

Continuous Random Variable: A random variable X is said to be continuous if it can take all possible values between certain limits, here the range space of X is infinite. Therefore the probability distribution function named for such random variable is Probability density function (PDF), which is defined as the pdf of X is a function $f(x)$ satisfying the following properties i) $f(x) \geq 0$

$$\text{ii) } \int_{-\infty}^{\infty} f(x) dx = 1$$

$$\text{iii) } \Pr\{a \leq X \leq b\} = \int_a^b f(x) dx \text{ for any } a, b \text{ such that } -\infty < a < b < \infty.$$

Note: 1. If X is a continuous random variable with pdf $f(x)$, then

$$P(a < X < b) = P(a \leq X < b) = P(a < X \leq b) = P(a \leq X \leq b) = \int_a^b f(x) dx.$$

2. $P(X = a) = 0$, if X is a continuous random variable.

Cumulative distribution function: Let X be random variable (discrete or continuous), we define F to be the cumulative distribution function of a random variable X given by $F(x) = \Pr\{X \leq x\}$.

Case i) If X is discrete random variable then

$$F(t) = \Pr\{X \leq t\} = P(x_1) + P(x_2) + \dots + P(t)$$

Case ii) If x is a continuous random variable then $F(x) = \Pr\{X \leq x\} = \int_{-\infty}^x f(x) dx$.

Two dimensional random variable: Let E be an experiment and S be a sample space associated with E . Let $X=X(s)$ and $Y=Y(s)$ be two functions each assigning a real number to each outcome s of S . We call (X, Y) to be two dimensional random variable.

Discrete 2D: If the possible values of (X, Y) are finite or countably infinite then (X, Y) is called discrete and it is defined as $P(x_i, y_j)$ satisfying the following condition,

$$\text{i) } P(x_i, y_j) \geq 0 \text{ and}$$

$$\text{ii) } \sum_{j=1}^{\infty} \sum_{i=1}^{\infty} P(x_i, y_j) = 1. \quad \text{The function } P(x_i, y_j) \text{ defined is called as Joint probability distribution function (Jpdf).}$$

Continuous 2D: If (X, Y) is a continuous random variable assuming all values in some region R of the Euclidean plane, then the Joint probability density function $f(x, y)$ is a function satisfying the following conditions

$$\text{i) } f(x, y) \geq 0 \text{ for all } (x, y) \in R$$

$$\text{ii) } \iint f(x, y) dx dy = 1 \text{ over the region } R.$$

Marginal Probability distribution: The marginal probability distribution is defined as

Case i) In the discrete (X, Y) , it is defined as $p(x_i) = P\{X = x_i\} = \sum_{j=1}^{\infty} P(x_i, y_j)$ is the marginal probability distribution of X . Similarly $q(y_j) = P\{Y = y_j\} = \sum_{i=1}^{\infty} P(x_i, y_j)$ is the marginal probability distribution of Y .

Case ii) In the continuous (X, Y) , it is defined as the marginal probability function of X is defined as $g(x) = \int_{-\infty}^{\infty} f(x, y) dy$ and the marginal probability function of Y is defined as $h(y) = \int_{-\infty}^{\infty} f(x, y) dx$.

To calculate the conditional probability:

Case i) Discrete: Probability of x_i given y_j is defined as $= \frac{P(x_i, y_j)}{q(y_j)}, q(y_j) > 0$

Probability of y_j given x_i is defined as $= \frac{P(x_i, y_j)}{p(x_i)}, p(x_i) > 0$

Case ii) Continuous: The pdf of X for given $Y=y$ is $= \frac{f(x, y)}{h(y)}, h(y) > 0$

The pdf of Y for given $X=x$ is $= \frac{f(x, y)}{g(x)}, g(x) > 0$.

Independent Random variable: If X and Y are independent random variable then two dimensional random variable in case of discrete is defined as $P(x_i, y_j) = p(x_i) \cdot q(y_j)$ for all the values of i and j. In case of Continuous it is defined as $f(x, y) = g(x) \cdot h(y)$.

Mathematical Expectation: If X is a discrete random variable with pmf p(x), then the expectation of X is given by $E(X) = \sum_x xp(x)$, provided the series is absolutely convergent.

If X is continuous with pdf f(x), then the expectation of X is given by $E(X) = \int xf(x)dx$, provided $\int |x|f(x)dx < \infty$.

Variance of X is given by $V(X) = E(X - E(X))^2 = E(X^2) - (E(X))^2$.

Chebyshev's inequality: Let x be random variable with mean μ and variance σ^2 then for any positive real number k(k>0)

$$P\{|x - \mu| \geq k\} \leq \frac{\sigma^2}{k^2} \text{ (Upper bound)}$$

$$P\{|x - \mu| < k\} > 1 - \frac{\sigma^2}{k^2} \text{ (Lower bound)}$$

Note: some other forms

$$1. \quad P\{|x - \mu| \geq k\sigma\} \leq \frac{1}{k^2} \quad \text{and} \quad P\{|x - \mu| < k\sigma\} \geq 1 - \frac{1}{k^2} \text{ (Upper bound)}$$

$$2. \quad P\{|x - \mu| \geq \epsilon\} \leq \frac{1}{\epsilon^2} E(x - c)^2 \quad \text{and} \quad P\{|x - \mu| < \epsilon\} \geq 1 - \frac{1}{\epsilon^2} E(x - c)^2$$

DISTRIBUTIONS:

Distribution	PMF/PDF	Mean	Variance
Binomial distribution $X \sim B(n, p)$	$P(x) = {}^nC_k p^k (1-p)^{n-k}, k = 0, 1, 2, \dots, n$	$E(x) = np$	$V(x) = np(1-p)$
Poisson's Distribution $X \sim P(\alpha)$	$P(x) = \frac{e^{-\alpha} \alpha^k}{k!}, k = 0, 1, 2, \dots, \alpha > 0$	$E(x) = \alpha = np$	$V(x) = \alpha = np$
Uniform Distribution $X \sim U(a, b)$	$f(x) = \begin{cases} \frac{1}{b-a}, & a < x < b \\ 0, & \text{otherwise} \end{cases}$	$E(x) = \frac{b+a}{2}$	$V(x) = \frac{(b-a)^2}{12}$
Normal Distribution $X \sim N(\mu, \sigma^2)$	$f(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{1}{2\sigma^2}(x-\mu)^2}, -\infty < x, \mu < \infty, \sigma > 0$	$E(x) = \mu$	$V(x) = \sigma^2$
Exponential Distribution $X \sim E(\lambda)$	$f(x) = \begin{cases} \lambda e^{-\lambda x}, & x > 0 \\ 0, & \text{otherwise} \end{cases}$	$E(x) = \frac{1}{\lambda}$	$V(x) = \frac{1}{\lambda^2}$
Gamma Distribution $X \sim G(r, \alpha)$	$f(x) = \begin{cases} \frac{x^{r-1} e^{-\alpha x} \alpha^r}{\Gamma(r)}, & x > 0, \alpha, r > 0 \\ 0, & \text{elsewhere} \end{cases}$	$E(x) = \frac{r}{\alpha}$	$V(x) = \frac{r}{\alpha^2}$

Chi-square Distribution $X \sim \chi^2(n)$	$f(x) = \begin{cases} \frac{x^{\frac{n}{2}-1} e^{-\frac{x}{2}}}{\Gamma(n/2) 2^{\frac{n}{2}}}, & x > 0 \\ 0, & \text{elsewhere} \end{cases}$	$E(x) = n$	$V(x) = 2n$
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Uniform distribution on a two dimensional set: If R is a set in the two-dimensional plane, and R has a finite area, then we may consider the density function equal to the reciprocal of the area of R inside R, and equal to 0 otherwise:

$$f(x,y) = \begin{cases} \frac{1}{\text{area } R}; & \text{if } (x,y) \in R \\ 0 & \text{otherwise} \end{cases}$$

Covariance: $\text{Cov}(x,y) = E(xy) - E(x)E(y)$

$$\text{Correlation coefficient: } \rho_{xy} = \rho = \frac{E(xy) - E(x)E(y)}{\sqrt{V(x)V(y)}}$$

Properties:

1. $E(c) = c$, where c is a constant.
2. $V(c) = 0$, where c is a constant.
3. If $E(xy) = 0$ then x and y are orthogonal.
4. $V(Ax + b) = A^2 V(x)$ when Ax+B is linear function of x.
5. If $\rho = 0$ then x and y are un correlated.
6. $V(Ax + by) = A^2 V(x) + B^2 V(y) + 2AB \text{Cov}(x,y)$

FUNCTIONS OF ONE DIMENSIONAL RANDOM VARIABLES

Let S be a sample space associated with a random experiment E, then it is known that a random variable X on S is a real valued function, i.e., $X: S \rightarrow R$, for each element $s \in S$, there is a real number associated.

Let X be a random variable defined on S. Let $y = H(x)$ is a real valued function of x. Then $Y = H(X)$ is a random variable on S. i.e., for each element $s \in S$, there is a real number associated, say $y = H(X(s))$. Here Y is called a function of the random variable X.

Notations:

1. R_X – the set of all possible values of the function X, called the **range space** of the random variable X.
2. R_Y – the set of all possible values of the function $Y = H(X)$, called the **range space** of the random variable Y.

Equivalent Events: Let C be an event associated with the range space R_Y . Let $B \subset R_X$ defined by $B = \{x \in R_X; H(x) \in C\}$, then B and C are called equivalent events.

Distribution function of functions of random variables:

Case 1: Let X be a discrete random variable with p.m.f. $p(x_i) = P(X = x_i)$ for $i = 1, 2, 3, \dots$. Let $Y = H(X)$ then Y is also a discrete random variable. If $Y = H(X)$ is a one to one function then the probability distribution of Y is as follows:

For the possible values of $y_i = H(x_i)$ for $i = 1, 2, 3, \dots$. The p.m.f. of $Y = H(X)$ is $q(y_i) = P(Y = y_i) = P(X = x_i) = p(x_i)$ for $i = 1, 2, 3, \dots$

Case 2: Let X be a discrete random variable with p.m.f. $p(x_i) = P(X = x_i)$ for $i = 1, 2, 3, \dots$. Let $Y = H(X)$ then Y is also a discrete random variable. Suppose that for one value of $Y = y_i$ there corresponds several values of X say $x_{i_1}, x_{i_2}, \dots, x_{i_j}, \dots$ then the p.m.f. of $Y = H(X)$ is

$$q(y_i) = P(Y = y_i) = p(x_{i_1}) + p(x_{i_2}) + \dots + p(x_{i_j}) + \dots$$

Sampling Theory:

Note: Let X_1, \dots, X_n be a random sample from a normal distribution $N(\mu, \sigma^2)$. Then

1. $\frac{(\bar{X} - \mu)\sqrt{n}}{\sigma} \sim N(0, 1)$
2. $\frac{nS^2}{\sigma^2} \sim \chi^2(n-1)$.

Estimation: $(1 - \alpha)$ 100% Confidence interval for mean when σ^2 is known is $\left(\bar{X} - \frac{a\sigma}{\sqrt{n}}, \bar{X} + \frac{a\sigma}{\sqrt{n}}\right)$, and $\left(\bar{X} - \frac{aS}{\sqrt{(n-1)}}, \bar{X} + \frac{aS}{\sqrt{(n-1)}}\right)$.