

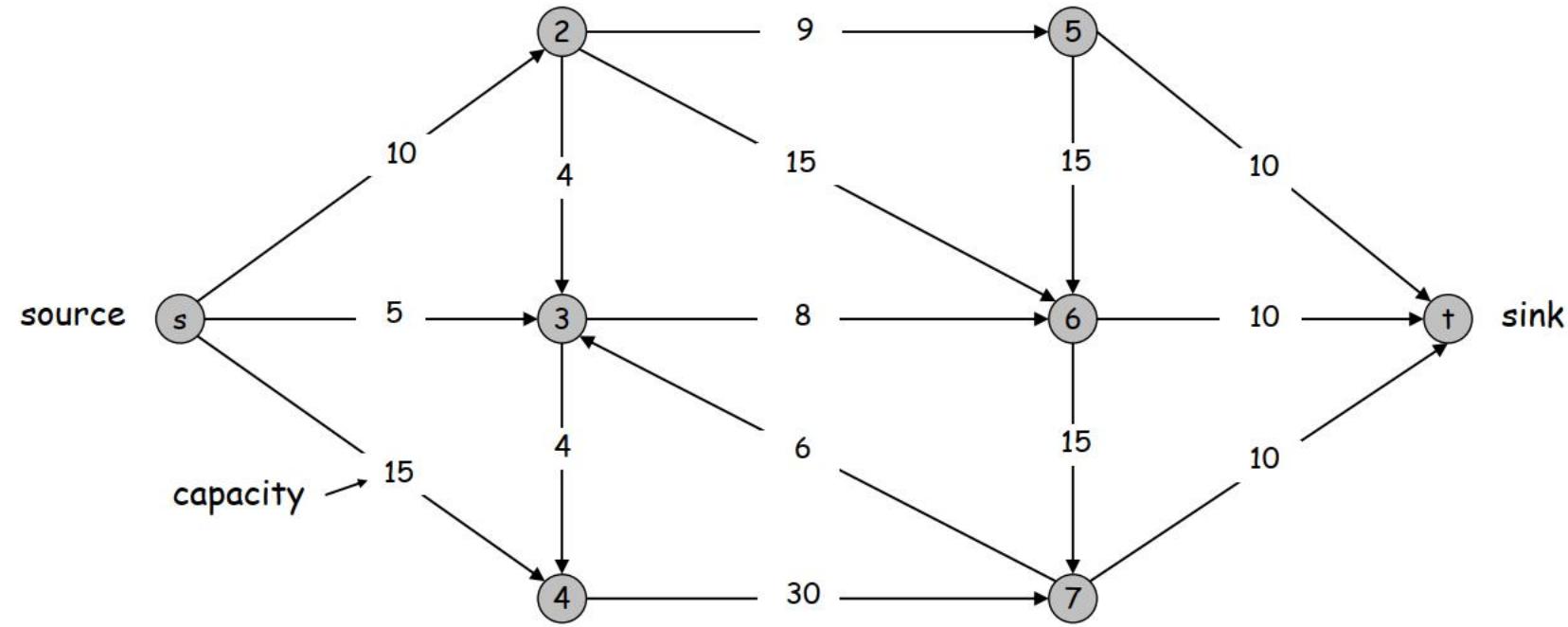
CS240 Algorithm Design and Analysis

Lecture 7

Network Flow

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Fall 2025
2025.10.12

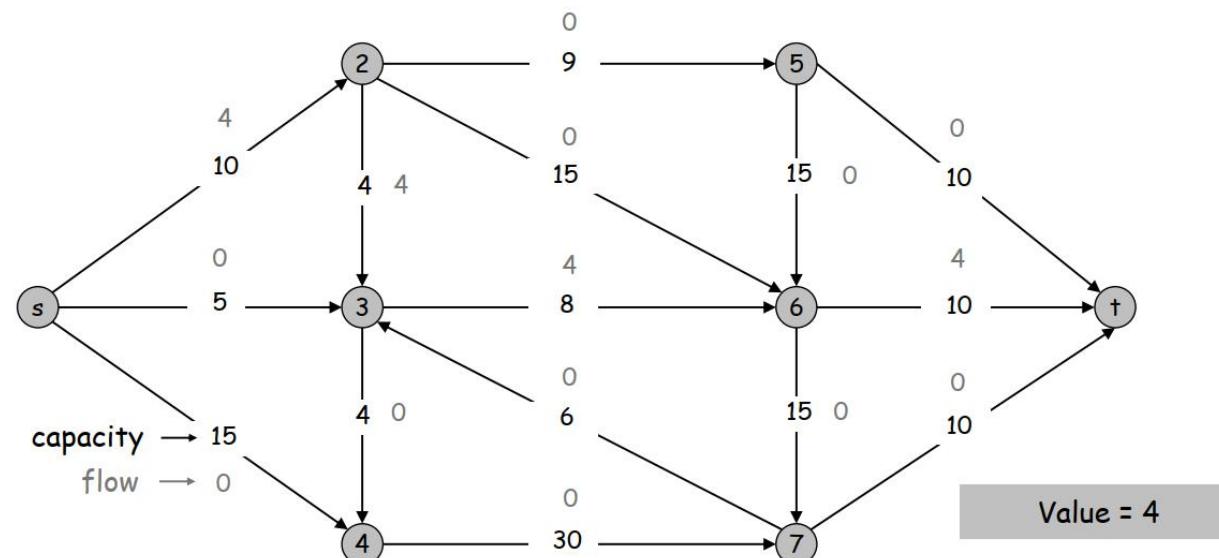
- Flow network
 - Abstraction for material **flowing** through the edges
 - $G = (V, E)$ = directed graph
 - Two distinguished nodes: s = source, t = sink
 - $c(e)$ = nonnegative capacity of edge e



- **Def.** An **s-t flow** is a function that satisfies:

- For each $e \in E$: $0 \leq f(e) \leq c(e)$ (capacity)
- For each $v \in V - \{s, t\}$: $\sum_{e \text{ in to } v} f(e) = \sum_{e \text{ out of } v} f(e)$ (conservation)

- **Def.** The value of a flow f is : $v(f) = \sum_{e \text{ out of } s} f(e)$



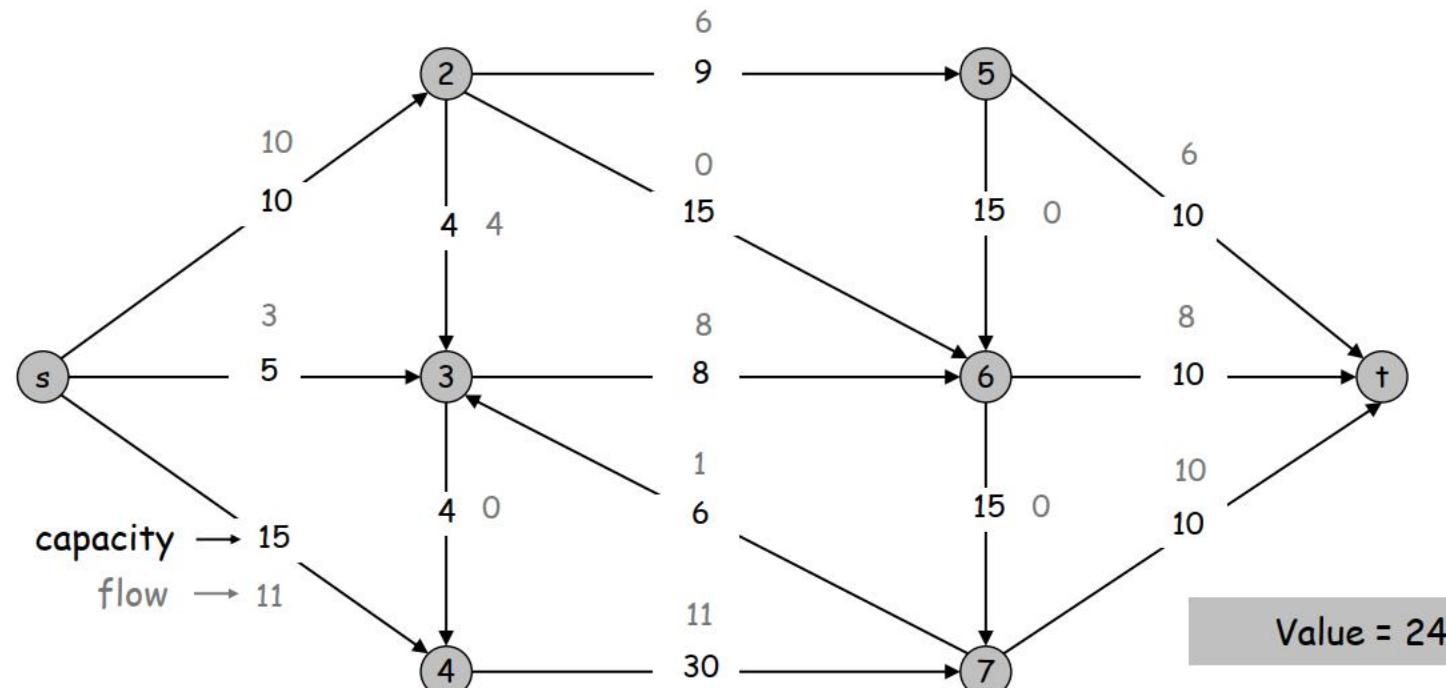
Flows



- **Def.** An **s-t flow** is a function that satisfies:

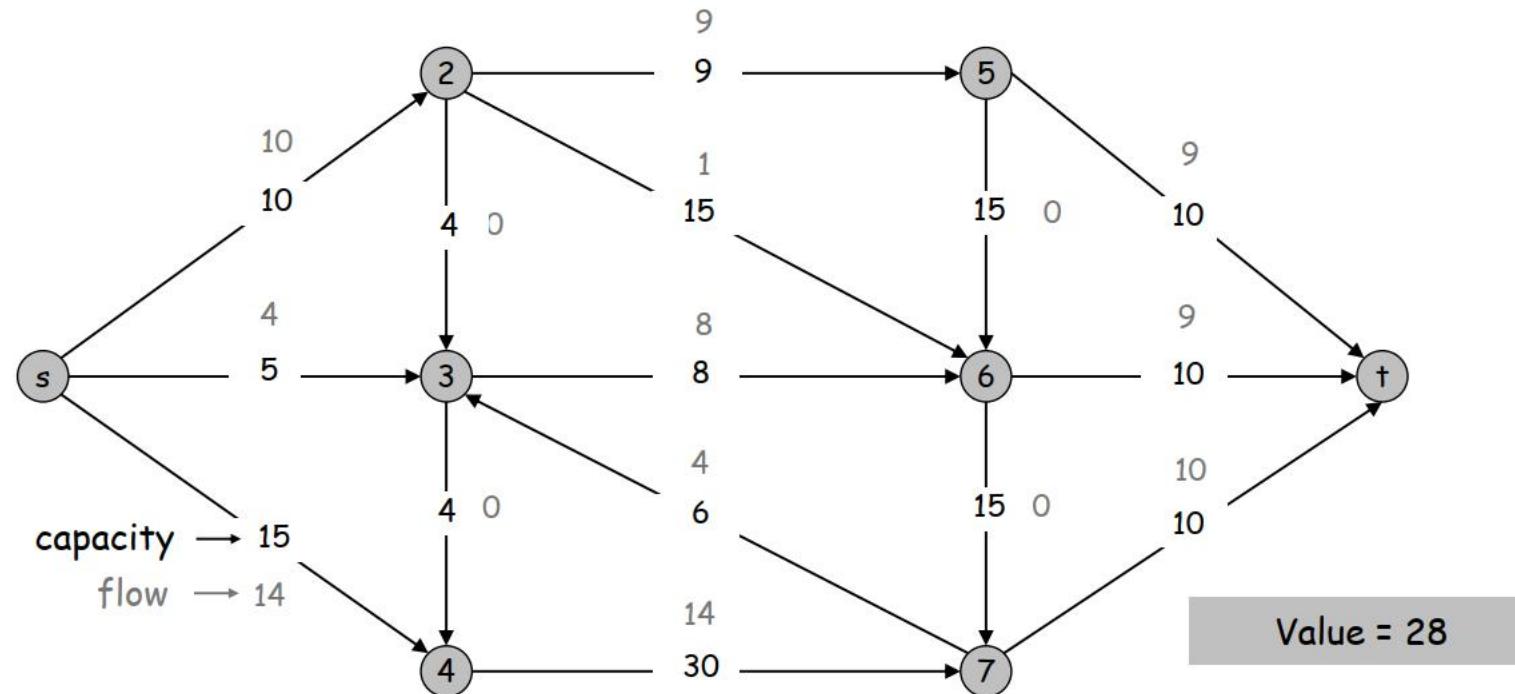
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- **Def.** The value of a flow f is : $v(f) = \sum_{e \text{ out of } s} f(e)$



Maximum Flow Problem

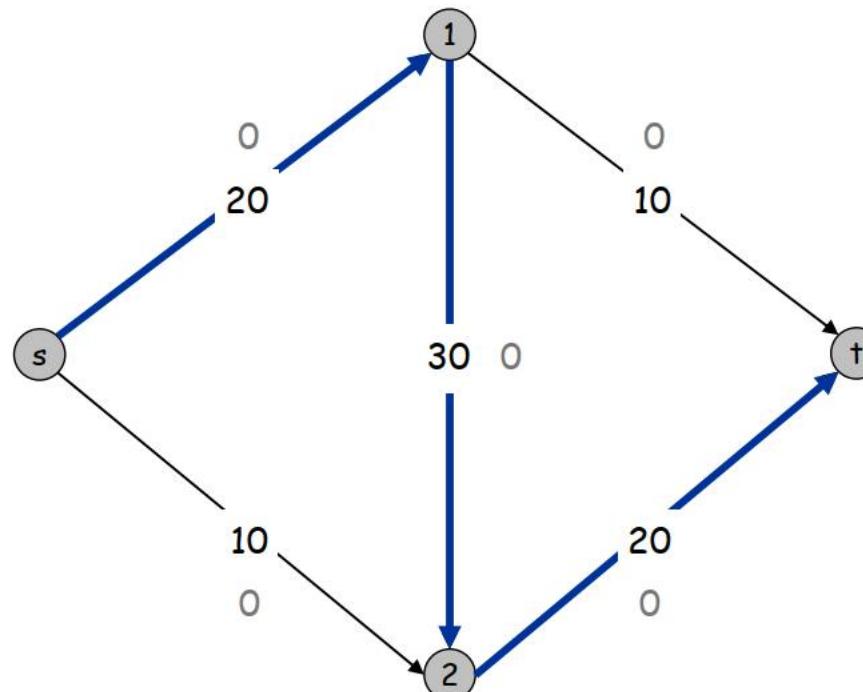
- **Max flow problem.** Find s-t flow of maximum value



Towards a Max Flow Algorithm

- **Greedy algorithm**

- Start with $f(e) = 0$ for all edge $e \in E$
- Find an $s-t$ path P where each edge has $f(e) < c(e)$
- Augment flow along path P
- Repeat until you get stuck



Flow value = 0

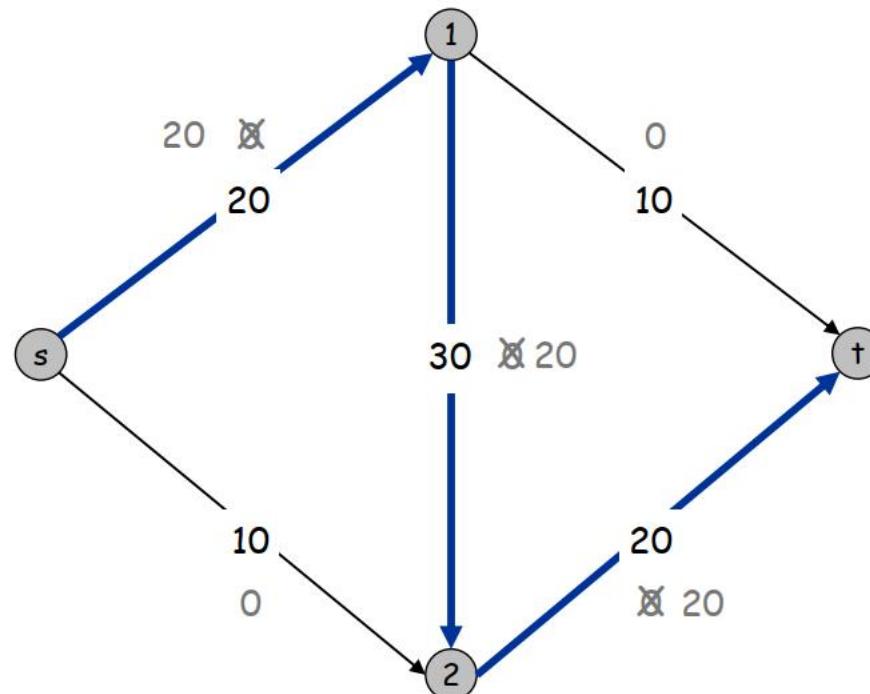


Towards a Max Flow Algorithm



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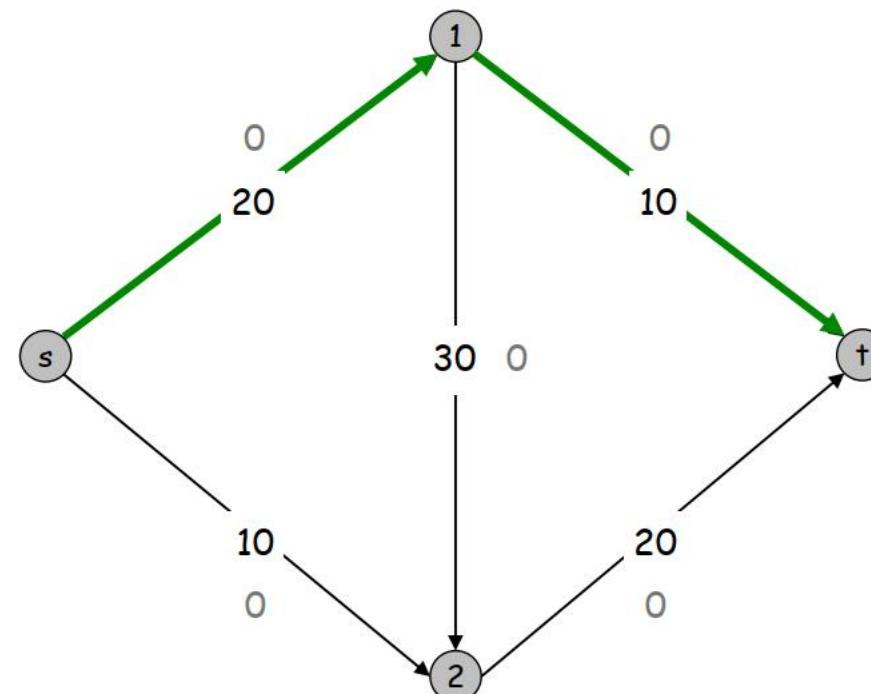
Flow value = 20



Towards a Max Flow Algorithm

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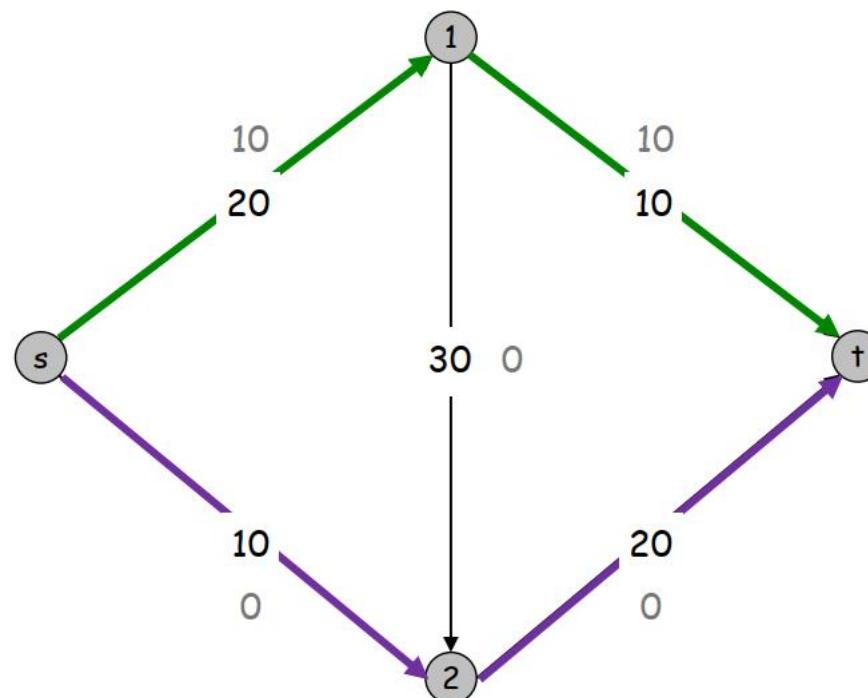


Flow value = 0

Towards a Max Flow Algorithm

- **Greedy algorithm**

- Start with $f(e) = 0$ for all edge $e \in E$
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Flow value = 10



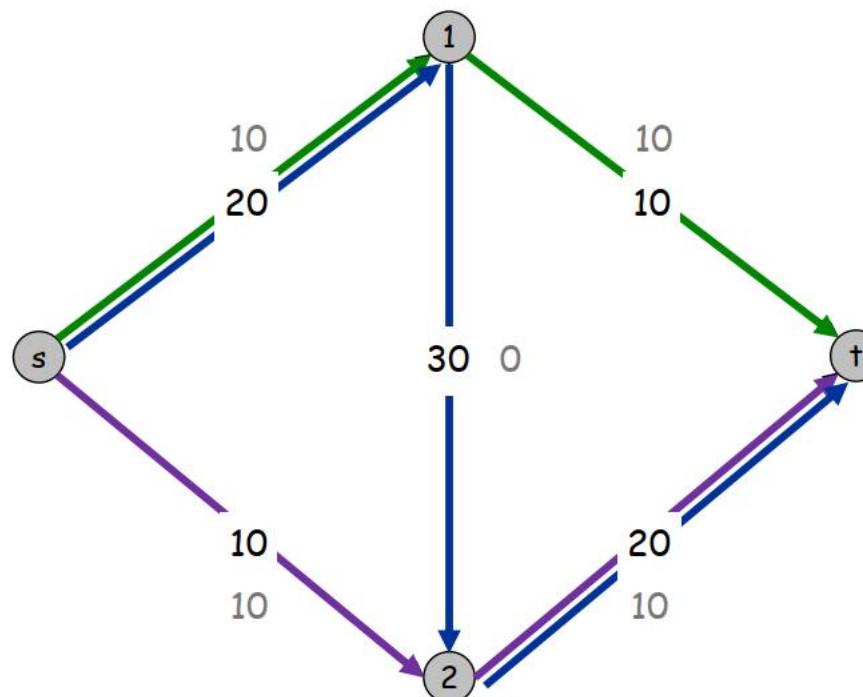


Towards a Max Flow Algorithm

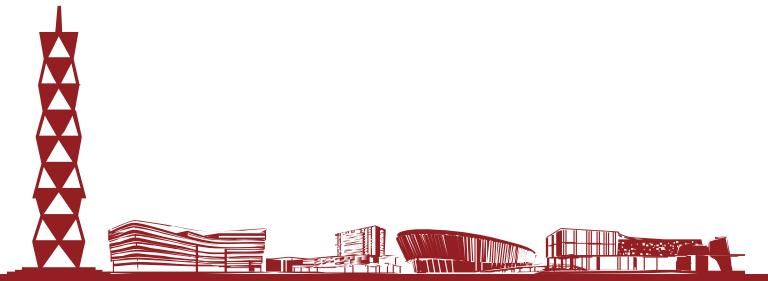


- **Greedy algorithm**

- Start with $f(e) = 0$ for all edge $e \in E$
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- Repeat until you get stuck



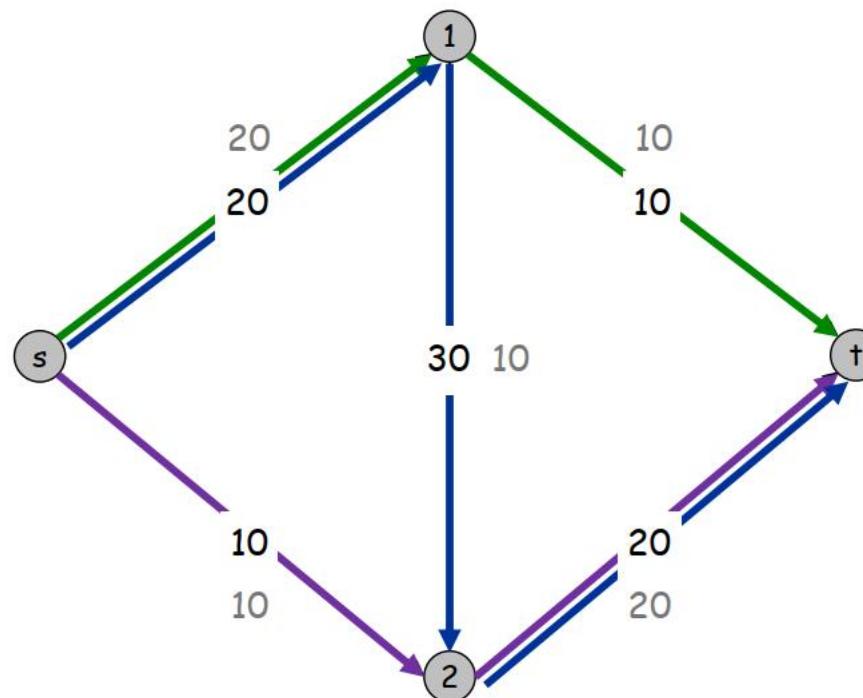
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Towards a Max Flow Algorithm

- **Greedy algorithm**

- Start with $f(e) = 0$ for all edge $e \in E$
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- Augment flow along path P
- Repeat until you get stuck



Flow value = 30

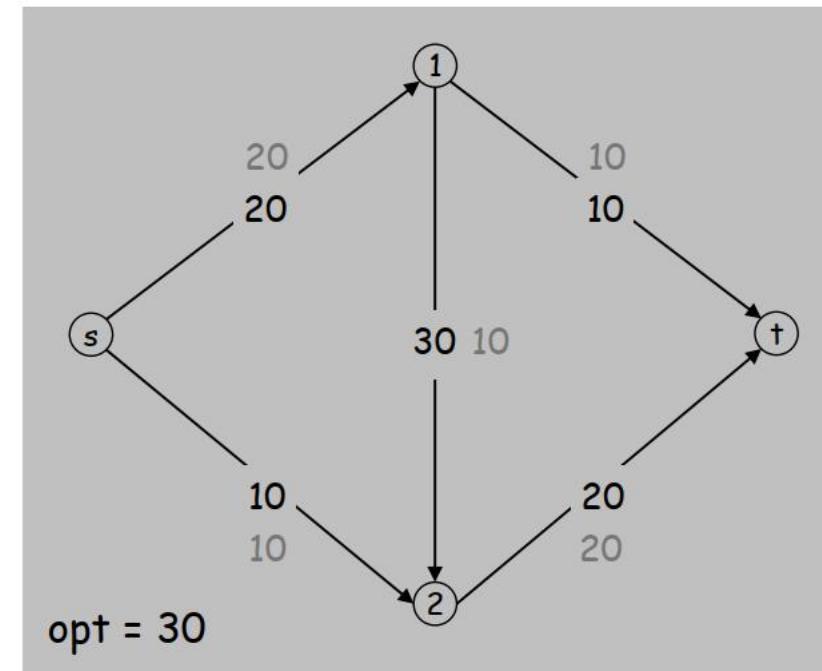
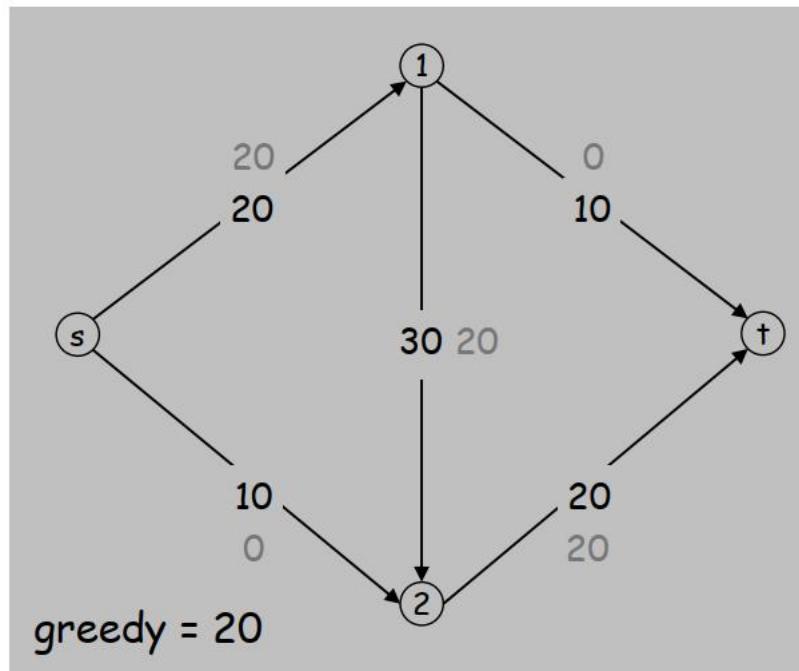


Towards a Max Flow Algorithm

- **Greedy algorithm**

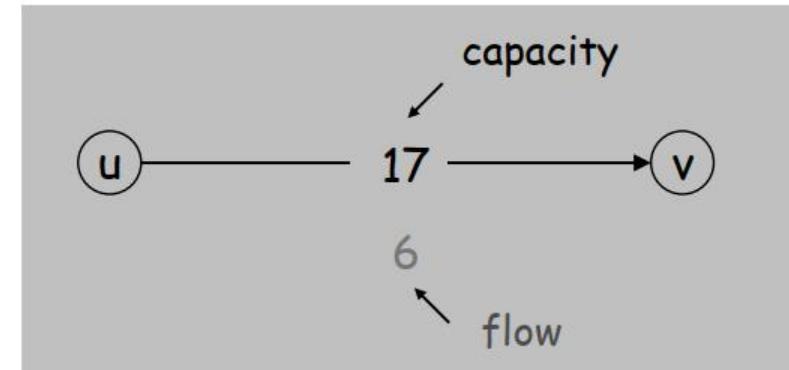
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- Find an $s-t$ path P where each edge has $f(e) < c(e)$
- Augment flow along path P
- Repeat until you get **stuck**

locally optimality $\not\Rightarrow$ globally optimality



Residual Graph

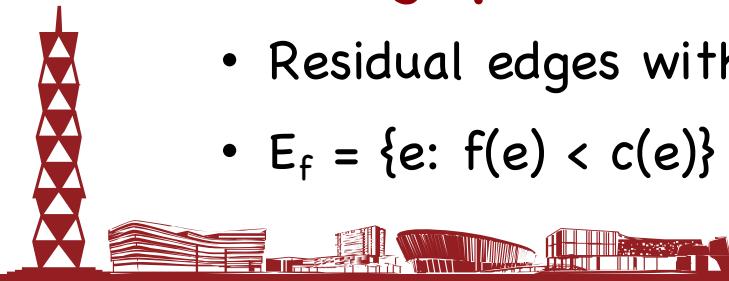
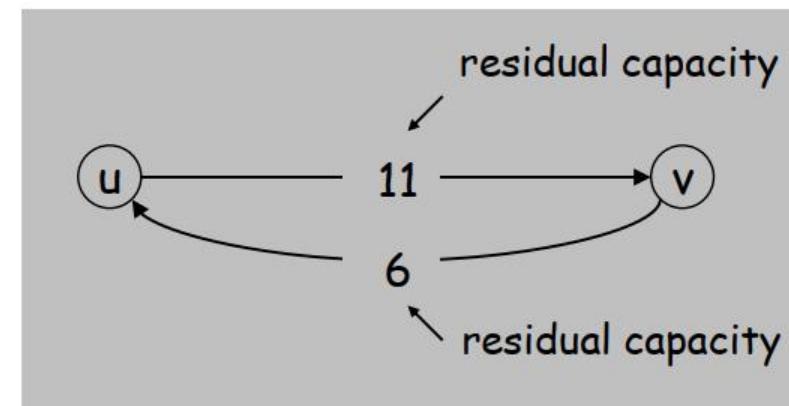
- **Original edge:** $e = (u, v) \in E$
 - Flow $f(e)$, capacity $c(e)$



- **Residual edge**
 - “Undo” flow sent
 - $e = (u, v)$ and $e^R = (v, u)$
 - Residual capacity:

$$c_f(e) = \begin{cases} c(e) - f(e) & \text{if } e \in E \\ f(e) & \text{if } e^R \in E \end{cases}$$

- **Residual graph:** $G_f = (V, E_f)$
 - Residual edges with positive residual capacity
 - $E_f = \{e: f(e) < c(e)\} \cup \{e^R: f(e) > 0\}$



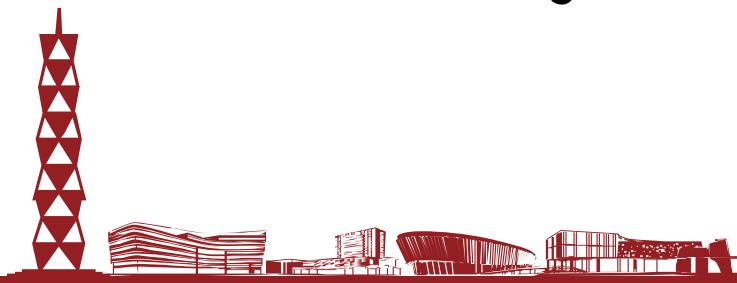


Augmenting Path

- **Augmenting path:** a simple s-t path P in the residual graph G_f
- **Bottleneck capacity** of an augmenting path P is the minimum residual capacity of any edge in P

```
Augment(f, c, P) {
    b ← bottleneck(P)
    foreach e ∈ P {
        if (e ∈ E) f(e) ← f(e) + b           forward edge
        else          f(eR) ← f(eR) - b   reverse edge
    }
    return f
}
```

- **Claim:** After augmentation, f is still a flow





Ford-Fulkerson Algorithm

- **Ford-Fulkerson Algorithm**

- Start with $f(e) = 0$ for all edge $e \in E$
- Find an augmenting path P in the residual graph G_f
- Augment flow along path P
- Repeat until you get stuck

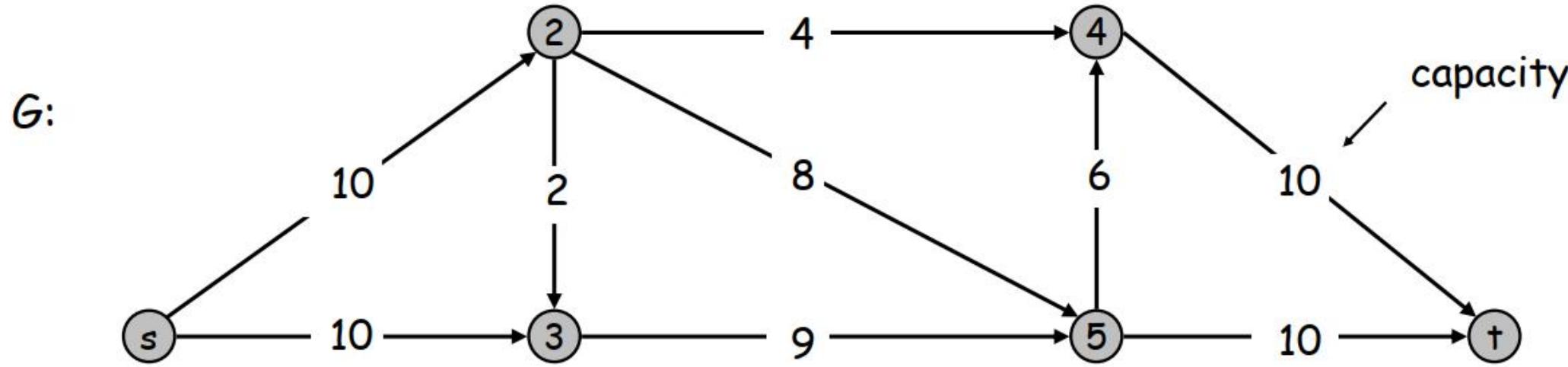
```
Ford-Fulkerson(G, s, t, c) {
    foreach e ∈ E   f(e) ← 0
    Gf ← residual graph

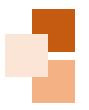
    while (there exists augmenting path P) {
        f ← Augment(f, c, P)
        update Gf
    }
    return f
}
```



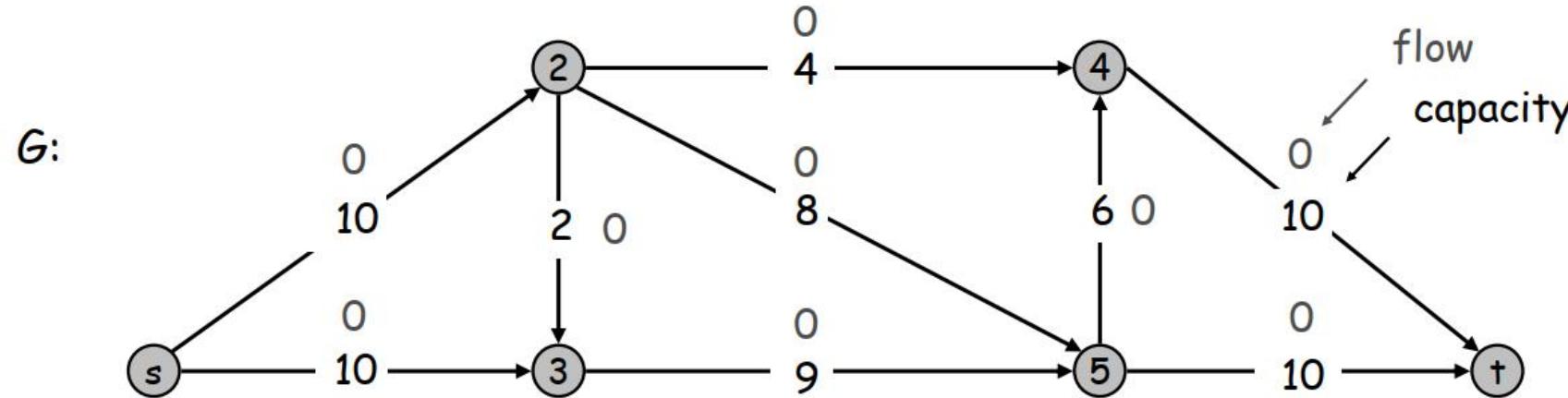


Ford-Fulkerson Algorithm

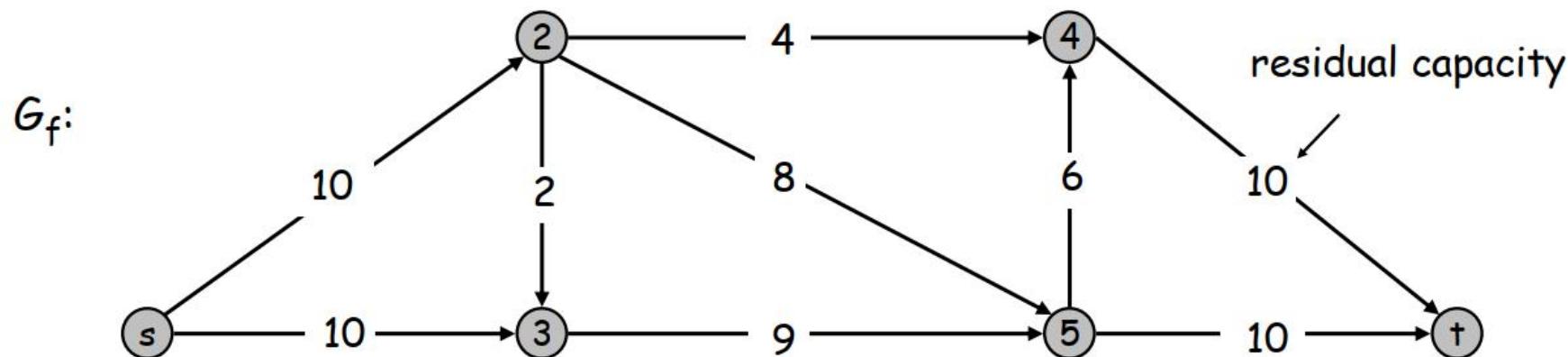


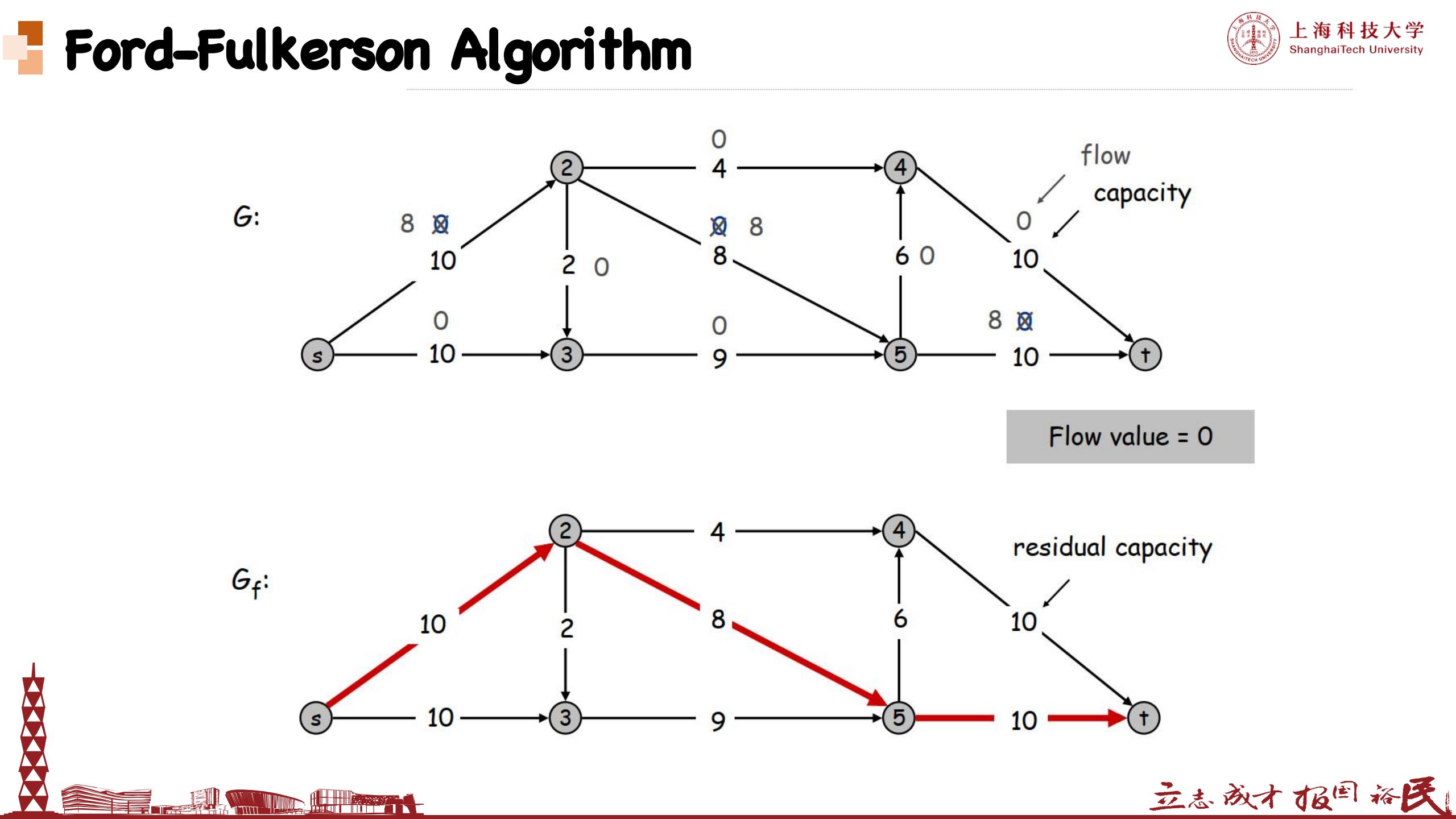


Ford-Fulkerson Algorithm



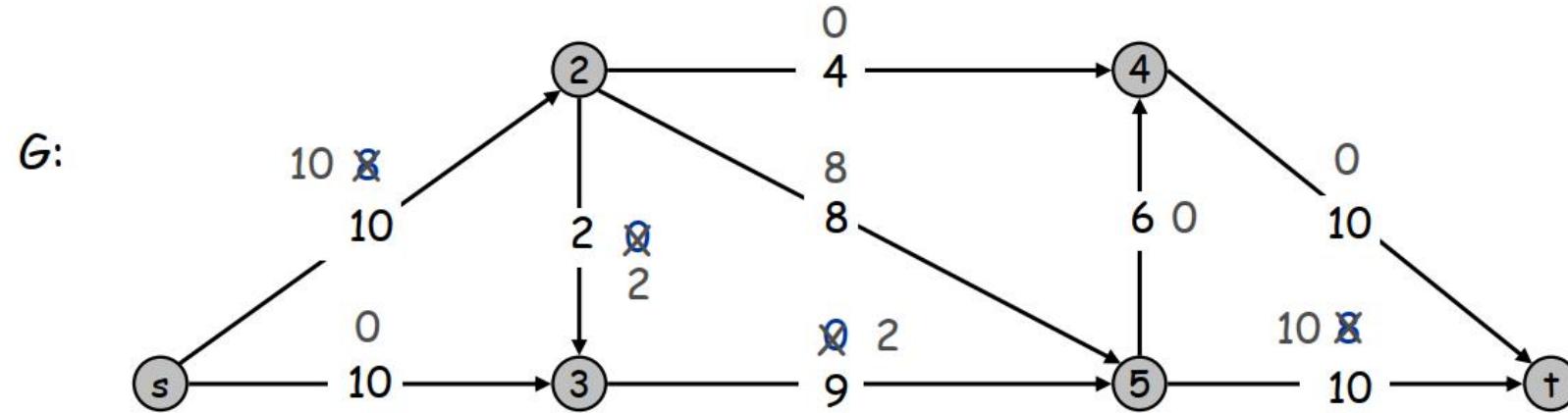
Flow value = 0



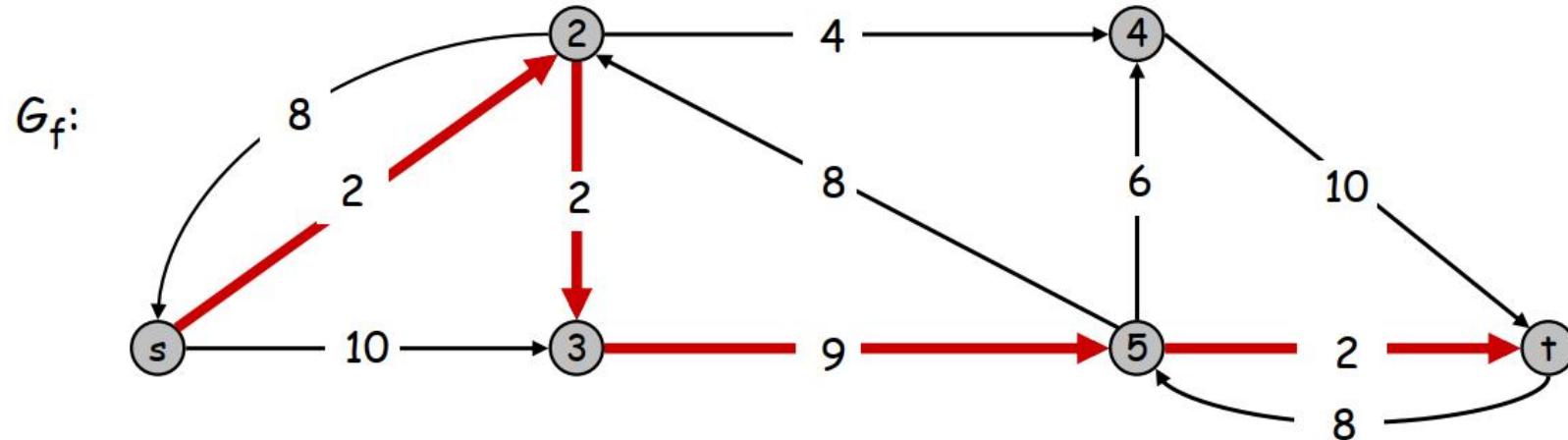




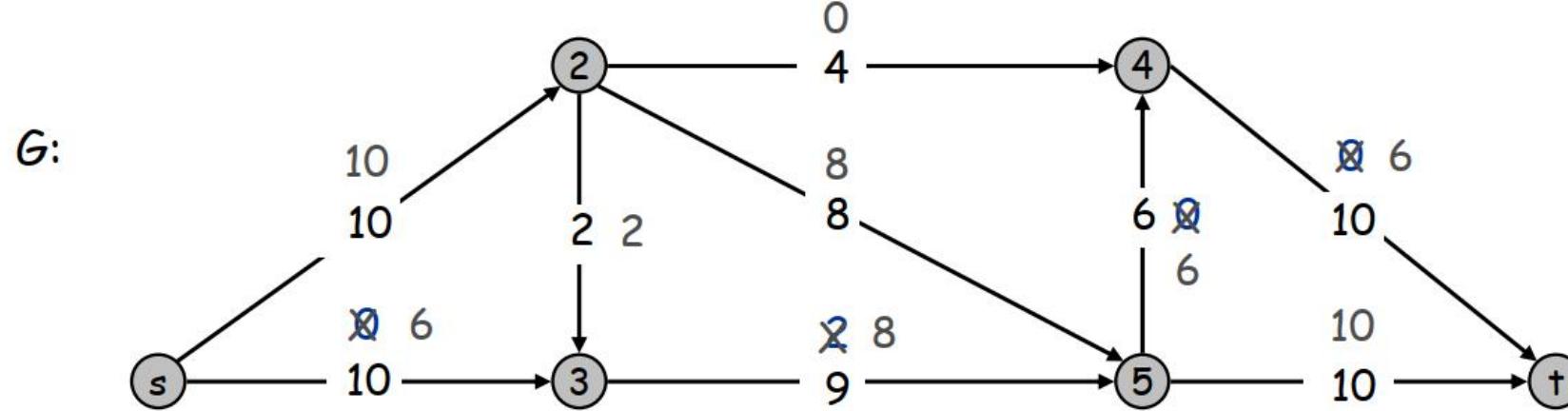
Ford-Fulkerson Algorithm



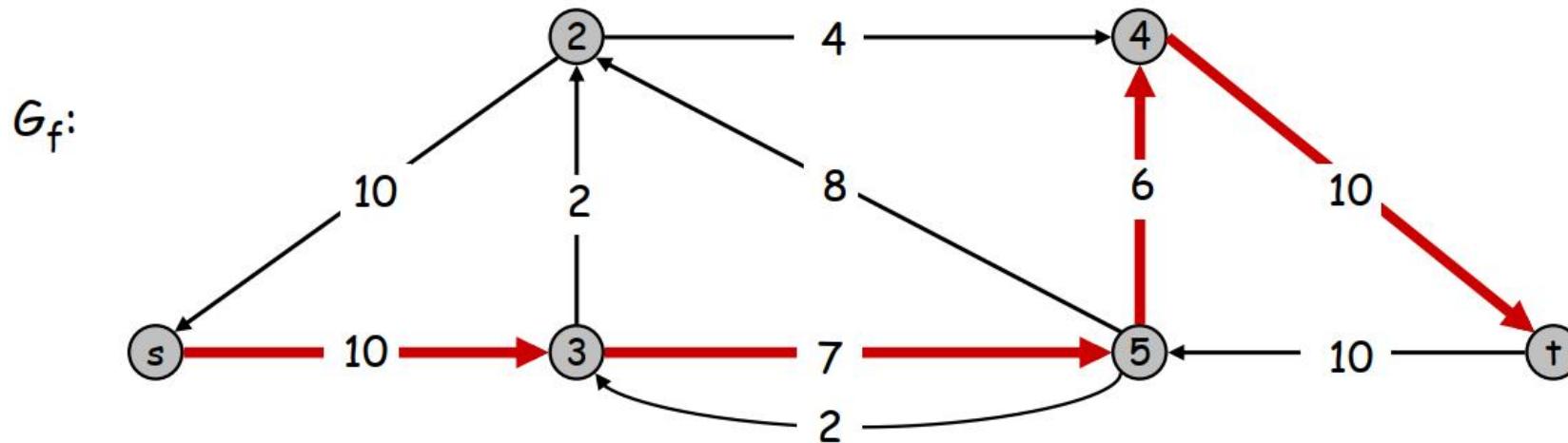
Flow value = 8

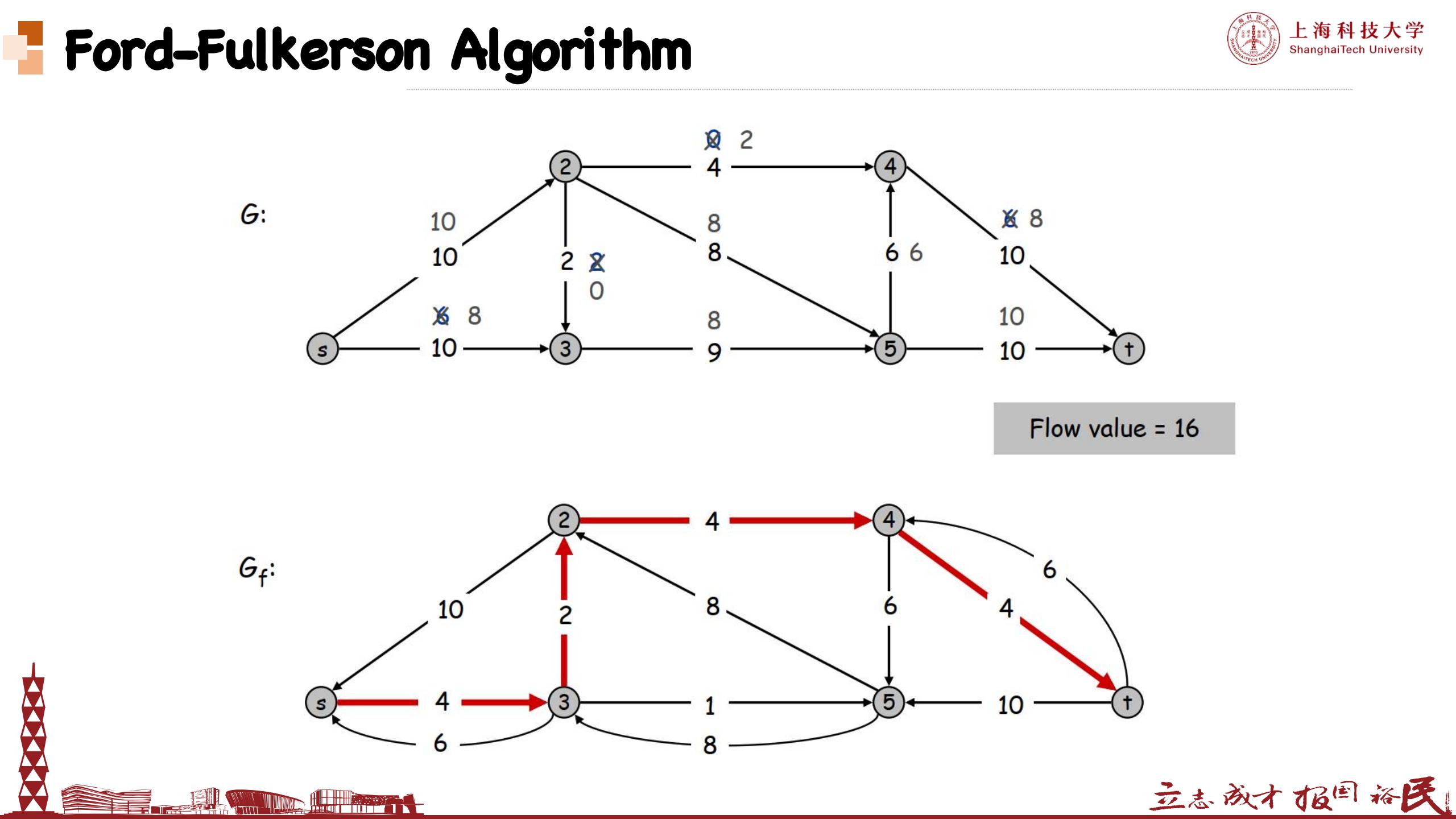


Ford-Fulkerson Algorithm

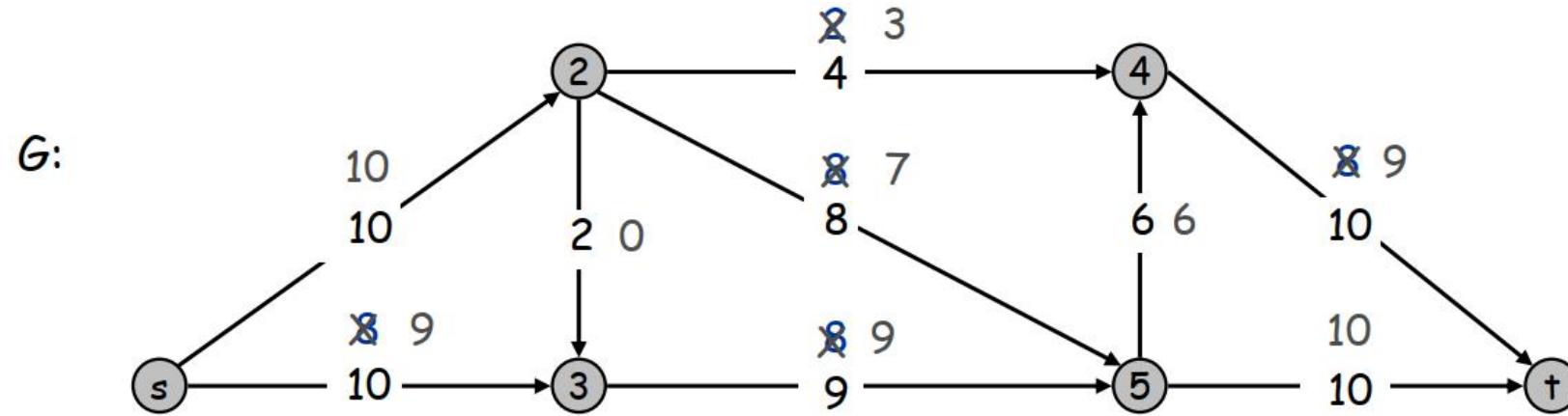


Flow value = 10

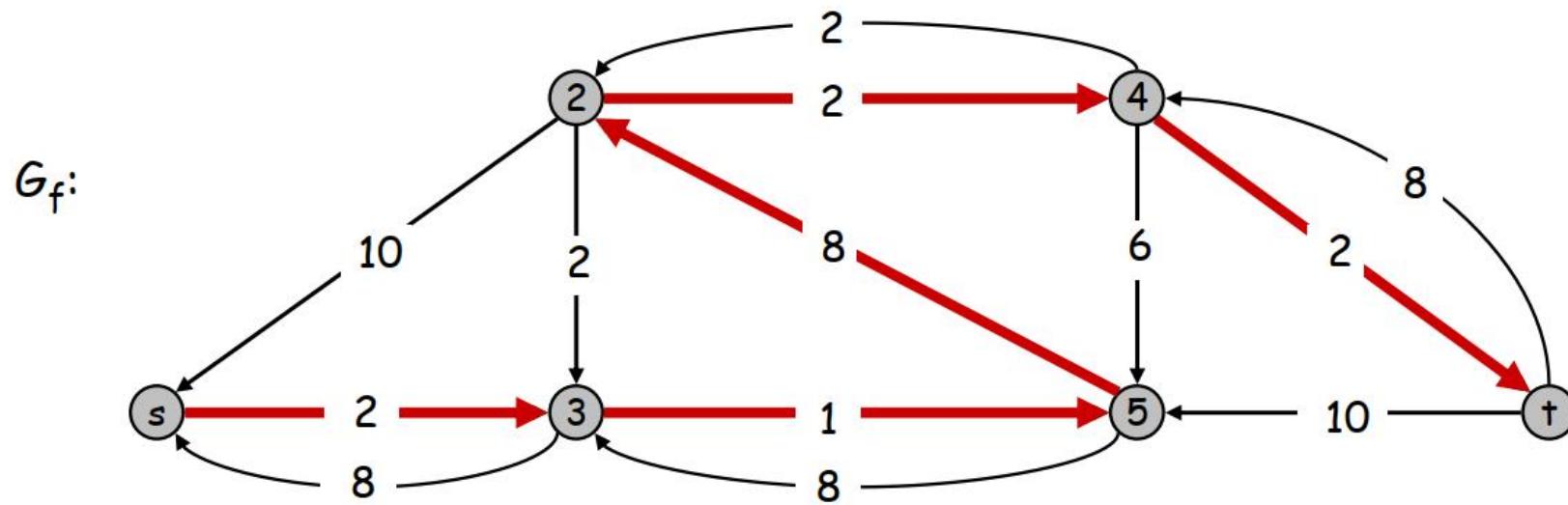




Ford-Fulkerson Algorithm

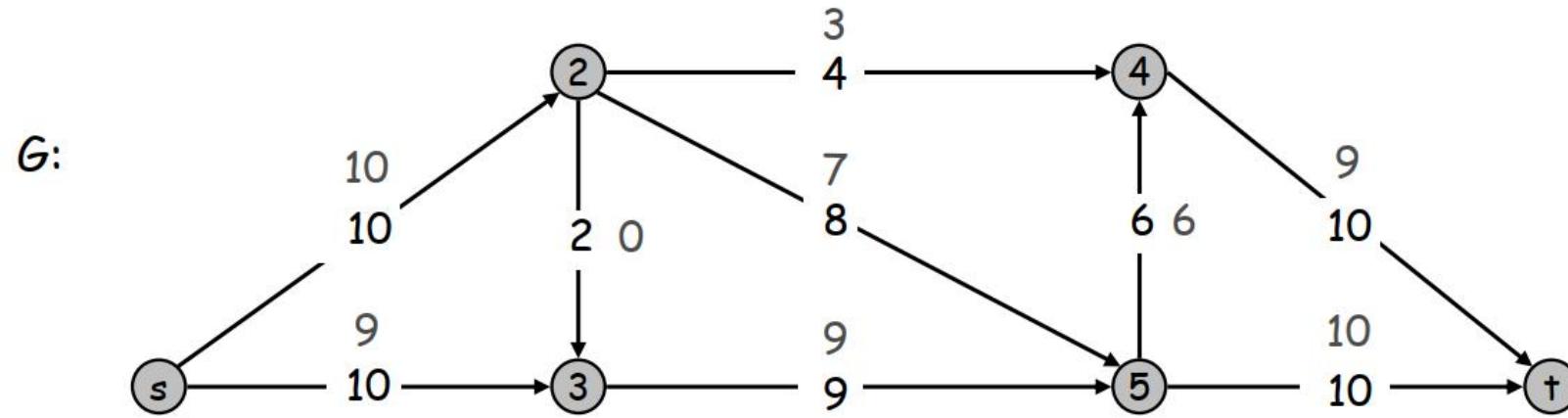


Flow value = 18

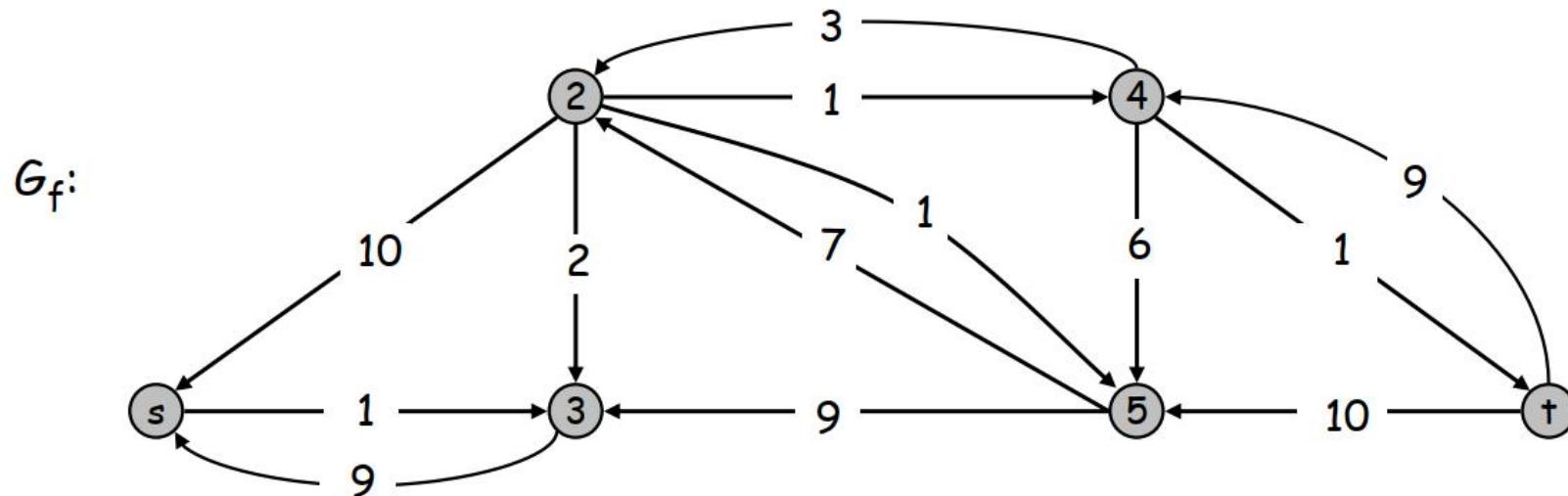




Ford-Fulkerson Algorithm

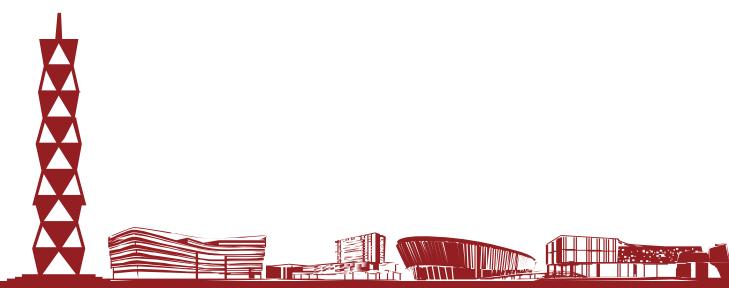


Flow value = 19



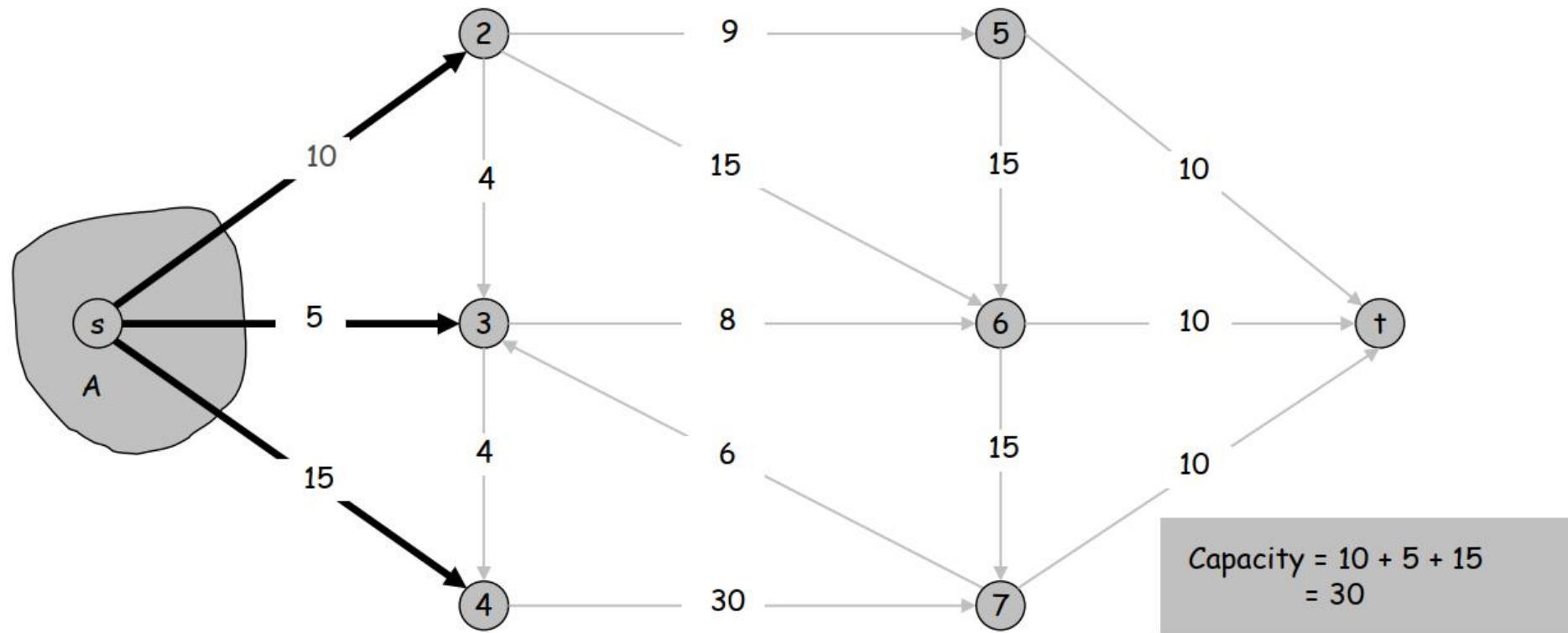


Max-flow and Min-Cut



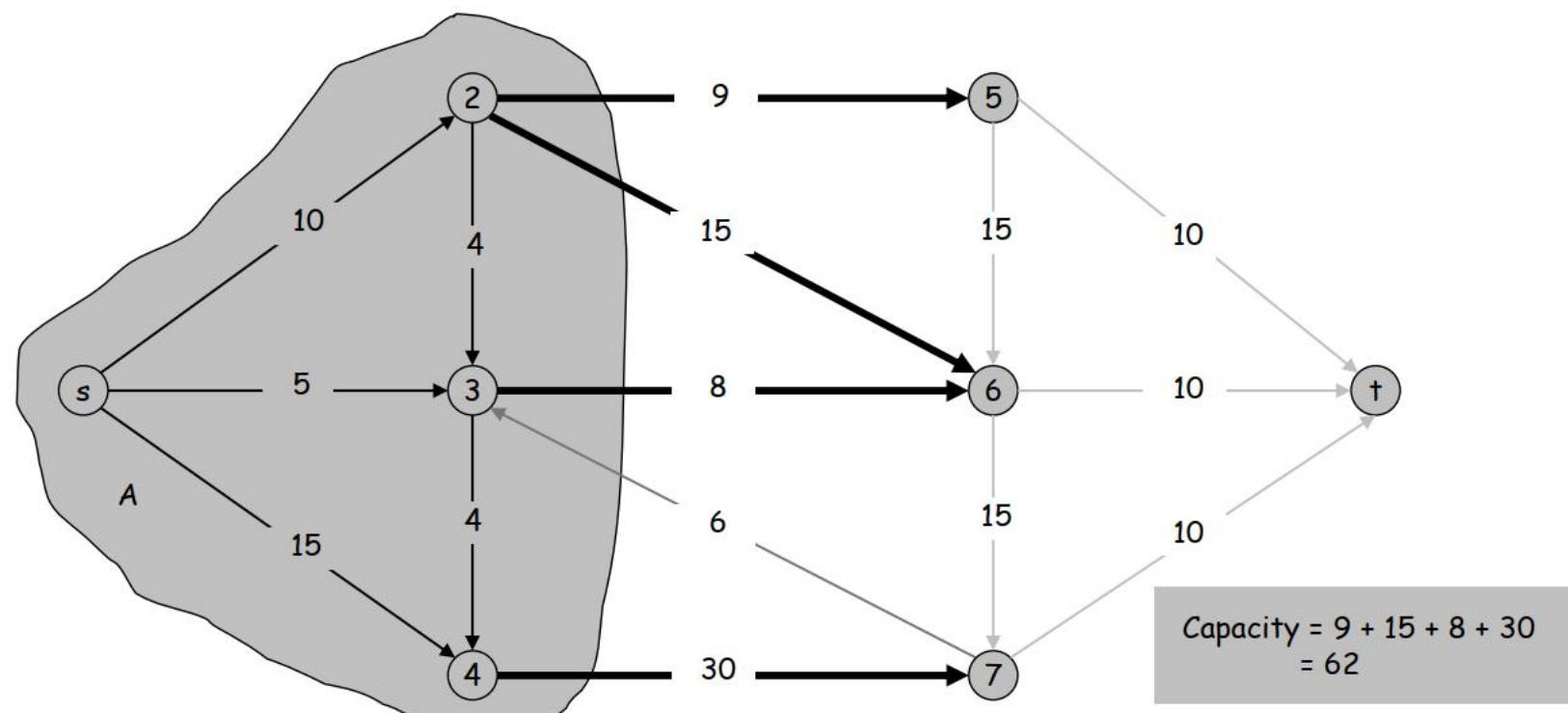
- **Def.** An s - t cut is a partition (A, B) of V with $s \in A$ and $t \in B$

- **Def.** The **capacity** of a cut (A, B) is:
$$\text{cap}(A, B) = \sum_{e \text{ out of } A} c(e)$$



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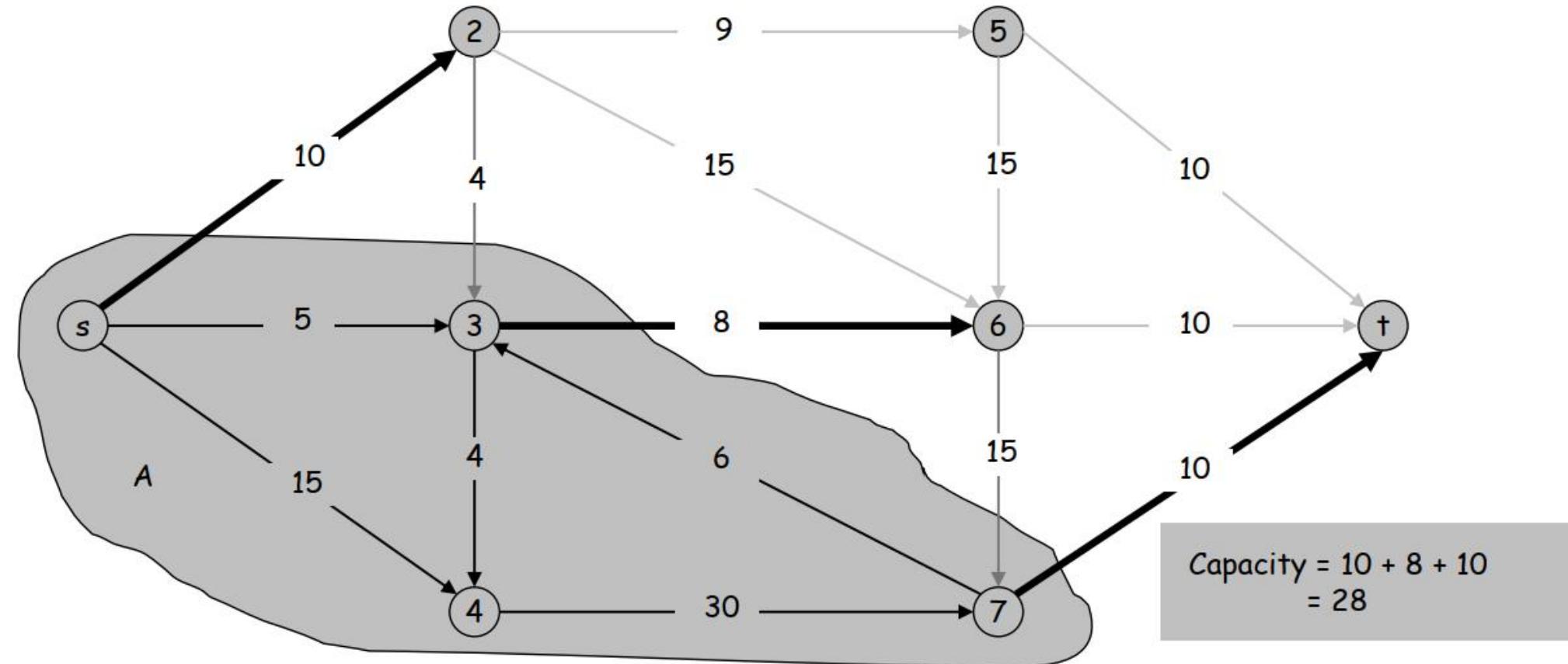
- **Def.** The **capacity** of a cut (A, B) is:
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Minimum Cut Problem



- Min s-t cut problem. Find an s-t cut of minimum capacity

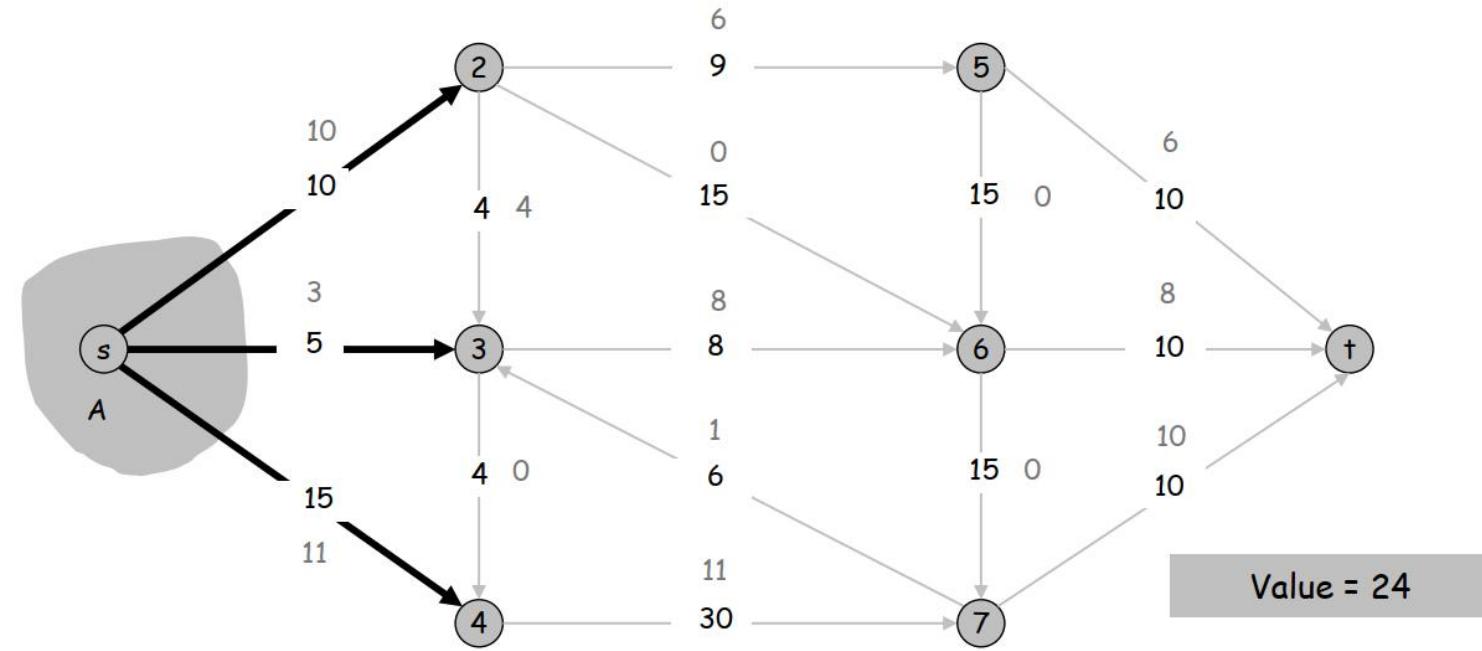


Flows and Cuts



- **Flow value lemma.** Let f be any flow, and let (A, B) be any $s-t$ cut
- Then, the net flow sent across the cut is equal to the amount leaving s

$$\sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) = v(f)$$

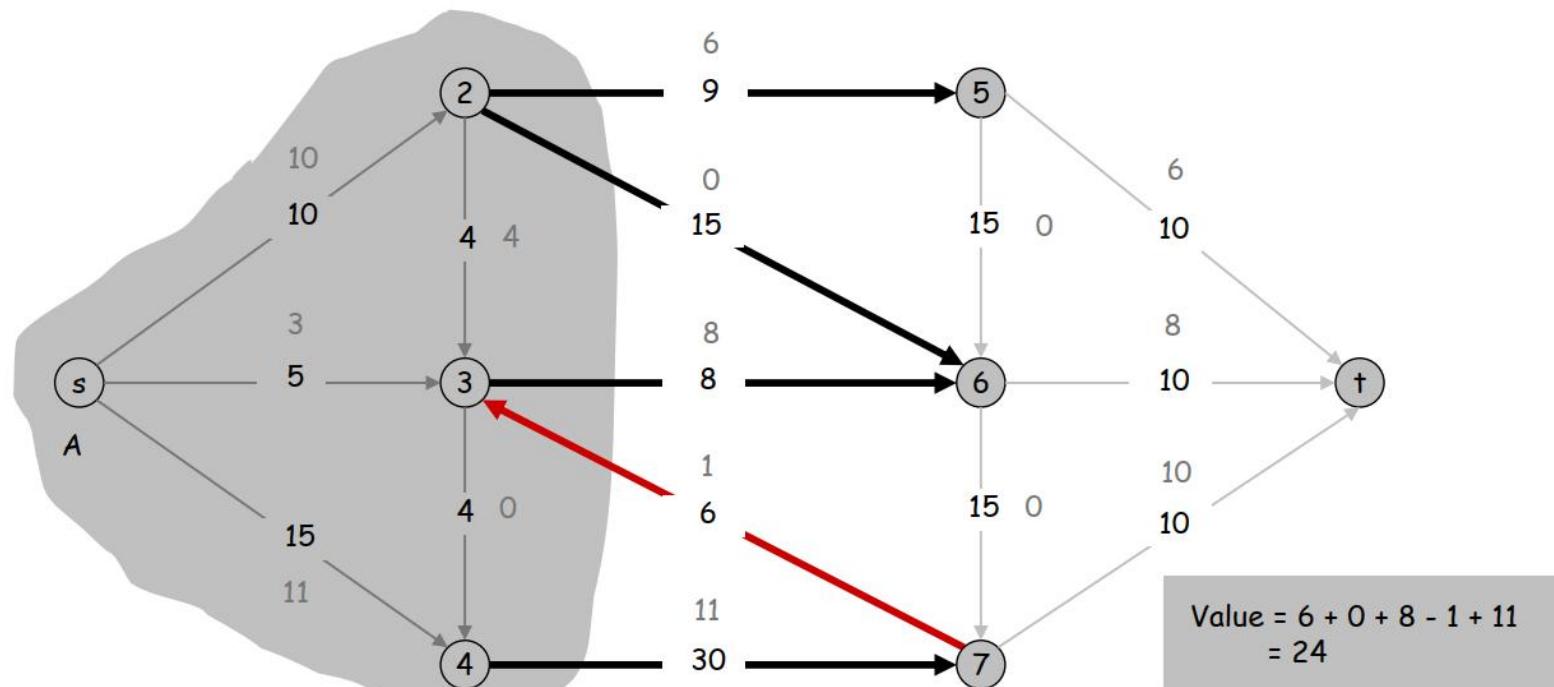


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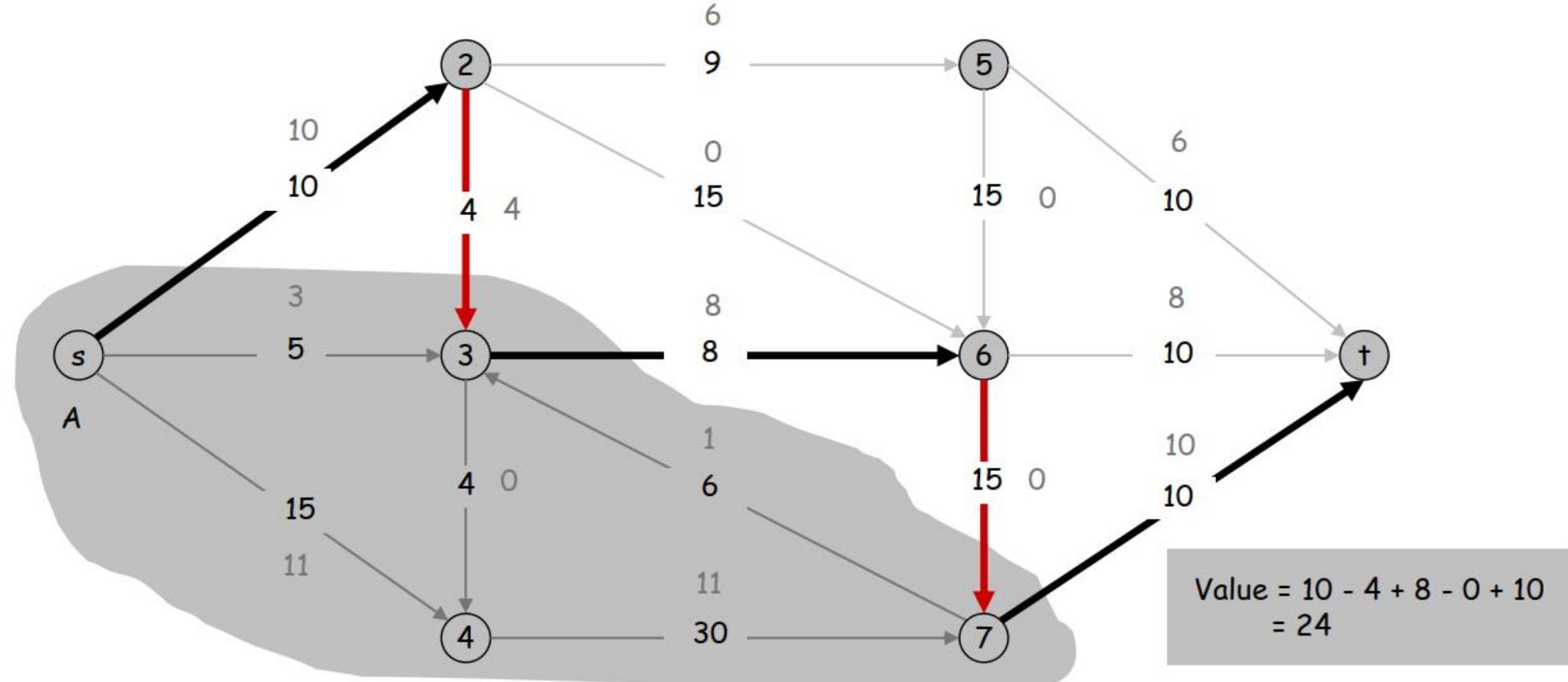




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Flows and Cuts

- **Flow value lemma.** Let f be any flow, and let (A, B) be any $s-t$ cut. Then,

$$\sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) = v(f).$$

Pf.

$$\begin{aligned}
 v(f) &= \sum_{e \text{ out of } s} f(e) \\
 \text{by flow conservation, all terms except } v = s \text{ are 0} \quad \rightarrow \quad &= \sum_{v \in A} \left(\sum_{e \text{ out of } v} f(e) - \sum_{e \text{ in to } v} f(e) \right) \\
 &= \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e).
 \end{aligned}$$

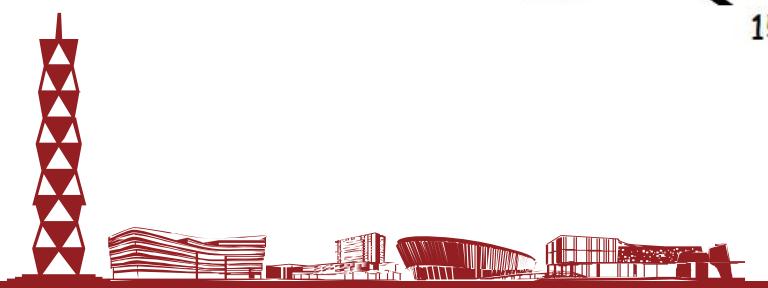
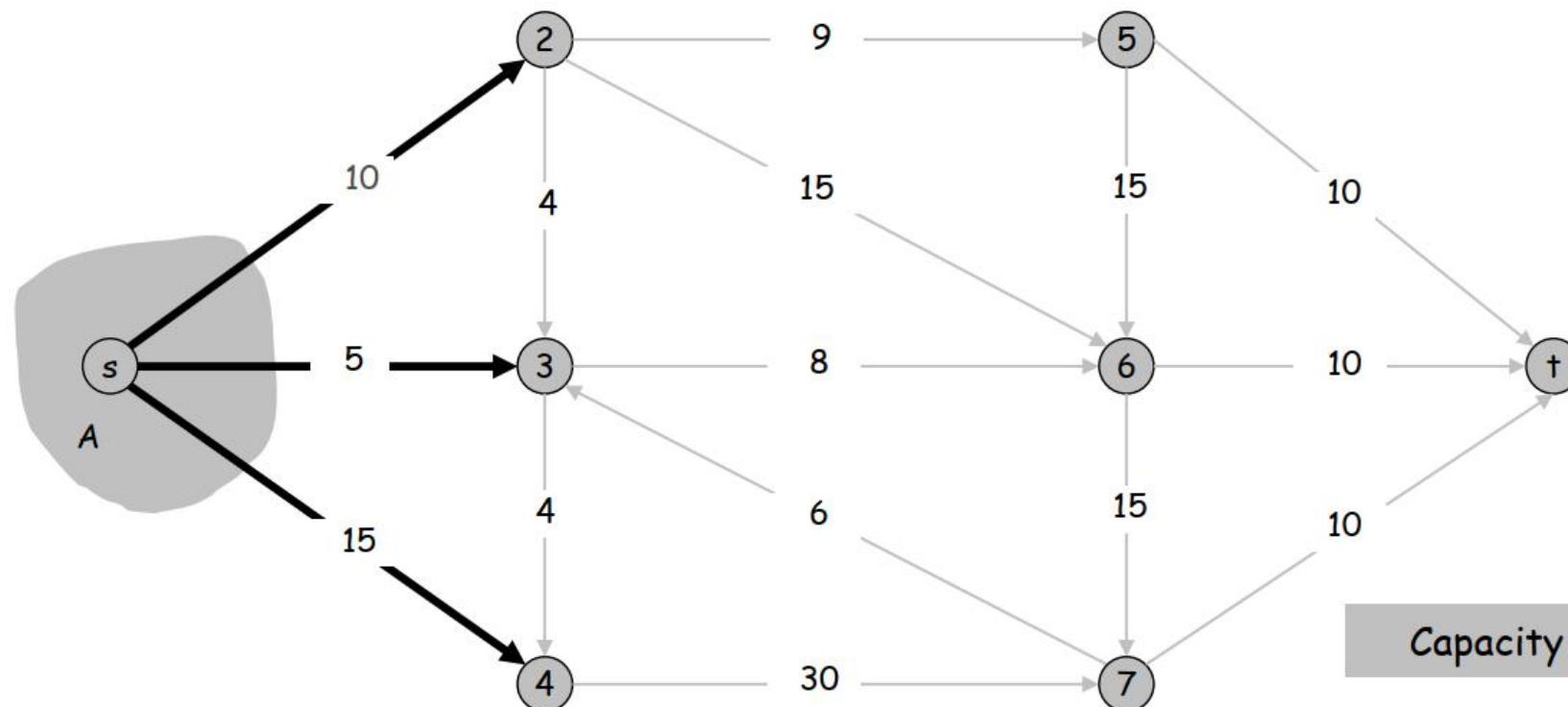


Flows and Cuts



- **Weak duality.** Let f be any flow, and let (A, B) be any $s-t$ cut. Then the value of the flow is at most the capacity of the cut

Cut capacity = 30 \Rightarrow Flow value ≤ 30

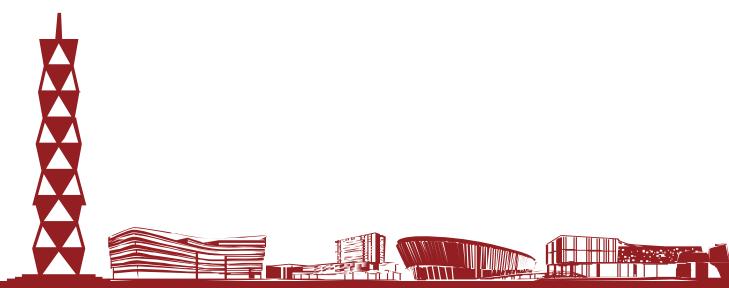




Flows and Cuts

- **Weak duality.** Let f be any flow. Then, for any $s-t$ cut (A, B) we have $v(f) \leq \text{cap}(A, B)$
- Pf.

$$\begin{aligned} v(f) &= \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) \\ &\leq \sum_{e \text{ out of } A} f(e) \\ &\leq \sum_{e \text{ out of } A} c(e) \\ &= \text{cap}(A, B) \quad . \end{aligned}$$



Max-Flow Min-Cut Theorem

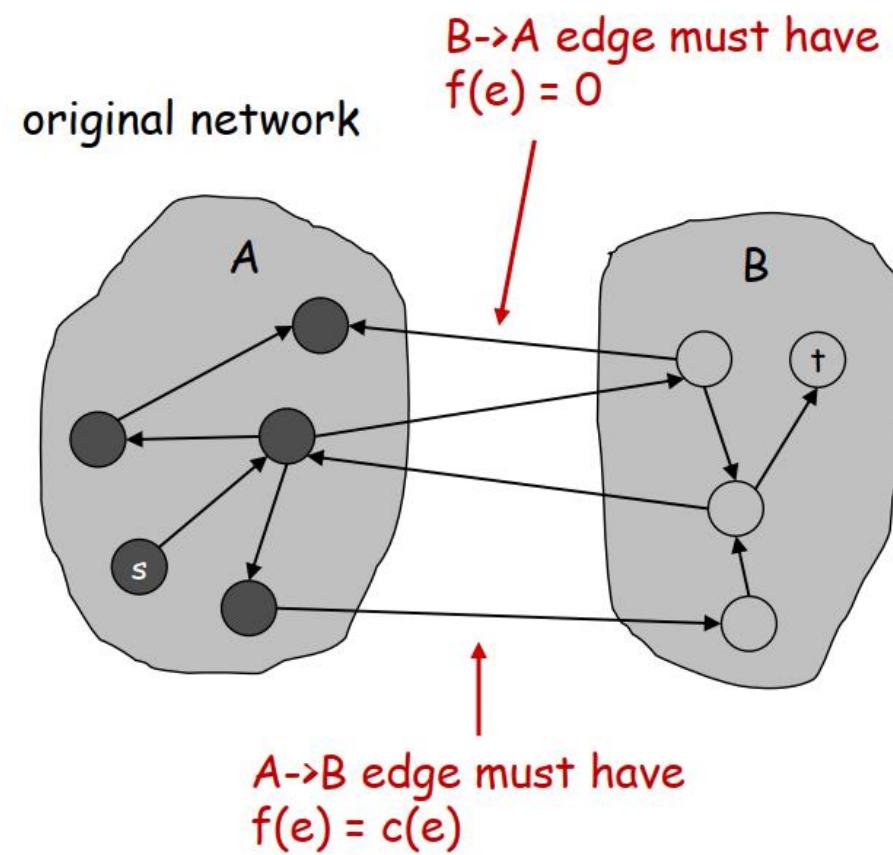
- **Augmenting path theorem.** Flow f is a max flow iff there are no augmenting paths
- **Max-flow min-cut theorem.** [Ford-Fulkerson 1956] The value of the max flow is equal to the value of the min cut
- **Proof strategy.** We prove both simultaneously by showing the equivalence of the following three conditions for any flow f :
 - (i) There exists a cut (A, B) such that $v(f) = \text{cap}(A, B)$
 - (ii) Flow f is a max flow
 - (iii) There is no augmenting path relative to f
- (i) \rightarrow (ii) This was the corollary to weak duality lemma
- (ii) \rightarrow (iii) We show contrapositive
 - If there exists an augmenting path, then we can improve f by sending flow along path



Proof of Max-Flow Min-Cut Theorem

- (iii) \rightarrow (i)
 - Let f be a flow with no augmenting paths
 - Let A be set of vertices reachable from s in residual graph
 - By definition of A , $s \in A$
 - By definition of f , $t \notin A$

$$\begin{aligned}
 v(f) &= \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) \\
 &= \sum_{e \text{ out of } A} c(e) \\
 &= \text{cap}(A, B) \quad \blacksquare
 \end{aligned}$$





Choosing Good Augmenting Paths



Running Time

- **Assumption.** All capacities are integers between 1 and C
- **Invariant.** Every flow value $f(e)$ and every residual capacities $c_f(e)$ remains an integer throughout the algorithm
- **Integrality theorem.** If all capacities are integers, then there exists a max flow f for which every flow value $f(e)$ is an integer
Pf. Since algorithm terminates, theorem follows from invariant
- **Theorem.** The algorithm terminates in at most $v(f^*) \leq nC$ iterations.
Pf. Each augmentation increase value by at least 1
- **Corollary.** Running time of Ford-Fulkerson is $O(mnC) \leftarrow$ Polynomial?

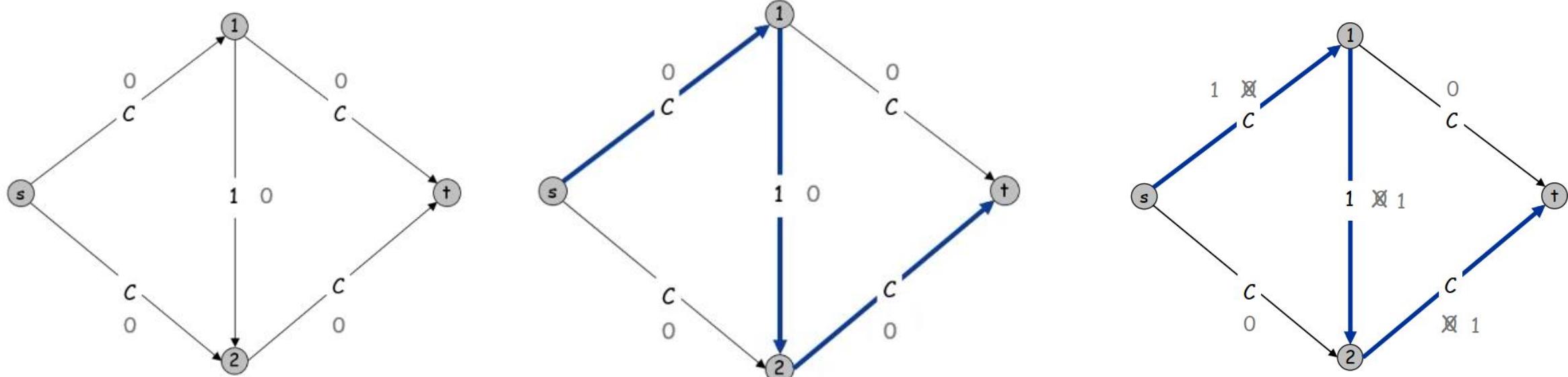


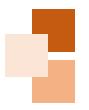
Ford-Fulkerson: Exponential Number of Augmentations

- Generic Ford-Fulkerson algorithm is not polynomial in input size?

m, n, and $\log C$

- An example: If max capacity is C , then the algorithm can take $\geq C$ iterations



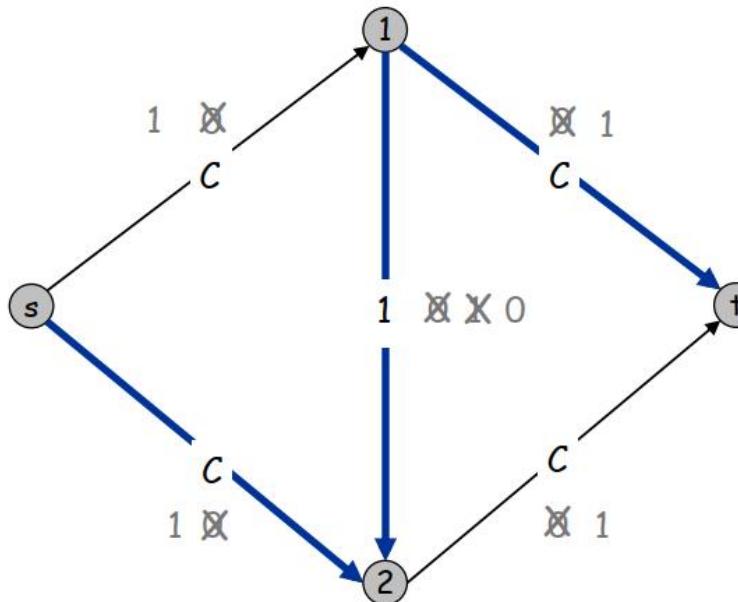
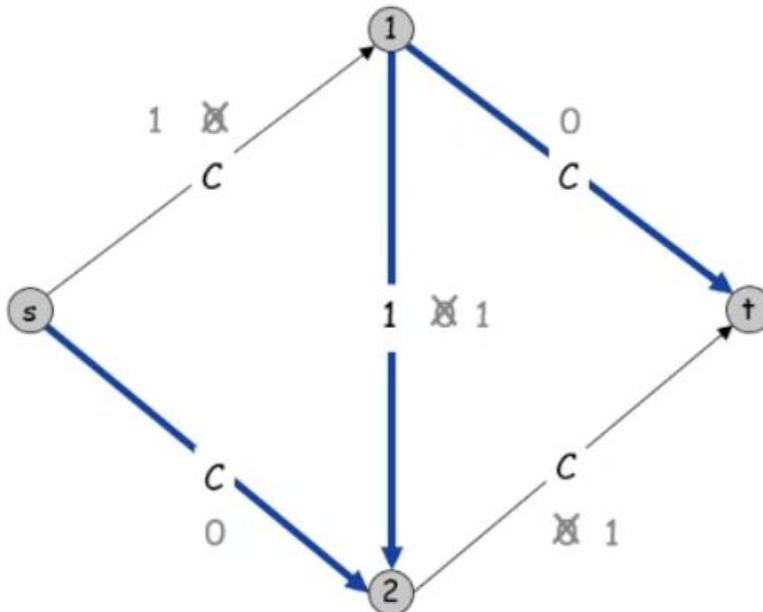


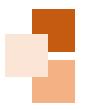
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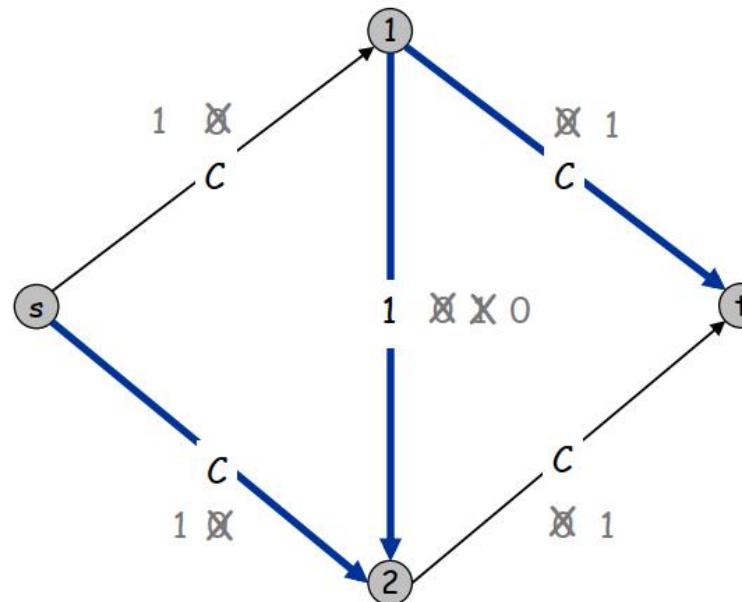


Ford-Fulkerson: Exponential Number of Augmentations

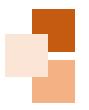
- Generic Ford-Fulkerson algorithm is not polynomial in input size?

m, n, and $\log C$

- An example: If max capacity is C , then the algorithm can take $\geq C$ iterations



Each augmenting path
sends only 1 unit of flow
(#augmenting paths = $2C$)



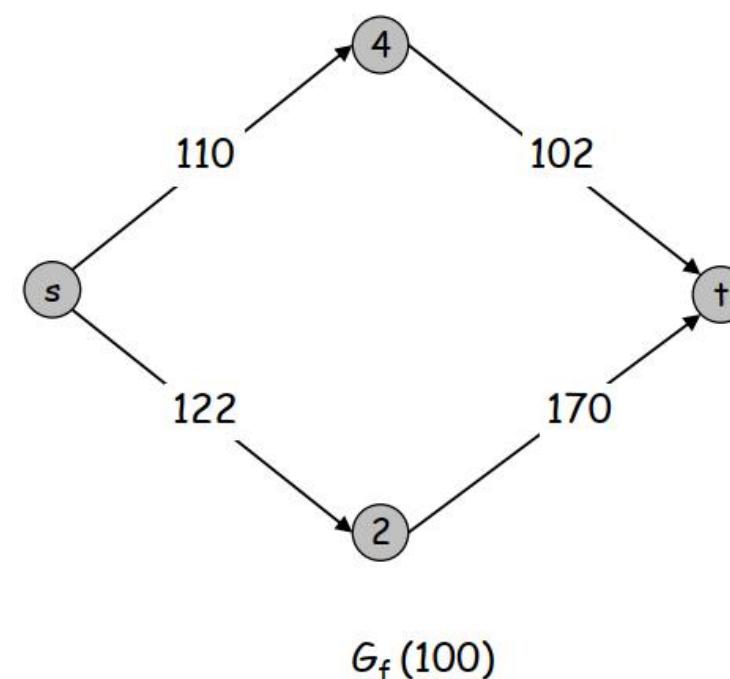
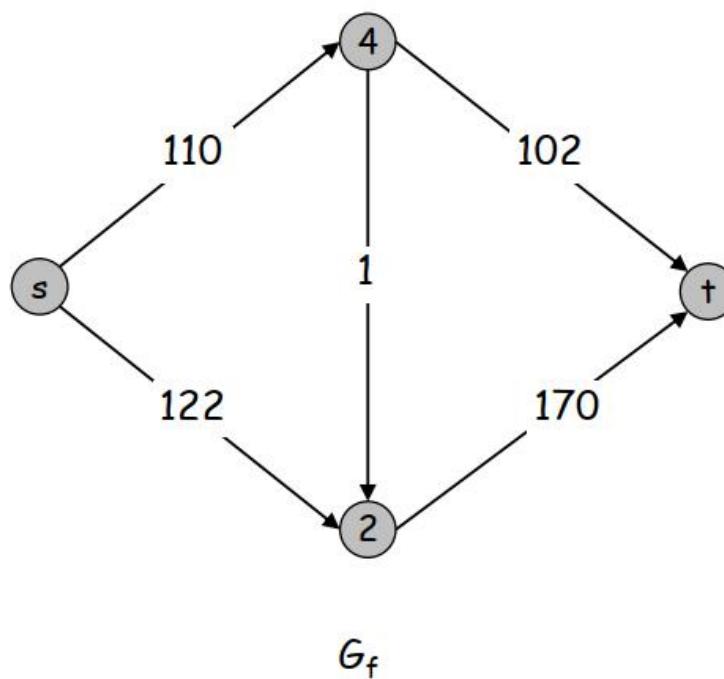
Choosing Good Augmenting Paths

- **Use care when selecting augmenting paths**
 - Some choices led to exponential algorithms
 - Clever choices lead to polynomial algorithms
 - (If capacities are irrational, algorithm not guaranteed to terminate!)
- **Goal: choose augmenting paths so that:**
 - Can find augmenting paths efficiently
 - Few iterations
- **Choose augmenting paths with: [Edmonds-Karp 1972, Dinitz 1970]**
 - Max bottleneck capacity
 - Fewest number of edges
 - **Sufficiently large bottleneck capacity**



Capacity Scaling

- **Intuition.** Choosing path with high bottleneck capacity
 - Maintain scaling parameter Δ
 - Let the **Δ -residual graph $G_f(\Delta)$** be the subgraph of the residual graph consisting of only arcs with capacity at least Δ

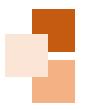




Capacity Scaling

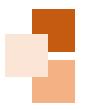
```
Scaling-Max-Flow(G, s, t, c) {
    foreach e ∈ E   f(e) ← 0
    Δ ← largest power of 2 ≤ c

    while (Δ ≥ 1) {
        Gf(Δ) ← Δ-residual graph
        while (there exists augmenting path P in Gf(Δ)) {
            f ← augment(f, c, P)
            update Gf(Δ)
        }
        Δ ← Δ / 2
    }
    return f
}
```



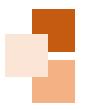
Capacity Scaling: Correctness

- **Assumption.** All edge capacities are integers between 1 and C
- **Integrality invariant.** All flow and residual capacity values are integral
- **Correctness.** If the algorithm terminates, then f is a max flow
- **Pf.**
 - By integrality invariant, when $\Delta = 1 \rightarrow G_f(\Delta) = G_f$
 - Upon termination of $\Delta = 1$ phase, there are no augmenting paths



Capacity Scaling: Running Time

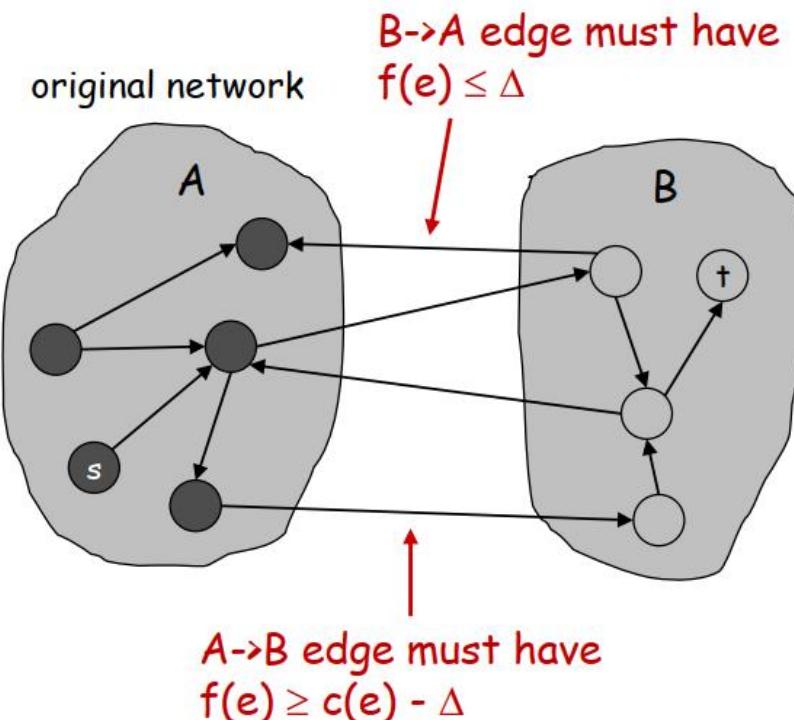
- **Lemma 1.** The outer while loop repeats $1 + \lfloor \log_2 C \rfloor$ times
- Pf. Initially $C/2 < \Delta \leq C$. Δ decreases by a factor of 2 each iteration
- **Lemma 2.** Let f be the flow at the end of a Δ -scaling phase. Then the value of the maximum flow is at most $v(f) + m\Delta \leftarrow$ proof on next slide
- **Lemma 3.** There are at most $2m$ augmentation per scaling phase.
 - Let f be the flow at the end of the previous scaling phase
 - $L2 \rightarrow V(f^*) \leq v(f) + m(2\Delta)$
 - Each augmentation in a Δ -phase increases $v(f)$ by at least Δ
- **Theorem.** The scaling max-flow algorithm finds a max flow in $O(m \log C)$ augmentations. It can be implemented to run in $O(m^2 \log C)$ time



Capacity Scaling: Running Time

- **Lemma 2.** Let f be the flow at the end of a Δ -scaling phase. Then the value of the maximum flow is at most $v(f) + m\Delta$
- **Pf.** (almost identical to proof of max-flow min-cut theorem)
 - We show that at the end of a Δ -phase, there exists a cut (A, B) such that $\text{cap}(A, B) \leq v(f) + m\Delta$
 - Choose A to be the set of nodes reachable from s in $G_f(\Delta)$
 - By definition of A , $s \in A$
 - By definition of f , $t \notin A$

$$\begin{aligned}v(f) &= \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) \\&\geq \sum_{e \text{ out of } A} (c(e) - \Delta) - \sum_{e \text{ in to } A} \Delta \\&= \sum_{e \text{ out of } A} c(e) - \sum_{e \text{ out of } A} \Delta - \sum_{e \text{ in to } A} \Delta \\&\geq \text{cap}(A, B) - m\Delta \quad \blacksquare\end{aligned}$$





**Next Time:
Network Flow (Cont.)**