:

· Params.h

6.7 DistanceKernelDispersal Class Reference

#include <Dispersal.h>

Inheritance diagram for DistanceKernelDispersal:

Dispersal

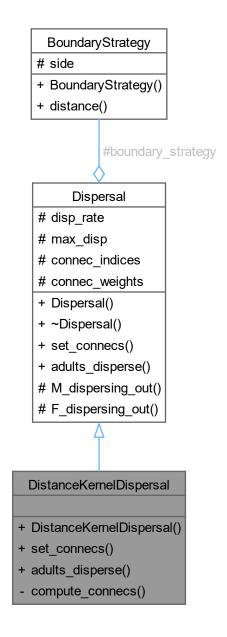
- # disp_rate
- # max_disp
- # connec_indices
- # connec_weights
- # boundary_strategy
- + Dispersal()
- + ~Dispersal()
- + set_connecs()
- + adults_disperse()
- # M_dispersing_out()
- # F_dispersing_out()

1

DistanceKernelDispersal

- + DistanceKernelDispersal()
- + set_connecs()
- + adults_disperse()
- compute_connecs()

Collaboration diagram for DistanceKernelDispersal:



Public Member Functions

- DistanceKernelDispersal (DispersalParams *params, BoundaryType boundary, double side)
- void set_connecs (std::vector< Patch * > &sites) override
- void adults_disperse (std::vector < Patch * > &sites) override

Public Member Functions inherited from Dispersal

- Dispersal (DispersalParams *params, BoundaryType boundary, double side)
- ∼Dispersal ()

Private Member Functions

 std::pair< std::vector< std::vector< double > > compute_connecs (std::vector< Patch * > &sites)

Additional Inherited Members

Protected Member Functions inherited from Dispersal

- std::vector< std::array< long long int, num_gen >> M_dispersing_out (const std::vector< Patch *> &sites)
- std::vector< std::array< std::array< long long int, num_gen >, num_gen > > F_dispersing_out (const std
 ::vector< Patch * > &sites)

Protected Attributes inherited from Dispersal

- · double disp_rate
- double max disp
- std::vector< std::vector< int > > connec_indices
- std::vector< std::vector< double >> connec weights
- BoundaryStrategy * boundary strategy

6.7.1 Constructor & Destructor Documentation

6.7.1.1 DistanceKernelDispersal()

6.7.2 Member Function Documentation

6.7.2.1 adults_disperse()

Implements Dispersal.



6.7.2.2 compute_connecs()

Here is the call graph for this function:



Here is the caller graph for this function:



6.7.2.3 set_connecs()

Implements Dispersal.

Here is the call graph for this function:



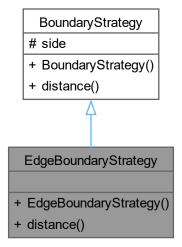
The documentation for this class was generated from the following files:

- · Dispersal.h
- Dispersal.cpp

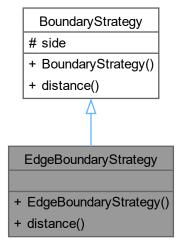
6.8 EdgeBoundaryStrategy Class Reference

#include <BoundaryStrategy.h>

Inheritance diagram for EdgeBoundaryStrategy:



Collaboration diagram for EdgeBoundaryStrategy:



Public Member Functions

- EdgeBoundaryStrategy (double side)
- double distance (const Point &p1, const Point &p2) override

Public Member Functions inherited from BoundaryStrategy

• BoundaryStrategy (double side)

Additional Inherited Members

Protected Attributes inherited from BoundaryStrategy

• double side

6.8.1 Constructor & Destructor Documentation

6.8.1.1 EdgeBoundaryStrategy()

```
\label{eq:deboundaryStrategy::EdgeBoundaryStrategy (} \\ \text{double } side \text{ ) [inline]}
```

6.8.2 Member Function Documentation

6.8.2.1 distance()

Implements BoundaryStrategy.

The documentation for this class was generated from the following files:

- · BoundaryStrategy.h
- · BoundaryStrategy.cpp

6.9 GDRelease Class Reference

```
#include <GDRelease.h>
```

Collaboration diagram for GDRelease:

GDRelease - driver_start - num_driver_M - num_driver_sites + GDRelease() + release_gene_drive() + is_release_time() - select_driver_sites() - put_driver_sites()

Public Member Functions

- GDRelease (ReleaseParams *params)
- void release_gene_drive (std::vector< Patch * > &sites)
- bool is_release_time (int day)

Private Member Functions

- std::vector< Patch * > select_driver_sites (int num_rel_sites, const std::vector< Patch * > &sites)
- void put_driver_sites (std::vector< Patch * > &rel_sites, std::vector< Patch * > &sites)

Private Attributes

- · int driver_start
- · int num driver M
- int num_driver_sites

6.9.1 Constructor & Destructor Documentation

6.9.1.1 GDRelease()

6.9.2 Member Function Documentation

6.9.2.1 is_release_time()

Here is the caller graph for this function:



6.9.2.2 put_driver_sites()



6.9.2.3 release_gene_drive()

```
void GDRelease::release_gene_drive (  std::vector < \ Patch \ * > \& \ sites \ )
```

Here is the call graph for this function:



Here is the caller graph for this function:



6.9.2.4 select_driver_sites()

Here is the call graph for this function:





6.9.3 Member Data Documentation

6.9.3.1 driver_start

```
int GDRelease::driver_start [private]
```

6.9.3.2 num_driver_M

```
int GDRelease::num_driver_M [private]
```

6.9.3.3 num_driver_sites

```
int GDRelease::num_driver_sites [private]
```

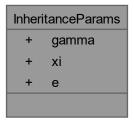
The documentation for this class was generated from the following files:

- · GDRelease.h
- GDRelease.cpp

6.10 InheritanceParams Struct Reference

```
#include <Params.h>
```

Collaboration diagram for InheritanceParams:



Public Attributes

- double gamma = 0.025
- double xi = 0.2
- double **e** = 0.95

6.10.1 Member Data Documentation

6.10.1.1 e

double InheritanceParams::e = 0.95

6.10.1.2 gamma

double InheritanceParams::gamma = 0.025

6.10.1.3 xi

double InheritanceParams::xi = 0.2

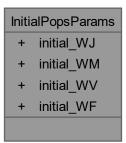
The documentation for this struct was generated from the following file:

· Params.h

6.11 InitialPopsParams Struct Reference

#include <Params.h>

Collaboration diagram for InitialPopsParams:



Public Attributes

- int initial_WJ = 10000
- int initial_WM = 50000
- int initial_WV = 10000
- int initial_WF = 40000

6.11.1 Member Data Documentation

6.11.1.1 initial_WF

int InitialPopsParams::initial_WF = 40000

6.11.1.2 initial_WJ

int InitialPopsParams::initial_WJ = 10000

6.11.1.3 initial_WM

int InitialPopsParams::initial_WM = 50000

6.11.1.4 initial_WV

int InitialPopsParams::initial_WV = 10000

The documentation for this struct was generated from the following file:

· Params.h

6.12 LifeParams Struct Reference

#include <Params.h>

Collaboration diagram for LifeParams:



Public Attributes

```
    double mu_j = 0.05
    double mu_a = 0.125
    double beta = 100.0
```

• double theta = 9.0

• double alpha0 = 100000.0

• double mean_dev = 15.0

• int min_dev = 10

6.12.1 Member Data Documentation

6.12.1.1 alpha0

```
double LifeParams::alpha0 = 100000.0
```

6.12.1.2 beta

```
double LifeParams::beta = 100.0
```

6.12.1.3 mean_dev

```
double LifeParams::mean_dev = 15.0
```

6.12.1.4 min_dev

```
int LifeParams::min_dev = 10
```

6.12.1.5 mu_a

```
double LifeParams::mu_a = 0.125
```

6.12.1.6 mu_j

```
double LifeParams::mu_j = 0.05
```

6.12.1.7 theta

```
double LifeParams::theta = 9.0
```

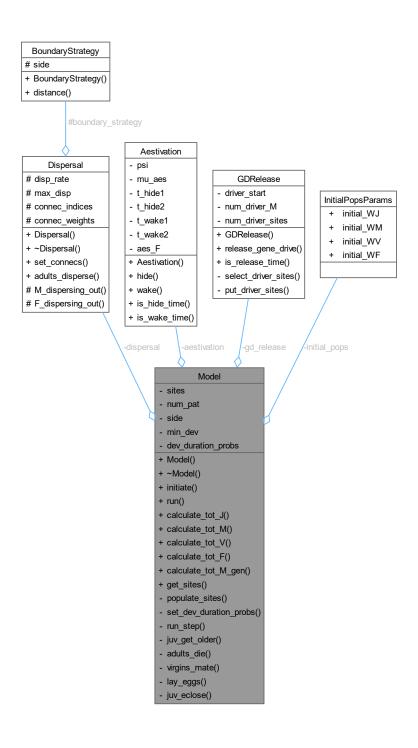
The documentation for this struct was generated from the following file:

· Params.h

6.13 Model Class Reference

#include <Model.h>

Collaboration diagram for Model:



Public Member Functions

 Model (AreaParams *area, InitialPopsParams *initial, LifeParams *life, AestivationParams *aes, DispersalParams *disp, ReleaseParams *rel, BoundaryType boundary=BoundaryType::Toroid, DispersalType disp_type=DispersalType::DistanceKernel, std::vector< Point > coords={})

- ∼Model ()
- · void initiate ()
- void run (int day, const std::array< std::array< double, num_gen >, num_gen >, num_gen >
 &inher fraction)
- long long int calculate_tot_J ()
- long long int calculate_tot_M ()
- long long int calculate_tot_V ()
- long long int calculate_tot_F ()
- std::array< long long int, num_gen > calculate_tot_M_gen ()
- std::vector< Patch * > get sites () const

Private Member Functions

- void populate sites ()
- void set_dev_duration_probs (int min_time, int max_time)
- void run_step (int day, const std::array< std::array< std::array< double, num_gen >, num_gen >, num_gen > &inher_fraction)
- void juv_get_older ()
- · void adults_die ()
- void virgins_mate ()
- void lay_eggs (const std::array< std::array< double, num_gen >, num_gen >, num_gen >, num_gen >
 &inher_fraction)
- void juv eclose ()

Private Attributes

- std::vector< Patch * > sites
- Dispersal * dispersal
- Aestivation * aestivation
- GDRelease * gd_release
- int num_pat
- double side
- InitialPopsParams * initial_pops
- int min_dev
- std::array< double, max_dev+1 > dev_duration_probs

6.13.1 Constructor & Destructor Documentation

6.13.1.1 Model()

6.13 Model Class Reference 39

6.13.1.2 ∼Model()

Model::~Model ()

6.13.2 Member Function Documentation

6.13.2.1 adults die()

```
void Model::adults_die ( ) [private]
```

Here is the caller graph for this function:



6.13.2.2 calculate_tot_F()

```
long long int Model::calculate_tot_F ( )
```

Here is the caller graph for this function:



6.13.2.3 calculate_tot_J()

```
long long int Model::calculate_tot_J ( )
```



6.13.2.4 calculate_tot_M()

```
long long int Model::calculate_tot_M ( )
```

Here is the caller graph for this function:



6.13.2.5 calculate_tot_M_gen()

```
\verb|std::array| < \verb|long| int, \verb|num_gen| > \verb|Model::calculate_tot_M_gen| ( )
```

Here is the caller graph for this function:



6.13.2.6 calculate_tot_V()

```
long long int Model::calculate_tot_V ( )
```

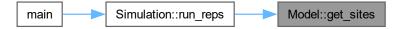


6.13 Model Class Reference 41

6.13.2.7 get_sites()

```
std::vector< Patch * > Model::get_sites ( ) const
```

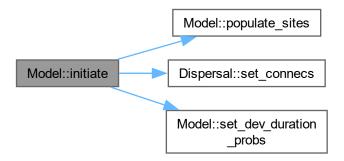
Here is the caller graph for this function:



6.13.2.8 initiate()

```
void Model::initiate ( )
```

Here is the call graph for this function:





6.13.2.9 juv_eclose()

```
void Model::juv_eclose ( ) [private]
```

Here is the caller graph for this function:



6.13.2.10 juv_get_older()

```
void Model::juv_get_older ( ) [private]
```

Here is the caller graph for this function:



6.13.2.11 lay_eggs()

Here is the caller graph for this function:



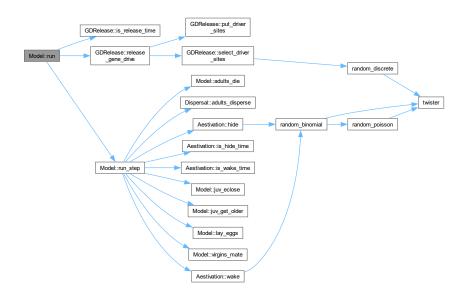
6.13.2.12 populate_sites()

```
void Model::populate_sites ( ) [private]
```



6.13.2.13 run()

Here is the call graph for this function:

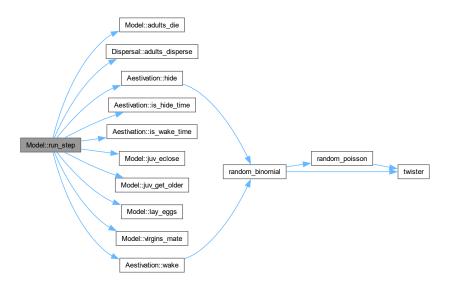


Here is the caller graph for this function:



6.13.2.14 run_step()

Here is the call graph for this function:



Here is the caller graph for this function:



6.13.2.15 set_dev_duration_probs()



6.13.2.16 virgins_mate()

```
void Model::virgins_mate ( ) [private]
```

Here is the caller graph for this function:



6.13.3 Member Data Documentation

6.13.3.1 aestivation

```
Aestivation* Model::aestivation [private]
```

6.13.3.2 dev_duration_probs

```
std::array<double, max_dev+1> Model::dev_duration_probs [private]
```

6.13.3.3 dispersal

```
Dispersal* Model::dispersal [private]
```

6.13.3.4 gd_release

```
GDRelease* Model::gd_release [private]
```

6.13.3.5 initial_pops

```
InitialPopsParams* Model::initial_pops [private]
```

6.13.3.6 min_dev

```
int Model::min_dev [private]
```

6.13.3.7 num_pat

```
int Model::num_pat [private]
```

6.13.3.8 side

```
double Model::side [private]
```

6.13.3.9 sites

```
std::vector<Patch*> Model::sites [private]
```

The documentation for this class was generated from the following files:

- Model.h
- Model.cpp

6.14 Patch Class Reference

#include <Patch.h>

Collaboration diagram for Patch:



Public Member Functions

- Patch (LifeParams *par, double side)
- Patch (LifeParams *par, Point point)
- void populate (int initial_WJ, int initial_WM, int initial_WV, int initial_WF)
- Point get_coords () const
- std::array< long long int, $num_gen>get_M$ () const

```
• std::array< std::array< long long int, num_gen >, num_gen > get_F () const
```

- long long int calculate_tot_J ()
- long long int calculate_tot_M ()
- long long int calculate_tot_V ()
- long long int calculate_tot_F ()
- void juv_get_older (int max_dev)
- void adults die ()
- · void virgins mate ()
- void lay_eggs (const std::array< std::array< double, num_gen >, num_gen >, num_gen > &f, const std::array< double, max_dev+1 > &dev_duration_probs)
- · void juv_eclose ()
- void update comp ()
- void update_mate ()
- void M_disperse_out (const std::array< long long int, num_gen > &m_out)
- void F_disperse_out (const std::array < std::array < long long int, num_gen >, num_gen > &f_out)
- void M_disperse_in (int gen, long long int m_in)
- void F_disperse_in (int f_gen, int m_gen, long long int f_disp)
- void F_hide (const std::array< std::array< long long int, num_gen >, num_gen > &f_try)
- void F_wake (const std::array< std::array< long long int, num_gen >, num_gen > &f_wake)
- void add_driver_M (int num_driver_M)

Private Attributes

- LifeParams * params
- · Point coords
- std::array< std::array< long long int, max_dev+1 >, num_gen > J
- std::array< long long int, num_gen > M
- std::array< long long int, num_gen > V
- std::array< std::array< long long int, num_gen >, num_gen > F
- · long double comp
- · long double mate rate

6.14.1 Constructor & Destructor Documentation

6.14.1.1 Patch() [1/2]

```
Patch::Patch (
LifeParams * par,
double side )
```



6.14 Patch Class Reference 49

6.14.1.2 Patch() [2/2]

Here is the call graph for this function:



6.14.2 Member Function Documentation

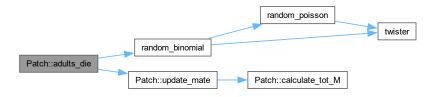
6.14.2.1 add_driver_M()

Here is the call graph for this function:



6.14.2.2 adults_die()

```
void Patch::adults_die ( )
```



6.14.2.3 calculate_tot_F()

```
long long int Patch::calculate_tot_F ( )
```

6.14.2.4 calculate_tot_J()

```
long long int Patch::calculate_tot_J ( )
```

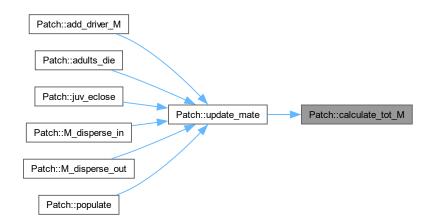
Here is the caller graph for this function:



6.14.2.5 calculate_tot_M()

```
long long int Patch::calculate_tot_M ( )
```

Here is the caller graph for this function:



6.14.2.6 calculate_tot_V()

long long int Patch::calculate_tot_V ()

6.14 Patch Class Reference 51

6.14.2.7 F_disperse_in()

6.14.2.8 F_disperse_out()

6.14.2.9 F_hide()

6.14.2.10 F_wake()

6.14.2.11 get_coords()

```
Point Patch::get_coords ( ) const
```

6.14.2.12 get_F()

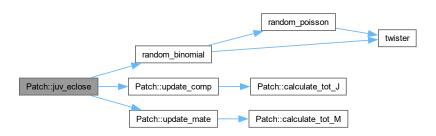
```
std::array< std::array< long long int, num_gen >, num_gen > Patch::get_F ( ) const
```

6.14.2.13 get_M()

```
std::array< long long int, num_gen > Patch::get_M ( ) const
```

6.14.2.14 juv_eclose()

```
void Patch::juv_eclose ( )
```



6.14.2.15 juv_get_older()

Here is the call graph for this function:



6.14.2.16 lay_eggs()

Here is the call graph for this function:



6.14.2.17 M_disperse_in()



6.14 Patch Class Reference 53

6.14.2.18 **M_disperse_out()**

```
void Patch::M_disperse_out ( const \ std::array < \ long \ long \ int, \ num\_gen > \& \ m\_out \ )
```

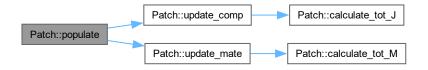
Here is the call graph for this function:



6.14.2.19 populate()

```
void Patch::populate (
    int initial_WJ,
    int initial_WM,
    int initial_WV,
    int initial_WF )
```

Here is the call graph for this function:

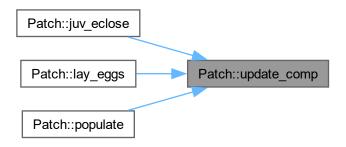


6.14.2.20 update_comp()

```
void Patch::update_comp ( )
```



Here is the caller graph for this function:



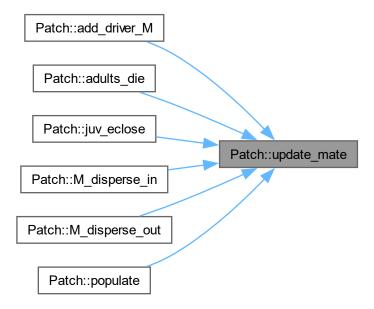
6.14.2.21 update_mate()

```
void Patch::update_mate ( )
```



6.14 Patch Class Reference 55

Here is the caller graph for this function:



6.14.2.22 virgins_mate()

```
void Patch::virgins_mate ( )
```

Here is the call graph for this function:



6.14.3 Member Data Documentation

6.14.3.1 comp

long double Patch::comp [private]

6.14.3.2 coords

Point Patch::coords [private]

6.14.3.3 F

```
std::array<std::array<long long int, num_gen>, num_gen> Patch::F [private]
```

6.14.3.4 J

```
std::array<std::array<long long int, max_dev+1>, num_gen> Patch::J [private]
```

6.14.3.5 M

```
std::array<long long int, num_gen> Patch::M [private]
```

6.14.3.6 mate_rate

```
long double Patch::mate_rate [private]
```

6.14.3.7 params

```
LifeParams* Patch::params [private]
```

6.14.3.8 V

```
std::array<long long int, num_gen> Patch::V [private]
```

The documentation for this class was generated from the following files:

- Patch.h
- · Patch.cpp

6.15 Point Struct Reference

#include <Point.h>

Collaboration diagram for Point:



Public Attributes

- double x = 0
- double y = 0

6.15.1 Member Data Documentation

6.15.1.1 x

```
double Point::x = 0
```

6.15.1.2 y

```
double Point::y = 0
```

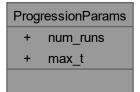
The documentation for this struct was generated from the following file:

• Point.h

6.16 ProgressionParams Struct Reference

```
#include <Params.h>
```

Collaboration diagram for ProgressionParams:



Public Attributes

- int num_runs = 1
- int $max_t = 1000$

6.16.1 Member Data Documentation

6.16.1.1 max_t

```
int ProgressionParams::max_t = 1000
```

6.16.1.2 num_runs

```
int ProgressionParams::num_runs = 1
```

The documentation for this struct was generated from the following file:

· Params.h

6.17 RadialDispersal Class Reference

```
#include <Dispersal.h>
```

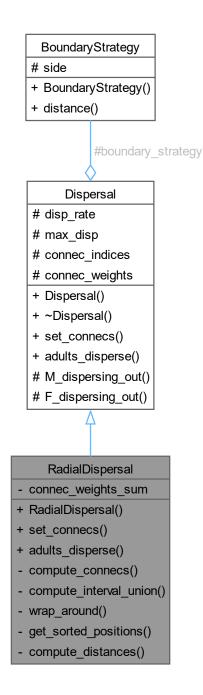
Inheritance diagram for RadialDispersal:

Dispersal # disp_rate # max_disp # connec_indices # connec_weights # boundary_strategy + Dispersal() + ~Dispersal() + set_connecs() + adults_disperse() # M_dispersing_out() # F_dispersing_out()

RadialDispersal

- connec_weights_sum
- + RadialDispersal()
- + set_connecs()
- + adults_disperse()
- compute_connecs()
- compute_interval_union()
- wrap_around()
- get_sorted_positions()
- compute_distances()

Collaboration diagram for RadialDispersal:



Public Member Functions

- RadialDispersal (DispersalParams *params, BoundaryType boundary, double side)
- void set_connecs (std::vector< Patch * > &sites) override
- void adults_disperse (std::vector < Patch * > &sites) override

Public Member Functions inherited from Dispersal

- Dispersal (DispersalParams *params, BoundaryType boundary, double side)
- ∼Dispersal ()

Private Member Functions

- std::pair< std::vector< std::vector< double >>> compute_connecs (std::vector< Patch *> &sites)
- std::pair< std::vector< std::pair< double, double > >, double > compute_interval_union (const std::pair< double, double, double > &qq, const std::vector< std::pair< double, double > > &input)
- double wrap_around (double value, double range)
- std::vector< int > get_sorted_positions (const std::vector< double > &numbers)
- std::vector< std::vector< double >> compute_distances (const std::vector< Patch *> &sites)

Private Attributes

• std::vector< double > connec_weights_sum

Additional Inherited Members

Protected Member Functions inherited from Dispersal

- std::vector< std::array< long long int, num_gen >> M_dispersing_out (const std::vector< Patch *> &sites)

Protected Attributes inherited from Dispersal

- double disp_rate
- double max_disp
- std::vector< std::vector< int > > connec_indices
- std::vector< std::vector< double >> connec_weights
- BoundaryStrategy * boundary_strategy

6.17.1 Constructor & Destructor Documentation

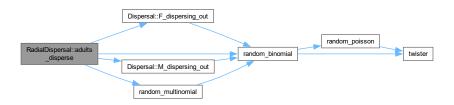
6.17.1.1 RadialDispersal()

6.17.2 Member Function Documentation

6.17.2.1 adults_disperse()

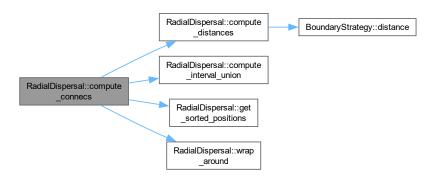
Implements Dispersal.

Here is the call graph for this function:



6.17.2.2 compute_connecs()

Here is the call graph for this function:





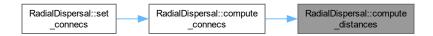
6.17.2.3 compute_distances()

```
\label{eq:std::vector} $$ std::vector< double >> RadialDispersal::compute_distances ( const std::vector< Patch *> & sites) [private] $$
```

Here is the call graph for this function:



Here is the caller graph for this function:



6.17.2.4 compute_interval_union()



6.17.2.5 get_sorted_positions()

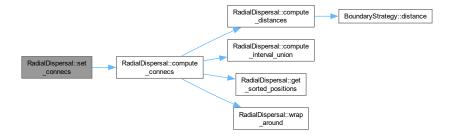
Here is the caller graph for this function:



6.17.2.6 set_connecs()

Implements Dispersal.

Here is the call graph for this function:



6.17.2.7 wrap_around()



6.17.3 Member Data Documentation

6.17.3.1 connec_weights_sum

```
std::vector<double> RadialDispersal::connec_weights_sum [private]
```

The documentation for this class was generated from the following files:

- Dispersal.h
- · Dispersal.cpp

6.18 Record Class Reference

#include <Record.h>

Collaboration diagram for Record:

Record - rec_start - rec_end - rec_interval_global - rec_interval_local - rec_sites_freq - set_label - rep_label - os1 - os2 - os3 - local_data - global_data - coord_list + Record() + ~Record() + record_coords() + record_global() + output_totals() + record_local() + is_rec_local_time() + is_rec_global_time()

Public Member Functions

- Record (RecordParams *rec params, int rep)
- ∼Record ()
- void record_coords (const std::vector< Patch * > &sites)
- void record_global (int day, const std::array< long long int, num_gen > &tot_M_gen)
- void output_totals (int day, long long int tot_J, long long int tot_M, long long int tot_V, long long int tot_F)
- void record_local (int day, const std::vector< Patch * > &sites)
- bool is rec local time (int day)
- bool is_rec_global_time (int day)

Private Attributes

- · int rec start
- int rec_end
- int rec_interval_global
- int rec_interval_local
- int rec_sites_freq
- int set_label
- int rep_label
- std::ostringstream os1
- std::ostringstream os2
- std::ostringstream os3
- std::ofstream local_data
- std::ofstream global_data
- · std::ofstream coord_list

6.18.1 Constructor & Destructor Documentation

6.18.1.1 Record()

6.18.1.2 ∼Record()

```
Record::\simRecord ( )
```

6.18.2 Member Function Documentation

6.18.2.1 is_rec_global_time()



6.18.2.2 is_rec_local_time()

Here is the caller graph for this function:



6.18.2.3 output_totals()

```
void Record::output_totals (
    int day,
    long long int tot_J,
    long long int tot_M,
    long long int tot_V,
    long long int tot_F)
```

Here is the caller graph for this function:



6.18.2.4 record_coords()



6.18.2.5 record_global()

```
void Record::record_global ( int \  \, day, \\ const \ std::array< long long int, \ num\_gen > \& \ tot\_M\_gen )
```

Here is the caller graph for this function:



6.18.2.6 record_local()

Here is the caller graph for this function:



6.18.3 Member Data Documentation

6.18.3.1 coord_list

```
std::ofstream Record::coord_list [private]
```

6.18.3.2 global_data

```
std::ofstream Record::global_data [private]
```

6.18.3.3 local_data

```
std::ofstream Record::local_data [private]
```

6.18.3.4 os1

```
std::ostringstream Record::os1 [private]
```

6.18.3.5 os2

```
std::ostringstream Record::os2 [private]
```

6.18.3.6 os3

```
std::ostringstream Record::os3 [private]
```

6.18.3.7 rec_end

```
int Record::rec_end [private]
```

6.18.3.8 rec_interval_global

```
int Record::rec_interval_global [private]
```

6.18.3.9 rec_interval_local

```
int Record::rec_interval_local [private]
```

6.18.3.10 rec_sites_freq

```
int Record::rec_sites_freq [private]
```

6.18.3.11 rec_start

```
int Record::rec_start [private]
```

6.18.3.12 rep_label

```
int Record::rep_label [private]
```

6.18.3.13 set_label

```
int Record::set_label [private]
```

The documentation for this class was generated from the following files:

- Record.h
- Record.cpp

6.19 RecordParams Struct Reference

```
#include <Params.h>
```

Collaboration diagram for RecordParams:

RecordParams + rec_start + rec_end + rec_interval_global + rec_interval_local + rec_sites_freq + set_label

Public Attributes

```
• int rec_start = 0
```

- int rec_end = 1000
- int rec_interval_global = 1
- int rec_interval_local = 200
- int rec_sites_freq = 1
- int set_label = 1

6.19.1 Member Data Documentation

6.19.1.1 rec_end

```
int RecordParams::rec_end = 1000
```

6.19.1.2 rec_interval_global

```
int RecordParams::rec_interval_global = 1
```

6.19.1.3 rec_interval_local

```
int RecordParams::rec_interval_local = 200
```

6.19.1.4 rec_sites_freq

```
int RecordParams::rec_sites_freq = 1
```

6.19.1.5 rec_start

```
int RecordParams::rec_start = 0
```

6.19.1.6 set_label

```
int RecordParams::set_label = 1
```

The documentation for this struct was generated from the following file:

· Params.h

6.20 ReleaseParams Struct Reference

```
#include <Params.h>
```

Collaboration diagram for ReleaseParams:

ReleaseParams + driver_start + num_driver_M + num_driver_sites

Public Attributes

- int driver_start = 200
- int num_driver_M = 1000
- int num_driver_sites = 5

6.20.1 Member Data Documentation

6.20.1.1 driver_start

int ReleaseParams::driver_start = 200

6.20.1.2 num_driver_M

int ReleaseParams::num_driver_M = 1000

6.20.1.3 num_driver_sites

```
int ReleaseParams::num_driver_sites = 5
```

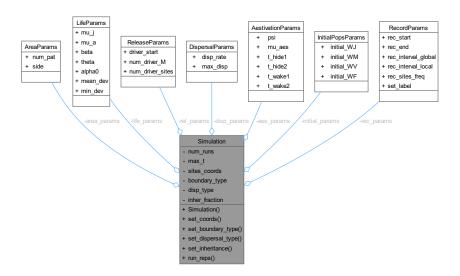
The documentation for this struct was generated from the following file:

· Params.h

6.21 Simulation Class Reference

#include <Simulation.h>

Collaboration diagram for Simulation:



Public Member Functions

- Simulation (ProgressionParams &prog, AreaParams &area, LifeParams &life, ReleaseParams &rel, DispersalParams &disp, AestivationParams &aes, InitialPopsParams &initial, RecordParams &rec)
- void set_coords (const std::string &coords_file)
- void set boundary type (BoundaryType boundary)
- void set_dispersal_type (DispersalType disp)
- void set_inheritance (InheritanceParams inher_params)
- void run_reps ()

Private Attributes

- int num_runs
- int max_t
- AreaParams * area params
- LifeParams * life_params
- ReleaseParams * rel_params
- DispersalParams * disp_params
- AestivationParams * aes_params
- InitialPopsParams * initial params
- RecordParams * rec_params
- std::vector< Point > sites_coords
- BoundaryType boundary_type
- DispersalType disp_type
- std::array< std::array< std::array< double, num_gen >, num_gen >, num_gen > inher_fraction

6.21.1 Constructor & Destructor Documentation

6.21.1.1 Simulation()

```
Simulation::Simulation (

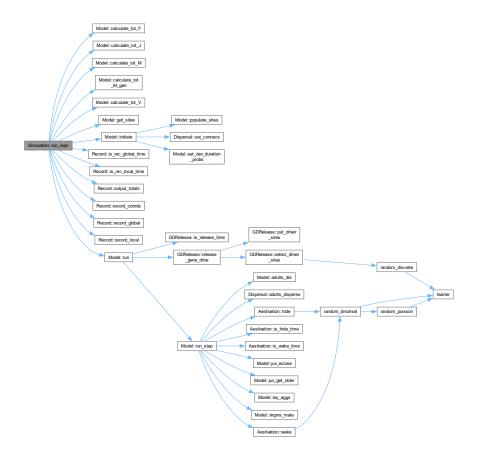
ProgressionParams & prog,
AreaParams & area,
LifeParams & life,
ReleaseParams & rel,
DispersalParams & disp,
AestivationParams & aes,
InitialPopsParams & initial,
RecordParams & rec)
```

6.21.2 Member Function Documentation

6.21.2.1 run_reps()

```
void Simulation::run_reps ( )
```

Here is the call graph for this function:



Here is the caller graph for this function:



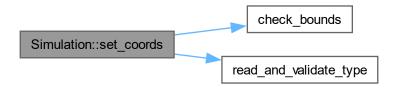
6.21.2.2 set_boundary_type()

Here is the caller graph for this function:



6.21.2.3 set_coords()

Here is the call graph for this function:



6.21.2.4 set_dispersal_type()



6.21.2.5 set_inheritance()

Here is the caller graph for this function:



6.21.3 Member Data Documentation

6.21.3.1 aes_params

AestivationParams* Simulation::aes_params [private]

6.21.3.2 area_params

AreaParams* Simulation::area_params [private]

6.21.3.3 boundary_type

BoundaryType Simulation::boundary_type [private]

6.21.3.4 disp_params

DispersalParams* Simulation::disp_params [private]

6.21.3.5 disp_type

DispersalType Simulation::disp_type [private]

6.21.3.6 inher_fraction

 $\verb|std::array| < \verb|std::array| < std::array| < st$

6.21.3.7 initial_params

```
InitialPopsParams* Simulation::initial_params [private]
```

6.21.3.8 life_params

```
LifeParams* Simulation::life_params [private]
```

6.21.3.9 max_t

```
int Simulation::max_t [private]
```

6.21.3.10 num_runs

```
int Simulation::num_runs [private]
```

6.21.3.11 rec_params

```
RecordParams* Simulation::rec_params [private]
```

6.21.3.12 rel_params

```
ReleaseParams* Simulation::rel_params [private]
```

6.21.3.13 sites_coords

```
std::vector<Point> Simulation::sites_coords [private]
```

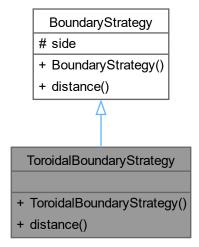
The documentation for this class was generated from the following files:

- Simulation.h
- · Simulation.cpp

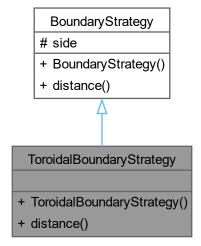
6.22 ToroidalBoundaryStrategy Class Reference

#include <BoundaryStrategy.h>

Inheritance diagram for ToroidalBoundaryStrategy:



Collaboration diagram for ToroidalBoundaryStrategy:



Public Member Functions

- ToroidalBoundaryStrategy (double side)
- double distance (const Point &p1, const Point &p2) override

Public Member Functions inherited from BoundaryStrategy

• BoundaryStrategy (double side)

Additional Inherited Members

Protected Attributes inherited from BoundaryStrategy

• double side

6.22.1 Constructor & Destructor Documentation

6.22.1.1 ToroidalBoundaryStrategy()

```
\label{toroidalBoundaryStrategy::ToroidalBoundaryStrategy (} $$ double $side$ ) [inline]
```

6.22.2 Member Function Documentation

6.22.2.1 distance()

Implements BoundaryStrategy.

The documentation for this class was generated from the following files:

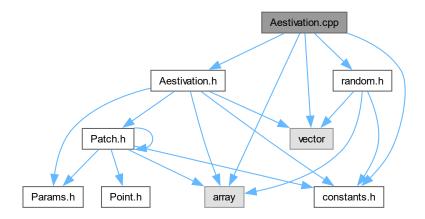
- · BoundaryStrategy.h
- · BoundaryStrategy.cpp

Chapter 7

File Documentation

7.1 Aestivation.cpp File Reference

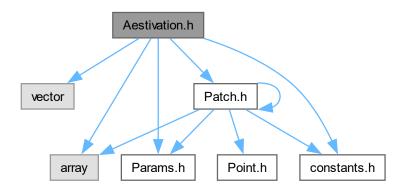
```
#include <array>
#include <vector>
#include "Aestivation.h"
#include "random.h"
#include "constants.h"
Include dependency graph for Aestivation.cpp:
```



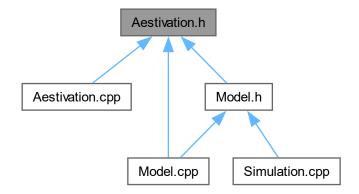
7.2 Aestivation.h File Reference

```
#include <vector>
#include <array>
#include "Params.h"
#include "Patch.h"
```

```
#include "constants.h"
Include dependency graph for Aestivation.h:
```



This graph shows which files directly or indirectly include this file:



Classes

· class Aestivation

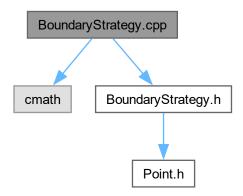
Aestivation.h

Go to the documentation of this file. 00001 #ifndef AESTIVATION_H 00002 #define AESTIVATION_H 00003 00004 #include <vector>

```
00005 #include <array>
00006 #include "Params.h"
00007 #include "Patch.h"
00008 #include "constants.h"
00009
00010 using namespace constants;
00011
00012 class Patch;
00013
00014 \!\!\!// Implement aestivative behaviour for the collection of mosquito sites.
00015 class Aestivation {
00016 public:
            Aestivation(AestivationParams *params, int sites_size);
00018
             void hide(std::vector<Patch*> &sites);
00019
            void wake(int day, std::vector<Patch*> &sites);
00020
            bool is_hide_time(int day);
00021
            bool is_wake_time(int day);
00022
00023 private:
00024
            double psi; // aestivation rate
            double mu_aes; // aestivation rate double mu_aes; // aestivation mortality int t_hide1; // start day of aestivation-entering period (day number of the year), not included int t_hide2; // end day of aestivation-entering period (day number of the year) int t_wake1; // start day of aestivation-waking period (day number of the year), not included
00025
00026
00027
00028
00029
            int t_wake2; // end day of aestivation-waking period (day number of the year)
00030
00031
            // number of mated female mosquitoes F_{ij} with female genotype i and carrying mated male
       genotype j that have gone into
00032
            // aestivation from each patch
             std::vector<std::array<std::array<long long int, num_gen>, num_gen» aes_F;
00033
00034 };
00035
00036 #endif //AESTIVATION_H
```

7.4 BoundaryStrategy.cpp File Reference

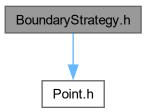
```
#include <cmath>
#include "BoundaryStrategy.h"
Include dependency graph for BoundaryStrategy.cpp:
```



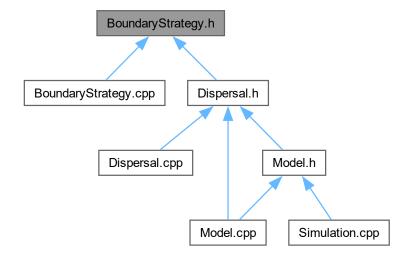
7.5 BoundaryStrategy.h File Reference

#include "Point.h"

Include dependency graph for BoundaryStrategy.h:



This graph shows which files directly or indirectly include this file:



Classes

- class BoundaryStrategy
- · class ToroidalBoundaryStrategy
- · class EdgeBoundaryStrategy

7.6 BoundaryStrategy.h

Go to the documentation of this file.

```
00001 #ifndef BOUNDARYSTRATEGY_H
00002 #define BOUNDARYSTRATEGY_H
00003
00004 #include "Point.h"
00005
00006 class BoundaryStrategy {
00007 public:
          BoundaryStrategy(double side): side(side) {};
80000
          virtual double distance(const Point& p1, const Point& p2) = 0;
00009
00010
00011 protected:
00012
          double side;
00013 };
00014
00015 class ToroidalBoundaryStrategy: public BoundaryStrategy {
00016 public:
          ToroidalBoundaryStrategy(double side): BoundaryStrategy(side) {};
00018
          double distance(const Point &p1, const Point &p2) override;
00019 };
00020
00021 class EdgeBoundaryStrategy: public BoundaryStrategy {
00022 public:
          EdgeBoundaryStrategy(double side): BoundaryStrategy(side) {};
00024
          double distance(const Point& p1, const Point& p2) override;
00025 };
00026
00027 #endif //BOUNDARYSTRATEGY_H
```

7.7 constants.h File Reference

This graph shows which files directly or indirectly include this file:



Namespaces

· namespace constants

Enumerations

- enum BoundaryType { Toroid , Edge }
- enum DispersalType { DistanceKernel , Radial }

Variables

- const int constants::max_dev = 20
- const int constants::num gen = 6

7.7.1 Enumeration Type Documentation

7.7.1.1 BoundaryType

enum BoundaryType

Enumerator

Toroid	
Edge	

7.7.1.2 DispersalType

enum DispersalType

Enumerator

DistanceKernel	
Radial	

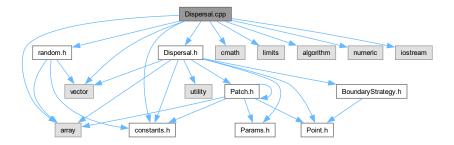
7.8 constants.h

Go to the documentation of this file.

7.9 Dispersal.cpp File Reference

```
#include <vector>
#include <array>
#include <cmath>
#include <limits>
#include <algorithm>
#include <numeric>
#include "Dispersal.h"
#include "random.h"
#include "constants.h"
#include <iostream>
```

Include dependency graph for Dispersal.cpp:



Variables

- const double PI = 3.14159265
- const double TWOPI = 2 * PI

7.9.1 Variable Documentation

7.9.1.1 PI

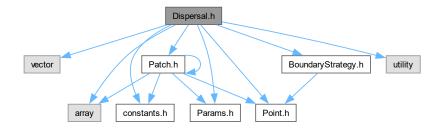
```
const double PI = 3.14159265
```

7.9.1.2 TWOPI

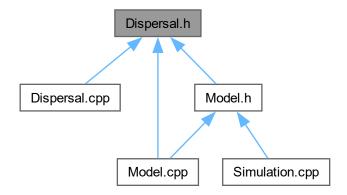
```
const double TWOPI = 2 * PI
```

7.10 Dispersal.h File Reference

```
#include <vector>
#include <array>
#include <utility>
#include "constants.h"
#include "Params.h"
#include "Patch.h"
#include "Point.h"
#include "BoundaryStrategy.h"
Include dependency graph for Dispersal.h:
```



This graph shows which files directly or indirectly include this file:



Classes

- · class Dispersal
- · class DistanceKernelDispersal
- · class RadialDispersal

7.11 Dispersal.h

Go to the documentation of this file.

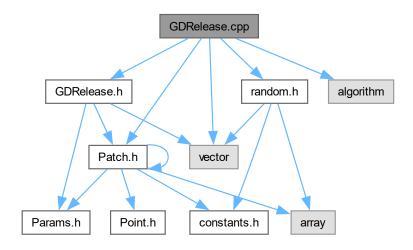
```
00001 #ifndef DISPERSAL_H
00002 #define DISPERSAL_H
00003
00004 #include <vector>
00005 #include <array>
00006 #include <utility>
00007 #include "constants.h"
00008 #include "Params.h"
00009 #include "Patch.h"
00010 #include "Point.h"
00011 #include "BoundaryStrategy.h"
00012
00013 using namespace constants;
00014
00015 class Patch;
00016
00017 \/\/ Implements dispersion across all mosquito sites in the collection.
00018 class Dispersal {
00019 public:
00020
        Dispersal(DispersalParams* params, BoundaryType boundary, double side);
00021
          ~Dispersal();
          virtual void set_connecs(std::vector<Patch*> &sites) = 0;
00022
00023
          virtual void adults_disperse(std::vector<Patch*> &sites) = 0;
00024
00025 protected:
00026
          double disp_rate; // adult dispersal rate
00027
          double max_disp; // maximum distance at which two sites are connected (km)
00028
          // connected patch indices ordered by each patch in sites, such that the first element contains
00029
     the indices of all the patches
00030
          // connected to the first sites patch, second element has all connection indices to the second
      sites patch, etc.
00031
         std::vector<std::vector<int» connec_indices;
00032
          // connection weights of the connected patches ordered by each patch in sites, such that the first
      element contains the connection
```

```
00033
          // weights between the first patch in sites and all the patches connected to it, the second
      element has all connection weights
00034
          // between the second sites element and all other patches connected to it, etc.
00035
          std::vector<std::vector<double> connec_weights;
00036
00037
          BoundaryStrategy* boundary strategy:
00039
          std::vector<std::array<long long int, num_gen» M_dispersing_out(const std::vector<Patch*> &sites);
00040
          std::vector<std::array<std::array<std:iong long int, num_gen>, num_gen> F_dispersing_out(const
     std::vector<Patch*> &sites);
00041 };
00042
00043
00044 class DistanceKernelDispersal: public Dispersal {
00045 public:
00046
         DistanceKernelDispersal(DispersalParams* params, BoundaryType boundary, double side):
     Dispersal(params, boundary, side) {};
00047
          void set connecs(std::vector<Patch*> &sites) override;
          void adults_disperse(std::vector<Patch*> &sites) override;
00049
00050 private:
00051
         std::pair<std::vector<std::vector<int>, std::vector<std::vector<double>>
      compute_connecs(std::vector<Patch*> &sites);
00052 };
00053
00054 class RadialDispersal: public Dispersal {
00055 public:
00056
         RadialDispersal(DispersalParams* params, BoundaryType boundary, double side);
00057
          void set_connecs(std::vector<Patch*> &sites) override;
00058
          void adults_disperse(std::vector<Patch*> &sites) override;
00059
00060 private:
00061
         std::vector<double> connec_weights_sum;
00062
00063
          std::pair<std::vector<std::vector<int>, std::vector<std::vector<double>>
     compute_connecs(std::vector<Patch*> &sites);
00064
         std::pair<std::vector<std::pair<double, double», double> compute_interval_union(const
     std::pair<double, double>& qq,
00065
              const std::vector<std::pair<double, double%& input);</pre>
00066
          double wrap_around(double value, double range);
00067
          std::vector<int> get_sorted_positions(const std::vector<double>& numbers);
00068
          std::vector<std::vector<double> compute_distances(const std::vector<Patch*> &sites);
00069 };
00070
00071 #endif //DISPERSAL_H
```

7.12 GDRelease.cpp File Reference

```
#include <vector>
#include <algorithm>
#include "GDRelease.h"
#include "Patch.h"
#include "random.h"
```

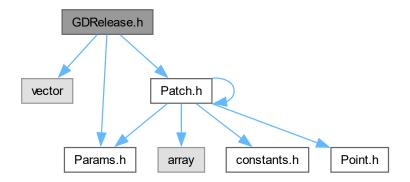
Include dependency graph for GDRelease.cpp:



7.13 GDRelease.h File Reference

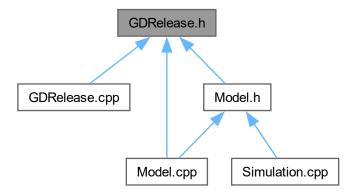
#include <vector>
#include "Params.h"
#include "Patch.h"

Include dependency graph for GDRelease.h:



7.14 GDRelease.h

This graph shows which files directly or indirectly include this file:



Classes

· class GDRelease

7.14 GDRelease.h

Go to the documentation of this file.

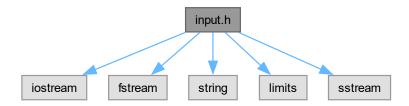
```
00001 #ifndef GDRELEASE_H
00002 #define GDRELEASE_H
00003
00003 #include <vector>
00005 #include "Params.h"
00006 #include "Patch.h"
00007
00008 class Patch;
00009
00010 // Implements gene drive release of mosquitoes into the collection of mosquito sites.
00011 class GDRelease {
00012 public:
00013
            GDRelease(ReleaseParams* params);
00014
            void release_gene_drive(std::vector<Patch*> &sites);
00015
            bool is_release_time(int day);
00016
00017 private:
            int driver_start; // time to start releasing drive alleles into the mosquito population int num_driver_M; // number of drive heterozygous (WD) male mosquitoes per release
00018
00019
00020
            int num_driver_sites; // number of gene drive release sites per year
00021
            std::vector<Patch*> select_driver_sites(int num_rel_sites, const std::vector<Patch*> &sites);
void put_driver_sites(std::vector<Patch*>& rel_sites, std::vector<Patch*> &sites);
00022
00023
00024 };
00025
00026 #endif //GDRELEASE_H
```

7.15 input.h File Reference

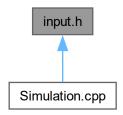
```
#include <iostream>
#include <fstream>
#include <string>
```

```
#include <limits>
#include <sstream>
```

Include dependency graph for input.h:



This graph shows which files directly or indirectly include this file:



Functions

- template<typename T >
 bool check_bounds (const std::string &par_name, T value, T lower_bound, bool inclusive_lower=true, T upper_bound=std::numeric_limits< T >::max(), bool inclusive_upper=true)
- template<typename T >
 bool read_and_validate_type (std::ifstream &file, T &par, const std::string &par_name, const std::string &par_type)
- template<typename T >
 bool read_and_validate_type (std::stringstream &linestream, T &par, const std::string &par_name, const std::string &par_type)

7.15.1 Function Documentation

7.15.1.1 check_bounds()

```
T value,
T lower_bound,
bool inclusive_lower = true,
T upper_bound = std::numeric_limits<T>::max(),
bool inclusive_upper = true )
```

Here is the caller graph for this function:



7.15.1.2 read_and_validate_type() [1/2]

Here is the caller graph for this function:

```
Simulation::set_coords read_and_validate_type
```

7.15.1.3 read_and_validate_type() [2/2]

7.16 input.h

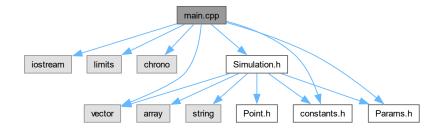
Go to the documentation of this file.

```
00001 #ifndef INPUT_H
00002 #define INPUT H
00003
00004 #include <iostream>
00005 #include <fstream>
00006 #include <string>
00007 #include <limits>
00008 #include <sstream>
00009
00010 // Checks if a value falls within bounds.
00011 template <typename T>
00012 bool check_bounds(const std::string &par_name, T value, T lower_bound, bool inclusive_lower = true,
00013 T upper_bound = std::numeric_limits<T>::max(), bool inclusive_upper = true)
00014 {
00015
           if (lower_bound >= upper_bound) {
              std::cerr « "Error: lower_bound must be less than upper_bound." « std::endl;
00016
00017
00018
00019
          bool lower_check = inclusive_lower ? value >= lower_bound : value > lower_bound;
00020
00021
          bool upper_check = inclusive_upper ? value <= upper_bound : value < upper_bound;</pre>
00023
          std::string lower_bound_char = inclusive_lower ? "\u2264" : "<";</pre>
          std::string upper_bound_char = inclusive_upper ? "\u2264" : "<";
00024
          if (!lower_check || !upper_check) {
   std::cout « "The parameter " « par_name « " is out of bounds. ";
   std::cout « par_name « " should be " « lower_bound « " " « lower_bound_char « " " « par_name «
00025
00026
00027
00028
              std::cout « upper_bound_char « " " « upper_bound « ". " « std::endl;
00029
00030
00031
           return lower_check && upper_check;
00032 }
00033
00034 // Reads a value from filestream and assigns it to the parameter variable if the types match.
00035 template <typename T>
00036 bool read_and_validate_type(std::ifstream &file, T &par, const std::string &par_name, const
std::string &par_type)
00037 {
00038
          if (!(file » par)) {
               std::cerr « "Error: invalid type for " « par_name « ". Expected " « par_type « "." «
      std::endl;
00040
             return false;
00041
          return true;
00042
00043 }
00044
00045 template <typename T>
00046 bool read_and_validate_type(std::stringstream &linestream, T &par, const std::string &par_name, const
      std::string &par_type)
00047 {
00048
           if (!(linestream » par)) {
               std::cerr « "Error: invalid type for " « par_name « ". Expected " « par_type « "." «
00049
      std::endl;
00050
             return false;
00051
00052
           return true;
00053 }
00054
00055 #endif //INPUT_H
```

7.17 main.cpp File Reference

```
#include <iostream>
#include <limits>
#include <chrono>
#include <vector>
#include "Simulation.h"
#include "Params.h"
```

#include "constants.h"
Include dependency graph for main.cpp:



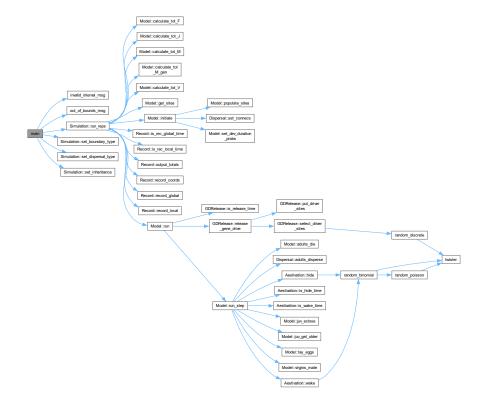
Functions

• int main ()

7.17.1 Function Documentation

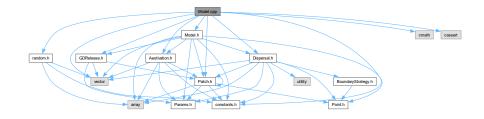
7.17.1.1 main()

int main ()



7.18 Model.cpp File Reference

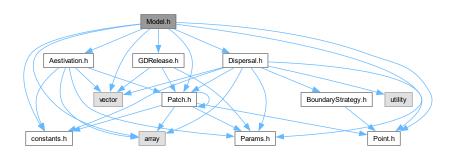
```
#include <vector>
#include <cmath>
#include <cassert>
#include "Model.h"
#include "random.h"
#include "constants.h"
#include "Patch.h"
#include "Dispersal.h"
#include "GDRelease.h"
#include "Aestivation.h"
Include dependency graph for Model.cpp:
```



7.19 Model.h File Reference

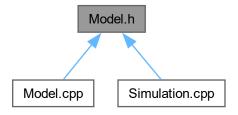
```
#include <vector>
#include <array>
#include "constants.h"
#include "Params.h"
#include "Patch.h"
#include "Dispersal.h"
#include "Aestivation.h"
#include "GDRelease.h"
#include "Point.h"
```

Include dependency graph for Model.h:



7.20 Model.h 95

This graph shows which files directly or indirectly include this file:



Classes

class Model

7.20 Model.h

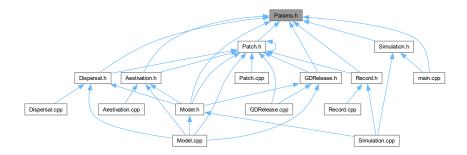
Go to the documentation of this file.

```
00001 #ifndef MODEL_H
00002 #define MODEL_H
00003
00004 #include <vector>
00005 #include <array>
00006 #include "constants.h"
00007 #include "Params.h"
00008 #include "Patch.h"
00009 #include "Dispersal.h"
00010 #include "Aestivation.h"
00011 #include "GDRelease.h"
00012 #include "Point.h"
00013
00014 using namespace constants;
00015
00016 // Runs the model.
00017 class Model {
00018 public:
00019
         Model(AreaParams *area, InitialPopsParams *initial, LifeParams *life, AestivationParams *aes,
     DispersalParams *disp,
00020
              ReleaseParams *rel, BoundaryType boundary = BoundaryType::Toroid, DispersalType disp_type =
     DispersalType::DistanceKernel,
00021
               std::vector<Point> coords = {});
          ~Model();
00022
00023
          void initiate();
          void run(int day, const std::array<std::array<std::array <double, num_gen>, num_gen>, num_gen>
00024
     &inher_fraction);
00025
00026
          long long int calculate_tot_J();
00027
          long long int calculate_tot_M();
00028
          long long int calculate_tot_V();
00029
          long long int calculate_tot_F();
00030
          std::array<long long int, num_gen> calculate_tot_M_gen();
00031
          std::vector<Patch*> get_sites() const;
00032
00033 private:
          std::vector<Patch*> sites;
00034
          Dispersal* dispersal;
00035
          Aestivation* aestivation;
00036
00037
          GDRelease* gd_release;
00038
00039
          // simulation area parameters
00040
          int num_pat; // number of population sites chosen for the simulation
          double side; // size of the square simulation area (side x side) (km)
00041
00042
00043
          // initial population values - common for all Patches
```

```
InitialPopsParams *initial_pops;
00045
           // juvenile development parameters - common for all Patches
int min_dev; // minimum development time for a juvenile (in days)
00046
00047
      std::array<double, max_dev+1> dev_duration_probs; // array of probabilities of juvenile
development duration for a new juvenile
00048
00049
           // (index indicates the number of days to develop or, equivalently, the age class the new juvenile
00050
            // initiation methods
00051
00052
           void populate_sites();
           void set_dev_duration_probs(int min_time, int max_time);
00053
00054
00055
            // life-processes - interface with Patch
00056
           void run_step(int day, const std::array<std::array<std::array <double, num_gen>, num_gen>,
       num_gen> &inher_fraction);
00057
           void juv_get_older();
void adults_die();
00058
00059
           void virgins_mate();
00060
            void lay_eggs(const std::array<std::array<std::array <double, num_gen>, num_gen>, num_gen>
       &inher_fraction);
00061
           void juv_eclose();
00062 };
00063
00064 #endif //MODEL_H
```

7.21 Params.h File Reference

This graph shows which files directly or indirectly include this file:



Classes

- struct ProgressionParams
- struct AreaParams
- struct LifeParams
- struct InheritanceParams
- struct ReleaseParams
- struct DispersalParams
- struct AestivationParams
- struct InitialPopsParams
- struct RecordParams

7.22 Params.h 97

7.22 Params.h

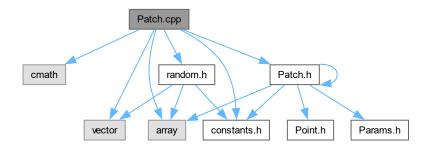
Go to the documentation of this file.

```
00001 #ifndef PARAMS_H
00002 #define PARAMS H
00004 // ** These parameters should not be modified after being passed to the Simulation or Model **
00005
00006 // Simulation progression parameters
00007 struct ProgressionParams {
00008    int num_runs = 1; // number of simulation replicates to run
00009    int max_t = 1000; // maximum simulated time (in days)
00011
00012 // Model area parameters
00013 struct AreaParams
         int num_pat = 50; // number of population sites chosen for the simulation
00014
00015
            double side = 1.0; // size of the square simulation area (side x side) (km)
00016 };
00017
00018 // Model life-process parameters
00019 struct LifeParams {
            double mu_j = 0.05; // juvenile density independent mortality rate per day double mu_a = 0.125; // adult mortality rate per day double beta = 100.0; // parameter that controls mating rate
00020
00021
00023
            double theta = 9.0; // average egg laying rate of wildtype females (eggs per day)
            double alpha0 = 100000.0; // baseline contribution to carrying capacity double mean_dev = 15.0; // mean juvenile development time (in days)
00024
00025
00026
           int min_dev = 10; // minimum development time for a juvenile (in days)
00027 };
00028
00029 // Gene drive inheritance parameters
00030 struct InheritanceParams {
00031
            double gamma = 0.025; // rate of r2 allele formation from W/D meiosis
            double xi = 0.2; // somatic Cas9 expression fitness cost double e = 0.95; // homing rate in females
00032
00033
00034 };
00035
00036 // Gene drive release model parameters
00037 struct ReleaseParams {
           int driver_start = 200; // time to start releasing drive alleles into the mosquito population
int num_driver_M = 1000; // number of drive heterozygous (WD) male mosquitoes per release
int num_driver_sites = 5; // number of gene drive release sites per year
00038
00039
00040
00042
00043 // Dispersal model parameters
00047 };
00048
00049 // Aestivation model parameters
00050 struct AestivationParams {
00051
           double psi = 0.0; // aestivation rate
            double mu_aes = 0.0; // aestivation mortality
00052
            int t hidel = 0; // start day of aestivation-entering period (day number of the year), not
00053
       included
00054
          int t_hide2 = 0; // end day of aestivation-entering period (day number of the year)
            int t_wakel = 0; // start day of aestivation-waking period (day number of the year), not included
00055
00056
           int t_wake2 = 0; // end day of aestivation-waking period (day number of the year)
00057 };
00058
00059 // Initial population values for the model
00060 struct InitialPopsParams {
            int initial_WJ = 10000; // array of number of initial juvenile mosquitoes with wild homozygous
       (WW) genotype for each age group
00062
           int initial WM = 50000; // number of initial adult male mosquitoes with wild homozygous (WW)
       genotype
00063
            int initial_WV = 10000; // number of initial adult unmated female (virgin) mosquitoes with wild
       homozygous (WW) genotype
00064
           int initial_WF = 40000; // number of initial adult mated female mosquitoes with wild homozygous
       (WW) genotype
00065 };
00066
00067 // Data-recording parameters
00068 struct RecordParams {
00069
          // recording window and intervals
            int rec_start = 0; // start time for the data recording window (in days) (non-inclusive)
int rec_end = 1000; // end time for the data recording window (in days) (inclusive)
int rec_interval_global = 1; // time interval for global data recording/output
int rec_interval_local = 200; // time interval at which to collect/record local data (in days)
int rec_sites_freq = 1; // fraction of sites to collect local data for (1 is all sites, 10 is 1 in
00070
00071
00072
00073
00075
00076
            // output filename labels
```

```
00077    int set_label = 1; // 'set of runs' index label for output files
00078 };
00079
00080 #endif //PARAMS_H
```

7.23 Patch.cpp File Reference

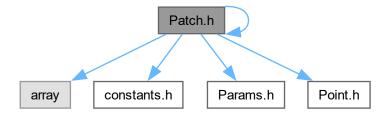
```
#include <cmath>
#include <array>
#include <vector>
#include "Patch.h"
#include "random.h"
#include "constants.h"
Include dependency graph for Patch.cpp:
```



7.24 Patch.h File Reference

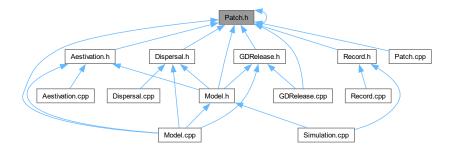
```
#include <array>
#include "Patch.h"
#include "constants.h"
#include "Params.h"
#include "Point.h"
Include dependency graph for Patch.h:
```

include dependency graph for Fatch.ii.



7.25 Patch.h 99

This graph shows which files directly or indirectly include this file:



Classes

· class Patch

7.25 Patch.h

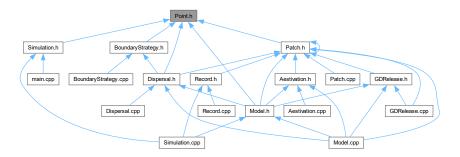
Go to the documentation of this file.

```
00001 #ifndef PATCH_H
00002 #define PATCH H
00003
00004 #include <array>
00005 #include "Patch.h"
00006 #include "constants.h"
00007 #include "Params.h"
00008 #include "Point.h"
00009
00010 using namespace constants;
00011
00012 // Contains the information of a local mosquito population
00013 class Patch {
00014 public:
00015
                      Patch(LifeParams* par, double side);
                       Patch(LifeParams* par, Point point); void populate(int initial_WJ, int initial_WM, int initial_WV, int initial_WF);
00016
00017
00018
00019
                       Point get_coords() const;
00020
                       \verb|std::array| < \verb|long int, num_gen| > \verb|get_M() const|; \\
00021
                       std::array<std::array<long long int, num_gen>, num_gen> get_F() const;
00022
00023
                        long long int calculate_tot_J();
00024
                        long long int calculate_tot_M();
00025
                       long long int calculate_tot_V();
00026
                       long long int calculate_tot_F();
00027
00028
                       // life-processes for the local site
00029
                       void juv_get_older(int max_dev);
00030
                       void adults_die();
00031
                       void virgins_mate();
00032
                       void lay_eggs(const std::array<std::array<std::array <double, num_gen>, num_gen>, num_gen> &f,
00033
                         const std::array<double, max_dev+1> &dev_duration_probs);
00034
                       void juv eclose();
                       void update_comp();
00035
00036
                       void update_mate();
00037
00038
                       // interface to Dispersal
00039
                       void M_disperse_out(const std::array<long long int, num_gen> &m_out);
                       void F_disperse_out(const std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<std::array<st
00040
00041
00042
00043
00044
                        // interface to Aestivation
00045
                       \label{long_problem} \mbox{void $F$\_hide(const std::array<std::array<long long int, num\_gen>, num\_gen> \&f\_try);}
00046
                       void F_wake(const std::array<std::array<long long int, num_gen>, num_gen> &f_wake);
00047
00048
                       // interface to GDRelease
```

```
void add_driver_M(int num_driver_M);
00050
00051 private:
00052
           LifeParams* params;
00053
           Point coords; // (x, y) coordinates of the site // number of juvenile mosquitoes with each genotype and in each age group.
00054
00055
00056
            // age ordered from oldest (0 days left to eclosion) to youngest (max_dev - 1 days left)
00057
            std::array<std::array<long long int, max_dev+1>, num_gen> J;
           std::array<long long int, num_gen> M; // number of male mosquitoes with each genotype std::array<long long int, num_gen> V; // number of unmated female (virgin) mosquitoes with each
00058
00059
       genotype
00060
            // number of mated female mosquitoes F_{ij} with female genotype i and carrying mated male
       genotype j
00061
            std::array<std::array<long long int, num_gen>, num_gen> F;
00062
            long double <code>comp;</code> // survival probability per juvenile per day (both density-dependent and
00063
       independent factors)
00064
            long double mate_rate; // probability of an unmated (virgin) female mating on a given day
00065 };
00066
00067 #endif //PATCH_H
```

7.26 Point.h File Reference

This graph shows which files directly or indirectly include this file:



Classes

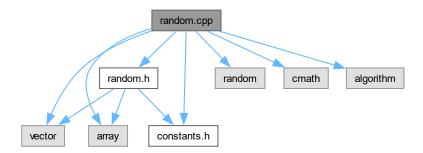
struct Point

7.27 Point.h

Go to the documentation of this file.

7.28 random.cpp File Reference

```
#include <vector>
#include <array>
#include <random>
#include <cmath>
#include <algorithm>
#include "random.h"
#include "constants.h"
Include dependency graph for random.cpp:
```



Functions

- std::mt19937 twister (1)
- double random_real ()
- int random_discrete (int a, int b)
- long long int random_poisson (double lambda)
- long long int random_binomial (long long int n, double p)
- std::vector< long long int > random_multinomial (long long int n, const std::vector< double > &probs)
- std::vector< long long int > random_multinomial (long long int n, const std::array< long long int, num_gen > &probs)
- std::vector< long long int > random_multinomial (long long int n, const std::array< double, max_dev+1 > &probs)

Variables

• std::random device rd

7.28.1 Function Documentation

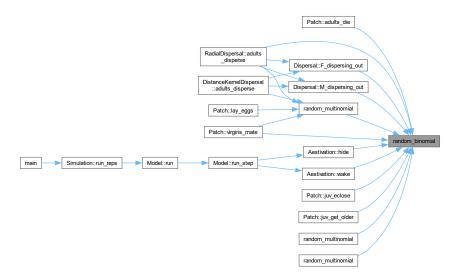
7.28.1.1 random_binomial()

```
long long int random_binomial ( \label{eq:long_long} \mbox{long int } n, \mbox{double } p \mbox{ )}
```

Here is the call graph for this function:



Here is the caller graph for this function:



7.28.1.2 random_discrete()

```
\begin{array}{ccc} \text{int random\_discrete (} \\ & \text{int } a, \\ & \text{int } b \text{ )} \end{array}
```

Here is the call graph for this function:



Here is the caller graph for this function:



7.28.1.3 random_multinomial() [1/3]

```
std::vector< long long int > random_multinomial ( long \ long \ int \ n, const \ std::array< \ double, \ max\_dev+1 > \& \ probs )
```

Here is the call graph for this function:



7.28.1.4 random_multinomial() [2/3]

```
std::vector< long long int > random_multinomial ( long \ long \ int \ n, const \ std::array< \ long \ long \ int, \ num\_gen > \& \ probs )
```

Here is the call graph for this function:



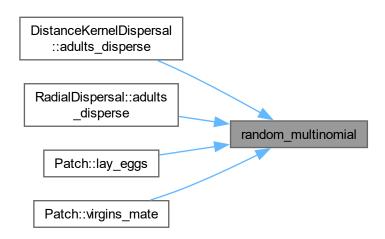
7.28.1.5 random_multinomial() [3/3]

```
std::vector< long long int > random_multinomial ( long long int n, const std::vector< double > & probs )
```

Here is the call graph for this function:



Here is the caller graph for this function:

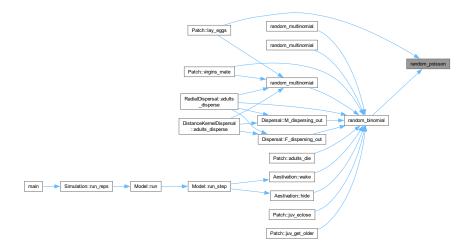


7.28.1.6 random_poisson()

Here is the call graph for this function:



Here is the caller graph for this function:



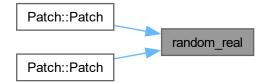
7.28.1.7 random_real()

```
double random_real ( )
```

Here is the call graph for this function:

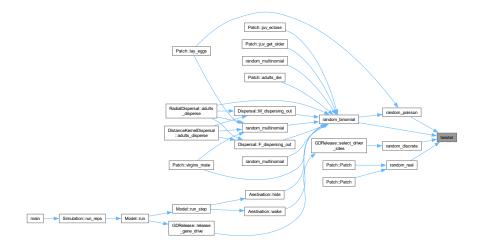


Here is the caller graph for this function:



7.28.1.8 twister()

Here is the caller graph for this function:



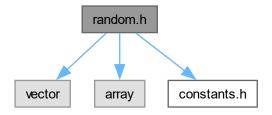
7.28.2 Variable Documentation

7.28.2.1 rd

std::random_device rd

7.29 random.h File Reference

```
#include <vector>
#include <array>
#include "constants.h"
Include dependency graph for random.h:
```



This graph shows which files directly or indirectly include this file:



Functions

- double random_real ()
- int random_discrete (int a, int b)
- long long int random_poisson (double lambda)
- long long int random_binomial (long long int n, double p)
- std::vector< long long int > random_multinomial (long long int n, const std::vector< double > &probs)
- std::vector< long long int > random_multinomial (long long int n, const std::array< long long int, num_gen > &probs)
- std::vector< long long int > random_multinomial (long long int n, const std::array< double, max_dev+1 > &probs)

7.29.1 Function Documentation

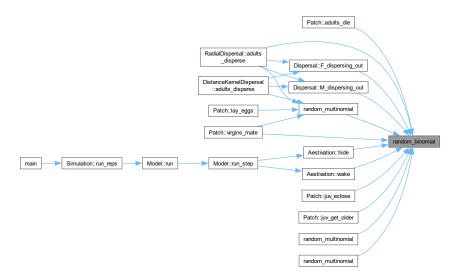
7.29.1.1 random_binomial()

```
long long int random_binomial ( \label{eq:long_long} \mbox{long int } n, \mbox{double } p \mbox{ )}
```

Here is the call graph for this function:



Here is the caller graph for this function:



7.29.1.2 random_discrete()

```
int random_discrete (
    int a,
    int b)
```

Here is the call graph for this function:



Here is the caller graph for this function:



7.29.1.3 random_multinomial() [1/3]

```
std::vector< long long int > random_multinomial ( long \ long \ int \ n, const \ std::array< \ double, \ max\_dev+1 > \& \ probs \ )
```

Here is the call graph for this function:



7.29.1.4 random_multinomial() [2/3]

```
std::vector< long long int > random_multinomial ( long \ long \ int \ n, const \ std::array< \ long \ long \ int, \ num\_gen > \& \ probs )
```

Here is the call graph for this function:



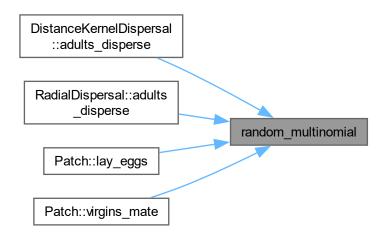
7.29.1.5 random_multinomial() [3/3]

```
\begin{tabular}{ll} \tt std::vector< long long int > random\_multinomial ( \\ long long int n, \\ const std::vector< double > & probs ) \end{tabular}
```

Here is the call graph for this function:



Here is the caller graph for this function:

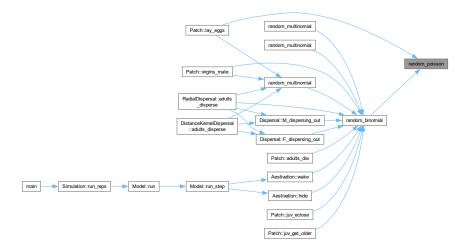


7.29.1.6 random_poisson()

Here is the call graph for this function:



Here is the caller graph for this function:



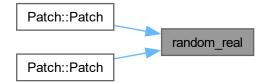
7.29.1.7 random_real()

```
double random_real ( )
```

Here is the call graph for this function:



Here is the caller graph for this function:



7.30 random.h

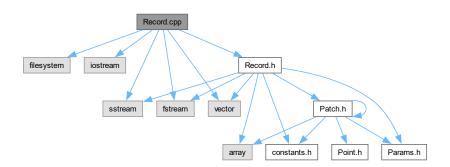
Go to the documentation of this file.

```
00001 #include <vector>
00002 #include <array>
00003 #include "constants.h"
00004
00005 using namespace constants;
00006
00007 // Random number generator functions
80000
00009 double random_real();
00010 int random_discrete(int a, int b);
00011 long long int random_poisson(double lambda);
00012 long long int random_binomial(long long int n, double p);
00013 std::vector<long long int> random_multinomial(long long int n, const std::vector<double>& probs);
00014 std::vector<long long int> random_multinomial(long long int n, const std::array<long long int,
      num_gen>& probs);
00015 std::vector<long long int> random_multinomial(long long int n, const std::array<double, max_dev+1>&
       probs);
```

Record.cpp File Reference

```
#include <filesystem>
#include <iostream>
#include <sstream>
#include <fstream>
#include <vector>
#include "Record.h"
```

Include dependency graph for Record.cpp:



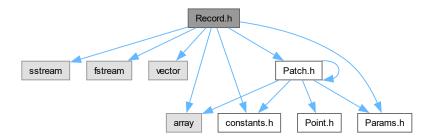
7.32 Record.h File Reference

```
#include <sstream>
#include <fstream>
#include <vector>
#include <array>
#include "constants.h"
#include "Patch.h"
```

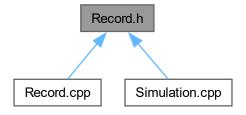
7.33 Record.h 113

```
#include "Params.h"
```

Include dependency graph for Record.h:



This graph shows which files directly or indirectly include this file:



Classes

• class Record

7.33 Record.h

Go to the documentation of this file.

```
00001 #ifndef RECORD_H
00002 #define RECORD_H
00003
00004 #include <sstream>
00005 #include <fstream>
00006 #include <vector>
00000 #include <array>
00008 #include <array>
00008 #include "constants.h"
00009 #include "Patch.h"
00010 #include "Params.h"
00011
00012 using namespace constants;
00013
00014 // Records model data.
00015 class Record {
00016 public:
00017
            Record(RecordParams *rec_params, int rep);
00018
              ~Record();
```

```
00019
            void record_coords(const std::vector<Patch*> &sites);
           void record_global(int day, const std::array<long int, num_gen> &tot_M_gen); void output_totals(int day, long long int tot_J, long long int tot_M, long long int tot_V, long
00020
00021
       long int tot_F);
00022
            void record_local(int day, const std::vector<Patch*> &sites);
00023
            bool is_rec_local_time(int day);
00025
            bool is_rec_global_time(int day);
00026
00027 private:
00028
            // recording window and intervals
            int rec_start; // start time for the data recording window (in days) (non-inclusive)
int rec_end; // end time for the data recording window (in days) (inclusive)
00029
00030
00031
            int rec_interval_global; // time interval for global data recording/output
00032
            int rec_interval_local; // time interval at which to collect/record local data (in days)
00033
            int rec_sites_freq; // fraction of sites to collect local data for (1 is all sites, 10 is 1 in 10
00034
00035
            // output filename labels
            int set_label; // 'set of repetitions' index label for output files int rep_label; // 'repetition' index label in given set of repetitions for output files
00036
00037
00038
00039
            std::ostringstream os1, os2, os3; // filenames
            std::ofstream local_data, global_data, coord_list; // file objects
00040
00041 };
00043 #endif //RECORD_H
```

7.34 Simulation.cpp File Reference

```
#include <array>
#include <iostream>
#include <filesystem>
#include <sstream>
#include <string>
#include "Simulation.h"
#include "constants.h"
#include "Model.h"
#include "Record.h"
#include "input.h"
```

Include dependency graph for Simulation.cpp:



Functions

- void out_of_bounds_msg (const std::string &par)
- void invalid_interval_msg (const std::string ¶m1, const std::string ¶m2)

7.34.1 Function Documentation

7.34.1.1 invalid_interval_msg()

Here is the caller graph for this function:



7.34.1.2 out_of_bounds_msg()

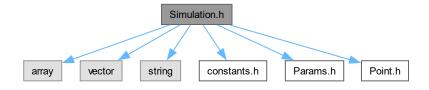
Here is the caller graph for this function:



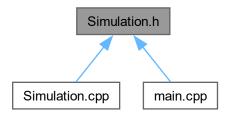
7.35 Simulation.h File Reference

```
#include <array>
#include <vector>
#include <string>
#include "constants.h"
#include "Params.h"
#include "Point.h"
```

Include dependency graph for Simulation.h:



This graph shows which files directly or indirectly include this file:



Classes

· class Simulation

Functions

- void out_of_bounds_msg (const std::string &par)
- void invalid_interval_msg (const std::string ¶m1, const std::string ¶m2)

7.35.1 Function Documentation

7.35.1.1 invalid_interval_msg()

Here is the caller graph for this function:



7.36 Simulation.h

7.35.1.2 out_of_bounds_msg()

Here is the caller graph for this function:



7.36 Simulation.h

Go to the documentation of this file.

```
00001 #ifndef SIMULATION H
00002 #define SIMULATION_H
00003
00004 #include <array>
00005 #include <vector>
00006 #include <string> // for error messages
00007 #include "constants.h"
00008 #include "Params.h"
00009 #include "Point.h"
00010
00011 using namespace constants;
00012
00013 void out_of_bounds_msg(const std::string& par);
00014 void invalid_interval_msg(const std::string& param1, const std::string& param2);
00016 \ensuremath{//} Sets up and controls the flow of the simulation.
00017 class Simulation {
00018 public:
00019
          Simulation (ProgressionParams &prog, AreaParams &area, LifeParams &life, ReleaseParams &rel,
     DispersalParams &disp,
00020
          AestivationParams &aes, InitialPopsParams &initial, RecordParams &rec);
00021
          void set_coords(const std::string& coords_file);
00022
          void set_boundary_type (BoundaryType boundary);
00023
          void set_dispersal_type(DispersalType disp);
00024
          void set_inheritance(InheritanceParams inher_params);
00025
          void run_reps();
00027 private:
00028
          int num_runs; // number of simulation replicates to run
00029
          int max_t; // maximum simulated time (in days)
00030
          AreaParams *area_params; // model area parameters
00031
          LifeParams *life_params; // model life-process parameters
00032
00033
          ReleaseParams *rel_params; // gene drive release model parameters
          DispersalParams *disp_params; // dispersal model parameters
AestivationParams *aes_params; // aestivation model parameters
00034
00035
          InitialPopsParams *initial_params; // initial population values
00036
00037
          RecordParams *rec_params; // data-recording parameters
00038
00039
          // additional parameter options
00040
          std::vector<Point> sites_coords; // 2D coordinates for the sites on the simulated square
00041
          BoundaryType boundary_type;
          DispersalType disp_type;
00042
00043
00044
          // inheritance
          // f_ijk is the fraction of genotype k offspring from mother with genotype i mated to father with
00046
          std::array<std::array<std::array<std::num_gen>, num_gen>, num_gen> inher_fraction;
00047 };
00048
00049 #endif //SIMULATION_H
```

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