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#include <iostream>
#include <vector>
#include <string>
#include <utility>
#include <limits>

using namespace std;

const int MAXSIZE = 20;

template<class type>
class uGraph
{
private:
#define noEdge 0
    int adjacency[MAXSIZE][MAXSIZE];
    vector<type> nodes;
    enum state = { unknown, visted, complete };

    void recur_dfs(int u, state states[], std::function<void(const type &)> process)
    {
        states[u] = visted;
        process(nodes[u]);
        for (int v = 0; v < nodes.size(); v++)
        {
            if (adjacent(nodes[u], nodes[v]) && states[v] == unknown)
            {
                recur_dfs(v, states);
            }
        }
        states[u] = complete;
    }

public:
    uGraph()
    {
        type t;
        for (int i = 0; i < MAXSIZE; i++)
        {
            for (int j = 0; j < MAXSIZE; j++)
            {
                adjacency[i][j] = noEdge;
            }
            nodes.push_back(t);
        }
    }
    bool adjacent(type x, type y)
    {
        int m = -1;
        int n = -1;
        for (int i = 0; i < nodes.size(); i++)
        {
            if (nodes[i] == x)
            {
                m = i;
            }
            else if (nodes[i] == y)
            {
                n = i;
            }
        }
    }

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    }
    if (m >= 0 && n >= 0)
    {
        if (adjacency[m][n] != noEdge && m != n)
        {
            return true;
        }
    }
    return false;
}
vector<type> neighbors(type x)
{
    vector<type> set;
    int m = -1;
    for (int i = 0; i < nodes.size(); i++)
    {
        if (nodes[i] == x)
        {
            m = i;
        }
    }
    if (m >= 0)
    {
        for (int j = 0; j < nodes.size(); j++)
        {
            if (adjacency[j][m] != noEdge && j != m)
            {
                set.push_back(nodes[j]);
            }
        }
    }
    return set;
}
void addNode(type x)
{
    for (int i = 0; i < MAXSIZE; i++)
    {
        if (adjacency[i][i] == noEdge)
        {
            nodes[i] = x;
            adjacency[i][i] = INT_MAX;
            return;
        }
    }
    return;
}
void deleteNode(type x)
{
    for (int i = 0; i < nodes.size(); i++)
    {
        if (nodes[i] == x)
        {
            for (int j = 0; j < MAXSIZE; j++)
            {
                adjacency[i][j] = noEdge;
                adjacency[j][i] = noEdge;
            }
            return;
        }
    }
}

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void addEdge(type x, type y)
{
    int m = -1;
    int n = -1;
    for (int i = 0; i < nodes.size(); i++)
    {
        if (nodes[i] == x)
        {
            m = i;
        }
        else if (nodes[i] == y)
        {
            n = i;
        }
    }
    if (m >= 0 && n >= 0)
    {
        adjacency[m][n] = 1;
        adjacency[n][m] = 1;
    }
    return;
}
```

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void addEdge(type x, type y, int weight)
{
    int m = -1;
    int n = -1;
    for (int i = 0; i < nodes.size(); i++)
    {
        if (nodes[i] == x)
        {
            m = i;
        }
        else if (nodes[i] == y)
        {
            n = i;
        }
    }
    if (m >= 0 && n >= 0)
    {
        adjacency[m][n] = weight;
        adjacency[n][m] = weight;
    }
    return;
}
```

```
void deleteEdge(type x, type y)
{
    int m = -1;
    int n = -1;
    for (int i = 0; i < nodes.size(); i++)
    {
        if (nodes[i] == x)
        {
            m = i;
        }
        else if (nodes[i] == y)
        {
            n = i;
        }
    }
}
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        if (m >= 0 && n >= 0)
        {
            adjacency[m][n] = noEdge;
            adjacency[n][m] = noEdge;
        }
        return;
    }

void dfs(std::function<void(const type &)> process)
{
    state states[nodes.size()];
    for (int i = 0; i < nodes.size(); i++)
    {
        states[i] = unknown;
    }
    int u = 0;
    while (nodes[u] != INT_MAX)
    {
        u++;
    }
    recur_dfs(u, state, process);
    return;
}

void bfs(std::function<void(const type &)> process)
{
    type u = nodes[0]; // starting vertex
    vector<type> visted;
    vector<type> complete;
    vector<pair<type, type>> edges;
    visted.push_back(u);

    while (visted.size() != 0)
    {
        vector<type> set = neighbors(u);
        for (int i = 0; i < set.size(); i++)
        {
            bool notFound = true;
            for (int j = 0; j < visted.size(); j++)
            {
                if (visted[j] == set[i])
                {
                    notFound = false;
                }
            }
            for (int j = 0; j < complete.size(); j++)
            {
                if (j < complete.size() && complete[j] == set[i])
                {
                    notFound = false;
                }
            }

            if (notFound == true)
            {
                visted.push_back(set[i]);
            }
        }
        for (int i = 0; i < visted.size(); i++)
        {

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        if (adjacent(u, visted[i]))
        {
            edges.push_back(make_pair(u, visted[i]));
            edges.push_back(make_pair(visted[i], u)); //handles undirected
        }
    }

    for (int i = 0; i < visted.size() - 1; i++)
    {
        visted[i] = visted[i + 1];
    }
    visted.pop_back();
    complete.push_back(u);
    if (visted.size() > 0)
    {
        u = visted[0];
    }
    if (true);
}
return;
}
};

template<class type>
class dGraph
{
private:
#define noEdge 0
    int adjacency[MAXSIZE][MAXSIZE];
    vector<type> nodes;
    enum state = { unknown, visted, complete };

    void recur_dfs(int u, state states[], std::function<void(const type &)> process)
    {
        states[u] = visted;
        process(nodes[u]);
        for (int v = 0; v < nodes.size(); v++)
        {
            if (adjacent(nodes[u], nodes[v]) && states[v] == unknown)
            {
                recur_dfs(v, states);
            }
        }
        states[u] = complete;
    }

public:
    dGraph()
    {
        type t;
        for (int i = 0; i < MAXSIZE; i++)
        {
            for (int j = 0; j < MAXSIZE; j++)
            {
                adjacency[i][j] = noEdge;
            }
            nodes.push_back(t);
        }
    }
    bool adjacent(type x, type y)

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{
    int m = -1;
    int n = -1;
    for (int i = 0; i < nodes.size(); i++)
    {
        if (nodes[i] == x)
        {
            m = i;
        }
        else if (nodes[i] == y)
        {
            n = i;
        }
    }
    if (m >= 0 && n >= 0)
    {
        if (adjacency[m][n] != noEdge)
        {
            return true;
        }
        else if (adjacency[n][m] != noEdge)
        {
            return true;
        }
    }
    return false;
}

vector<type> neighbors(type x)
{
    vector<type> set;
    int m = -1;
    for (int i = 0; i < nodes.size(); i++)
    {
        if (nodes[i] == x)
        {
            m = i;
        }
    }
    if (m >= 0)
    {
        for (int j = 0; j < nodes.size(); j++)
        {
            if (adjacency[j][m] != noEdge && j != m)
            {
                set.push_back(nodes[j]);
            }
            else if (adjacency[m][j] != noEdge && j != m)
            {
                set.push_back(nodes[j]);
            }
        }
    }
    return set;
}

void addNode(type x)
{
    for (int i = 0; i < MAXSIZE; i++)
    {
        if (adjacency[i][i] == noEdge)
        {
            nodes[i] = x;

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        adjacency[i][i] = INT_MAX;
        return;
    }
}
return;
}
void deleteNode(type x)
{
    for (int i = 0; i < nodes.size(); i++)
    {
        if (nodes[i] == x)
        {
            for (int j = 0; j < MAXSIZE; j++)
            {
                adjacency[i][j] = noEdge;
                adjacency[j][i] = noEdge;
            }
            return;
        }
    }
}
void addEdge(type x, type y)
{
    int m = -1;
    int n = -1;
    for (int i = 0; i < nodes.size(); i++)
    {
        if (nodes[i] == x)
        {
            m = i;
        }
        else if (nodes[i] == y)
        {
            n = i;
        }
    }
    if (m >= 0 && n >= 0)
    {
        adjacency[m][n] = 1;
    }
    return;
}

void addEdge(type x, type y, int weight)
{
    int m = -1;
    int n = -1;
    for (int i = 0; i < nodes.size(); i++)
    {
        if (nodes[i] == x)
        {
            m = i;
        }
        else if (nodes[i] == y)
        {
            n = i;
        }
    }
    if (m >= 0 && n >= 0)
    {
        adjacency[m][n] = weight;
    }
}

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    }
    return;
}

void deleteEdge(type x, type y)
{
    int m = -1;
    int n = -1;
    for (int i = 0; i < nodes.size(); i++)
    {
        if (nodes[i] == x)
        {
            m = i;
        }
        else if (nodes[i] == y)
        {
            n = i;
        }
    }
    if (m >= 0 && n >= 0)
    {
        adjacency[m][n] = noEdge;
    }
    return;
}

void dfs(std::function<void(const type &)> process)
{
    state states[nodes.size()];
    for (int i = 0; i < nodes.size(); i++)
    {
        states[i] = unknown;
    }
    int u = 0;
    while (nodes[u] != INT_MAX)
    {
        u++;
    }
    recur_dfs(u, state, process);
    return;
}

void bfs(std::function<void(const type &)> process)
{
    type u = nodes[0]; // starting vertex
    vector<type> visted;
    vector<type> complete;
    vector<pair<type, type>> edges;
    visted.push_back(u);

    while (visted.size() != 0)
    {
        vector<type> set = neighbors(u);
        for (int i = 0; i < set.size(); i++)
        {
            bool notFound = true;
            for (int j = 0; j < visted.size(); j++)
            {
                if (visted[j] == set[i])
                {

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        notFound = false;
    }
}
for (int j = 0; j < complete.size(); j++)
{
    if (j < complete.size() && complete[j] == set[i])
    {
        notFound = false;
    }
}

if (notFound == true)
{
    visted.push_back(set[i]);
}
}
for (int i = 0; i < visted.size(); i++)
{
    if (adjacent(u, visted[i]))
    {
        edges.push_back(make_pair(u, visted[i]));
    }
}

for (int i = 0; i < visted.size() - 1; i++)
{
    visted[i] = visted[i + 1];
}
visted.pop_back();
complete.push_back(u);
if (visted.size() > 0)
{
    u = visted[0];
}
if (true);
}
return;
}
};

int main()
{

    system("pause");
    return 0;
}

```