



Perceptron與多層感知器(Multi-Layer Perceptrons)

林郁修

Yu-Hsiu Lin

yhlin@ntut.edu.tw

<https://sites.google.com/view/aici>

*Graduate Institute of Automation Technology,
National Taipei University of Technology*

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Outline

- 機器學習的架構
- 感知器 (Perceptron)
- 感知器的學習
- 感知器 VS. 多層感知器 (Multi-Layer Perceptrons)
- 多層感知器的學習

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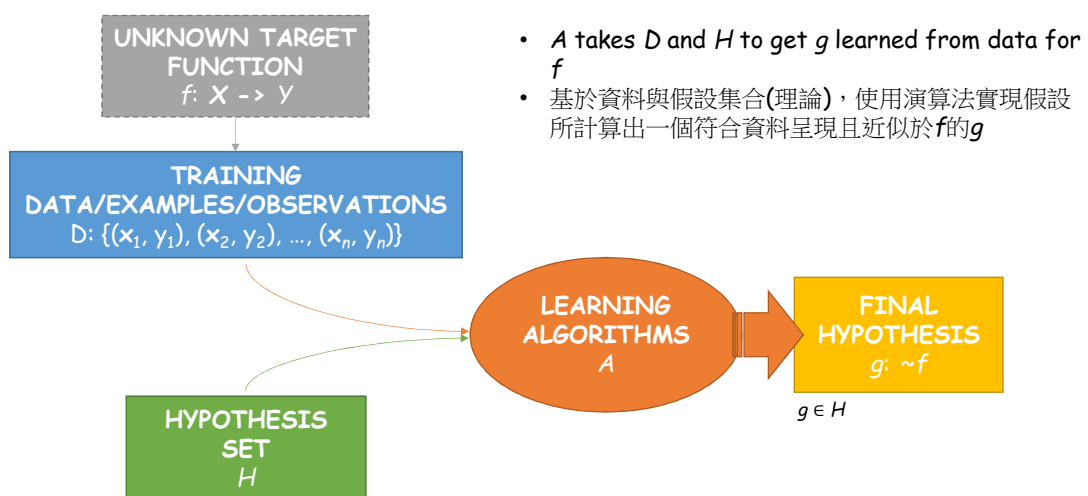
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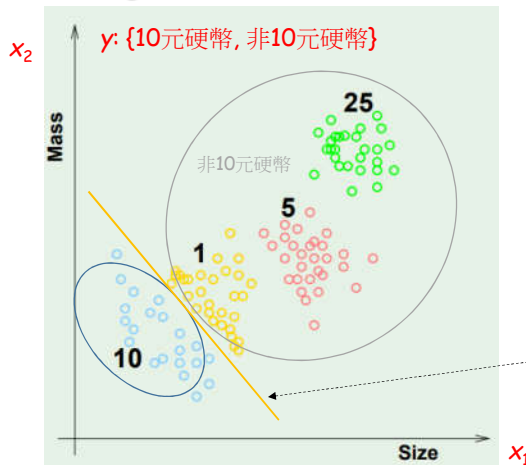
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機器學習的架構



• coin recognition



- 資料集 D (每一筆資料由2維特徵/屬性所組成) 作為 (訓練) 資料
- 自機器學習理論 H 實踐演算法 A 找出 g

the perceptron that can also be used to Approve/Deny credits ... for Credit Analysis

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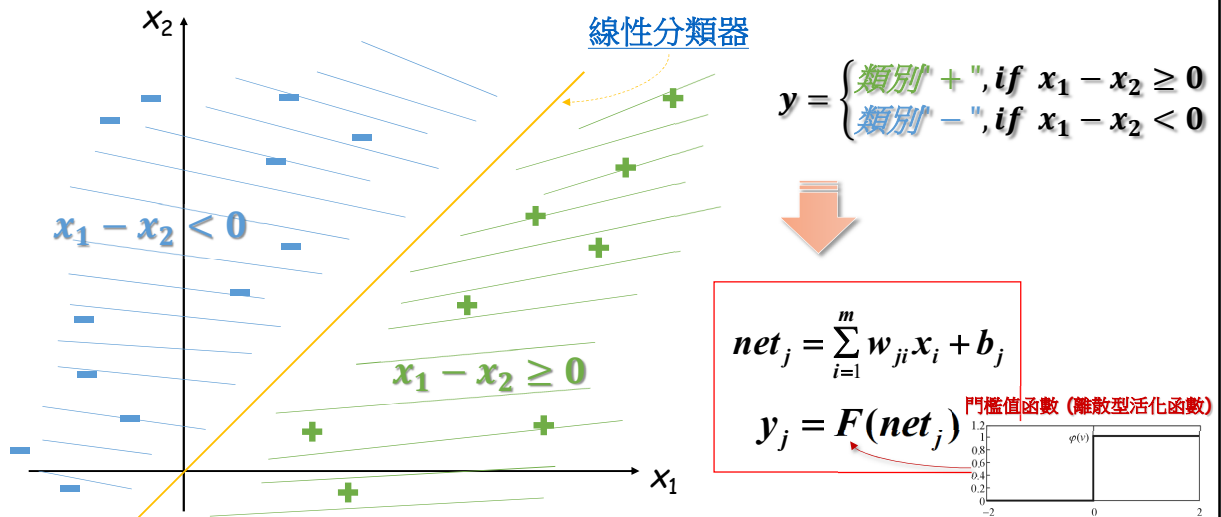
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感知器 (Perceptron)

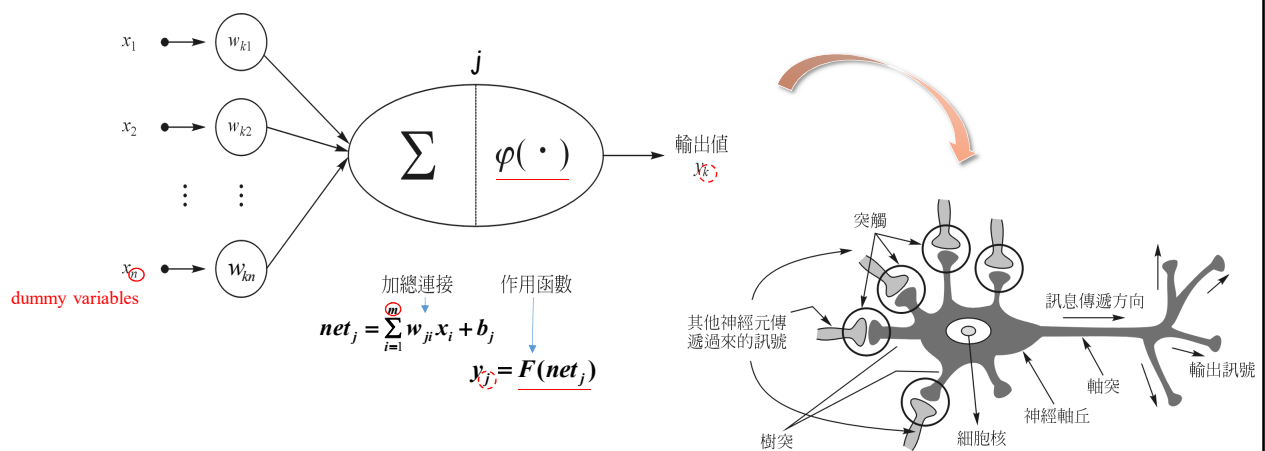


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• 感知器/類神經元(neuron)數學模型 -- Rosenblatt (1958)



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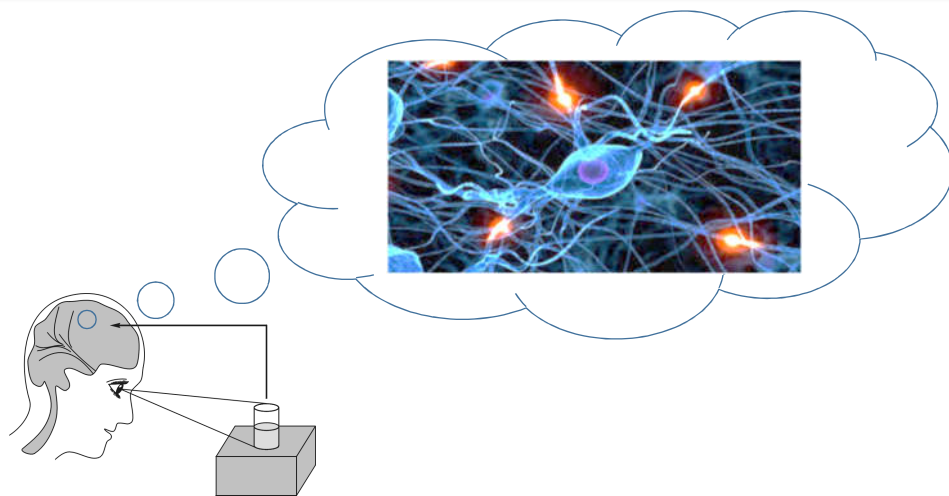
- 生物大腦中約有數十億個到數百億個神經元，有的神經元間沒有相互連結，有的則以非常錯綜複雜的方式相連結，甚至有環狀或有回饋(**feedback**)式的連結
- 生物對新事物的學習(**learning**)，基本上是造成神經元間連結(**weights**)強弱的改變(**weighting**)，或是使原本沒有連結的神經元間產生新的連結
 - 連結權重 w_{ji} 即模擬不同生物神經元之間的連結強弱
 - 連結權重值可為正亦可為負；分別代表**刺激**或是**抑制**反應
- 神經元太少無法處理較複雜的問題
 - 深度學習的發展



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- Activations functions

- Identity



- TanH

$$\tanh(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}}$$



- Rectified Linear Unit (ReLU)



- ...

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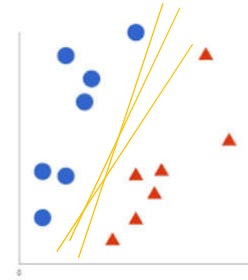
感知器的學習 (Perceptron Learning Algorithm)

- 為何需要“學習”？

- 平面中可以有無限多條的決策線 (超平面(hyper-plane)/決策邊界(decision boundaries))...
- 高維度的特徵空間 (feature space)
- ...



1. 隨機決定一條決策線
2. 分類錯誤
3. “修正”參數



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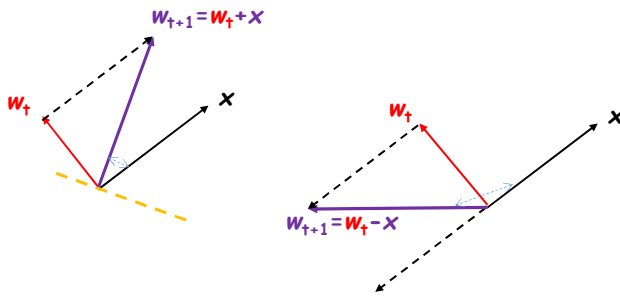
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- PLA

- 決策超平面: 兩個多維度的向量做內積 $w^T x$

- 向量加、減法



$$y = \begin{cases} \text{類別} + 1, & \text{if } x_1 - x_2 \geq 0 \\ \text{類別} - 1, & \text{if } x_1 - x_2 < 0 \end{cases}$$

$$\Delta w_j = \eta \left[d - \text{sgn}(w_j^T x) \right] x$$

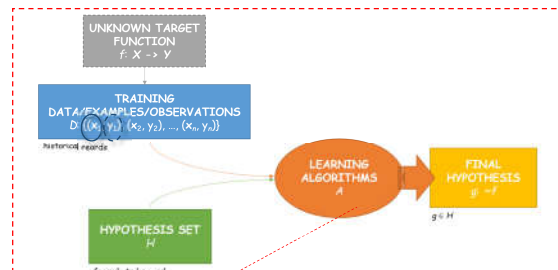
$$\Delta w_j = \begin{cases} \pm 2\eta x, & \text{目標值與類神經元輸出值不一致} \\ 0, & \text{目標值與類神經元輸出值一致} \end{cases}$$



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$$\Delta w_j = \eta [\bar{d} - \text{sgn}(w_j^T \bar{x})] \bar{x}$$

$$\Delta w_j = \begin{cases} \pm 2\eta \bar{x} & \text{目標值與類神經元輸出值不一致} \\ 0 & \text{目標值與類神經元輸出值一致} \end{cases}$$

PLA pseudo-code (參考)

- If a mis-classification exists, a perceptron that aims to classify all patterns correctly is trained.

```

1: initialize weight vector  $\vec{w}$  and bias weight  $w_0$  arbitrarily
2: while exist misclassified pattern  $\vec{x} \in \mathcal{P} \cup \mathcal{N}$  do
3:   if  $\vec{x} \in \mathcal{P}$  then
4:      $\vec{w} \leftarrow \vec{w} + \vec{x}$ 
5:      $w_0 \leftarrow w_0 + 1$ 
6:   else
7:      $\vec{w} \leftarrow \vec{w} - \vec{x}$ 
8:      $w_0 \leftarrow w_0 - 1$ 
9:   end if
10: end while
11: return  $\vec{w}$  and  $w_0$ 

```

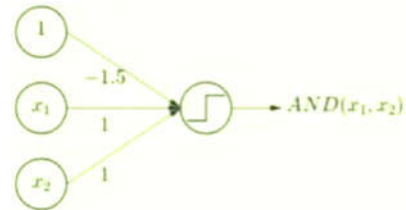
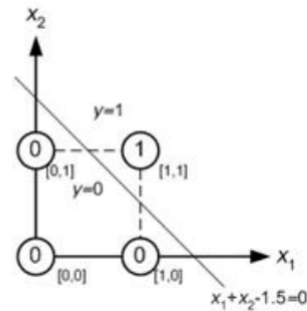
\mathcal{P} : positive training patterns

\mathcal{N} : negative training patterns

Assignment #1 (Part I)

- 解決AND gate分類問題
- 利用Perceptron學習法(PLA)更新感知器的權重值

x_1	x_2	y
0	0	0
0	1	0
1	0	0
1	1	1



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epoch

- $w_{t=0} = (0.5, 0.5, 0.5) \leftarrow 0.5x_1 + 0.5x_2 + 0.5$ (the initial decision boundary)
- $w_1 = w_0 - x = (0.5, 0.5, 0.5) - (0, 0, 1) = (0.5, 0.5, -0.5)$
 $0.5x_1 + 0.5x_2 - 0.5$
- $w_2 = w_1 - x = (0.5, 0.5, -0.5) - (0, 1, 1) = (0.5, -0.5, -1.5)$
 $0.5x_1 - 0.5x_2 - 1.5$
- $w_3 = w_2$
- $w_4 = w_3 + x = (0.5, -0.5, -1.5) + (1, 1, 1) = (1.5, 0.5, -0.5)$
 $1.5x_1 + 0.5x_2 - 0.5$
- $w_5 = w_4$
- $w_6 = w_5 - x = (1.5, 0.5, -0.5) - (0, 1, 1) = (1.5, -0.5, -1.5)$
 $1.5x_1 - 0.5x_2 - 1.5$
- ...

$$\Delta w_j = \eta [d - \text{sgn}(w_j^T x)] x$$

$$\Delta w_j = \begin{cases} \pm 2\eta x, & \text{目標值與類神經元輸出值不一致} \\ 0, & \text{目標值與類神經元輸出值一致} \end{cases}$$

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- the code

```
import numpy as np

inputs = []
inputs.append(np.array([1, 1, 1]))
inputs.append(np.array([1, 0, 1]))
inputs.append(np.array([0, 1, 1]))
inputs.append(np.array([0, 0, 1]))

labels = np.array([1, 0, 0, 0])

Iters = 10

no_of_inputs = 2
weights = np.random.randn(no_of_inputs + 1)
print("initial: " + str(weights))

learning_rate = 0.15
```

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```
# cont'd
for _ in range(Iters):
    for _input, label in zip(inputs, labels):

        summation = np.dot(_input, weights) # dot product

        if summation > 0: # the step activation function
            predicted = 1
        else:
            predicted = 0

        weights += learning_rate * (label - predicted) * _input

print("trained: " + str(weights))
```

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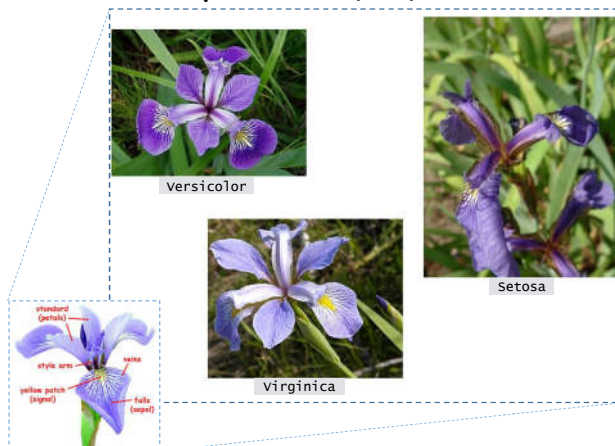
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- initial:
[0.73421793 -0.38731 0.85634143]
- trained:
[0.13421793 0.06269 -0.19365857]

Assignment #1 (Part II)

- 解決Iris鳶尾花分類問題
- 利用Perceptron學習法(PLA)更新感知器（階層式）的權重值



Samples (instances, observations)

	Sepal length	Sepal width	Petal length	Petal width	Class label
1	5.1	3.5	1.4	0.2	Setosa
2	4.9	3.0	1.4	0.2	Setosa
...
50	6.4	3.5	4.5	1.2	Versicolor
...
150	5.9	3.0	5.0	1.8	Virginica

Features (attributes, measurements, dimensions)

Class labels (targets)

Assignment #1 (Part II) (Cont'd)

• Hints

- `import pandas as pd`
- `iris = pd.read_csv('https://raw.githubusercontent.com/mwaskom/seaborn-data/master/iris.csv')`
- `iris.head()`

	sepal_length	sepal_width	petal_length	petal_width	species
0	5.1	3.5	1.4	0.2	setosa
1	4.9	3.0	1.4	0.2	setosa
2	4.7	3.2	1.3	0.2	setosa
3	4.6	3.1	1.5	0.2	setosa
4	5.0	3.6	1.4	0.2	setosa

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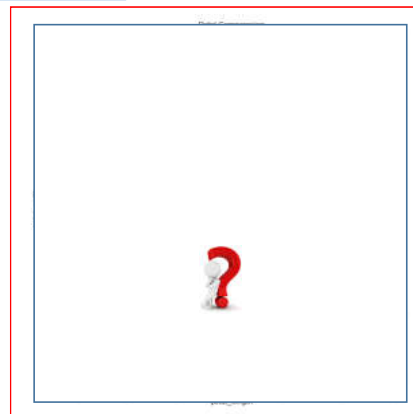
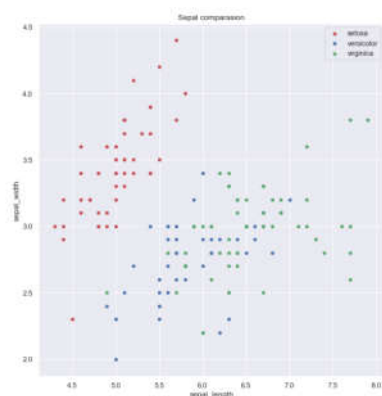
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Assignment #1 (Part II) (Cont'd)

• Hints (Cont'd)

- 特徵選取於變量使用：sepal length vs. sepal width, sepal length vs. petal width, or ...
- <https://ithelp.ithome.com.tw/articles/10264416>



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• Hints (Cont'd)

- https://scikit-learn.org/stable/modules/generated/sklearn.model_selection.train_test_split.html
- <https://scikit-learn.org/stable/modules/generated/sklearn.utils.resample.html>

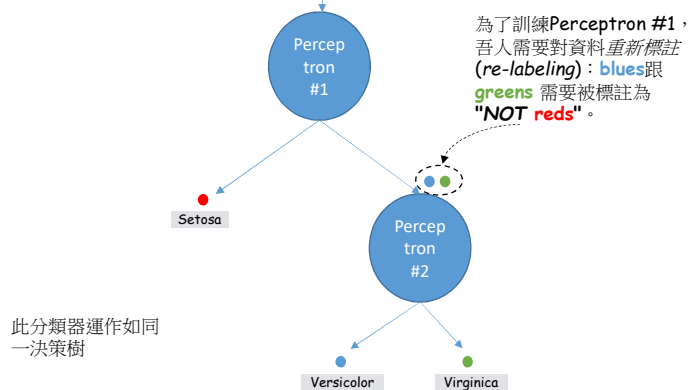
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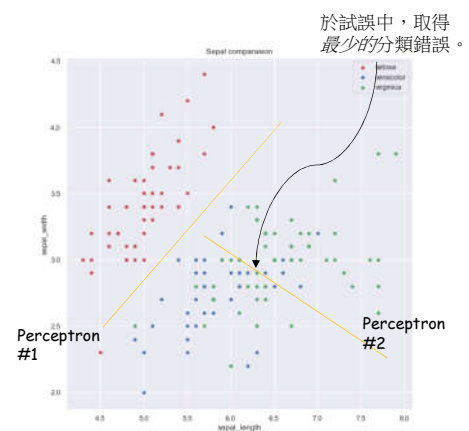
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• Hints (Cont'd)

- 階層式二元分類Perceptrons



- 若某一筆資料輸入至Perceptron #1且被分類為"非Setosa"，則該筆資料被接著輸入至Perceptron #2。
- 其中，該筆資料的類別可能為"Versicolor"或"Virginica"。



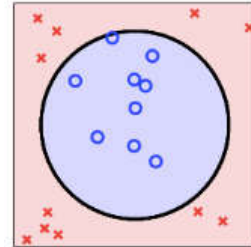
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- Hints (Cont'd)

- 什麼情況PLA不會停止？
 - 資料分佈為非線性可分離 (non-linearly separable)
 - 有限的PLA學習迭代次數



- POCKET ALGORITHM

- 雜訊資料 (真實世界一定存在著分類錯誤情況 (*nothing is perfect*))
- 口袋名單 ($g \in H$)

- Hints (Cont'd)

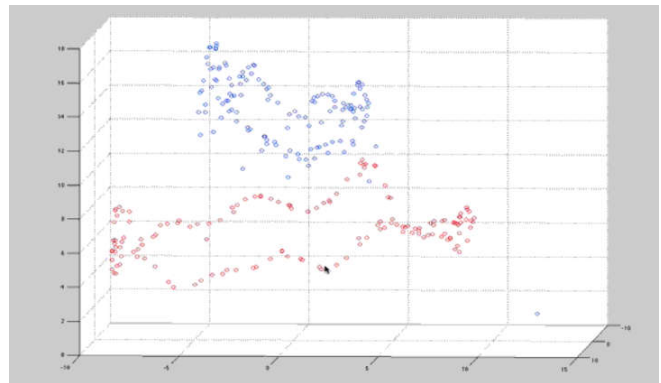
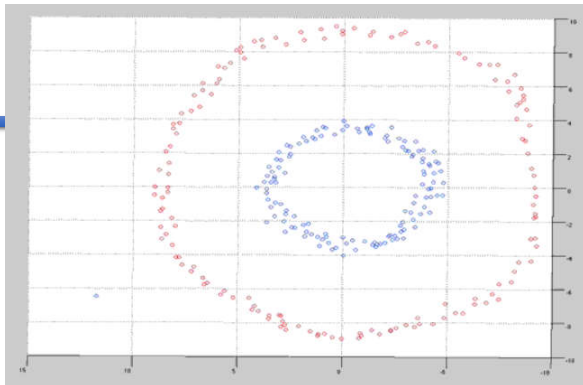
- https://scikit-learn.org/stable/modules/generated/sklearn.metrics.accuracy_score.html

- 需說明特徵選取(考量哪兩個特徵作為分類器的輸入變量)
- 需視覺化呈現決策邊界
- 佔本課程學期總成績**15%**
- Due : 4/5(三), 2023 23:59前上傳PPT檔至i學園作業繳交區
- Oral: 4/6(四), 2023 約10分鐘/人

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Perceptron Convergence Theorem (參考)

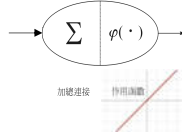
- <http://www.cs.columbia.edu/~mccollins/courses/6998-2012/notes/perc.converge.pdf>
- <http://www.cems.uvm.edu/~rsnapp/teaching/cs295ml/notes/perceptron.pdf>

(參考)

學習演算法	Δw_{ji}	初始權重	學習法	神經元特性
Hebbian	$\eta y_j x_i(t)$	0	非監督式	任意
Perceptron	$\eta [d_j - \text{sgn}(w_j x)] x_i$	任意	監督式	binary/bi-polar
Delta	$\eta (d_j - y_j) f'(net_j) x$	任意	監督式	連續
Widrow-Hoff	$\eta (d_j - w_j x) x$	任意	監督式	任意
Correlation	$\eta d_j x$	0	監督式	任意
Winner-takes-all	$\alpha (x_i - w_{mi})$	任意 (正規化)	非監督式	連續
Grossberg	$\beta (d_m - w_{mi})$	0	監督式	連續

連續型活化函數

- Perceptron: $y=f(x)=w \cdot x$
- Activation function: Identity

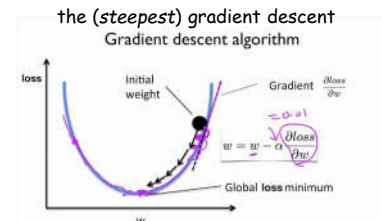


- Error function/cost function:

$$E(w) = \frac{1}{2} (\underbrace{d}_{\text{期望}} - \underbrace{y}_{\text{預測}})^2$$

- Goal: Learn the output towards the value of 50
– $x=5$

- Derivatives: $[(d-w \cdot x)(-x)]$
- Learning: $\Delta w = -\eta [(d-w \cdot x)(-x)]$



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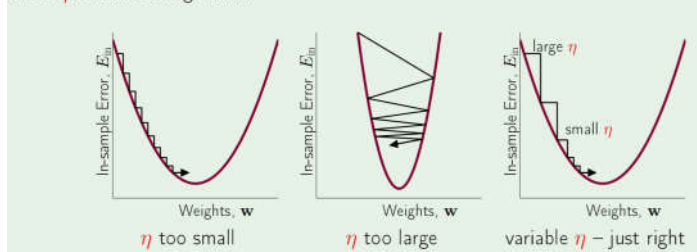
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- $\eta: 0.01 (\in (0, 1))$

- Results ($\Delta w = +\eta[(d-w \cdot x)(x)]$):

– $7 * 5 = 35$
 – $8.5 * 5 = 42.5$
 – $9.25 * 5 = 46.25$
 – $9.625 * 5 = 48.125$
 – $9.8125 * 5 = 49.0625$
 – $9.90625 * 5 = 49.5312$
 – ...
 – $9.98828 * 5 = 49.9414$
 – $9.99414 * 5 = 49.9707$

How η affects the algorithm:



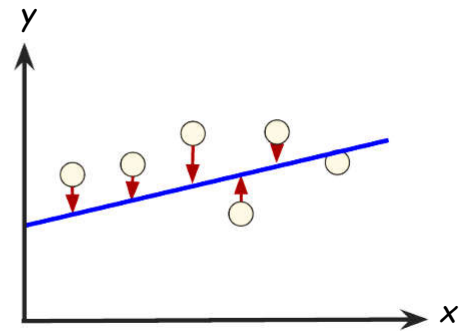
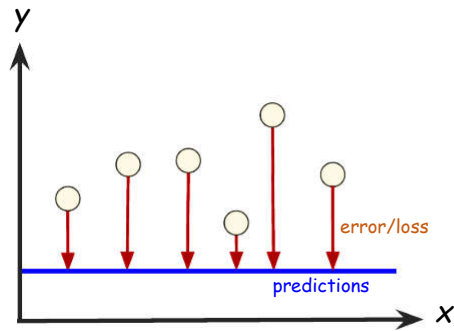
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$$\text{MSE} = \frac{1}{N} \sum_{i=1}^N (\underbrace{y_i}_{\text{期望}} - \underbrace{\hat{y}_i}_{\text{预测}})^2$$

(Mean Squared Error)



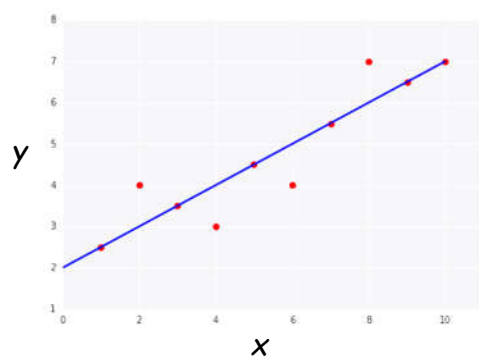
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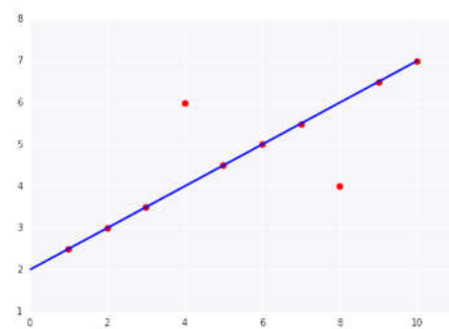
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L2損失函數/最小化平方誤差
(Least Square Error)

$$\text{MSE} = \frac{1}{N} \sum_{i=1}^N (y_i - \hat{y}_i)^2$$



?



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```

• import numpy as np

• inputs = [] # x
• inputs.append(np.array([0.922]))
• inputs.append(np.array([0.459]))
• inputs.append(np.array([0.984]))
• inputs.append(np.array([0.794]))
• inputs.append(np.array([0.119]))
• inputs.append(np.array([0.258]))
• inputs.append(np.array([0.734]))
• inputs.append(np.array([0.123]))
• inputs.append(np.array([0.713]))
• inputs.append(np.array([0.943]))

• labels = np.array([0.559, 0.298, 0.639, 0.516, 0.077, 0.167, 0.477, 0.079, 0.463, 0.612]) # y

• Iters = 10

• no_of_inputs = 1
• np.random.seed(55)
• weights = np.random.randn(no_of_inputs)
• print("initial: " + str(weights))

• learning_rate = 0.1

```

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```

• Err = []
• #_W = []
• for _ in range(Iters):
•     err = 0
•     W = []
•     for _input, label in zip(inputs, labels):
•         predicted = np.dot(_input, weights) # dot product
•         weights -= learning_rate * (label - predicted) * (-1) * _input
•         err += (label - predicted)** 2
•         #W.append(weights)
•     Err.append(err/len(inputs))
•     #_W.append(np.std(W))

• print("trained: " + str(weights))

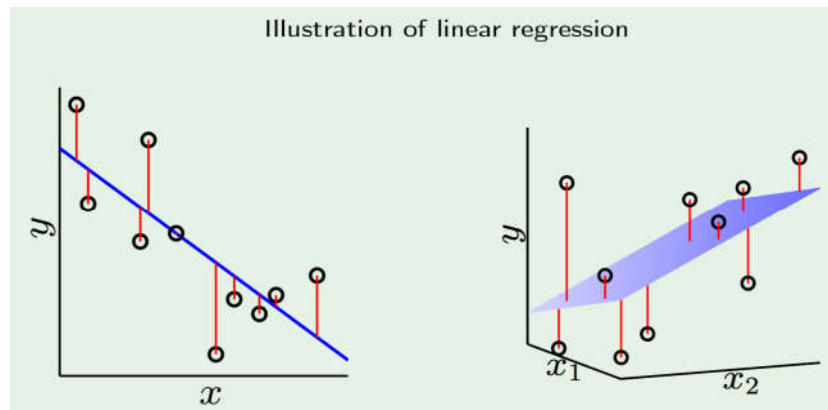
• import matplotlib.pyplot as plt
• %pylab inline
• plt.plot(range(0, len(Err)), Err)
• plt.xlabel('Iteration')
• plt.ylabel('loss/error')

```

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Hyper-plane!?