

T.T.N

UNIVERSITY OF BUEA
FACULTY OF ENGINEERING AND TECHNOLOGY
LEVEL 400 ELECTRICAL ENGINEERING AND COMPUTER ENGINEERING
Continuous Assessment
February 2014

Course Title: Feedback Systems
Course Code: EEF 409
Course Instructor: Professor Tanyi Emmanuel
Time: 2 Hours

Tables of Laplace Transforms are allowed

Question 1

Routh formulated necessary and sufficient conditions for the **Absolute Stability** of a system, but did not address the problem of **Relative Stability**: If stable, how stable?.

The **Nyquist Criterion** addresses the twin-problem of **Absolute** and **Relative Stability**.

- a) Use the Routh Criterion to analyze the stability of a system with characteristic equation
 $q(s) = s^4 + 3s^3 + 6s^2 + 12s + K$
- i) For $K=8$
ii) For $K=10$
- b) Use the Routh Criterion to analyze the stability of a system with characteristic equation
 $q(s) = s^5 + s^4 + 4s^3 + 4s^2 + 2s + 1$
- c) Apply the Nyquist Criterion to determine the Value of the Gain $K = K_{\max}$ for which the system with Open-loop Transfer Function $L(s) = \frac{K}{(1+s)(1+2s)(1+10s)}$ is marginally stable.

For $K = \frac{K_{\max}}{2}$, calculate:

- i) The Gain Margin
ii) The Phase Margin

Question 2

A system is described by the Open-loop Transfer Function $L(s) = \frac{10(1+s)}{s(1+0.1s)(1+0.01s)}$

- a) Represent the Frequency Response on a Bode Diagram.
Calculate the Phase Margin from the Bode Diagram.
- b) Represent the Frequency Response on a Polar Diagram.
Calculate the Gain Margin from the Polar Diagram

Question 3

A system is described by the closed-loop Transfer Function $W(s) = \frac{100}{s^2 + 4s + 100}$

A unit step input is applied to the system. Calculate:

- a) The output, $y(t)$.
- b) The Peak Response (Maximum Response), M_p
- c) The time-to-peak (time taken to reach the maximum response), T_p
- d) $y(T_p + T)$, where T is the period of the damped oscillation
- e) The ratio $\frac{a_1}{a_2}$, where a_1 and a_2 are the first and second overshoots respectively
- f) The steady-state error to the unit step input