

Data Structures and Algorithms

Lecture 4: Analysis of Algorithms



Introduction

■ What is Algorithm?

- ◆ a clearly specified **set of simple instructions** to be followed to solve a problem
 - Takes a set of values, as input and
 - produces a value, or set of values, as output
- ◆ May be specified
 - In English
 - As a computer program
 - As a pseudo-code

■ Data structures

- ◆ Methods of organizing data

■ Program = algorithms + data structures

Introduction

- Why need algorithm analysis ?
 - ◆ writing a working program is not good enough
 - ◆ The program may be inefficient!
 - ◆ If the program is run on a **large data set**, then the running time becomes an issue

Example: Selection Problem

- Given a list of N numbers, determine the k th **largest**, where $k \leq N$.
- Algorithm 1:
 - (1) Read N numbers into an array
 - (2) Sort the array in decreasing order by some simple algorithm
 - (3) Return the element in position k

Example: Selection Problem...

■ Algorithm 2:

- (1) Read the first k elements into an array and sort them in decreasing order
- (2) Each remaining element is read one by one
 - If smaller than the k th element, then it is ignored
 - Otherwise, it is placed in its correct spot in the array, bumping one element out of the array.
- (3) The element in the k th position is returned as the answer.

Example: Selection Problem...

- Which algorithm is better when
 - ◆ $N = 100$ and $k = 100$?
 - ◆ $N = 100$ and $k = 1$?
- What happens when $N = 1,000,000$ and $k = 500,000$?
- There exist better algorithms

Algorithm Analysis

- We only analyze *correct* algorithms
- An algorithm is correct
 - ◆ If, for every input instance, it halts with the correct output
- Incorrect algorithms
 - ◆ Might not halt at all on some input instances
 - ◆ Might halt with other than the desired answer
- Analyzing an algorithm
 - ◆ **Predicting** the resources that the algorithm requires
 - ◆ Resources include
 - Memory
 - Communication bandwidth
 - Computational time (usually most important)

Algorithm Analysis...

■ Factors affecting the running time

- ◆ computer
- ◆ compiler
- ◆ algorithm used
- ◆ input to the algorithm
 - The content of the input affects the running time
 - typically, the *input size* (number of items in the input) is the main consideration
 - E.g. sorting problem \Rightarrow the number of items to be sorted
 - E.g. multiply two matrices together \Rightarrow the total number of elements in the two matrices

■ Machine model assumed

- ◆ Instructions are executed one after another, with no concurrent operations \Rightarrow Not parallel computers

Example

- Calculate

$$\sum_{i=1}^N i^3$$

```
int sum(int n)
{
    int partialSum;

    1  partialSum=0;           1
    2  for (int i=1;i<=n;i++)  2N+2
    3      partialSum += i*i*i; 4N
    4  return partialSum;      1
}
```

- Lines 1 and 4 count for one unit each
- Line 3: executed N times, each time four units
- Line 2: (1 for initialization, N+1 for all the tests, N for all the increments) total $2N + 2$
- total cost: $6N + 4 \Rightarrow O(N)$

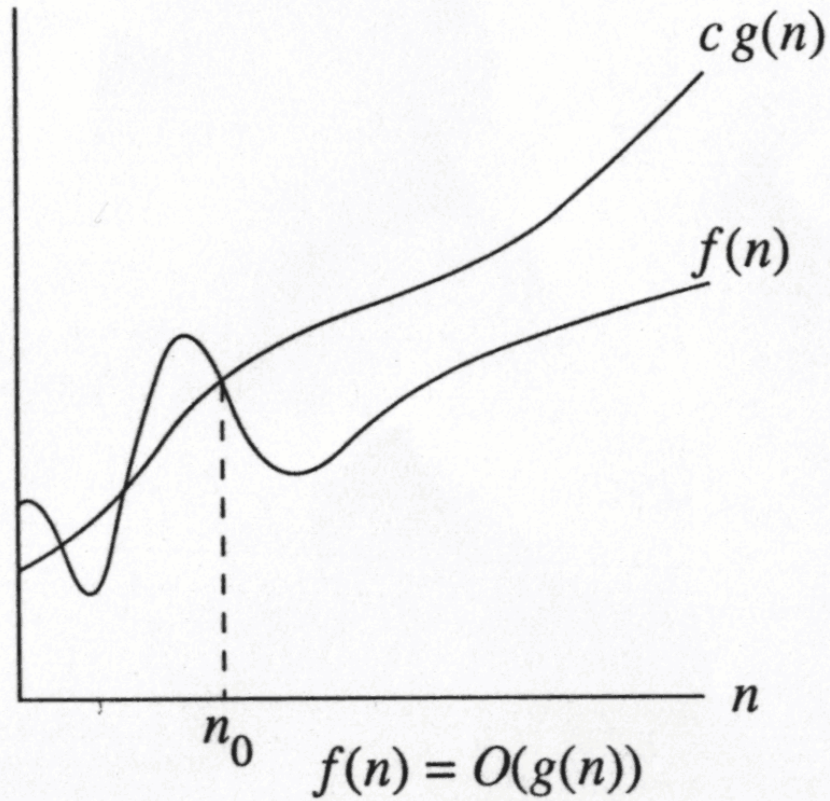
Worst- / average- / best-case

- Worst-case running time of an algorithm
 - ◆ The longest running time for **any** input of size n
 - ◆ An upper bound on the running time for any input
 - ⇒ guarantee that the algorithm will never take longer
 - ◆ Example: Sort a set of numbers in increasing order; and the data is in decreasing order
 - ◆ The worst case can occur fairly often
 - E.g. in searching a database for a particular piece of information
- Best-case running time
 - ◆ sort a set of numbers in increasing order; and the data is already in increasing order
- Average-case running time
 - ◆ May be difficult to define what “average” means

Running-time of algorithms

- Bounds are for the **algorithms**, rather than **programs**
 - ◆ programs are just implementations of an algorithm, and almost always the details of the program do not affect the bounds
- Bounds are for **algorithms**, rather than **problems**
 - ◆ A problem can be solved with several algorithms, some are more efficient than others

Growth Rate



- The idea is to establish a relative order among functions **for large n**
- $\exists c, n_0 > 0$ such that **$f(N) \leq c g(N)$ when $N \geq n_0$**
- $f(N)$ grows no faster than $g(N)$ for “large” N

Asymptotic notation: Big-Oh

- $f(N) = O(g(N))$
- There are positive constants c and n_0 such that
$$f(N) \leq c g(N) \text{ when } N \geq n_0$$
- The growth rate of $f(N)$ is *less than or equal to* the growth rate of $g(N)$
- $g(N)$ is an upper bound on $f(N)$

Big-Oh: example

- Let $f(N) = 2N^2$. Then
 - ◆ $f(N) = O(N^4)$
 - ◆ $f(N) = O(N^3)$
 - ◆ $f(N) = O(N^2)$ (best answer, asymptotically tight)
- $O(N^2)$: reads “order N-squared” or “Big-Oh N-squared”

Big Oh: more examples

- $N^2 / 2 - 3N = O(N^2)$
- $1 + 4N = O(N)$
- $7N^2 + 10N + 3 = O(N^2) = O(N^3)$
- $\log_{10} N = \log_2 N / \log_2 10 = O(\log_2 N) = O(\log N)$
- $\sin N = O(1); 10 = O(1), 10^{10} = O(1)$
- $$\sum_{i=1}^N i \leq N \cdot N = O(N^2)$$
$$\sum_{i=1}^N i^2 \leq N \cdot N^2 = O(N^3)$$
- $\log N + N = O(N)$
- $\log^k N = O(N)$ for any constant k
- $N = O(2^N)$, but 2^N is not $O(N)$
- 2^{10N} is not $O(2^N)$

Math Review: logarithmic functions

$$x^a = b \quad \text{iff} \quad \log_x b = a$$

$$\log ab = \log a + \log b$$

$$\log_a b = \frac{\log_m b}{\log_m a}$$

$$\log a^b = b \log a$$

$$a^{\log n} = n^{\log a}$$

$$\log^b a = (\log a)^b \neq \log a^b$$

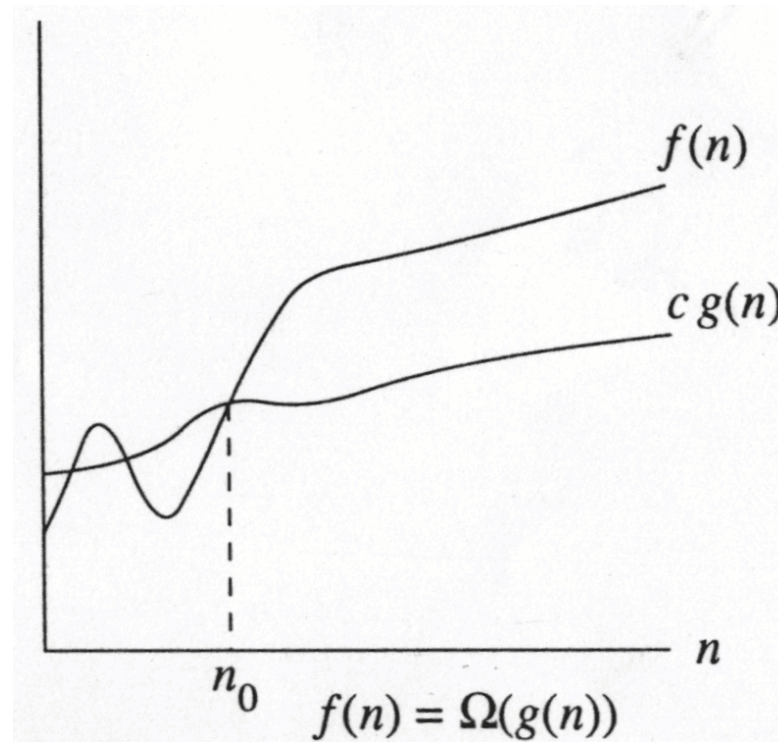
$$\frac{d \log_e x}{dx} = \frac{1}{x}$$

Some rules

When considering the growth rate of a function using Big-Oh

- Ignore the lower order terms and the coefficients of the highest-order term
- No need to specify the base of logarithm
 - ◆ Changing the base from one constant to another changes the value of the logarithm by only a constant factor
- If $T_1(N) = O(f(N))$ and $T_2(N) = O(g(N))$, then
 - ◆ $T_1(N) + T_2(N) = \max(O(f(N)), O(g(N)))$,
 - ◆ $T_1(N) * T_2(N) = O(f(N) * g(N))$

Big-Omega



- $\exists c, n_0 > 0$ such that $f(N) \geq c g(N)$ when $N \geq n_0$
- $f(N)$ grows no slower than $g(N)$ for “large” N

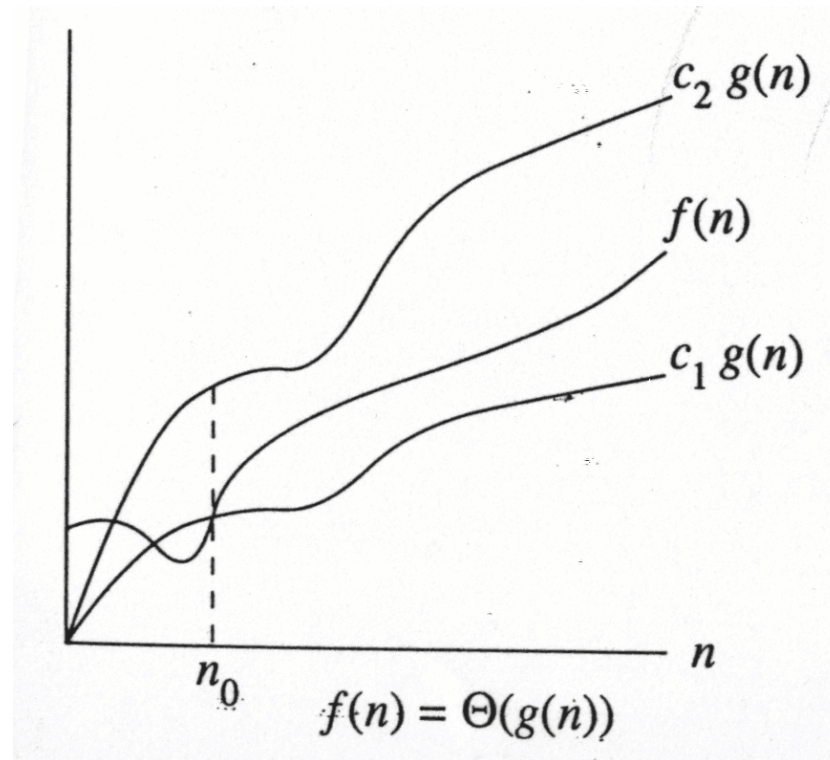
Big-Omega

- $f(N) = \Omega(g(N))$
- There are positive constants c and n_0 such that
$$f(N) \geq c g(N) \text{ when } N \geq n_0$$
- The growth rate of $f(N)$ is *greater than or equal to* the growth rate of $g(N)$.

Big-Omega: examples

- Let $f(N) = 2N^2$. Then
 - ◆ $f(N) = \Omega(N)$
 - ◆ $f(N) = \Omega(N^2)$ (best answer)

$$f(N) = \Theta(g(N))$$



- the growth rate of $f(N)$ *is the same as* the growth rate of $g(N)$

Big-Theta

- $f(N) = \Theta(g(N))$ iff
 $f(N) = O(g(N))$ and $f(N) = \Omega(g(N))$
- The growth rate of $f(N)$ *equals* the growth rate of $g(N)$
- Example: Let $f(N)=N^2$, $g(N)=2N^2$
 - ◆ Since $f(N) = O(g(N))$ and $f(N) = \Omega(g(N))$,
thus $f(N) = \Theta(g(N))$.
- Big-Theta means the bound is the tightest possible.

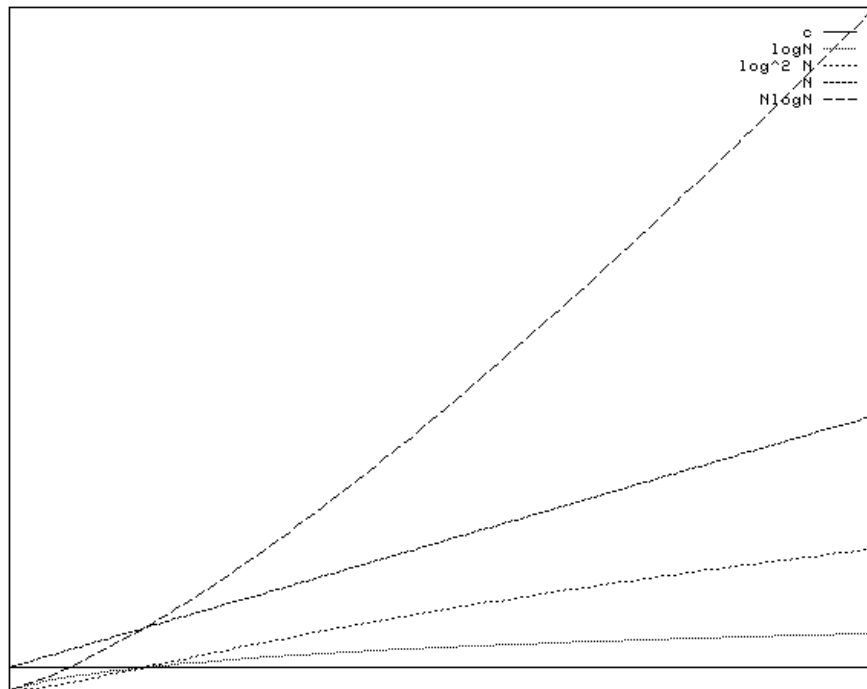
Some rules

- If $T(N)$ is a polynomial of degree k , then
$$T(N) = \Theta(N^k).$$
- For logarithmic functions,
$$T(\log_m N) = \Theta(\log N).$$

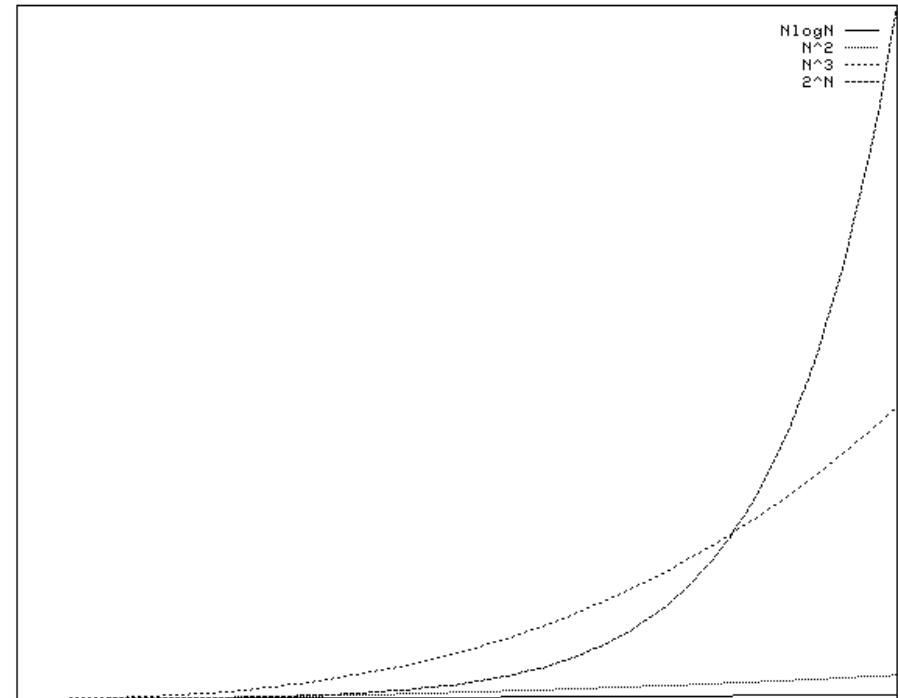
Typical Growth Rates

Function	Name
c	Constant
$\log N$	Logarithmic
$\log^2 N$	Log-squared
N	Linear
$N \log N$	
N^2	Quadratic
N^3	Cubic
2^N	Exponential

Figure 2.1 Typical growth rates



N



N

Growth rates ...

■ Doubling the input size

- ◆ $f(N) = c \Rightarrow f(2N) = f(N) = c$
- ◆ $f(N) = \log N \Rightarrow f(2N) = f(N) + \log 2$
- ◆ $f(N) = N \Rightarrow f(2N) = 2 f(N)$
- ◆ $f(N) = N^2 \Rightarrow f(2N) = 4 f(N)$
- ◆ $f(N) = N^3 \Rightarrow f(2N) = 8 f(N)$
- ◆ $f(N) = 2^N \Rightarrow f(2N) = f^2(N)$

■ Advantages of algorithm analysis

- ◆ To eliminate bad algorithms early
- ◆ pinpoints the bottlenecks, which are worth coding carefully

Using L' Hopital's rule

- L' Hopital's rule

- ◆ If $\lim_{n \rightarrow \infty} f(N) = \infty$ and $\lim_{n \rightarrow \infty} g(N) = \infty$

- then $\lim_{n \rightarrow \infty} \frac{f(N)}{g(N)} = \lim_{n \rightarrow \infty} \frac{f'(N)}{g'(N)}$

- Determine the relative growth rates (using L' Hopital's rule if necessary)

- ◆ compute $\lim_{n \rightarrow \infty} \frac{f(N)}{g(N)}$

- ◆ if 0: $f(N) = O(g(N))$ and $f(N)$ is not $\Theta(g(N))$

- ◆ if constant $\neq 0$: $f(N) = \Theta(g(N))$

- ◆ if ∞ : $f(N) = \Omega(g(N))$ and $f(N)$ is not $\Theta(g(N))$

- ◆ limit oscillates: no relation

General Rules

- For loops

- ◆ at most the running time of the statements inside the for-loop (including tests) times the number of iterations.

- Nested for loops

```
for (i=0;i<n;i++)  
    for (j=0;j<n;j++)  
        k++;
```

- ◆ the running time of the statement multiplied by the product of the sizes of all the for-loops.
- ◆ $O(N^2)$

General rules (cont'd)

■ Consecutive statements

```
for (i=0;i<n;i++)  
    a[i]=0;  
for (i=0;i<n;i++)  
    for (j=0;j<n;j++)  
        a[i] += a[j]+i+j;
```

- ◆ These just add
- ◆ $O(N) + O(N^2) = O(N^2)$

■ If S1

Else S2

- ◆ never more than the running time of the test plus the larger of the running times of S1 and S2.

Another Example

- Maximum Subsequence Sum Problem
- Given (possibly negative) integers A_1, A_2, \dots, A_n , find the maximum value of
$$\sum_{k=i}^j A_k$$
 - ◆ For convenience, the maximum subsequence sum is 0 if all the integers are negative
- E.g. for input $-2, 11, -4, 13, -5, -2$
 - ◆ Answer: 20 (A_2 through A_4)

Algorithm 1: Simple

- Exhaustively tries all possibilities (brute force)

```
int maxSubSum1 (const vector<int> &a)
{
    int maxSum=0;

    for (int i=0;i<a.size();i++)
        for (int j=i;j<a.size();j++)
        {
            int thisSum=0;

            for (int k=i;k<=j;k++)
                thisSum += a[k];

            if (thisSum > maxSum)
                maxSum = thisSum;
        }
    return maxSum;
}
```

- $O(N^3)$

Algorithm 2: Divide-and-conquer

■ Divide-and-conquer

- ◆ split the problem into two roughly equal subproblems, which are then solved **recursively**
- ◆ patch together the two solutions of the subproblems to arrive at a solution for the whole problem

First half				Second half			
4	-3	5	-2	-1	2	6	-2

- The maximum subsequence sum can be
 - Entirely in the left half of the input
 - Entirely in the right half of the input
 - It crosses the middle and is in both halves

Algorithm 2 (cont'd)

The first two cases can be solved recursively

■ For the last case:

- ◆ find the largest sum in the first half **that includes the last element in the first half**
- ◆ the largest sum in the second half **that includes the first element in the second half**
- ◆ add these two sums together

1	-5	4	2	-7	3	6	-1		2	-4	7	-10	2	6	1	-3
1	-5	4	2	-7	3	6	-1		2	-4	7	-10	2	6	1	-3

Algorithm 2 ...

// Input : $A[i \dots j]$ with $i \leq j$

// Output : the MCS of $A[i \dots j]$

$MCS(A, i, j)$

1. If $i == j$ return $A[i]$ $O(1)$
2. Else
3. Find $MCS(A, i, \lfloor \frac{i+j}{2} \rfloor)$; $T(m/2)$
4. Find $MCS(A, \lfloor \frac{i+j}{2} \rfloor + 1, j)$; $T(m/2)$
5. Find MCS that contains $O(m)$
 $both\ A[\lfloor \frac{i+j}{2} \rfloor] \text{ and } A[\lfloor \frac{i+j}{2} \rfloor + 1];$
6. Return Maximum of the three sequences found $O(1)$

Algorithm 2 (cont'd)

- Recurrence equation

$$T(1) = 1$$

$$T(N) = 2T\left(\frac{N}{2}\right) + N$$

- ◆ $2 T(N/2)$: two subproblems, each of size $N/2$
- ◆ N : for “patching” two solutions to find solution to whole problem

Algorithm 2 (cont'd)

- Solving the recurrence:

$$\begin{aligned}T(N) &= 2T\left(\frac{N}{2}\right) + N \\&= 4T\left(\frac{N}{4}\right) + 2N \\&= 8T\left(\frac{N}{8}\right) + 3N \\&= \dots \\&= 2^k T\left(\frac{N}{2^k}\right) + kN\end{aligned}$$

- With $k = \log N$ (i.e. $2^k = N$), we have

$$\begin{aligned}T(N) &= NT(1) + N \log N \\&= N \log N + N\end{aligned}$$

- Thus, the running time is $O(N \log N)$
 - faster than Algorithm 1 for large data sets