

# COUVERTURE

## Technical Report on OBC/MCDC properties

### Abstract

This document gathers results established or formalized by the COUVERTURE project team about relationships between specific coverage criteria. We focus in particular on how *Object Branch Coverage* (OBC) relates to the *Modified Condition/Decision Coverage* (MC/DC) criterion.

We provide two broad categories of results: formal proofs of important properties over a model of the two criteria, and a machine-automated verification of some of these properties for concrete subsets of the model expressed in Alloy. These results constitute the grounds on which our project coverage analysis framework operates to infer source coverage results from object coverage information out of an instrumented execution environment.

# 1 Common definitions

## 1.1 Decisions, conditions

We are considering decisions that are short circuit boolean expressions, i.e. expressions consisting in elementary boolean conditions combined together using only the and then, or else and not operators.

In order to compare *Object Branch Coverage* to *Modified Condition/Decision Coverage*, it will be shown that the appropriate abstractions are Reduced Ordered Binary Decision Diagram. For each decision (ROBDD), we will provide an algorithm that constructs the associated ROBDD, whose nodes are conditions. (RO)BDDs have an entry point, and two or more exit edges labeled True and False.

In the remainder of this document, unless otherwise indicated, all references to BDDs denote reduced ordered BDDs. For a set  $S$ ,  $\#S$  will refer to this set's cardinal. For a decision  $D$ ,  $\text{cond}(D)$  will be the set of its conditions.

## 1.2 Coverage metrics

Coverage assessment is accomplished by exercising some piece of object code in a variety of test cases, recording data along the way, and then determining whether the successive executions of the object code satisfy a given criterion of exhaustiveness. This section will define the main coverage criterion that we will consider.

The minimum number of distinct executions required to achieve a specific criterion is an important aspect in the evaluation of any coverage assessment methodology. Here we establish some properties that give a hard limit on test set size for various coverage metrics.

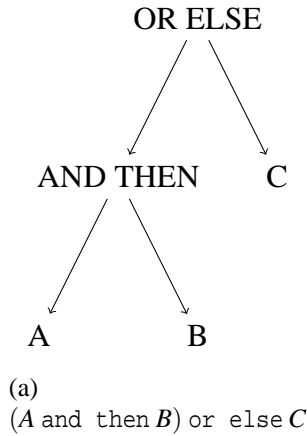
### 1.2.1 MC/DC

**Formal definition:** The formal definition of MC/DC that it used here is the one given in [Chi01], using a graph-coloring algorithm to determine whether two given evaluations show the independent influence of a condition. Amongst the various formal definitions that you may find in the litterature, this one has the advantage to apply also to short-circuit operators, which is mandatory in the context of COUVERTURE.

The following will not re-define what has already detailed in [Chi01]; we will just give an example on how it works and will invit the interested reader to consult the

original document. A formal definition may also be found in the Alloy model, in file `decision_coverage.als`.

This formal definition of MC/DC uses a simple graph-coloring algorithm to determine whether two given evaluations show the independent influence of a condition. It first colors each node of the decision syntax tree with both evaluations; for example, for a decision  $(A \text{ and then } B) \text{ or else } C$ , the syntax tree can be seen on figure 1(a).



For each evaluation, each node of the tree (atomic condition or root of sub-decision) is colored with the value that it takes in this evaluation: True (T), False (F), Not\_Evaluated (X). For the evaluation  $e1 = (A = \text{True}, B = \text{True}, C = \text{Not\_Evaluated})$ , we have the coloring given on figure 1(b); and for  $e2 = (A = \text{False}, B = \text{Not\_Evaluated}, C = \text{False})$ , we have the coloring given on figure 1(c).

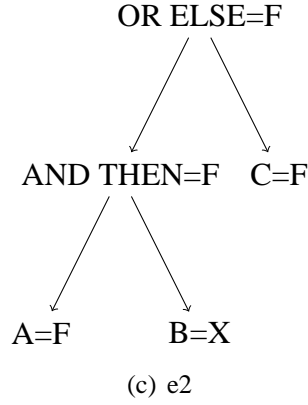
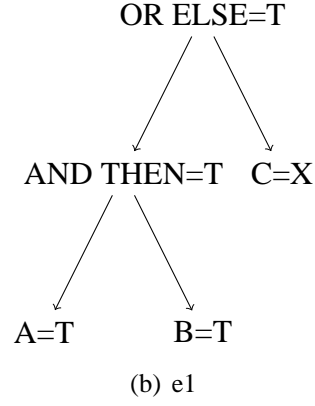
Both graphs are then combined into an influence tree by xor'ing each node. An extension of xor to three-value boolean algebra is used: anything xor Not\_Evaluated gives False. In our case, the result is showed on figure 1(d).

The influence set of these two evaluations for the given decision is the set of conditions that have a path of “True nodes” to the root. So here, it is the singleton  $\{A\}$ .

The two classical variants of MC/DC are then defined as follow:

**DEFINITION 1** *Given a decision  $D$ , a pair of truth vectors satisfies Masking MC/DC for a condition  $c$  in  $\text{cond}(D)$  if and only if its influence set is the singleton  $\{c\}$ .*

*A test set satisfies Masking MC/DC for a decision  $D$  if, and only if, for each condition in  $\text{cond}(D)$ , there exists a pair of tests in the test set that satisfies Masking MC/DC.*



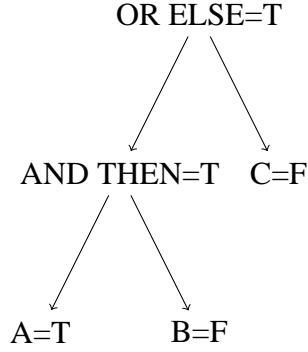
**DEFINITION 2** *Given a decision  $D$ , a pair of truth vectors satisfies Unique Cause MC/DC for a condition  $c$  in  $\text{cond}(D)$  if and only if its influence set is the singleton  $\{c\}$  and if  $c$  is the only condition that is colored with True in the influence tree.*

*A test set satisfies Unique Cause MC/DC for a decision  $D$  if, and only if, for each condition in  $\text{cond}(D)$ , there exists a pair of tests in the test set that satisfies Unique Cause MC/DC.*

In our example, our pair of truth vectors satisfies both Unique Cause and Masking MC/DC for condition A.

**Properties:** For Unique Cause, the following property holds:

**THEOREM 1** *Unique MC/DC on a decision with  $n$  independent conditions is achieved with a test set of exactly  $n + 1$  tests, and cannot be achieved in fewer tests.*



(d) Influence tree

The existence of the test set is proved by induction. For one condition, MC/DC is achieved with two tests, one setting it True and the other False.

Now assume that the property holds for all  $n \leq N$ , and consider a decision with  $N + 1$  conditions. It is of the form  $D = D_l \star D_r$  where  $\star$  is either and then or or else. There is also possibly a negation, which is omitted here since it has no impact on MC/DC. For the remainder of this proof we assume the operator is and then; the same reasoning applies similarly for the case of or else.

$D_l$  and  $D_r$  are decisions with respectively  $n_l$  and  $n_r$  conditions (both at most  $N$ ), and  $n_l + n_r = N + 1$ . From the induction hypothesis we have two test vector sets  $T_l = \{v_l(0) \dots v_l(n_l)\}$  and  $T_r = \{v_r(0) \dots v_r(n_r)\}$  that satisfy MC/DC for  $D_l$  and  $D_r$  respectively, and we can arbitrarily choose the indices so that  $D_l$  is True for  $v_l(0)$  and  $D_r$  is True for  $v_r(0)$ .

We can now create a combined test set for the complete decision as follows.

$$(\forall j \in [0, n_l]) v(j) = (v_l(j) \cdot v_r(0))$$

$$(\forall j \in [1, n_r]) v(n_l + j) = (v_l(0) \cdot v_r(j))$$

We have thus created a set  $T = \{v(0) \dots v(n_l + n_r)\}$  of  $N + 2$  tests. It is immediate that the elements with indices 0 to  $n_l$  give for  $D$  the same outcome as the corresponding elements of  $T_l$  for  $D_l$ , and they all have identical values for the conditions coming from  $D_r$ , so they show independent influence of all conditions coming from  $D_l$ . Similarly the vector set  $\{v(0), v(n_l + 1) \dots v(n_l + n_r)\}$  shows independent influence of those conditions coming from  $D_r$ , so the new test set  $T$  satisfies MC/DC for  $D$  and thus the induction property holds at  $N + 1$  as well, since  $T$  has  $n_l + n_r + 1 = N + 2$  elements.

The proof that this is the minimal test set size is given in [Chi01]. As for Masking MC/DC, we have the following property:

**THEOREM 2** *Masking MC/DC on a decision with  $n$  independent conditions requires a minimum of  $RUTW(2 * SQRT(n))$  tests, where RUTW stands for round up to whole.*

The proof of this property is given in [Chi01] as well.

### 1.2.2 OBC

Applicants for DO-178 certification have sometimes proposed the use of object code coverage instead of source code coverage as a metric to satisfy the objectives of DO-178. The proposed approach involves measuring either instruction coverage or branch coverage. Object instruction coverage (OIC) requires assessing whether all object instructions are executed at least once; object branch coverage (OBC) in addition requires that all conditional branches be exercised for both directions (branch and fall through). The use of object code coverage has also been proposed as a way to cope with untraceable object code. Section 6.4.4.2 of DO-178 indeed states: *The structural coverage analysis may be performed on the Source Code, unless the software level is A and the compiler generates object code that is not directly traceable to Source Code statements. Then, additional verification should be performed on the object code to establish the correctness of such generated code sequences.*

Untraceable object code is compiler generated machine code that impacts the execution control flow in a way not directly visible from source code. An example is the Ada mod operator, which requires an implicit conditional branch to distinguish between positive and negative moduli. Achieving a certain source coverage level is not indicative of coverage of untraceable code: even a comprehensive testing campaign (from a source coverage point of view) may not assure all object code is executed. The untraceable object code is nevertheless present in the application and may lead to unintended behaviour not verified during the testing process.

Measuring object code coverage may be a way to ensure even untraceable code is executed during the requirement-driven testing campaign. However, CAST paper 12 [CAS02] suggests the use of a *traceability study* to satisfy the additional verification activities on untraceable object code for level A software: a traceability study provides evidence that, in a given context (coding standard, compiler, compilation switches), the compiler either generates traceable code or the untraceable code is correct — i.e. it correctly implements the requirements expressed by the specifications of the chosen programming language.

The issue raised by section 6.4.4.2 of DO-178, and in general the equivalence of source and object coverage, is considered in both FAQ 42 of DO-248B [RTC01] (*Can structural coverage be demonstrated by analyzing the object code instead of the source*

code?) and CAST paper 17 (*Structural Coverage of Object Code*) issued by the Federal Aviation Administration [CAS03].

Both documents assert that object code coverage can substitute for source code coverage *as long as analysis can be provided which demonstrates that the coverage analysis conducted at the object code will be equivalent to the same coverage analysis at the source code level*. In the following section, we provide a precise analysis of the conditions under which the OBC and MC/DC properties imply each other, for a given set of test cases. It should be noted that such an equivalence applies only in the context of a given code generator and coding guidelines: different code generation algorithms may produce object code whose OBC status is different for the same set of inputs achieving a given source coverage objective.

### 1.2.3 BDDBC

As stated earlier, Binary Decision Diagrams are good abstractions to compare the two criteria that we are considering; this section will justify this choice. It will also introduce a new structural coverage criterion, named *Binary Decision Diagram Branch Coverage*, that relates naturally to OBC.

A Binary Decision Diagrams is a standard data structure that can be used to represent a decision; a formal definition, along with a set of associated algorithms and properties, can be found in [Bry86]. In a nutshell, BDDs can be described as an directed acyclic graph; each node is mapped to one condition, and leaf nodes are outcome True or False; two edges labeled True and False link each condition to its children nodes ; those children nodes are either a decision outcome or the next condition to evaluate, and are executed if the father condition takes the value labeled on the corresponding edge. Let us illustrate that on our decision (A and then B) or else C; one of its BDD is shown on figure 1(e).

One key property of BDDs is that they have a reduced form (no isomorphic subgraph, no trivial node), and that this reduced form is canonical (unique) for a particular decision. For instance, figure 1(e) is a reduced ordered BDD.

Now we can define BDDBC as follow:

**DEFINITION 3** *Given a decision D, a set of truth vectors satisfies BDDBC if the corresponding set of paths through its reduced ordered BDD covers all edges of the BDD.*

One can now understand how this relates to OBC. For each pair of edges that exits from a condition node, the compiler will generate a branch that may or may not be taken,

depending on the value of the corresponding condition; both possibilities (taking it, not taking it) maps to one edge of the pair. If OBC is reached, then both edges should be taken, and consequently all edges of the BDD. In other words: OBC implies BDDBC.

This assumes that the compiler will generate one branch per condition for each decision. In the context of COUVERTURE, an compilation option `-fpreserve-control-flow` is provided that enforces this property; this allows a straight-forward comparizon between OBC and BDDBC. In the following, we specifically assume when discussing object branch coverage of the object code, that we can instead reason, unless indicated explicitly, on BDD branch coverage of the corresponding (RO)BDD.

## 2 Characterization of cases of BDDBC — MC/DC equivalence

This section discusses the distinction between expressions for which BDDBC of the associated ROBDD implies MC/DC, and expressions for which no such implication holds.

### 2.1 Some cases of non equivalence between OBC and MC/DC

First let us have a look at how MC/DC and object coverage relate to each other on some simple cases. Cases of non-equivalence for decisions with up to 5 conditions have been studied in [FAA07]: non-equivalence cases have been shown to occur in decisions with three or more conditions, and an illustration is provided with (A and then B) or else C, where A, B and C are three independent conditions. A representation of this decision's BDD is depicted on figure 1(e).

From this representation, we can see that a set of three evaluations can achieve branch coverage of the whole BDD, corresponding to the three vertical paths in figure 1(e). These evaluations are:

A	B	C	(A and then B) or else C
T	T	x	T
T	F	T	T
F	x	F	F



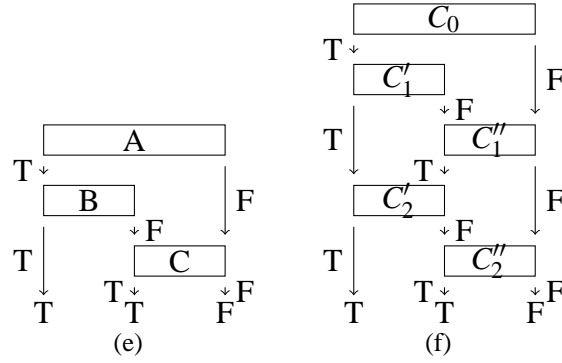


Figure 1: Example decision BDDs

where “x” means not evaluated and thus can be indifferently True or False. Now, indeed, even though all the BDD edges are covered, MC/DC is not met. In particular, the independent effect of conditions B on the decision is not shown in the case of Masking MC/DC, and the independent effect of both B and C are not shown in the case of Unique Cause. Since  $n + 1$  tests are needed to cover a decision with  $n$  conditions with respect to Unique Cause MC/DC, 3 evaluations cannot cover a three-condition decision. Masking MC/DC requires a minimum of 4 evaluations as well in this particular case.

It turns out that this particular case can be generalized in a quite spectacular counterexample: there exists classes of decisions with an arbitrary high number of conditions that can be branch covered by just three evaluations; the previous example was one element of this class with 3 conditions.

Consider the following set  $\{D_n\}_{n \in \mathbb{N}}$  of decisions:

- let  $D_0$  be a simple condition decision; by convention, we will call  $C_0$  its condition;
- let us define  $D_n$ , for any  $n > 0$ , as follows:  
 $D_n = (D_{n-1} \text{ and then } C'_n) \text{ or else } C''_n$   
 $C'_n$  and  $C''_n$  being independent from each other and from any condition in  $D_{n-1}$ .

In other words:

- $D_0 = C_0$
- $D_1 = (C_0 \text{ and then } C'_1) \text{ or else } C''_1$
- $D_2 = (((C_0 \text{ and then } C'_1) \text{ or else } C''_1) \text{ and then } C'_2) \text{ or else } C''_2$

- $D_3 = (((((C_0 \text{ and then } C'_1) \text{ or else } C''_1)$   
and then  $C'_2)$  or else  $C''_2)$   
and then  $C'_3)$  or else  $C''_3)$
- ...

Figure 1(f) shows the BDD for  $D_2$ , where it is visible that all the edges can be covered by three evaluation paths which only demonstrate the independent effect of  $C_0$ :

$C_0$	$C'_1$	$C''_1$	$C'_2$	$C''_2$	$D_2$
T	T	x	T	x	T
T	F	T	F	T	T
F	x	F	x	F	F

We can thus build a decision  $D_n$  with an arbitrary number of conditions, that can be BDD branch covered by just three evaluation paths. As Unique Cause MC/DC can only be achieved with a minimal number of  $n + 1$  evaluations, and Masking MC/DC with a minimal number of  $RUTW(2 * SQRT(N))$  tests, this is a striking case where BDD branch coverage (and consequently OBC) is far from being equivalent to MC/DC.

We can now adopt a more general perspective and characterize more precisely the difference between these two criteria.

## 2.2 Construction of the ROBDD

The BDD we associate with a decision is constructed using the following recursive procedure:

**Build\_BDD.Condition** The BDD for a decision consisting in a single condition  $C$  has the node "test  $C$ " as its entry point, the label True is assigned to the branch corresponding to " $C$  is True", and the label False is assigned to the branch corresponding to " $C$  is False".

**Build\_BDD.NOT** The BDD for  $\text{not}(D)$  is the BDD for  $D$  where the labels of the exit edges have been swapped.

**Build\_BDD.Short\_Circuit\_Operator** This rule defines how the BDD for  $(DL) \star (DR)$  is constructed for any short-circuit operator  $\star$ .

If  $\star$  is `and` then, let SC be False;

if  $\star$  is `or` else, let SC be True.

Let BL be the BDD for DL, and BR the BDD for DR.

Then B, the BDD for D is obtained by combining BL and BR as follows:

- the entry point is that of BL
- the exit edge labeled SC of BL is an exit edge labeled SC of B
- the other exit edge of BL connects to the entry point of BR
- the exit edges of BR are exit edges of B with the same labels

The following invariants of ROBDDs follow from the construction process:

- There is exactly one BDD node for each condition.
- All condition nodes are reachable (i.e. there is a path from the entry point to any node in the BDD).
- There are no cycles in the BDD.
- Both outcomes are reachable (i.e. there is a path from the entry point to an exit edge labeled True and to an exit edge labeled False).

This algorithm is formally described in Alloy, in `build_bdd.als`. Given a decision D, we will now call BDD(D) its (RO)BDD as built by this recursive procedure.

## 2.3 Node ordering

For a decision D and a condition C in D, let us call  $\text{index}(D, C)$  the positive number built by the following recursive procedure:

**Build\_BDD\_Order.Condition** The sub-decision is a single condition decision, it is of the form:

$D ::= C$

then  $\text{index}(D, C) = 1$

**Build\_BDD\_Order.NOT** The sub-decision is of the form:

$D ::= \text{not } D1$

then for each condition  $C$  in  $D$ ,  $\text{index}(D, C) = \text{index}(D1, C)$

**Build\_BDD\_Order.Short\_Circuit\_Operator** The sub-decision is of the form:

$D ::= DL \star DR$

then, for each condition  $C$  in  $D$ :

- if  $C$  is in  $DL$ ,  $\text{index}(D, C) = \text{index}(DL, C)$
- if  $C$  is in  $DR$ ,  $\text{index}(D, C) = \text{index}(DR, C) + \#cond(DL)$

This builds a total order over the conditions of a decision; it is a general result for reduced order BDD that the reflexive transitive closure defines a total order over its nodes; this order is the same as the one we just defined. It can also be demonstrated easily, by structural induction, that this order is the order of conditions in the decision's expression.

For a decision  $D$ , we will call  $\text{root}(D)$  and  $\text{root}(BDD(D))$  the unique node with index 1. This node is indeed the root node of the BDD.

## 2.4 Evaluation of a decision

Given the transformation of a decision into its ROBDD, evaluating the decision consists in computing its value using the following BDD traversal procedure:

**Eval.Condition** The value of a decision that consists in a lone condition is the value of the condition.

**Eval.Not** To evaluate  $\text{not}(D)$ , evaluate  $D$  and take the opposite value

**Eval.Short\_Circuit\_Operator** To evaluate  $(D1) \star (D2)$ , evaluate  $D1$ . If  $D1 = SC$  then the value is  $SC$ , else evaluate  $D2$ , and the value is that of  $D2$ .

This algorithm is modeled in `decision_evaluations.als` The following property holds:

**Eval\_Are\_Paths** Evaluating a decision is equivalent to traversing the BDD, evaluating each condition as BDD nodes are traversed, and using the label of the exit edge as the value of the decision.

This property, and most properties that we'll discuss here, is proved by induction on the structure of the decision. For each case of the `BDD_Build` procedure (`Build_BDD.Condition`, `Build_BDD.Not`, `Build_BDD.Short_Circuit_Operator`), we will assume that the property holds for the parameters and prove that the build step preserves the property. A formal model for this proof can be found in `bdd_dec_evaluations.als`.

Note that the practical implementation of coverage analysis systems based on control flow traces relies on the assumption that the code generator used to produce executable code from expressions actually implements this evaluation strategy.

## 2.5 Equivalence case

We now consider the case of an expression whose BDD has no diamond path, i.e. for each BDD node there is exactly one path from the entry point to that node. The following property holds:

**BDDBC\_No\_Diamond\_Indep\_Implies\_MCDC** For a BDD with no diamond, if conditions are independent, then BDD branch coverage implies Unique Cause MC/DC and Masking MC/DC.

Let's consider a condition *C*. Since we have BDD branch coverage, all possible paths starting at *C* have been taken (by recurrence on path length, taking advantage of no cycles and no diamonds).

From the independent outcome reachability property, we have two paths starting at *C*, beginning each with one edge from *C*, and ending on the two outcomes of the decision. Let's call them PCT and PCF.

These paths are disjoint: any condition appearing in one is not evaluated in the other (because of no-diamond).

These two paths are parts of paths PT and PF from the BDD entry point to either outcome, and they cannot differ on the part of the path from the entry point to *C*.

So, PT and PF differ in *C*, in no other condition before *C*, and in no other non-masked condition after *C*, so they prove independent influence of *C* over the decision.

This holds for each condition in the decision, so Unique Cause MC/DC is proved; and since Unique Cause is stronger than Masking MC/DC, Masking MC/DC is proved as well.

This property and the non-equivalence case that follows is modeled in `bdd_coverage.als`.

## 2.6 Non-equivalence case

The general idea of this proof is to show that, for any BDD with a diamond, we can build a set of evaluations that covers the BDD branches in such a way that there is at least one condition for which MC/DC is not met.

If we want to have a proof that will work for any definition of MC/DC, we cannot rely on a failure of the independence criteria; *to independently affect* means something different in Unique Cause MC/DC or in Masking MC/DC. So we should rather rely, if it is possible, on the set of properties that these criteria have in common; a sort of *greatest common divisor* of the two criteria. Let us define this Weak MC/DC criteria as follow:

- every possible outcome of the decision have been tried;
- each condition in the decision has taken on every possible outcome;
- each condition in the decision is shown to affect the outcome of the decision.

The only difference with MC/DC here is that Weak MC/DC does not care if the condition *independently* affects the outcome of the decision; whatever *independently* means. Weak MC/DC is weaker than any other MC/DC criteria. So, if a set of evaluations does not satisfy Weak MC/DC, it won't satisfy Unique Cause MC/DC or Masking MC/DC.

The formal definition would be:

**DEFINITION 4** *Given a decision D, a pair of truth vectors satisfies Weak MC/DC for a condition c if and only if, in their influence tree, the node c and the root node are both colored in True.*

*A test set satisfies Weak MC/DC for a decision D if, and only if, for each condition in cond(D), there exists a pair of tests in the test set that satisfies Weak MC/DC.*

It turns out that we can build a set of evaluations such that BDDBC is reached, but not MC/DC, when the BDD has a diamond. Let's take the canonical example:

(A and then B) or else C  
and these evaluations:

A	B	C	(A and then B) or else C
T	T	x	T
T	F	T	T
F	x	F	F

This set covers this decision for BDDBC. However, this does not meet Weak MC/DC; whenever B is evaluated, the decision outcome is True. So this cannot show that B affects the outcome of the decision.

Let us give a general idea of how we would prove that in the general case. First, remember that we are dealing with reduced ordered BDDs; so each node can be ordered. This property allows us to have a proper concept of “last diamond node” and its “last parent”. In our example, the last diamond node would be C, its last parent B.

Now, we would show that the last parent of the last diamond node has an interesting property: one of its exit edge is always connected directly to an outcome (for B, it is outcome True). Its other exit edge being connected to the last diamond node (obviously), it is possible to cover this edge in such a way that the outcome of the corresponding evaluation is the same as the “direct outcome”; e.g. when evaluating B to False, we would evaluate C to True and exit on True. We know that this is possible using the property that, from each node of the BDD (and, in this case, the diamond C), there exists at least one evaluation that reaches outcome True and at least one that reach outcome False.

This means that we can cover all exit and incoming edges of the last parent of the last diamond in such a way that the evaluations *always* exit on the same outcome; and, from the property of its exit edges, we can see that this set of evaluations can be completed to reach BDDBC *without evaluating this node anymore*. This builds a BDD coverage that does not satisfy Weak MC/DC for this node.

The following sections will detail this proof.

### 2.6.1 Last diamond

We have previously built a function  $\text{index}(D,C)$  that defines a full order over the nodes of a (RO)BDD. Based on this function, we can define the following entities:

- in a BDD, let the last node be the node with the greatest index;
- let a diamond node be a node with more than one parent;
- let the last diamond node of a decision be the diamond with the greatest index;
- let the last parent of a node be the parent with the greatest index.

Some examples from our canonical case  $D ::= (A \text{ and then } B) \text{ or else } C$ :

- $\text{index}(D,A) = 1$ ,  $\text{index}(D,B) = 2$ ,  $\text{index}(D,C) = 3$ ;
- the last diamond node is C; it is also the last node;
- the last parent of C is B.

We have the following properties:

**Lemma 2.6.1** *The two exit edges of the last node are connected to both outcomes.*

**Lemma 2.6.2** *If a BDD contains diamonds, then the last parent of the last diamond has an exit edge that is directly connected to an outcome.*

*This outcome will be called the direct outcome (of the last of parent of the last diamond). The edge connected to the the direct outcome will be called the direct exit edge.*

This can be seen in our example:

- the last node being C, its exit edges are connected directly to True and False;
- the last parent of the last diamond being B; when it is True, the outcome True is reached.

The two properties can be proved by structural induction on the BDD. The first is the easiest one and we will let it as an exercise for the reader. Here is a proof of the second one:

- if  $D ::= C$  (simple condition decision):  
the BDD does not contain any diamond, so the property is trivially true in this case.
- if  $D ::= \text{not } D1$ :  
if  $D1$  does not contain diamond,  $D$  does not either, the property is trivial as well. If it does contain diamond, well, only outcome labels are different between  $\text{BDD}(D)$  and  $\text{BDD}(D1)$ , so the property holds for  $D$  if it holds for  $D1$ .
- if  $D ::= DL \star DR$ , supposing that the property holds for  $DL$  and  $DR$ ; four cases then:
  - If no diamonds were in  $\text{BDD}(DL)$  and  $\text{BDD}(DR)$ , and none were introduced by building  $\text{BDD}(D)$  from them: then  $\text{BDD}(D)$  contains no diamonds, the property is trivial.



- If DR contains a diamond: then the last diamond node of D is the last diamond node in DR. By construction,  $BDD(DR)$  is a sub-tree of  $BDD(D)$ , the exit edges of the last diamond node are the same in  $BDD(DR)$  and in  $BDD(D)$ . So if the property holds for DR, it holds for D.
- If DR contains no diamonds, and if building  $BDD(D)$  from  $BDD(DR)$  and  $BDD(DL)$  introduces a new diamond: this new diamond node has to be root(DR), as only this node has gained new incoming edges: in Build\_BDD, the exit edges of  $BDD(DR)$  labeled “not SC” are connected to  $BDD(DL)$ ’s root. Therefore, its parent nodes are all in  $cond(DL)$ . And the last node of  $BDD(DL)$  is one of these parent nodes; by property 2.6.1, it has an exit edge to “not SC” in  $BDD(DL)$ . Its other exit edge will remain unchanged in  $BDD(D)$  and will be connected to an outcome (“SC”). This last node of  $BDD(DL)$  is also the last parent of this diamond node, as no other nodes in  $cond(DL)$  have an greater index. And (finally), this introduced diamond node is D’s last diamond node, as DR contains no diamonds (initial hypothesis). So we have identified the last parent of the last diamond and showed that one of exit edge is connected to an outcome in  $BDD(D)$ ; that’s the property that we were trying to prove.
- If DR contains no diamonds, and if no diamonds were introduced when building  $BDD(D)$ , but if DL contains a diamond: the last diamond node in D is the same node as the last diamond node in DL. The last parent of the last diamond in DL has an exit edge that connects to SC; otherwise, it would be connected to  $BDD(DR)$ ’s root when building  $BDD(D)$ , and as the last node would also be connected to this root node (it also has an exit edge to SC in DR, as a consequence of property 2.6.1),  $BDD(DR)$ ’s root would have at least two fathers in D, which contradicts the hypothesis that no diamonds were introduced. So this exit edges of the last parent of the last diamond in DL (and D) will still be connected to an outcome after building D. So the property is true in this case as well.

The property 2.6.2 has now been established in all possible cases. This proof will actually be quite useful as its structure will be used to build a coverage that satisfies BDDBC but not Weak MC/DC.

## 2.6.2 Path through BDDs - Conventions

Some conventions first to help us manipulate paths through BDD:

- For two paths  $pl$ ,  $pr$  into two different BDDs,  $concat(pl, pr)$  is the concatenation of these two paths obtained by replacing the outcome of  $pl$  by the first node in  $pr$ .

- For two set of paths PL, PR through two different BDDs,  $\text{merge}(PL, PR)$  is the set built by doing an arbitrary mapping of each element of PL to each element of PR, and concatenating each pair; as these two sets may not have the same number of elements, all the remaining elements of the greatest set will be mapped to one arbitrary element of the smallest set.
- For any set of paths PS through a BDD (each going from the root node to an outcome), let us call  $\text{path\_to}(\text{True}, PS)$  the subset of paths reaching outcome True, and  $\text{path\_to}(\text{False}, PS)$  the subset reaching False. We have the obvious property:  

$$PS = \text{path\_to}(\text{True}, PS) + \text{path\_to}(\text{False}, PS)$$

### 2.6.3 Building a BDD branch coverage that does not verify Weak MC/DC

For a given decision D, our coverage will be ensured by the union of three sets of paths  $\text{Short\_Circuit\_LPLD}(D)$ ,  $\text{Long\_Circuit\_LPLD}(D)$  and  $\text{LPLD\_Not\_Evaluated}(D)$ , which verifies the following set-specific invariants:

**Short\_Circuit\_LPLD\_Invariant** If  $\text{BDD}(D)$  is diamondless,  $\text{Short\_Circuit\_LPLD}(D)$  is empty; otherwise, it contains a non-empty set of paths, each reaching the last parent of the last diamond node and then exiting on its direct outcome.

**Long\_Circuit\_LPLD\_Invariant** If  $\text{BDD}(D)$  is diamondless,  $\text{Long\_Circuit\_LPLD}(D)$  is empty; otherwise, it contains a non-empty set of paths, each reaching the last parent of the last diamond node, then going to the last diamond node, and then reaching the same outcome as  $\text{Short\_Circuit\_LPLD}(D)$ .

**LPLD\_Not\_Evaluated\_Invariant** No path in  $\text{LPLD\_Not\_Evaluated}(D)$  evaluates the last parent of the last diamond node.

...plus one other “global” invariants:

**BDDBC\_Coverage\_Invariant** The union of these three sets covers each edges of the considered BDD.

As a consequence of this last invariant, we will now call  $\text{BDDBC\_Coverage}$  the union of these three sets:

$$\begin{aligned}
BDDBC\_Coverage(D) &= Short\_Circuit\_LPLD(D) \\
&+ Long\_Circuit\_LPLD(D) \\
&+ LPLD\_Not\_Evaluated(D)
\end{aligned}$$

Note also that an other property falls naturally from LPLD\_Not\_Evaluated\_Invariant and BDDBC\_Coverage\_Invariant:

**Incoming Edges** The union of Long\_Circuit\_LPLD and Short\_Circuit\_LPLD covers all incoming edges of the last parent of the last diamond node.

Anyway, here is the definition, case by case, of a recursive build procedure that builds such sets from a decision D. As always when doing a structural induction, it assumes that all its sub-decisions have such sets verifying these invariants (not considering D as a sub-decision of D, obviously; “strict” sub-decisions):

**Build\_BDD\_Cov.Condition** The sub-decision is a single condition decision, it is of the form:

$D ::= C$

In this case:

$$\begin{aligned}
Short\_Circuit\_LPLD(D) &= Long\_Circuit\_LPLD(D) = \{\} \\
LPLD\_Not\_Evaluated(D) &= \{C \rightarrow True, C \rightarrow False\}
\end{aligned}$$

**Build\_BDD\_Cov.NOT** The sub-decision is of the form:

$D ::= \text{not } D1$

Then Short\_Circuit\_LPLD(D) is built by switching the outcome of each path contained in Short\_Circuit\_LPLD(D1). Same operations for Long\_Circuit\_LPLD(D) and No\_LPLD(D).

**Build\_BDD\_Cov.Short\_Circuit\_Operator** The sub-decision is of the form:

$D ::= DL \star DR$

Four sub-cases:

- No diamonds:  
No diamonds in BDD(DL) and BDD(DR), and none were introduced by

building  $BDD(D)$  from them. Then:

$$\begin{aligned}
Short\_Circuit\_LPLD(D) &= \{\} \\
Long\_Circuit\_LPLD(D) &= \{\} \\
LPLD\_Not\_Evaluated(D) &= path\_to(SC, BDDBC\_Coverage(DL)) \\
&\quad + merge(path\_to(notSC, BDDBC\_Coverage(DL)), \\
&\quad \quad BDDBC\_Coverage(DR))
\end{aligned}$$

- Diamond in DR:  
i.e.  $Short\_Circuit\_LPLD(DR)$  and  $Long\_Circuit\_LPLD(DR)$  contain at least one element each. Let  $p\_dl$  be an arbitrary path to “not SC” in  $BDD(DL)$ , taken from  $BDDBC\_Coverage(DL)$ . In  $BDD(D)$ , it corresponds to a path to  $root(DR)$ . Then:

$$\begin{aligned}
Short\_Circuit\_LPLD(D) &= merge(p\_dl, Short\_Circuit\_LPLD(DR)) \\
Long\_Circuit\_LPLD(D) &= merge(p\_dl, Long\_Circuit\_LPLD(DR)) \\
LPLD\_Not\_Evaluated(D) &= path\_to(SC, BDDBC\_Coverage(DL)) \\
&\quad + merge(path\_to(notSC, BDDBC\_Coverage(DL)), \\
&\quad \quad LPLD\_Not\_Evaluated(DR))
\end{aligned}$$

- Last diamond introduced:  
i.e. no diamonds in  $BDD(DR)$  and a diamond has been created when building  $BDD(D)$ . In this case:

- $Short\_Circuit\_LPLD(DR) = Long\_Circuit\_LPLD(DR) = \{\}$
- the last diamond node in  $D$  is  $root(DR)$ .

Let  $SC\_DL$  be the subset of paths in  $path\_to(SC, BDDBC\_Coverage(DL))$  that evaluates the last node in  $BDD(DL)$ . Similarly, let  $LC\_DL$  be the subset of paths in  $path\_to(notSC, BDDBC\_Coverage(DL))$  that evaluates the last node in  $BDD(DL)$ ; in  $BDD(D)$ , this one corresponds to a path to  $root(DR)$ . Let  $REST\_DL = BDDBC\_Coverage(DL) - (SC\_DL + LC\_DL)$  be the subset of paths in  $BDDBC\_Coverage(DL)$  that do not evaluate this last node. Let  $sc\_dr$  be an arbitrary path in  $DR$  exiting on  $SC$ .

Then the coverage for  $BDD(D)$  is built as follows:

$$\begin{aligned}
Short\_Circuit\_LPLD(D) &= SC\_DL \\
Long\_Circuit\_LPLD(D) &= merge(LC\_DL, sc\_dr) \\
LPLD\_Not\_Evaluated(D) &= path\_to(SC, REST\_DL) \\
&\quad + merge(path\_to(notSC, REST\_DL), \\
&\quad \quad BDDBC\_Coverage(DR))
\end{aligned}$$

(Note that we are allowed to merge  $\text{path\_to}(\text{not SC}, \text{REST\_DL})$  because it is non-empty; there is at least one other node that has an exit edge directly connected to “not SC” in  $\text{BDD}(\text{DL})$ , otherwise no diamond would have been created; so it must have at least one path that does not evaluate the last node in  $\text{BDD}(\text{DL})$ ; that property gives us the right to use the merge operation. Same thing for  $\text{LC\_DL}$  and  $\text{SC\_DL}$  that are both non-empty thanks to property 2.6.1).

- Diamond in DL only:  
i.e. no diamonds in  $\text{BDD}(\text{DR})$ , no new diamonds introduced when building  $\text{BDD}(\text{D})$ , but at least one diamond in  $\text{BDD}(\text{DL})$ . The last parent of the last diamond in DL has its “direct” exit edge that connects to SC; otherwise, it would have been connected to  $\text{BDD}(\text{DR})$ ’s root when building  $\text{BDD}(\text{D})$ , and as the last node would also be connected to this root node (it also has an exit edge to SC in DR, as a consequence of property 2.6.1),  $\text{BDD}(\text{DR})$ ’s root would have at least two fathers in D, which contradicts the hypothesis that no diamonds were introduced. Let  $\text{sc\_dr}$  be an arbitrary path in DR exiting on SC. Then the coverage for  $\text{BDD}(\text{D})$  is built as follows:

$$\begin{aligned} \text{Short\_Circuit\_LPLD}(\text{D}) &= \text{Short\_Circuit\_LPLD}(\text{DL}) \\ \text{Long\_Circuit\_LPLD}(\text{D}) &= \text{merge}(\text{Long\_Circuit\_LPLD}, \text{sc\_dr}) \\ \text{LPLD\_Not\_Evaluated}(\text{D}) &= \text{path\_to}(\text{SC}, \text{LPLD\_Not\_Evaluated}(\text{DL})) \\ &\quad + \text{merge}(\text{path\_to}(\text{notSC}, \text{LPLD\_Not\_Evaluated}(\text{DL}), \\ &\quad \text{BDDBC\_Coverage}(\text{DR})) \end{aligned}$$

Our sets are now defined in all possible cases. It is quite easy to check that  $\text{Short\_Circuit\_LPLD\_Invariant}$ ,  $\text{Long\_Circuit\_LPLD\_Invariant}$ ,  $\text{LPLD\_Not\_Evaluated\_Invariant}$  and  $\text{BDDBC\_Coverage\_Invariant}$  are enforced by this build procedure; each one falls so obviously from the construction (in every case) that it will be quite painful to elaborate.

So we can build a BDD coverage in such a way that, if there is a diamond in the BDD, then the decision will have the same outcome for any evaluation where the last parent of the last diamond is evaluated. This means that this BDD coverage does not imply Weak MC/DC; that which was to be demonstrated.

## 2.7 Conclusion

We have therefore proved the following property:

**THEOREM 3** *Given a decision  $D$ , branch coverage of the BDD implies MC/DC if, and only if, there is no diamond in the BDD (i.e. no node of the BDD is reachable through more than one path from the root).*

Intuitively, BDDBC is a local property of BDD traversals (i.e. of evaluations of the decision): it is evaluated individually for each BDD node, without respect to how the BDD node was reached. In contrast, MC/DC is a non-local property, since it involves the complete path through the BDD. To establish independent influence of condition  $C$ , it is necessary to study what happens for two values of  $C$  leading to different outcomes, *with all other conditions fixed or masked*.

### 3 A second characterization of the equivalence case

In this section we provide an alternative (equivalent) property that characterizes cases where BDD branch coverage implies MC/DC:

**THEOREM 4** *Given a decision  $D$ , BDD branch coverage implies MC/DC if, and only if, when considering the negation normal form  $D'$  of  $D$ , for every sub-decision  $E$  of  $D'$ , all binary operators in the left-hand-side operand of  $E$ , if any, are of the same kind as  $E$ 's operator.*

The negative normal form is obtained by rewriting the expression using De Morgan's laws so that negations apply only to atomic conditions (and not to more complex subexpressions).

We prove this theorem by showing that this alternative characterization is equivalent to having no diamond in the associated BDD. Theorem 4 follows by application of Theorem 3.

Let's consider a decision  $D$  and its BDD.

There is a diamond in a BDD if and only if there is at least one node such that the number of paths to reach it from root is strictly greater than 1; we will use this characterization to prove our property.

*Proof of the simplified case:*

Consider first the case where decision  $D$  does not contain any negation. Each node in the BDD corresponds to a sub-decision  $D'$  in  $D$  (i.e. the root of each sub-decision is a node in  $D$ 's BDD).

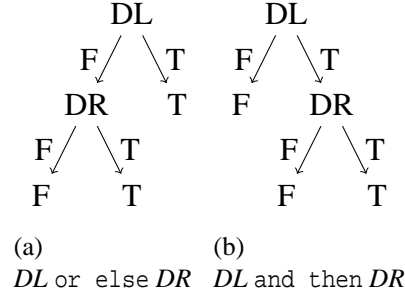


Figure 2: case 2 and 3

*Proof of reverse implication (simplified case):*

Let's call  $NF(D)$  the number of paths from the root of decision  $D$  to False (F) and  $NT(D)$  the number of paths from the root of decision  $D$  to True (T). We then have three cases:

*case 1:*  $D = A$  (atom)  
 $NF(D) = NT(D) = 1$

*case 2:*  $D = DL \text{ or } \text{else } DR$   
 $BDD(D)$  is constructed from  $BDD(DL)$  and  $BDD(DR)$ . It is shown in Figure 2(a). Then:  
 $NF(D) = NF(DL) * NF(DR)$   
 $NT(D) = NT(DL) + NF(DL) * NT(DR)$

*case 3:*  $D = DL \text{ and then } DR$   
 $BDD(D)$  is constructed from  $BDD(DL)$  and  $BDD(DR)$ . It is shown in Figure 2(b). Then:  
 $NF(D) = NF(DL) + NT(DL) * NF(DR)$   
 $NT(D) = NT(DL) * NT(DR)$

**Lemma 3.0.1** *For every decision  $D$ ,  $NF(D) \geq 1$  and  $NT(D) \geq 1$ .*

*If  $D$  is of the form  $\text{or } \text{else}$  then  $NT(D) \geq 2$ .*

*If  $D$  is of the form  $\text{and then}$  then  $NF(D) \geq 2$ .*

**Lemma 3.0.2**  *$NF$  and  $NT$  are monotonic functions, i.e. if  $D'$  is a sub-decision of  $D$ , then we have  $NF(D') \leq NF(D)$  and  $NT(D') \leq NT(D)$ .*

Proofs of Lemmas 3.0.1 and 3.0.2 are on structural induction on the form of decisions, based on the three cases distinguished above.

Then, suppose that a decision  $D$  of the form  $\text{and then}$  contains a sub-decision  $D'$  of the form  $\text{or } \text{else}$  on the left-hand side. If  $DL, DR$  are the two sub-decisions such that  $D = DL \text{ and then } DR$ , then  $D'$  is also a sub-decision of  $DL$ .

By Lemma 3.0.1, we know that  $NT(D') \geq 2$ . By Lemma 3.0.2, we know that  $NT(DL) \geq NT(D')$ .

Then, in  $BDD(D)$ , the paths reaching the DR's root node are exactly those paths in  $BDD(DL)$  reaching True, by construction; the number of these paths is  $NT(DL)$ .

Thus, DR's root node in the  $BDD(DL)$  is reachable by more than one path. As a consequence, there is a diamond in this BDD.

Similarly, if a decision  $D$  of the form `or else` contains a sub-decision  $D'$  of the form `and then` on the left-hand side, we can exhibit a node in the  $BDD(D)$  that is reachable by more than one path.

By contraposition, if there are no diamonds in the BDD associated to a decision  $D$ , then  $D$  has no `or else` sub-decision on the left of its `and then` sub-decisions, and no `and then` sub-decision to the left of its `or else` sub-decision.

*Proof of implication (simplified case):*

Now suppose that for every sub-decision in decision  $D$ , the left operand of an `and then` sub-decision contains only `and then` sub-decisions and the left operand of an `or else` sub-decision contains only `or else` sub-decisions.

**Lemma 3.0.3** *If  $E$  contains only `or else` sub-decisions then  $NF(E) = 1$ . If  $E$  contains only `and then` sub-decisions then  $NT(E) = 1$ .*

Proof of Lemma 3.0.3 is on structural induction on the form of decisions, based on the 3 cases distinguished above.

By structural induction on the depth of the BDD, we can show that there cannot be any diamond in the BDD associated to  $D$ , which proves that the desired implication holds.

*Proof of the general case:*

In the general case, decision  $D$  may contain not sub-decisions. Then, consider  $D'$  the negation normal form of  $D$ . Since  $D$  and  $D'$  are represented by the same BDD, Theorem 4 follows.

## 4 Coupled conditions

Handling of coupled conditions is a well-known problem that one has to face when considering MC/DC, and in particular Unique Cause. It may be stated as follow:



**DEFINITION 5** *Two or more conditions are said to be coupled if changing one condition can cause the other condition(s) to change.*

*Conditions are said to be strongly coupled if changing one always changes the others. At the contrary, they are said to be weakly coupled if changing one sometimes (but not always) changes the others.*

In [VB02], it is proven that strongly coupled conditions are pairs of conditions that are either equal, or complimentary. In other words, if A and B are strongly coupled, then either  $A = B$  or  $A = \text{not } B$

Without short-circuit operators, decisions with coupling cannot be covered for Unique Cause MC/DC; Masking MC/DC has been defined to solve this problem. When proving Masking MC/DC for a condition C, one may exhibit a pair of evaluation that have different values for other conditions, as long as it can be shown, by a structural analysis of the decision, that changing these other conditions had no influence on the result. Typically, for a decision A and SUBDEC (SUBDEC being a sub-decision, A being a condition), any evaluation that sets SUBDEC to True ensures that only the value of A impacts the value of the decision. e.g. if  $\text{SUBDEC} = (B \text{ or } C)$ , the following evaluation pairs proves Masking MC/DC, but not Unique Cause MC/DC:

A	B	C	SUBDEC ::= B or C	A and SUBDEC
T	F	T	T	T
F	T	F	T	F

B and C change, so Unique Cause MC/DC is not reached; but SUBDEC is kept to True, so Masking MC/DC is reached. So if C and A were strongly coupled ( $A = C$ ), we would still be able to cover this decision for Masking MC/DC; but we would not be able to reach Unique Cause.

When using only short-circuit operators, one may wonder if the problem still holds. It can be seen that the previous example is covered for Unique Cause MC/DC when the operators are short-circuit; in this case, the evaluations are:

A	B	C	A and then (B or else C)
T	F	T	T
F	x	x	F

So there are some cases of coupling that are not problematic in the case of short-circuit operator; short-circuits seem to offer some sort of masking by avoiding to evaluate some sub-decisions. The question would now be: can we show some cases of coupling for which Unique Cause may not be reached even with short-circuit operators? Would these cases show up in real life, or would they be dummy decisions that may be trivially simplified (e.g.  $A$  and then  $A$ )?

The following sections shed some light on these problems. First, Masking MC/DC is characterized in terms of BDD, in order to make use of the results that have been demonstrated in the previous sections. This characterization would then allow to comment on coupling in the context of short-circuit operators.

## 4.1 MC/DC in terms of BDD

### 4.1.1 Unique Cause MC/DC

**THEOREM 5** *Given a decision  $D$ , a pair of evaluations of  $D$  satisfies Unique Cause MC/DC for a condition  $C$  if and only if:*

- *both reach  $C$  using the same path through  $BDD(D)$ ;*
- *their paths from  $C$  exits on two different outcomes and do not cross each other ( $C$  excluded).*

Let us first prove that this characterization implies Unique Cause MC/DC as defined previously.

Both evaluations reach  $C$  using the same path; this implies that all conditions that are before  $C$  are either not evaluated by any of the two evaluations, or that they have the same value. In both cases, they are colored with False in the influence tree.

After  $C$ , their paths through the BDD do not cross each other; this means that they evaluate  $C$  to both values, otherwise they would have at least one edge in common.  $C$  is evaluated to True and False, which means that it is colored with True in the influence tree.

An other consequence of this hypothesis is that all conditions after  $C$  are not evaluated in at least one of the two paths; a condition that would be evaluated on both paths would be a meeting point of the two paths, which would contract the hypothesis. This means that any condition after  $C$  is colored with False as, by definition, anything xor Not\_Evaluated gives False.

So, of all conditions, only  $C$  is colored with True. As the two paths exits on two different outcomes, the root node of the influence tree is colored with True as well. We now have these general properties of influence trees:

**Lemma 4.1.1** *If the root node of an influence tree is colored with True, then its influence set is not empty.*

*If the root node of an influence tree is colored with True, and if only one condition  $c$  is colored with True, then the corresponding influence set is  $\{c\}$*

This lemma can be proved by induction on the structure of a decision; the first property is easier to prove and comes in handy to prove the second property. We will not detail these proofs here as they offer no technical difficulty.

Applying the second property to our case, we can now prove that the influence set of our decision is the singleton  $\{C\}$  ; so the two evaluations satisfy Masking MC/DC. As all other conditions are colored with False in the influence tree, Unique Cause MC/DC is satisfied.

To demonstrate the other side of the equivalence, let us assume that one of the two properties on the BDD is violated and let us show Unique Cause MC/DC cannot be achieved.

If the two paths are not identical before the considered condition: they start from the same node (the root of the BDD) and ends up on the same node ( $C$ ), so it means that there exists at least one node from which those paths diverge (this is a general property of paths through graphs). This node takes therefore two different values in the two evaluations; so it is colored with True in the influence tree. It is the second condition colored with True in the influence tree (with  $C$ ), so Unique Cause MC/DC cannot be achieved.

If the paths from  $C$  cross each other, then there is at least one condition after  $C$  that is evaluated in both paths. Let us call  $lc$  the last condition where the two paths cross. By definition of  $lc$ , the two sub-paths that start from  $lc$  and go to outcomes do not cross each other. This means that they exit by two different edges from  $lc$ ; otherwise, the node that they would reach would be a common node after  $lc$ , which would contradict the fact that  $lc$  is the last common node. So  $lc$  takes two different values, True and False, on these two paths. As a consequence,  $lc$  is colored with True in the Influence Tree, and therefore  $C$  is not the only one colored with True, so Unique Cause MC/DC cannot be achieved.

The two sides of the equivalence in Theorem 5 are now proved.

### 4.1.2 Masking MC/DC

**THEOREM 6** *Given a decision  $D$ , a pair of evaluations of  $D$  satisfies Masking MC/DC for a condition  $C$  if and only if:*

- *both reach  $C$ ;*
- *their paths from  $C$  exit on two different outcomes and do not cross each other ( $C$  excluded).*

The difference with Unique Cause is that the paths to reach  $C$  may be different. That is to say: only the sub-bdd of  $BDD(D)$  whose root is  $C$  is taken into account when proving Masking MC/DC; anything before  $C$  does not matter (as long as  $C$  is reached). An other way to see that: Masking MC/DC is achieved for  $C$  if Unique Cause MC/DC is achieved on the sub-bdd of  $BDD(D)$  whose root is  $C$ . Or: any condition on the left of  $C$  is not considered when trying to achieve Masking MC/DC for  $C$ .

This may be justified as follow: we have seen that short-circuit operators do provide some sort of masking in our original example  $A$  and then  $SUBDEC$ . Now, consider  $SUBDEC$  and then  $A$ ; in this case,  $SUBDEC$  will always be executed before  $A$ , so the short-circuit operator and then will not mask  $SUBDEC$ . Short-circuit operators are non-commutative, and introduce this asymetricity. Say, if  $SUBDEC ::= B \text{ or } \text{else } C$ , then the following evaluations satisfy Masking MC/DC for  $C$ , but not Unique Cause:

A	B	C	SUBDEC ::= B or else C	SUBDEC and then A
T	F	T	T	T
F	T	x	T	F

For Masking MC/DC, we have to ignore the details of the evaluation of  $SUBDEC$ , as long as it ends up being evaluated to True. In terms of BDD, that means that we do not care about how we reached the considered condition, as long as we reached it.

The proof of this theorem is still to be produced. We have however used the Alloy model `bdd_dec_coverage.als` with up to 4 conditions in decisions; which already gives a good hint of the validity of this conjecture.

## 4.2 Coupled conditions without diamonds

First, it can be seen that strong coupling only gives degraded case, where some branches of the BDD cannot possibly be covered; this is what the following theorem states:

**THEOREM 7** *A BDD with no diamond and with strongly coupled conditions cannot be covered for BDD branch coverage, Masking MC/DC, Unique Cause MC/DC.*

As Unique Cause MC/DC and Masking MC/DC are stronger than BDD branch coverage, we only need to prove this theorem for BDD branch coverage.

In a BDD with no diamond, there is only one possible path to each node, traversing all the previous conditions in the BDD ordering. Take two strongly coupled conditions; let us call *fc* the first one in the BDD ordering, *lc* the second one. When *lc* is executed, *fc* has been evaluated to a given value, and this value is the same for any evaluation that reaches *lc*. Let us call this value *V*. Now, as *lc* and *fc* are strongly coupled, there are only two possibilities: either *lc* is always equal to *fc*, and evaluates to *V*, in which case the exit edge for not *V* is never executed; or it is always the complementary of *c*, and evaluates to not *V*, in which case the other exit edge is never executed. In any case, BDD branch coverage cannot be achieved, as at least one edge is never taken.

This means that there are no meaningful cases of strong coupling without diamonds. They could typically be optimized out by the compiler.

We can however exhibit some cases of weak coupling that makes sense. For instance:

*Dec* ::= *t* > *T* or else (*t* = *T* and then *A*)

Or a even more common pattern, that can often be found in C:

```
name != NULL && strcmp (name, "something")
```

In these two examples, BDD branch coverage can be reached. For the first one, it can be checked that these evaluations cover the decision for BDD branch coverage, Masking MC/DC and Unique Cause MC/DC:

<i>t</i> > <i>T</i>	<i>t</i> = <i>T</i>	<i>A</i>	<i>Dec</i>
T	x	x	T
F	F	x	F
F	T	T	T
F	T	F	F

It can be seen that Unique Cause MC/DC and Masking MC/DC are equivalent in the case of no diamonds, as there is only one possible path to each node; this is a consequence of Theorem 6 and Theorem 5. So, with no diamonds, Masking MC/DC does not gain us anything, comparing to Unique Cause MC/DC (or BDD branch coverage):

- in the cases of strong coupling, none of these coverage criteria can be reached;
- in all other cases, all of them are equivalent anyway.

If Masking MC/DC is of some help to handle coupled conditions, it has to be when the decision's BDD contains diamonds. That is the second case that we will investigate.

### 4.3 Coupled conditions with diamonds

The Theorem 7 cannot be extended to the case of diamonds. Take for instance this decision:

$Dec ::= (A \text{ and then } B) \text{ or else } (\text{not } A \text{ and then } C)$

This decision is a common pattern, logically equivalent to  $\text{if } A \text{ then } B \text{ else } C$ . It cannot be covered for Unique Cause MC/DC, because the first and the third condition are strongly coupled; but it can be covered for Masking MC/DC, with the following evaluations:

A	B	not A	C	Dec
F	x	T	T	T
F	x	T	F	F
T	T	x	x	T
T	F	F	x	F

More precisely: the third condition cannot be covered for Unique Cause; but the first and the last evaluation cover it for Masking MC/DC.

Another example with weak coupling:

$Dec ::= (t < T \text{ and then } A) \text{ or else } (t = T \text{ and then } B) \text{ or else } (t > T \text{ and then } C)$

...which is another case where the logical space is partitioned into three cases ( $t < T$ ,  $t = T$ ,  $t > T$ ) using three conditions that are such that exactly one is True for each evaluation.

From the truth table, the only condition for which we cannot reach Unique Cause is  $t > T$ :

- when it is True, both  $t < T$  and  $t = T$  have been evaluated to False;
- when it is False, either  $t < T$  or  $t = T$  has been evaluated to True;

so we cannot reach Unique Cause for this one. We can cover it for Masking MC/DC though, with any of the pairs (eT, eF1) and (eT, eF2), these three evaluations being:

- eT =  
( $t < T = \text{False}$ ,  $A = \text{Not\_Evaluated}$ ,  
 $t = T = \text{False}$ ,  $B = \text{Not\_Evaluated}$ ,  
 $t > T = \text{True}$ ,  $C = \text{True}$ )
- eF1 =  
( $t < T = \text{True}$ ,  $A = \text{False}$ ,  
 $t = T = \text{False}$ ,  $B = \text{Not\_Evaluated}$ ,  
 $t > T = \text{False}$ ,  $C = \text{Not\_Evaluated}$ )
- eF2 =  
( $t < T = \text{False}$ ,  $A = \text{Not\_Evaluated}$ ,  
 $t = T = \text{True}$ ,  $B = \text{False}$ ,  
 $t > T = \text{False}$ ,  $C = \text{Not\_Evaluated}$ )

One could object that this decision may be rewritten as follow:

( $A$  and then  $t < T$ ) or else ( $B$  and then  $t = T$ ) or else ( $C$  and then  $t > T$ )

...in which case Unique Cause MC/DC could be achieved. However, such a rewriting may not be possible; the execution of condition may have the precondition that  $t < T$ , in which case the rewriting would not be valid. So re-ordering the decision to allow Unique Cause MC/DC to be reached is not an appropriate general solution to the coupling problem.

In other words, Masking MC/DC is still useful in the case of short-circuit operators; but only when there are diamonds in the decision's BDD.

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