## TenezBot (Group: 10) UML Class Diagram Pruthvi Sanghavi (116951005) | Achal Vyas (116869560)

RoboTrack
- roboCoord : vector
+ getOdometry()

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BallCollect
+ cmdMotor : bool + collectMotor : bool
+ ballproximity() + commandMotor() + collectBall() + roboReach(coord, angle)

## BallReach - ballCoord : int + ballDetect() + ballproximity() + forward() + stop() + homeState() + roboRotate() + getRobotOdom() + roboReach(coord, angle)