

→ Aufgabe 8 b und c als MEP - Vorbereitung

# Multivariable Calculus - Exercise 2

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I.BA\_IMATH, Semesterweek 06

Please write down to solution of the exercises in a concise but comprehensible way. Numerical results should be accurate to 4 digits. Sketches should be correct qualitatively. At least 75% of the exercises have to be solved satisfactorily. Due time is one week after we have discussed the corresponding topics in class.

## 1 Total differential I: The *Cow-culus* Exercise

A cow's udder is in the shape of a hemisphere.

1. If its diameter is measured to be 26cm with a possible error of 0.5cm, then use differentials to approximate the
  - (a) propagated error
  - (b) relative error
  - (c) percent errorin computing its volume.
2. Estimate the maximum allowable percent error in measuring the diameter if the error in computing the volume must not exceed 3%.

Note: In this exercise the diameter is the quantity being measured, while the volume is being computed. You should therefore express the volume as a function of the diameter.

## 2 Total differential II

- (a) Find the (total) differential of  $g(u, v) = u^2 + uv$ .
- (b) Use your answer to part (a) to estimate the change in  $g$  as you move from  $(1, 2)$  to  $(1.2, 2.1)$ .

## 3 Total differential III

In a room, the temperature is given by  $T = f(x, t)$  degrees Celsius, where  $x$  is the distance from a heater (in meters) and  $t$  is the elapsed time (in minutes) since the heater has been turned on.

A person standing 3 m from the heater 5 min after it has been turned on observes the following:

## Aufgabe 1

Volumen hemisphäre:  $V = \frac{2}{3} \pi \cdot r^3 = \frac{2}{3} \pi \cdot \left(\frac{d}{2}\right)^3$       Diameter:  $d = 26 \text{ cm}$   
 Error:  $e = 0.5 \text{ cm}$

1)

(a) Propagated error

$$\begin{aligned} \frac{dV}{e} &= \frac{\partial V}{\partial d} \cdot e \\ dV &= \frac{\partial V}{\partial d} \cdot e \\ &= \frac{d^2 \cdot \pi}{4} \cdot e \\ &= \frac{26^2 \cdot \pi \cdot 0.5}{4} \\ &= \underline{\underline{265.4646 \text{ cm}^3}} \end{aligned}$$

(b) Relative error

$$\begin{aligned} \frac{dV}{V} &= \frac{\frac{\partial V}{\partial d} \cdot e}{V} \\ &= \frac{\frac{d^2 \cdot \pi \cdot e}{4}}{\frac{1}{12} d^3 \cdot \pi} \\ &= \frac{\frac{1}{4} e}{\frac{1}{12} d} \\ &= 3 \frac{e}{d} \\ &= 3 \cdot \frac{0.5}{26} = \underline{\underline{0.0577}} \end{aligned}$$

(c) Percent error

$$\underline{\underline{5.77\%}}$$

2) Es muss gelten:

$$\begin{aligned} \frac{\frac{\partial V}{\partial d} \cdot e}{V} &\leq 0.03 \\ \frac{3 \cdot \frac{e}{26}}{1} &\leq 0.03 \quad | \cdot 26 \\ 3e &\leq 0.78 \quad | :3 \\ e &\leq \underline{\underline{0.26 \text{ cm}}} \end{aligned}$$

Der Fehler darf höchstens 0.26 cm betragen

## Aufgabe 2

(a)  $g(u, v) = u^2 + uv$

$$dg = \frac{\partial g}{\partial u} du + \frac{\partial g}{\partial v} dv = (2u + v) du + u \cdot dv$$

(b) (1,2) to (1.2, 2.1)

also sind  $du = 0.2$  und  $dv = 0.1$

$$(2 \cdot 1 + 2) \cdot 0.2 + 1 \cdot 0.1 = 0.8 + 0.1 = \underline{\underline{0.9}} = dg$$

überprüfen mit der Funktion:

$$\begin{aligned} g(1.2, 2.1) - g(1, 2) &= (1.44 + 2.52) - 3 \\ &= 3.96 - 3 = \underline{\underline{0.96}} \end{aligned}$$

## Aufgabe 3

$T = f(x, t)$

distance in m  
elapsed time in minutes

Folgende Beobachtungen:

$$\left. \frac{dT}{dt} \right|_{(3m, 5min)} = 1.2^\circ \text{C min}^{-1} \quad : \text{Distanz konstant, deshalb } x \text{ als Konstante betrachten}$$

$$\left. \frac{dT}{dx} \right|_{(3m, 5min)} = 2^\circ \text{C m}^{-1} \quad : \text{Zeit konstant}$$

$$\begin{aligned} \rightarrow \text{Totales Differential} \quad df &= \frac{\partial f}{\partial t} \cdot dt + \frac{\partial f}{\partial x} \cdot dx \\ dt &= 6 \text{ min} - 5 \text{ min} = 1 \text{ min} \\ dx &= 2.5 \text{ m} - 3 \text{ m} = -0.5 \text{ m} \\ &= 1.2^\circ \text{C min}^{-1} \cdot 1 \text{ min} + 2^\circ \text{C m}^{-1} \cdot (-0.5 \text{ m}) \\ &= \underline{\underline{1.2^\circ \text{C min}^{-1} - 2^\circ \text{C m}^{-1} \cdot 0.5}} \end{aligned}$$

keine Ahnung wie man das jetzt rechnen sollte :C

## 4 Linearization I

1.  $T$  is increasing  $1.2^\circ\text{Cmin}^{-1}$ , and
2. by walking away from the heater,  $T$  decreases by  $2^\circ\text{Cm}^{-1}$  as time is held constant.

Estimate (using the total differential) how much cooler or warmer it would be 2.5 m from the heater after 6 min.

## 4 Linearization I

Niveau linéaire

From a differentiable function  $f(x,y)$  we know  $f(1,3) = 7$  and  $\nabla f(1,3) = [2, -5]^T$ .

- (a) Find the equation of the tangent line to the level curve of  $f$  through the point  $(1,3)$ .
- (b) Find the equation of the tangent plan to the surface  $z = f(x,y)$  at the point  $(1,3)$ .

## 5 Linearization II

Suppose the gradient of  $f$  at  $\mathbf{x}_0 = [x_0, y_0]^T$  is nonzero. Using linearization and the definition of the total derivative the change in  $f$  when we move from  $\mathbf{x}_0$  to  $\mathbf{x}$  is

$$df = \nabla f(\mathbf{x}_0) \bullet (\mathbf{x} - \mathbf{x}_0)$$

Therefore, the tangent line to the contourline satisfies

$$df = 0 \quad \Leftrightarrow \quad \nabla f(\mathbf{x}_0) \bullet (\mathbf{x} - \mathbf{x}_0) = 0$$

Therefore, the contourline through  $\mathbf{x}_0$  is perpendicular to the gradient  $\nabla f(\mathbf{x}_0)$  at this point.

Verify this for

- (a)  $f(x,y) = y - x^2$  and  $\mathbf{x}_0 = [1, 1]^T$ .
- (b)  $g(x,y) = x^2 - y^2$  and  $\mathbf{x}_0 = [2, \sqrt{3}]^T$ .

Check by drawing the contour and the tangent line!

## 6 Newton-Raphson Method

Using the Newton-Raphson Method solve the following system of nonlinear equations

$$\begin{aligned} x - y + 1 &= 0 \\ x^2 - y - 1 &= 0 \end{aligned}$$

Use Octave/Matlab and verify that the programs on the slides work. Check the result by an analytical solution of this system of nonlinear equations. As the starting value use  $(1,1)$ . You must compute the Jacobian Matrix.

#### Aufgabe 4

$$f(1,3) = 7 \quad \text{und} \quad \nabla f(1,3) = [2, -5]^T$$

$$(a) \nabla f(\vec{x}_0) \cdot (\vec{x} - \vec{x}_0) = 0$$

$$\Rightarrow \begin{bmatrix} 2 \\ -5 \end{bmatrix} \cdot \begin{bmatrix} x-1 \\ y-3 \end{bmatrix} = 2(x-1) - 5(y-3) = 0$$

$$2x - 2 - 5y + 15 \stackrel{!}{=} 0$$

$$2x - 5y + 13 \stackrel{!}{=} 0 \Rightarrow y = \frac{2x + 13}{5}$$

$$(b) L(x) = f(x_0) + \nabla f(x_0) \cdot (x - x_0)$$

$$\Rightarrow L(x) = 7 + \begin{bmatrix} 2 \\ -5 \end{bmatrix} \cdot \begin{bmatrix} x-1 \\ y-3 \end{bmatrix}$$

$$= 7 + 2x - 5y + 13$$

$$\stackrel{!}{=} 2x - 5y + 20 = z$$

$$\Rightarrow \text{plane: } 2x - 5y - z + 20$$

Überprüfen mit  $P(1,3) = 7$

$$2 - 15 - z + 20 = 0$$

$$\stackrel{!}{=} 7 = z \quad \checkmark$$

**Aufgabe 5** - zeigen, dass Niveaulinien und Gradient bei  $x_0$  senkrecht zueinander sind

$$(a) f(x,y) = y - x^2 \quad \text{and} \quad x_0 = [1, 1]^T$$

Contour line:  $y - x^2 = 0 \Rightarrow y = x^2$   
 $1 - 1 = 0$

Tangente an Niveaulinie:

$$\vec{\nabla} f(x,y) = \begin{bmatrix} -2x \\ 1 \end{bmatrix} \Rightarrow \vec{\nabla} f(1,1) = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$$

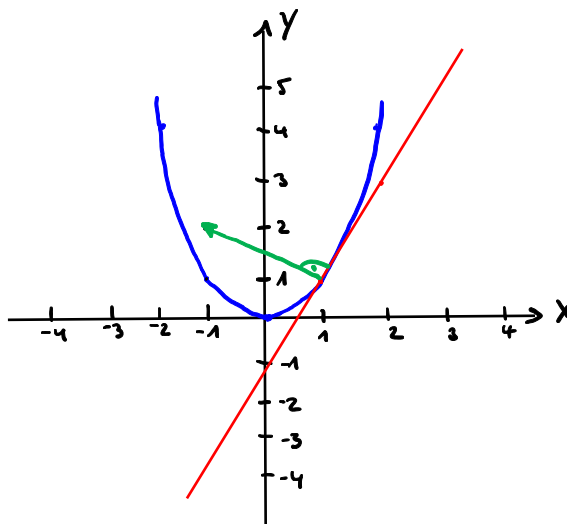
$$= \vec{\nabla} f(1,1) \cdot \begin{bmatrix} x-1 \\ y-1 \end{bmatrix}$$

$$= \begin{bmatrix} -2 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} x-1 \\ y-1 \end{bmatrix} \stackrel{!}{=} -2x + 2 + y - 1 = 0$$

$$\rightarrow L(x) = f(x_0) + \nabla f(x_0) \cdot (x - x_0)$$

$$\stackrel{!}{=} 0 - 2x + y + 1$$

$$\stackrel{!}{=} -2x + y + 1 \Rightarrow y = 2x - 1$$



(b)  $g(x,y) = x^2 - y^2$  and  $x_0 = [2, \sqrt{3}]^T$  ← need to check again, bc  $2^2 - \sqrt{3}^2 = ?$

Contour lines:  $x^2 - y^2 = 1 \Rightarrow y^2 = x^2 - 1$   
 $4 - 3 = 1$   $y = \sqrt{x^2 - 1}$

Tangente an Niveaulinie:

$$\vec{\nabla} g(x,y) = \begin{bmatrix} 2x \\ -2y \end{bmatrix} \Rightarrow \vec{\nabla} g(2, \sqrt{3}) = \begin{bmatrix} 4 \\ -2\sqrt{3} \end{bmatrix}$$

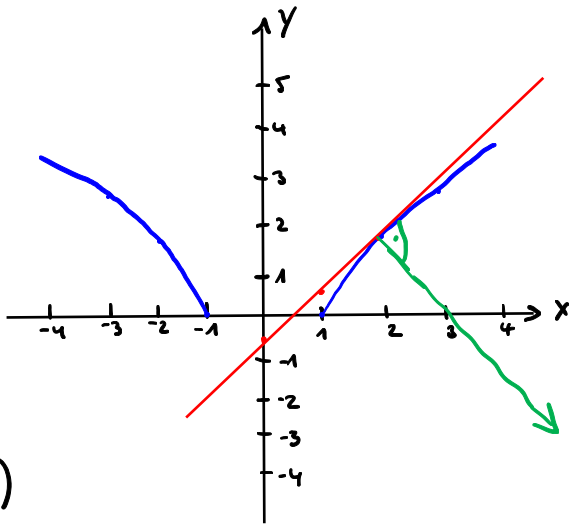
$$= \vec{\nabla} g(2, \sqrt{3}) \cdot \begin{bmatrix} x-2 \\ y-\sqrt{3} \end{bmatrix}$$

$$\begin{aligned} &= \begin{bmatrix} 4 \\ -2\sqrt{3} \end{bmatrix} \cdot \begin{bmatrix} x-2 \\ y-\sqrt{3} \end{bmatrix} = 4(x-2) - 2\sqrt{3}(y-\sqrt{3}) \\ &= 4x - 8 - 2\sqrt{3}y + 6 \\ &= 4x - 2\sqrt{3}y - 2 = 0 \end{aligned}$$

$$\rightarrow L(x) = \nabla f(x_0) \cdot (x - x_0)$$

$$= 4x - 2\sqrt{3}y - 2$$

$$= -2\sqrt{3}y - 2 \Rightarrow y = \frac{4x - 2}{2\sqrt{3}}$$



## Aufgabe 6

$$\begin{aligned}x - y + 1 &= 0 \\ x^2 - y - 1 &= 0\end{aligned}$$

$$x_0 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$k=0$ :

$$J_F(x_k) = \begin{bmatrix} \frac{\partial F_1}{\partial x}(x_k) & \frac{\partial F_1}{\partial y}(x_k) \\ \frac{\partial F_2}{\partial x}(x_k) & \frac{\partial F_2}{\partial y}(x_k) \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 2x_k & -1 \end{bmatrix}$$

$$J_F(x_0) \Delta x_0 = -F(x_0) \Leftrightarrow \begin{bmatrix} 1 & -1 \\ 2 & -1 \end{bmatrix} \Delta x_0 = \begin{bmatrix} -1 \\ 1 \end{bmatrix} \Rightarrow \Delta x_0 = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

$$\underline{k=1}: x_1 = \overset{x_0}{\begin{bmatrix} 1 \\ 1 \end{bmatrix}} + \overset{\Delta x_0}{\begin{bmatrix} 2 \\ 3 \end{bmatrix}} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

$$J_F(x_1) \Delta x_1 = -F(x_1) \Leftrightarrow \begin{bmatrix} 1 & -1 \\ 6 & -1 \end{bmatrix} \Delta x_1 = \begin{bmatrix} 0 \\ -4 \end{bmatrix} \Rightarrow \Delta x_1 = \begin{bmatrix} -\frac{4}{5} \\ -\frac{4}{5} \end{bmatrix}$$

usw.  $\rightarrow$  Octave :)

## 7 Chain-Rule I

### 7 Chain-Rule I

Find  $dz/dt$  using the chain rule if

- (a)  $z = xy^2, x = e^{-t}, y = \sin t$
- (b)  $z = \ln(x^2 + y^2), x = 1/t, y = \sqrt{t}$
- (c)  $z = (x + y)e^y, x = 2t, y = 1 - t^2$ .

### 8 Chain-Rule II

Find  $\partial z/\partial u = z_u$  and  $\partial z/\partial v = z_v$  using the chain rule if

- (a)  $z = xe^y, x = \ln u, y = u$
- (b)  $z = xe^y, x = u^2 + v^2, y = u^2 - v^2$
- (c)  $z = \ln(xy), x = (u^2 + v^2)^2, y = (u^3 + v^3)^2$ .

→ b und c in MEP Vorbereitung

**Viel Spass!**

# Aufgabe 7

(a)  $z = xy^2$ ,  $x = e^t$ ,  $y = \sin(t)$

$$\begin{array}{c} \frac{\partial z}{\partial x} = y^2 \\ \frac{\partial z}{\partial y} = 2xy \\ \frac{dx}{dt} = e^t \\ \frac{dy}{dt} = \cos(t) \end{array}$$

$$\begin{aligned} \frac{dz}{dt} &= \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt} \\ &= y^2 \cdot (-e^t) + 2xy \cdot \cos(t) \\ &= -y^2 e^t + 2xy \cos(t) \\ &= -(\sin(t))^2 \cdot e^t + 2e^t \cdot \sin(t) \cos(t) \\ &= \sin(t) e^t (-\sin(t) + 2 \cos(t)) \end{aligned}$$

(b)  $z = \ln(x^2 + y^2)$ ,  $x = 1/t$ ,  $y = \sqrt{t}$

$$\begin{array}{c} \frac{\partial z}{\partial x} = \frac{2x}{x^2 + y^2} \\ \frac{\partial z}{\partial y} = \frac{2y}{x^2 + y^2} \\ \frac{dx}{dt} = -\frac{1}{t^2} \\ \frac{dy}{dt} = \frac{1}{2\sqrt{t}} \end{array}$$

$$\begin{aligned} \frac{dz}{dt} &= \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt} \\ &= \frac{2x}{x^2 + y^2} \cdot \frac{-1}{t^2} + \frac{2y}{x^2 + y^2} \cdot \frac{1}{2\sqrt{t}} \\ &= \frac{2}{(x^2 + y^2)} \left( \frac{-x}{t^2} + \frac{y}{2\sqrt{t}} \right) \\ &= \frac{2}{\left(\frac{1}{t}\right)^2 + \left(\frac{1}{t}\right)^2} \left( \frac{\frac{1}{t}}{t^2} + \frac{\sqrt{t}}{2\sqrt{t}} \right) \\ &= \frac{2}{\frac{1}{t^2} + \frac{1}{t^2}} \left( \frac{t^{-1}}{t^2} + \frac{1}{2} \right) \\ &= \frac{2t^2}{1 + t^3} \left( \frac{-1}{t^3} + \frac{1}{2} \right) \\ &= \frac{2t^2}{1 + t^3} \cdot \frac{-2 + t^3}{2t^3} \\ &= \frac{-4t^2 + 2t^5}{2t^3 + 2t^6} = \frac{-4t^2 + 2t^5}{2t^3(1 + t^3)} = \frac{-2 + t^3}{1 + t^3} \end{aligned}$$



$$(c) z = (x+y)e^y, x = 2t, y = 1-t^2$$

$$(x+y)e^y = xe^y + ye^y$$

$$\frac{\partial z}{\partial x} = e^y$$

$$\frac{\partial z}{\partial y} = xe^y + ye^y + e^y = e^y(x+y+1)$$

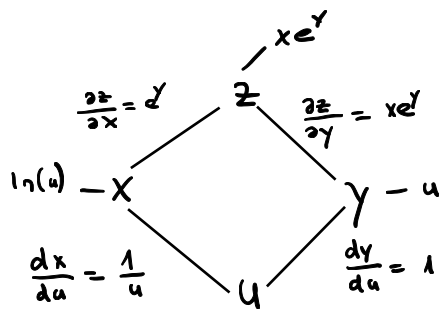
$$2t - x \quad y - 1-t^2$$

$$\frac{dx}{dt} = 2 \quad \frac{dy}{dt} = -2t$$

$$\begin{aligned} \frac{dz}{dt} &= \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt} \\ &= e^y \cdot 2 + e^y(x+y+1) \cdot (-2t) \\ &= 2e^y - 2te^y(x+y+1) \\ &= 2e^y(1 - t(x+y+1)) \\ &= 2e^{(1-t^2)}(1 - t(2t + (1-t^2) + 1)) \\ &= 2e^{(1-t^2)}(1 - t(2t + 1 - t^2 + 1)) \\ &= 2e^{(1-t^2)}(1 - t(-t^2 + 2t + 2)) \\ &= 2e^{(1-t^2)}(1 + t^3 - 2t^2 - 2t) \\ &= \underline{\underline{2e^{(1-t^2)}(t^3 - 2t^2 - 2t + 1)}} \end{aligned}$$

## Aufgabe 8

(a)  $z = xe^y$ ,  $x = \ln(u)$ ,  $y = u$



$$\begin{aligned}\frac{dz}{du} &= \frac{\partial z}{\partial x} \frac{dx}{du} + \frac{\partial z}{\partial y} \frac{dy}{du} \\ &= e^y \cdot \frac{1}{u} + xe^y \cdot 1 \\ &= \frac{e^y}{u} + xe^y \\ &= e^y \left( \frac{1}{u} + x \right) = \underline{\underline{e^u \left( \frac{1}{u} + \ln(u) \right) }}\end{aligned}$$