

## Problem 1 : Backpropagation.

$$\delta W_{mn} = -\eta \frac{\partial H}{\partial W_{mn}} = -\eta \sum_{p \neq m} \frac{\partial H}{\partial \sigma_p} \frac{\partial \sigma_p}{\partial W_{mn}}$$

$$= -\eta \sum_p \frac{\partial H}{\partial \sigma_p} \sigma'(B_p) \sum_2 \frac{\partial W_{p2}}{\partial W_{mn}} x_2$$

$$= +\eta \sum_{np} \left( \frac{t_p^{(n)}}{\sigma_p^{(n)}} - \frac{(1-t_p^{(n)})}{1-\sigma_p^{(n)}} \right) \sigma'(B_p) \sum_2 \delta_{pm} \delta_{qn} x_2$$

$$= \eta \sum_m \left( \frac{t_m^{(n)} - \sigma_m^{(n)}}{\sigma_m^{(n)} (1-\sigma_m^{(n)})} \right) \sigma'(B_m) (1-\sigma(B_m)) x_n$$

using  $\tilde{\sigma}_m^{(n)} = \sigma(B_m)$

$$= \eta \sum_m (t_m^{(n)} - \sigma_m^{(n)}) x_n$$

Similarly by chain rule, obtain.

$$\delta w_{mn} = \eta \sum_{np} (t_p^{(n)} - \sigma_p^{(n)}) w_{pm} \sigma'(B_m) x_n$$

## Problem 2: Restricted Boltzmann Machine.

Definitions:  $\eta$  : learning rate  
 $\delta w_{mn}^{(u)}$  : weight update for the weight  
 $w_{mn}$ , corresponding to pattern "u".

$h_m$ : state of the  $m^{\text{th}}$  hidden neuron

$x_n^{(u)}$ : input

$v_n$ : state of the  $n^{\text{th}}$  visible neuron.

How to perform the averages:

$\langle h_m v_n \rangle_{\text{data}}$  is computed by averaging over all states  
of the hidden neurons, given that pattern  
"u" is applied to the visible neurons.

$\langle h_m v_n \rangle_{\text{model}}$  can be simplified in a similar  
manner to the  $\langle \cdot \rangle_{\text{data}}$  average, but is  
computed in simulations by M-C sampling.

$$\begin{aligned}
 \langle h_m x_n^{(u)} \rangle_{\text{data}} &= \sum_{\substack{h_i=0,1 \\ h_m=0,1}} h_m x_n^{(u)} \prod_{i=1}^I p(h_i | V=x^{(u)}) \\
 &= \sum_{h_m=0,1} h_m p(h_m | V=x) \\
 &= 1 \cdot p(b_m^{(u)}) + 0 \cdot (1 - p(b_m^{(u)})) \\
 &\Rightarrow p(b_m^{(u)})
 \end{aligned}$$

where  $p(b_m^{(u)}) = \frac{1}{1 + e^{-2b_m^{(u)}}}$

similarly,

$$\langle h_m v_n \rangle_{\text{model}} = \left\langle \frac{v_n}{1 + e^{-2b_m^{(u)}}} \right\rangle_{\text{model}}$$

Contrast: we find a sigmoid dependence on  $b_m^{(u)}$   
 instead of a tanh dependence, reflecting that  
 the 0/1 neurons do not have a "0" mean.

Whereas 1/-1 neurons do.

choose the following filters:

$$1. \begin{bmatrix} +1 & +1 \\ -1 & -1 \end{bmatrix}$$

$$2. \begin{bmatrix} -1 & -1 \\ 1 & 1 \end{bmatrix}$$

$$3. \begin{bmatrix} 1 & -1 \\ 1 & -1 \end{bmatrix}$$

$$4. \begin{bmatrix} -1 & 1 \\ -1 & 1 \end{bmatrix}$$

choose thresholds = 0, stride = 1, padding = 0.

Use max pooling,  $2 \times 2$  layers

Let bars be monochromatic columns, and stripes be monochromatic rows.

for bars, filters 1,2 output 0, whereas  
(+ max pool)

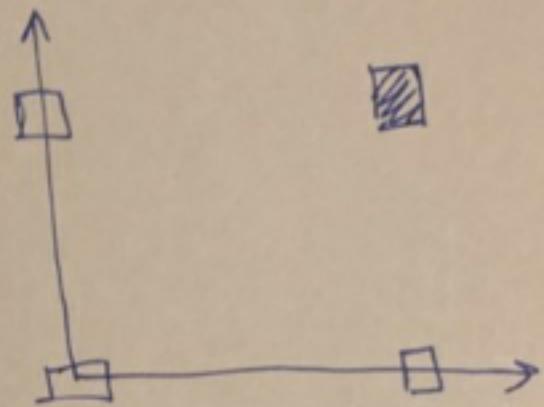
3,4 + max pool output 2, and vice versa for

stripes. Let  $x_i$  be the output of the  $i^{\text{th}}$  filter +  
max pool.

Then a F.C. layer,  $g(w_1x_1 + w_2x_2 + w_3x_3 + w_4x_4 + \dots - \theta)$   
with  $w_1 = w_2 = +1$ ,  $w_3 = w_4 = -1$ ,  $\theta = 0$ , and ~~act~~  
Step activation "g" outputs 0 for bars & 1 for stripes.

#### 4. Boolean AND problem

Input		Output
0	0	-1
0	1	-1
1	0	-1
1	1	1



$$\begin{aligned}\square &= -1 \\ \blacksquare &= +1\end{aligned}$$

f)  $H = \frac{1}{2} \left[ (-w_1 - w_2 + \theta)^2 + (-1 - w_1 + \theta)^2 + (-1 - w_2 + \theta)^2 + (-1 + \theta)^2 \right]$

Let  $\frac{\partial H}{\partial w_1}, \frac{\partial H}{\partial w_2}, \frac{\partial H}{\partial \theta} > 0$ .

$$\frac{\partial H}{\partial w_1} = 2w_1 + w_2 - 2\theta > 0$$

$$\frac{\partial H}{\partial w_2} = w_1 + 2w_2 - 2\theta > 0$$

$$\frac{\partial H}{\partial \theta} = -2 - 2w_1 - 2w_2 + 4\theta = 0$$

Solution:  $w_1 = 1, w_2 = 1, \theta = 3/2$

(c)

See Book section 5.3.

Reason: oneslap matrix not invertible for l.d. w/ infew.

(d) No, do not solve the Boolean AND.

The above procedure is equivalent to computing the pseudo inverse for the oneslap matrix. Thus essentially works as a best fit

## ⑤ Auto encoders

- write output of a layer as  $b_i^{(n)} = w_{ij} x_j^{(n)} - \theta_i$   
then, average over  $n$  and set-assume inputs have mean,

$$\langle b_i^{(n)} \rangle_n = w_{ij} \langle x_j^{(n)} \rangle_n - \theta_i$$

$$\langle b_i^{(n)} \rangle_n = -\theta_i$$

choosing  $\theta_i = 0$ , sets  $\langle b_i^{(n)} \rangle_n > 0$

$$b) H = \frac{1}{2} \sum_{i,n} \left( t_i^{(n)} - \sum_{j,k} (w_d)_{ij} (w_e)_{jk} x_k^{(n)} \right)^2$$

$$f = \frac{1}{2} \| \hat{\mathbf{x}} - W_d W_c \mathbf{x} \|^2$$

- write  $\hat{\mathbf{x}}_n = W_c \mathbf{x}$

- $\mathbf{x} = n \times N$

- assume that  $\mathbf{x}$  has rank  $n$ .

In the given case,  $|W_d| = n \times 2$ ,  $n > 2$ ,  
 so can have rank at most 2.

the matrix  $W_d \hat{\mathbf{x}}_n$  that minimises  $f$   
 is the best rank 2 approximation of  $\mathbf{x}$ .  
 can be solved using SVD.

- $\mathbf{x} = U_n \Sigma_n V_n^T$

$$W_d \hat{\mathbf{x}}_n = U_p \Sigma_p V_p^T ; p=2.$$

thus the solution can be written

$$W_d = V_p T^{-1} ; \hat{\mathbf{x}}_n = T \Sigma_p V_p^T$$

for arbit,  $p \times p$   $T$ .

finally, need to solve

$$W_e \mathbf{x} = \pi \sum_p V_p^T$$

$\underset{P \times n}{\mathbf{x}}$      $\underset{n \times N}{\mathbf{x}}$      $\underset{P \times P}{\Sigma_p}$      $\underset{P \times P}{V_p}$      $\underset{P \times N}{\mathbf{x}}$

takes SVD pseudo inverse

$$\mathbf{A}^{\dagger} \mathbf{x}$$

$$W_c = \pi \underbrace{\sum_p V_p^T V_n \Sigma_n^{-1} U_n^T}_{\frac{1}{\sigma_p} \underset{P \times N}{\mathbf{x}} \underset{N \times n}{\Sigma_n} \underset{n \times n}{U_n^T} \underset{n \times n}{\mathbf{x}}}$$

6.  $P_{\text{error}}^{t=1} = P_{\text{obs}} (C_i^{(v)} > 1)$

using CLT,  $C_i^{(v)}$  is normally distributed

with mean=0 & variance  $\sigma_c^2 \approx \frac{P}{N}$

$$P_{\text{error}}^{t=1} = \int_1^{\infty} \frac{1}{\sqrt{2\pi \sigma_c^2}} e^{-\frac{c^2}{2\sigma_c^2}}$$

$$= [1 - \text{erf}\left(\frac{1}{\sqrt{2\sigma_c^2}}\right)]$$