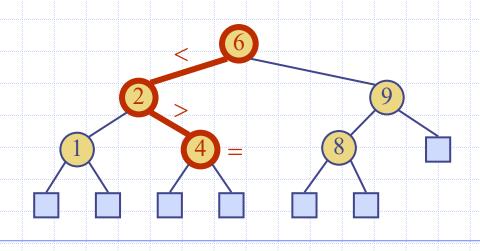
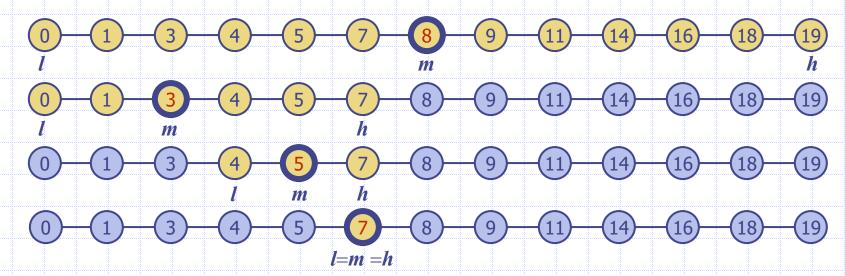
## Binary Search Trees



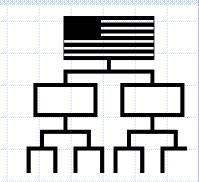
### Binary Search



- Binary search can perform nearest neighbor queries on an ordered map that is implemented with an array, sorted by key
  - similar to the high-low children's game
  - at each step, the number of candidate items is halved
  - terminates after O(log n) steps
- Example: find(7)

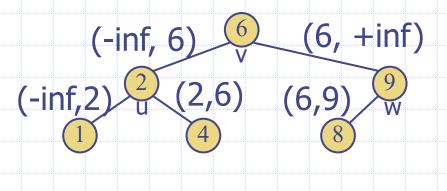


### Binary Search Trees

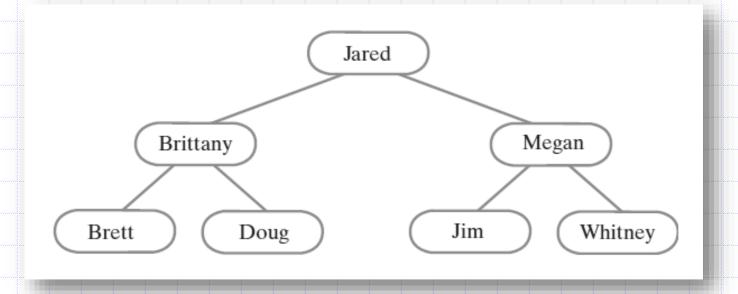


- A binary search tree is a binary tree storing keys (or key-value items) at its nodes and satisfying the following property:
- An inorder traversal of a binary search trees visits the keys in increasing order

■ Let u, v, and w be three nodes such that u is in the left subtree of v and w is in the right subtree of v. We have key(u) < key(v) < key(w)

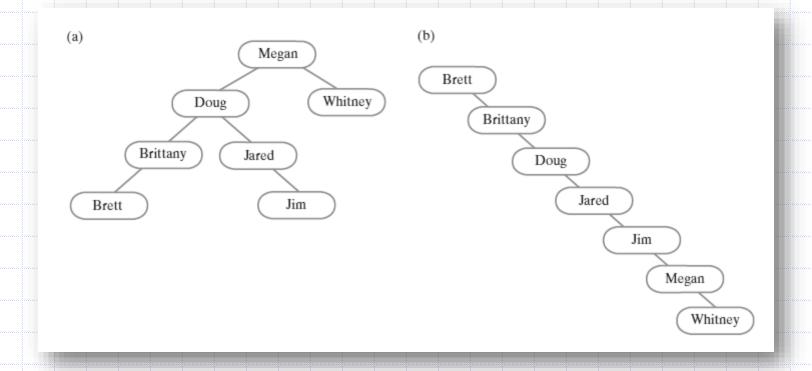


### Binary Search Tree



A binary search tree of names

### Binary Search Tree



Two BSTs containing the same data as the previous BST

#### Search

- To search for a key k, we trace a downward path starting at the root
- The next node visited depends on the comparison of k with the key of the current node
- If we reach a leaf (square box), the key is not found
- Example: find(4):Call TreeSearch(T, T.root(), 4)
- The algorithms for nearest neighbor queries are similar

```
Algorithm TreeSearch(T, p, k):

if k == p.key() then

return p {successful search}

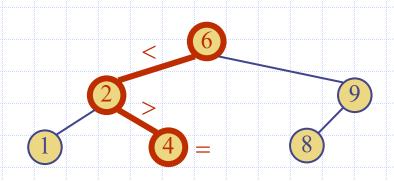
else if k < p.key() and T.left(p) is not None then

return TreeSearch(T, T.left(p), k) {recur on left subtree}

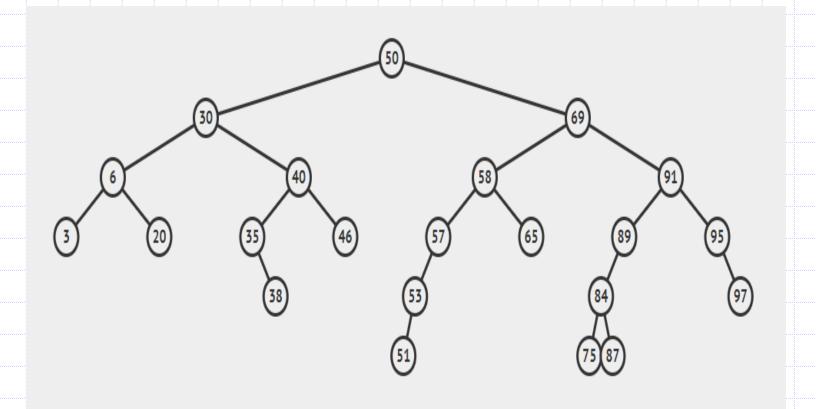
else if k > p.key() and T.right(p) is not None then

return TreeSearch(T, T.right(p), k) {recur on right subtree}

return p {unsuccessful search}
```

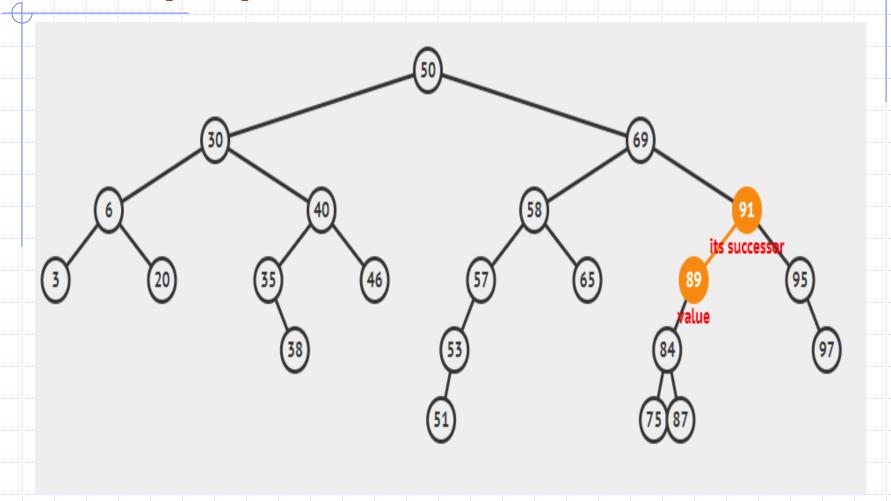


# Successor of a node after(p)

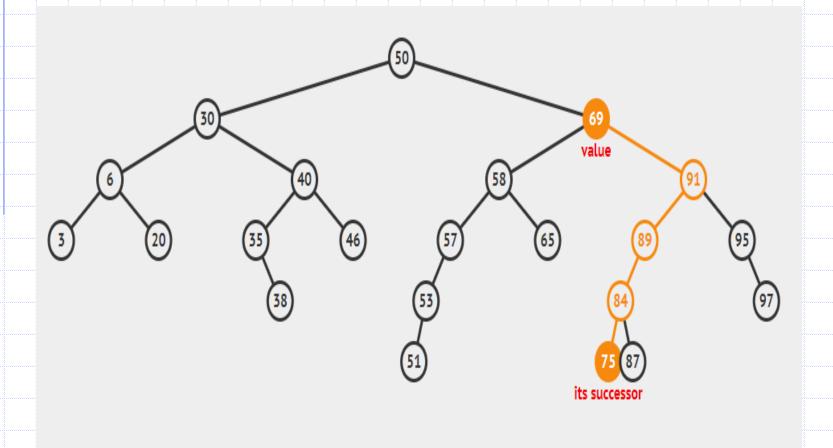


In-order traversal of BST results in a sorted sequence

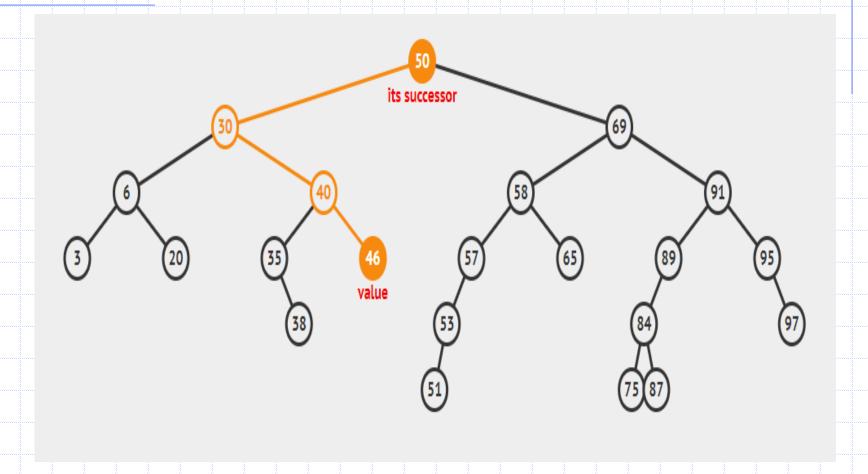
## Successor of 89 is 91after(89) = 91



## Successor of 69 is 75after(69) = 75



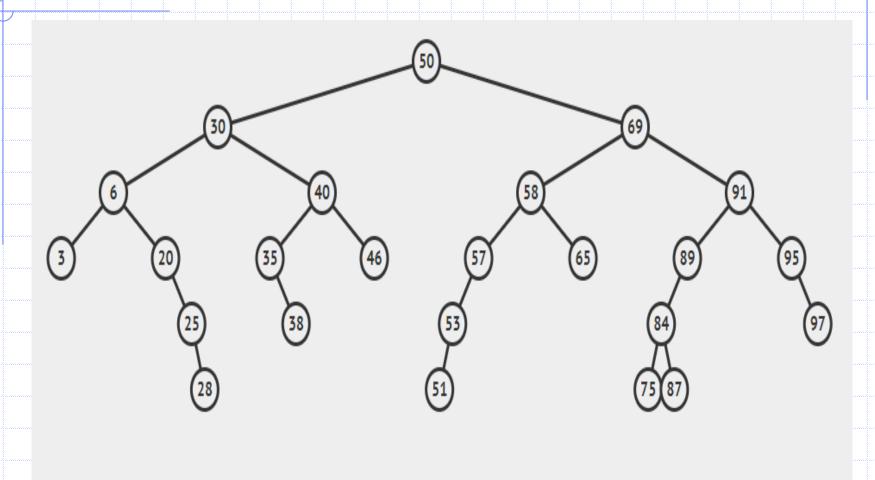
# Successor of 46 is 50 after(46) = 50



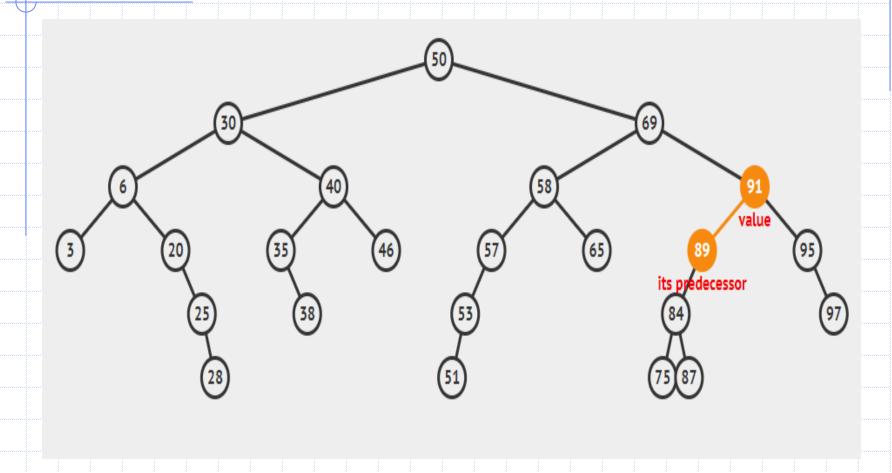
## Algorithm for after(p)

```
Algorithm after(p):
   if right(p) is not None then {successor is leftmost position in p's right subtree}
      walk = right(p)
                                        Find the smallest node
      while left(walk) is not None do
                                        in left subtree
        walk = left(walk)
      return walk
   else {successor is nearest ancestor having p in its left subtree}
      walk = p
      ancestor = parent(walk)
      while ancestor is not None and walk == right(ancestor) do
        walk = ancestor
                                        Find the ancestor that
        ancestor = parent(walk)
                                        has a bigger value
      return ancestor
```

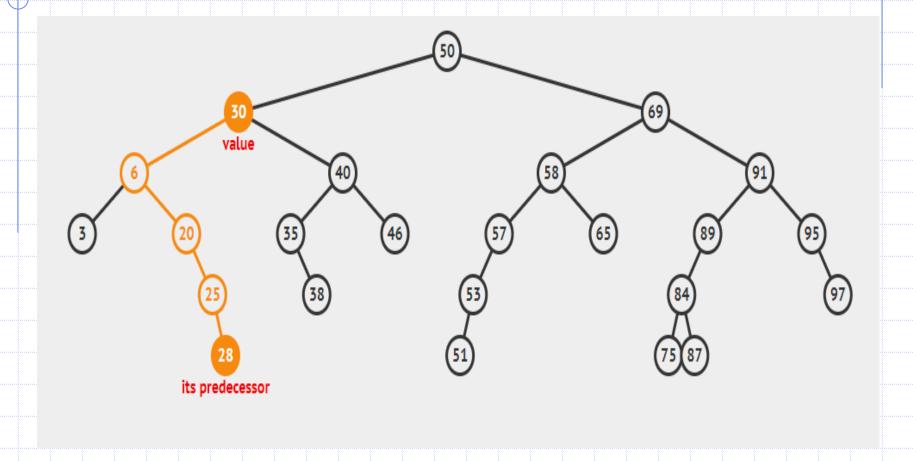
# Predecessor of a node before(p)



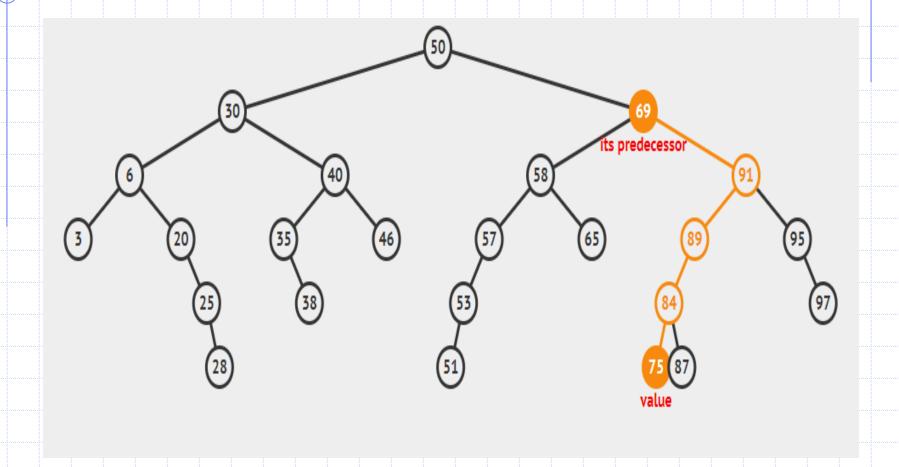
## before(91) = 89



## before(30) = 28



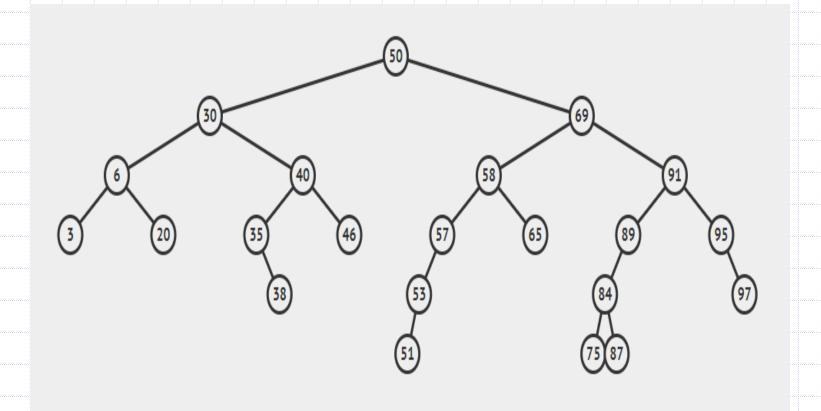
# before(75) = 69



#### First and Last

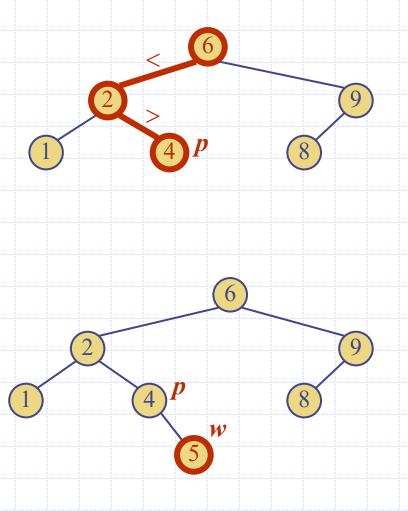
- first(): Return the position containing the least key, or None if the tree is empty.
- last(): Return the position containing the greatest key, or None if empty tree.

# What is first() and last() position for this binary tree?



#### Insertion

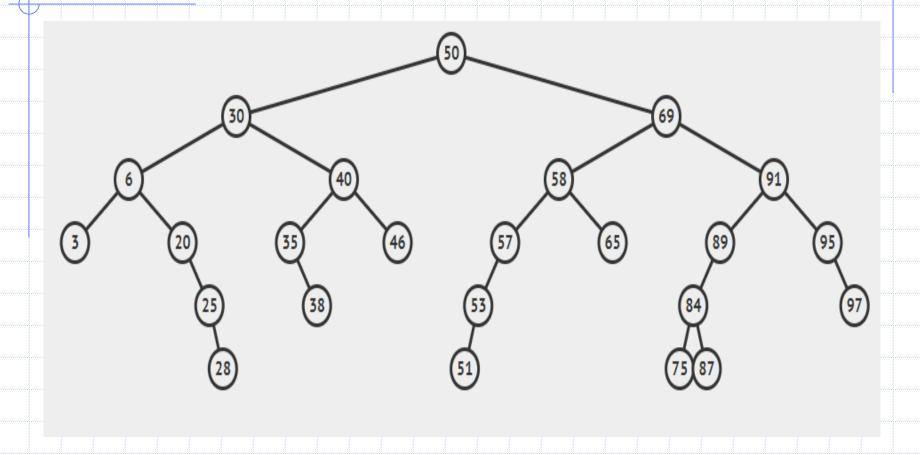
- To perform operation put(k, v), we search for key k (using TreeSearch)
- Assume k is not already in the tree, and let p be the node reached by the search
- We insert a new child node for p accordingly
- Example: insert 5



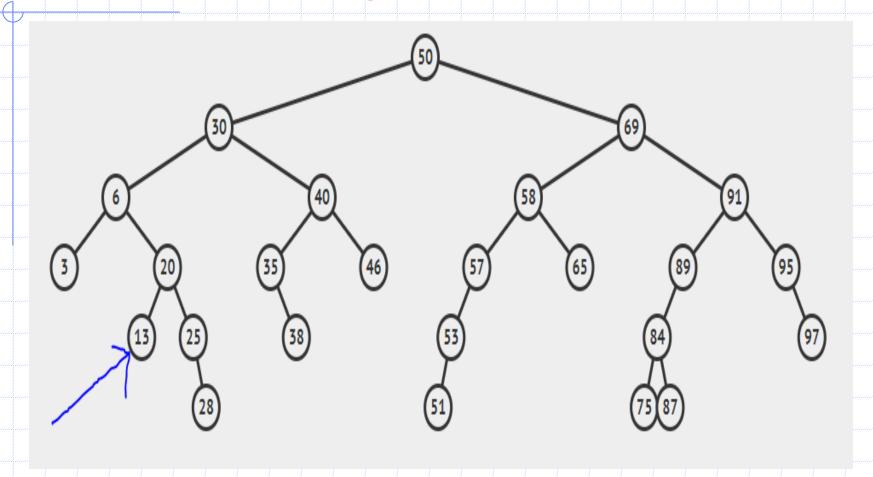
#### Insertion Pseudo-code

```
Algorithm TreeInsert(T, k, v):
    Input: A search key k to be associated with value v
    p = TreeSearch(T,T.root(),k)
    if k == p.key() then
        Set p's value to v
    else if k < p.key() then
        add node with item (k,v) as left child of p
    else
        add node with item (k,v) as right child of p</pre>
```

### Insert 13 in this tree

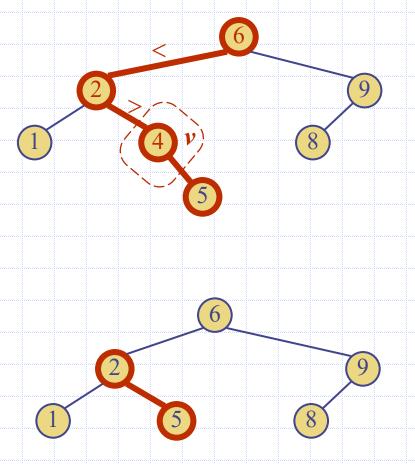


## After inserting 13



#### Deletion

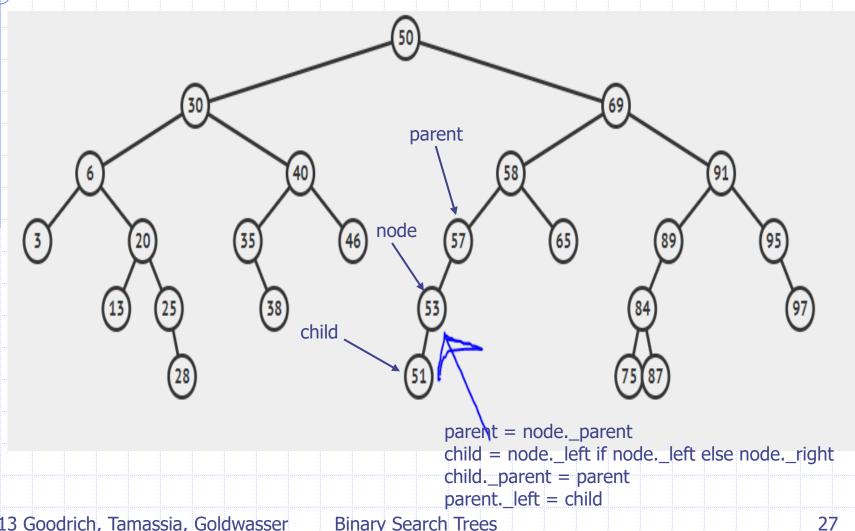
- To perform operation remove(k), we search for key k
- Assume key k is in the tree,
  and let v be the node storing
  k
- If node v has at most 1 child, connect v.parent with v.child
- Example: remove 4



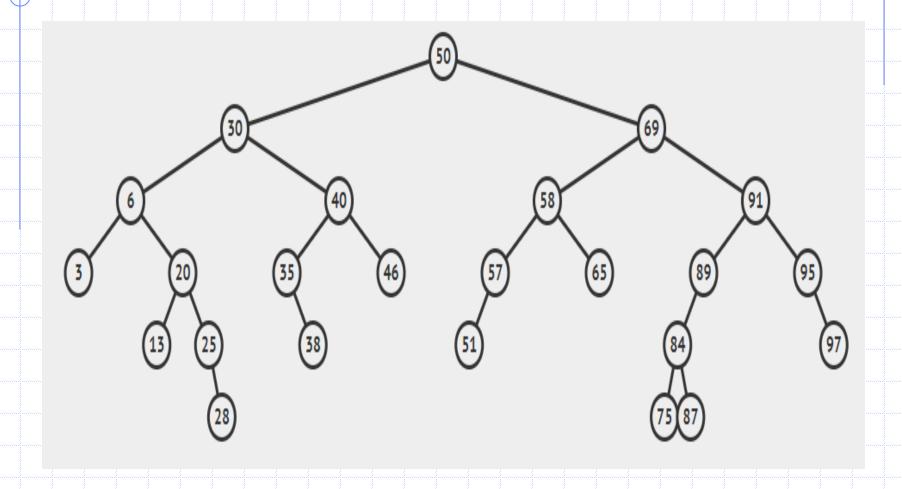
# \_delete method from LinkedBinaryTree Class

```
def _delete(self, p):
     Delete the node at Position p, and replace it with its child, if any.
  Return the element that had been stored at Position p.
  Raise ValueError if Position p is invalid or p has two children.
  node = self._validate(p)
 if self.num_children(p) == 2: raise ValueError('p has two children')
  child = node._left if node._left else node._right
                                                      # might be None
  if child is not None:
    child._parent = node._parent
                                    # child grandparent becomes parent
  if node is self. root:
   self. root = child
                                    # child becomes root
  else:
    parent = node._parent
                                    Check if node is a left or
    if node is parent._left: ←
      parent.\_left = child
                                    right child of its parent for
    else:
      parent._right = child
                                    correct connectivity
  self. size -=1
                                    # convention for deprecated node
  node._parent = node
  return node._element
```

## delete(53) 53 has just one child.

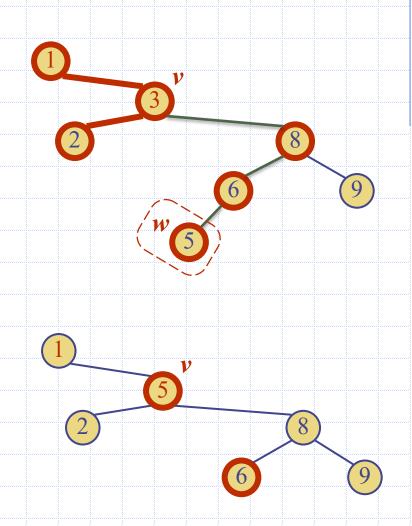


## After deleting 53

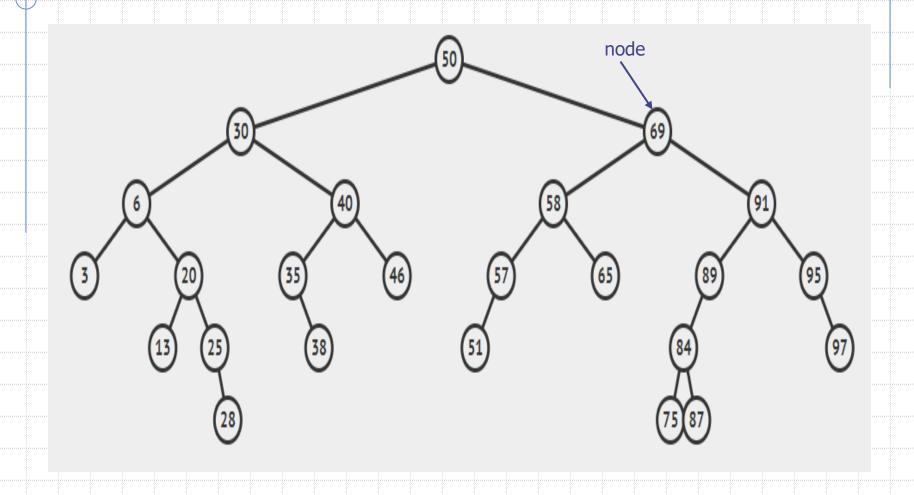


### Deletion (cont.)

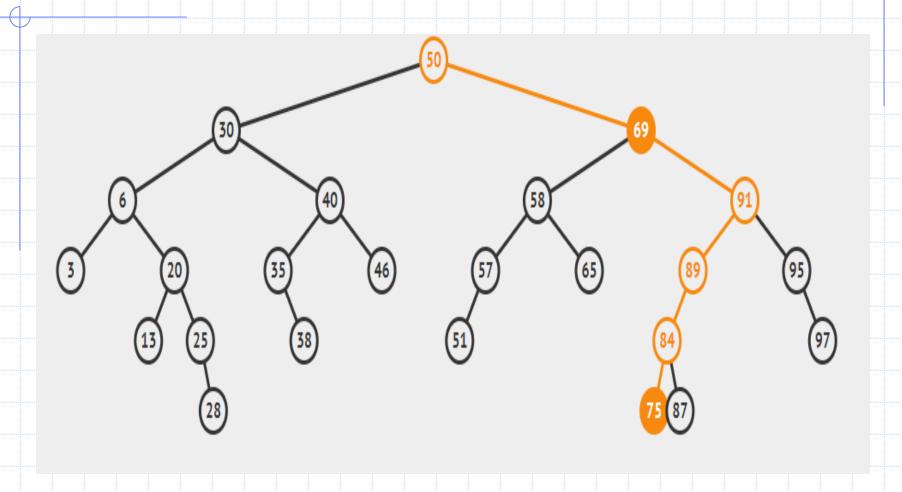
- We consider the case where the key k to be removed is stored at node v with 2 children
  - we find another node w that follows v in an inorder traversal (Find a substitution)
  - Leftmost node in subtreev.right
  - we copy key(w) into node v
  - we remove node w
- Example: remove 3



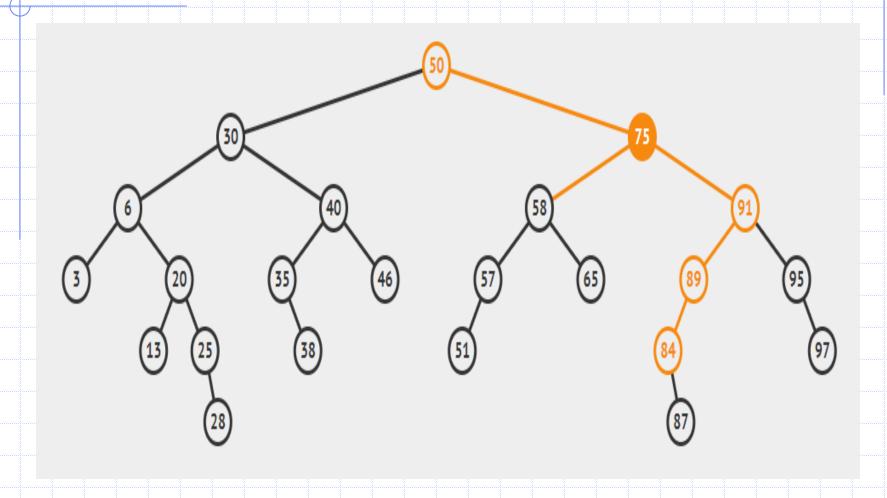
# delete(69) 69 has two children.



Let's find successor of 69 after(69) = 75, replace 69 with 75 and then delete 69.

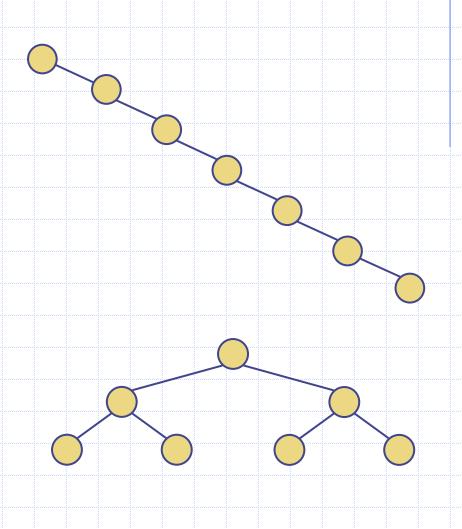


## After removing 69



#### Performance

- Consider an ordered map with n items implemented by means of a binary search tree of height h
  - the space used is O(n)
  - Search and update methods take O(h) time
- The height h is O(n) in the worst case and O(log n) in the best case



#### In-class exercise

- Download
   BinarySearchTree\_without\_position\_stu

   dent.py from Brightspace
- ◆ Implement several functions in class BinarySearchTree
  - Please refer to TODO in the code

#### Performance of BST

	Operation	Running Time
	k in T	O(h)
	T[k], T[k] = v	O(h)
	T.delete(p), del T[k]	O(h)
	$T.find_position(k)$	O(h)
	$T.first(), T.last(), T.find_min(), T.find_max()$	O(h)
	T.before(p), T.after(p)	O(h)
T	$\Gamma.find_lt(k)$ , $T.find_le(k)$ , $T.find_gt(k)$ , $T.find_ge(k)$	O(h)
	T.find_range(start, stop)	O(s+h)
	iter(T), $reversed(T)$	O(n)

• Space usage is O(n), where n is the number of items stored in the map.

#### **Animation for BST**

https://visualgo.net/bn/bst