

```
In [ ]: ## Rapport Laboratoire 1
# Adam Osmani, 2026348
print("Hello World!")
using Pkg;

Pkg.add("JuMP")
using JuMP

Pkg.add("Ipopt")
using Ipopt

Pkg.add("MathOptInterface")
using MathOptInterface
```

Hello World!

```
Resolving package versions...
No Changes to `C:\Users\adamo\.julia\environments\v1.10\Project.toml`
No Changes to `C:\Users\adamo\.julia\environments\v1.10\Manifest.toml`
Resolving package versions...
No Changes to `C:\Users\adamo\.julia\environments\v1.10\Project.toml`
No Changes to `C:\Users\adamo\.julia\environments\v1.10\Manifest.toml`
Resolving package versions...
No Changes to `C:\Users\adamo\.julia\environments\v1.10\Project.toml`
No Changes to `C:\Users\adamo\.julia\environments\v1.10\Manifest.toml`
```

Le bloc de code suivant permet de calculer les solutions à l'équation $ax^2+bx+c=0$ tel que démontré:

```
In [ ]: function quadsolv(a,b,c)
    Δ = b^2-4*a*c
    if(Δ < 0)
        sln1 = (-b+sqrt(-Δ)*im)/2*a
        sln2 = (-b-sqrt(-Δ)*im)/2*a
        return [sln1, sln2]
    end
    sln1 = (-b+sqrt(Δ))/2*a
    sln2 = (-b-sqrt(Δ))/2*a
    return [sln1, sln2]
end

println("Les solutions sont : ",quadsolv(1,3,4))
println("Les solutions sont : ",quadsolv(1,5,4))
```

```
Les solutions sont : ComplexF64[-1.5 + 1.3228756555322954im, -1.5 - 1.3228756555322954im]
Les solutions sont : [-1.0, -4.0]
```

Le code suivant permet de d'optimiser la fonction $100(x^2-x)^2+(1-x)^2$ de façon linéaire :

```
In [ ]: model2D = Model(Ipopt.Optimizer)
        @variable(model2D,x1)
        @variable(model2D,x2)

        @objective(model2D, Min, 100(x2-x1^2)^2+(1-x1)^2)

        optimize!(model2D)
        println("x1 = ",value(x1))
        println("x2 = ",value(x2))
```

```

*****
This program contains Ipopt, a library for large-scale nonlinear optimization.
Ipopt is released as open source code under the Eclipse Public License (EPL).
For more information visit https://github.com/coin-or/Ipopt
*****

```

This is Ipopt version 3.14.13, running with linear solver MUMPS 5.6.2.

```

Number of nonzeros in equality constraint Jacobian...:      0
Number of nonzeros in inequality constraint Jacobian.:      0
Number of nonzeros in Lagrangian Hessian.....:          3

```

```

Total number of variables.....:          2
      variables with only lower bounds:          0
      variables with lower and upper bounds:       0
      variables with only upper bounds:            0
Total number of equality constraints.....:          0
Total number of inequality constraints.....:          0
      inequality constraints with only lower bounds:  0
      inequality constraints with lower and upper bounds: 0
      inequality constraints with only upper bounds:  0

```

| iter | objective | inf_pr | inf_du | lg(mu) | d | lg(rg) | alpha_du | alpha_pr | ls |
|------|---------------|----------|----------|--------|----------|--------|----------|-----------|----|
| 0 | 1.0000000e+00 | 0.00e+00 | 2.00e+00 | -1.0 | 0.00e+00 | - | 0.00e+00 | 0.00e+00 | 0 |
| 1 | 9.5312500e-01 | 0.00e+00 | 1.25e+01 | -1.0 | 1.00e+00 | - | 1.00e+00 | 2.50e-01f | 3 |
| 2 | 4.8320569e-01 | 0.00e+00 | 1.01e+00 | -1.0 | 9.03e-02 | - | 1.00e+00 | 1.00e+00f | 1 |
| 3 | 4.5708829e-01 | 0.00e+00 | 9.53e+00 | -1.0 | 4.29e-01 | - | 1.00e+00 | 5.00e-01f | 2 |
| 4 | 1.8894205e-01 | 0.00e+00 | 4.15e-01 | -1.0 | 9.51e-02 | - | 1.00e+00 | 1.00e+00f | 1 |
| 5 | 1.3918726e-01 | 0.00e+00 | 6.51e+00 | -1.7 | 3.49e-01 | - | 1.00e+00 | 5.00e-01f | 2 |
| 6 | 5.4940990e-02 | 0.00e+00 | 4.51e-01 | -1.7 | 9.29e-02 | - | 1.00e+00 | 1.00e+00f | 1 |
| 7 | 2.9144630e-02 | 0.00e+00 | 2.27e+00 | -1.7 | 2.49e-01 | - | 1.00e+00 | 5.00e-01f | 2 |
| 8 | 9.8586451e-03 | 0.00e+00 | 1.15e+00 | -1.7 | 1.10e-01 | - | 1.00e+00 | 1.00e+00f | 1 |
| 9 | 2.3237475e-03 | 0.00e+00 | 1.00e+00 | -1.7 | 1.00e-01 | - | 1.00e+00 | 1.00e+00f | 1 |
| iter | objective | inf_pr | inf_du | lg(mu) | d | lg(rg) | alpha_du | alpha_pr | ls |
| 10 | 2.3797236e-04 | 0.00e+00 | 2.19e-01 | -1.7 | 5.09e-02 | - | 1.00e+00 | 1.00e+00f | 1 |
| 11 | 4.9267371e-06 | 0.00e+00 | 5.95e-02 | -1.7 | 2.53e-02 | - | 1.00e+00 | 1.00e+00f | 1 |
| 12 | 2.8189506e-09 | 0.00e+00 | 8.31e-04 | -2.5 | 3.20e-03 | - | 1.00e+00 | 1.00e+00f | 1 |
| 13 | 9.6379884e-16 | 0.00e+00 | 8.68e-07 | -5.7 | 9.78e-05 | - | 1.00e+00 | 1.00e+00f | 1 |
| 14 | 1.9721523e-29 | 0.00e+00 | 1.57e-13 | -8.6 | 4.65e-08 | - | 1.00e+00 | 1.00e+00f | 1 |

Number of Iterations.....: 14

| | (scaled) | (unscaled) |
|----------------------------|------------------------|------------------------|
| Objective.....: | 1.9721522630525295e-29 | 1.9721522630525295e-29 |
| Dual infeasibility.....: | 1.5720758028692217e-13 | 1.5720758028692217e-13 |
| Constraint violation.....: | 0.0000000000000000e+00 | 0.0000000000000000e+00 |
| Variable bound violation: | 0.0000000000000000e+00 | 0.0000000000000000e+00 |
| Complementarity.....: | 0.0000000000000000e+00 | 0.0000000000000000e+00 |
| Overall NLP error.....: | 1.5720758028692217e-13 | 1.5720758028692217e-13 |

```

Number of objective function evaluations      = 36
Number of objective gradient evaluations      = 15
Number of equality constraint evaluations      = 0
Number of inequality constraint evaluations    = 0
Number of equality constraint Jacobian evaluations = 0
Number of inequality constraint Jacobian evaluations = 0
Number of Lagrangian Hessian evaluations     = 14
Total seconds in IPOPT                       = 0.035

```

EXIT: Optimal Solution Found.

x1 = 0.9999999999999899

x2 = 0.999999999999793

Le code suivant permet de d'optimiser la fonction $100(x_2 - x_1^2)^2 + (1 - x_1)^2$ de façon non linéaire :

```
In [ ]: model = Model(Ipopt.Optimizer)
x0 = [-1.2; 1.0]
@variable(model, x[i=1:2], start=x0[i])
@NLobjective(model, Min, (x[1] - 1)^2 + 100 * (x[2] - x[1]^2)^2)
optimize!(model)

println("x1 = ", value(x[1]))
println("x2 = ", value(x[2]))
```

This is Ipopt version 3.14.13, running with linear solver MUMPS 5.6.2.

Number of nonzeros in equality constraint Jacobian...: 0
 Number of nonzeros in inequality constraint Jacobian.: 0
 Number of nonzeros in Lagrangian Hessian.....: 3

Total number of variables.....: 2
 variables with only lower bounds: 0
 variables with lower and upper bounds: 0
 variables with only upper bounds: 0
 Total number of equality constraints.....: 0
 Total number of inequality constraints.....: 0
 inequality constraints with only lower bounds: 0
 inequality constraints with lower and upper bounds: 0
 inequality constraints with only upper bounds: 0

| iter | objective | inf_pr | inf_du | lg(mu) | d | lg(rg) | alpha_du | alpha_pr | ls |
|------|---------------|----------|----------|--------|----------|--------|----------|-----------|----|
| 0 | 2.4200000e+01 | 0.00e+00 | 1.00e+02 | -1.0 | 0.00e+00 | - | 0.00e+00 | 0.00e+00 | 0 |
| 1 | 4.7318843e+00 | 0.00e+00 | 2.15e+00 | -1.0 | 3.81e-01 | - | 1.00e+00 | 1.00e+00f | 1 |
| 2 | 4.0873987e+00 | 0.00e+00 | 1.20e+01 | -1.0 | 4.56e+00 | - | 1.00e+00 | 1.25e-01f | 4 |
| 3 | 3.2286726e+00 | 0.00e+00 | 4.94e+00 | -1.0 | 2.21e-01 | - | 1.00e+00 | 1.00e+00f | 1 |
| 4 | 3.2138981e+00 | 0.00e+00 | 1.02e+01 | -1.0 | 4.82e-01 | - | 1.00e+00 | 1.00e+00f | 1 |
| 5 | 1.9425854e+00 | 0.00e+00 | 1.62e+00 | -1.0 | 6.70e-02 | - | 1.00e+00 | 1.00e+00f | 1 |
| 6 | 1.6001937e+00 | 0.00e+00 | 3.44e+00 | -1.0 | 7.35e-01 | - | 1.00e+00 | 2.50e-01f | 3 |
| 7 | 1.1783896e+00 | 0.00e+00 | 1.92e+00 | -1.0 | 1.44e-01 | - | 1.00e+00 | 1.00e+00f | 1 |
| 8 | 9.2241158e-01 | 0.00e+00 | 4.00e+00 | -1.0 | 2.08e-01 | - | 1.00e+00 | 1.00e+00f | 1 |
| 9 | 5.9748862e-01 | 0.00e+00 | 7.36e-01 | -1.0 | 8.91e-02 | - | 1.00e+00 | 1.00e+00f | 1 |
| 10 | 4.5262510e-01 | 0.00e+00 | 2.42e+00 | -1.7 | 2.97e-01 | - | 1.00e+00 | 5.00e-01f | 2 |
| 11 | 2.8076244e-01 | 0.00e+00 | 9.25e-01 | -1.7 | 1.02e-01 | - | 1.00e+00 | 1.00e+00f | 1 |
| 12 | 2.1139340e-01 | 0.00e+00 | 3.34e+00 | -1.7 | 1.77e-01 | - | 1.00e+00 | 1.00e+00f | 1 |
| 13 | 8.9019501e-02 | 0.00e+00 | 2.25e-01 | -1.7 | 9.45e-02 | - | 1.00e+00 | 1.00e+00f | 1 |
| 14 | 5.1535405e-02 | 0.00e+00 | 1.49e+00 | -1.7 | 2.84e-01 | - | 1.00e+00 | 5.00e-01f | 2 |
| 15 | 1.9992778e-02 | 0.00e+00 | 4.64e-01 | -1.7 | 1.09e-01 | - | 1.00e+00 | 1.00e+00f | 1 |
| 16 | 7.1692436e-03 | 0.00e+00 | 1.03e+00 | -1.7 | 1.39e-01 | - | 1.00e+00 | 1.00e+00f | 1 |
| 17 | 1.0696137e-03 | 0.00e+00 | 9.09e-02 | -1.7 | 5.50e-02 | - | 1.00e+00 | 1.00e+00f | 1 |
| 18 | 7.7768464e-05 | 0.00e+00 | 1.44e-01 | -2.5 | 5.53e-02 | - | 1.00e+00 | 1.00e+00f | 1 |
| 19 | 2.8246695e-07 | 0.00e+00 | 1.50e-03 | -2.5 | 7.31e-03 | - | 1.00e+00 | 1.00e+00f | 1 |
| 20 | 8.5170750e-12 | 0.00e+00 | 4.90e-05 | -5.7 | 1.05e-03 | - | 1.00e+00 | 1.00e+00f | 1 |
| 21 | 3.7439756e-21 | 0.00e+00 | 1.73e-10 | -5.7 | 2.49e-06 | - | 1.00e+00 | 1.00e+00f | 1 |

Number of Iterations.....: 21

| | (scaled) | (unscaled) |
|---------------------------|------------------------|------------------------|
| Objective..... | 1.7365378678754519e-21 | 3.7439756431394737e-21 |
| Dual infeasibility..... | 1.7312156654298279e-10 | 3.7325009746667082e-10 |
| Constraint violation..... | 0.0000000000000000e+00 | 0.0000000000000000e+00 |
| Variable bound violation: | 0.0000000000000000e+00 | 0.0000000000000000e+00 |
| Complementarity..... | 0.0000000000000000e+00 | 0.0000000000000000e+00 |
| Overall NLP error..... | 1.7312156654298279e-10 | 3.7325009746667082e-10 |

Number of objective function evaluations = 45
 Number of objective gradient evaluations = 22
 Number of equality constraint evaluations = 0
 Number of inequality constraint evaluations = 0
 Number of equality constraint Jacobian evaluations = 0
 Number of inequality constraint Jacobian evaluations = 0

Number of Lagrangian Hessian evaluations = 21
Total seconds in IPOPT = 0.028

EXIT: Optimal Solution Found.

x1 = 0.9999999999400667

x2 = 0.9999999998789006