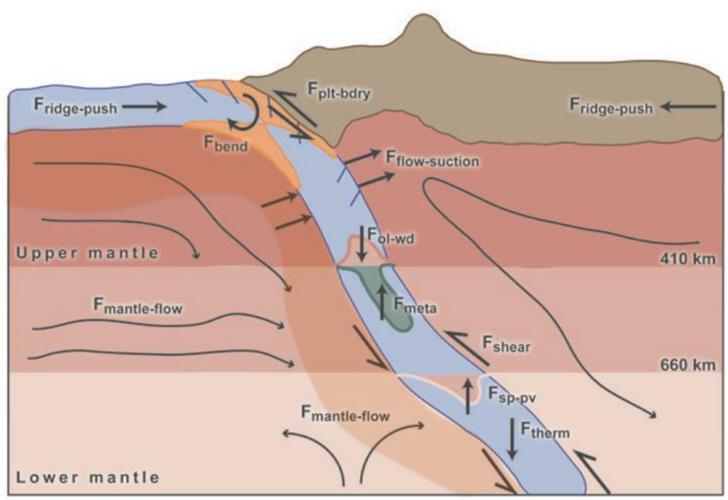
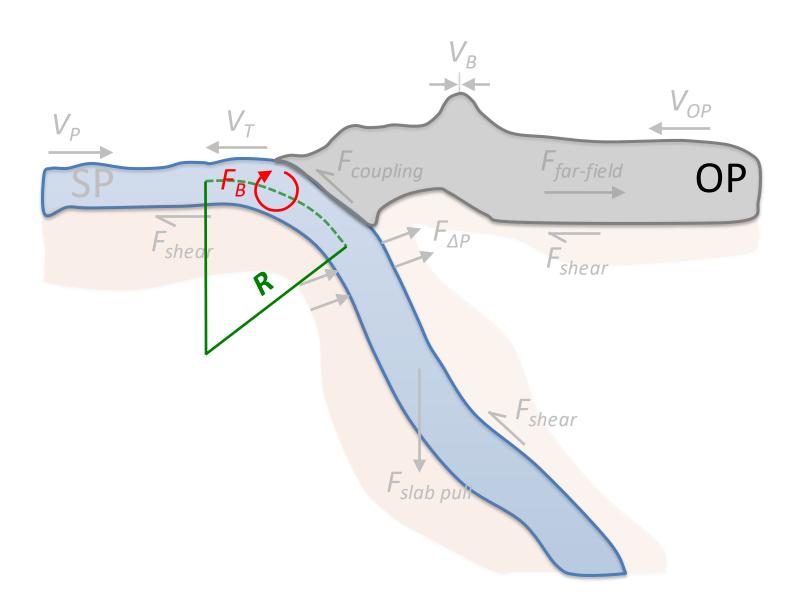
Slab bending



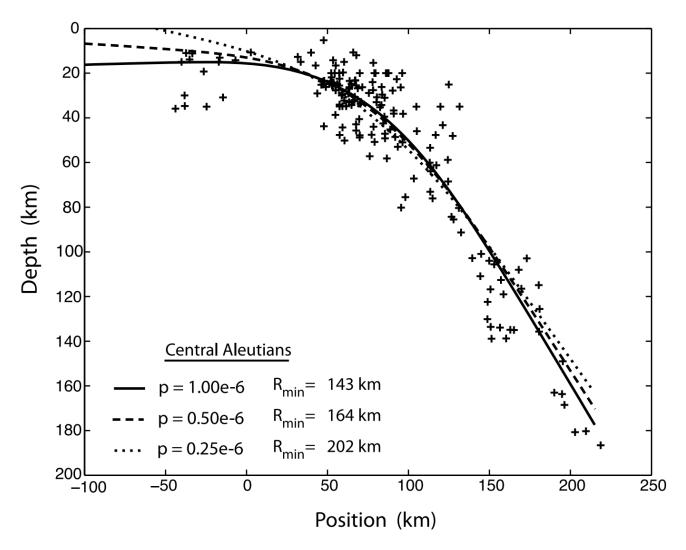
Billen, 2008



- Radius of curvature
- Viscous bending
 Dissipation, force, plate motions, time-dependence.
- More complex viscous rheologies
 Visco-plasticity; Elasticity
- Visco-elasto-plastic and comparing with seismicity.

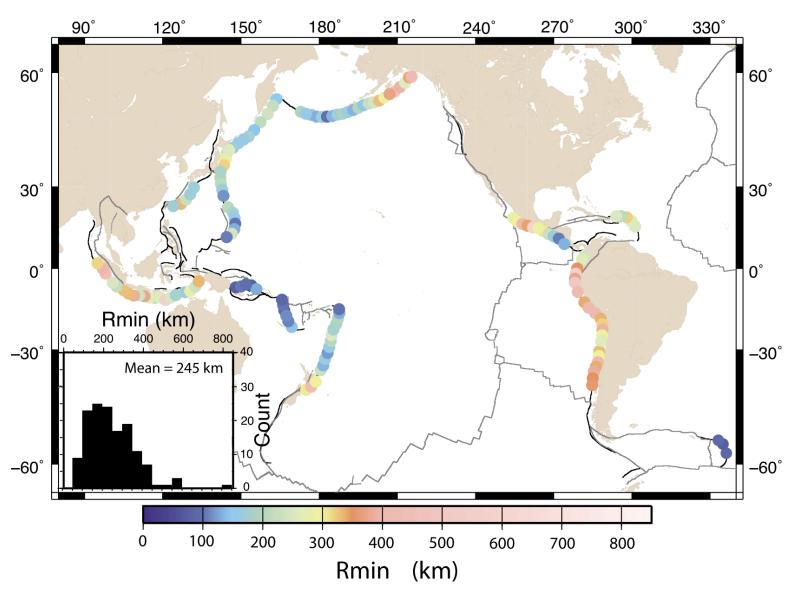
Radius of curvature

Fitting splines (piecewise polynomials) through earthquake locations



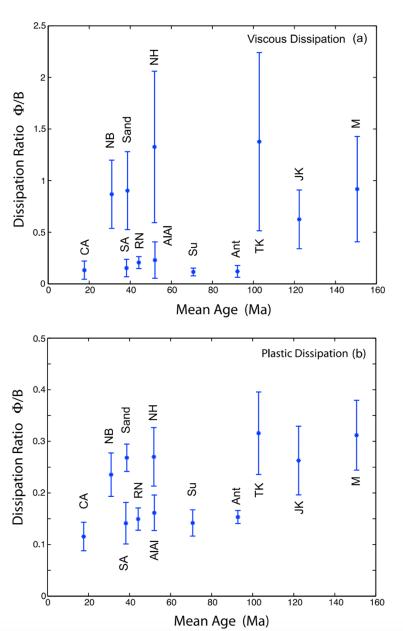
Buffett & Heuret, 2011

Radius of curvature



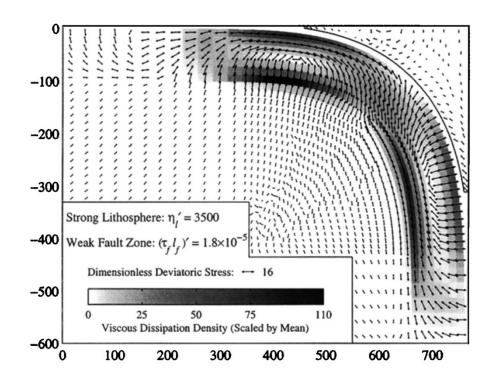
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Radius of curvature



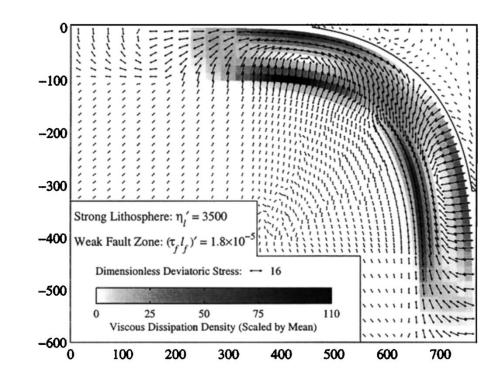
Radius of curvature – R – a key control on bending dissipation or forces, irrespective of assumed rheology (more to come...).

 Finite element models to probe the dependence of viscous dissipation (in the bending lithosphere) on subduction zone properties.



- Finite element models to probe the dependence of viscous dissipation (in the bending lithosphere) on subduction zone properties.
- Dissipation balance assuming a totally viscous system:

$$\Phi^{\mathrm{pe}} = \Phi^{\mathrm{vd}}_m + \Phi^{\mathrm{vd}}_f + \Phi^{\mathrm{vd}}_l$$



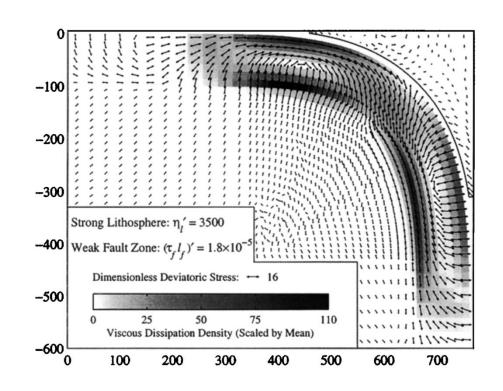
(The rate of energy supplied by mass anomalies moving through the gravity field is to equal the work done by stresses in deforming the material.)

- Finite element models to probe the dependence of viscous dissipation (in the bending lithosphere) on subduction zone properties.
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 - printe element models to probe the dependence of bending lithosphere) on subduction zone properties.

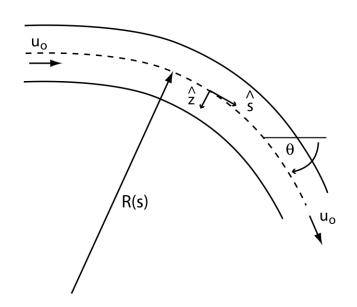
 Dissipation balance assuming a totally viscous system:

 \circ Where the ϕ_f^{vd} given by:

$$\Phi_l^{\text{vd}} = C_l v_p^2 \eta_l \left(\frac{h_s}{R}\right)^3$$



The baseline: Viscous bending

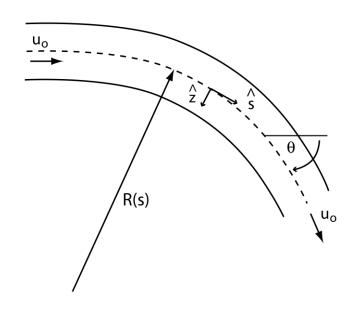


$$N = \int_{-H/2}^{H/2} au_{ss} dz \qquad M = \int_{-H/2}^{H/2} au_{ss} z dz$$

$$M(s) = -\frac{1}{3}\eta u_0 H^3 \left(\frac{dK}{ds}\right) \qquad \frac{dK}{ds} \approx \frac{1}{R_{\min}^2}$$

$$\Delta N(0) = -rac{2}{3} \left(rac{H}{R_{
m min}}
ight)^3 \eta u_0$$

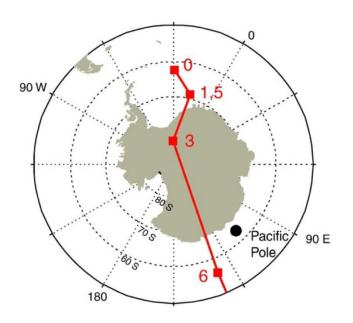
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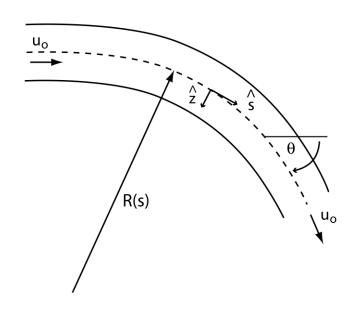
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Proposed to affect plate velocities. Plot shows predicted (red) and observed (black) Euler poles for different slab viscosities (units of 10²² Pas).

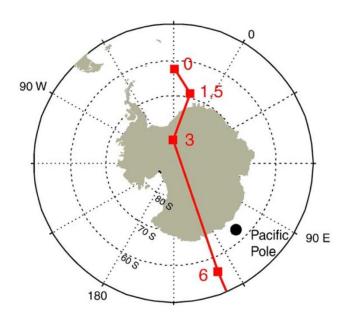
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Proposed to affect plate velocities. Plot shows predicted (red) and observed (black) Euler poles for different slab viscosities (units of 10^{22} Pas). Assumes R = 200 km and proposes that bending dissipates ~40 % of slab's potential energy.

But not so quick, e.g.:



Article

Volume 10, Number 4 1 April 2009 Q04002, doi:10.1029/2008GC002348 ISSN: 1525-2027

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Dynamics of plate bending at the trench and slab-plate coupling

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Evolution of the slab bending radius and the bending dissipation in three-dimensional subduction models with a variable slab to upper mantle viscosity ratio

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ABSTRACT

Three-dimensional laboratory subduction models are presented investigating the influence of the slab/upper mantle viscosity ratio (η_{SP}/η_{UM}) on the slab bending radius (R_B), with η_{SP}/η_{UM} = 66-1375. Here, R_B is non-dimensionalized by dividing it by the upper mantle thickness (T_{UM}). The results show that R_B/T_{UM} varies with time, reaching a maximum when the subduction velocity is maximum. Furthermore, R_B/T_{UM} increases approximately linearly with increasing η_{SP}/η_{UM} for the investigated viscosity range. The model results show that the slab bending

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(Friday's discussion!)



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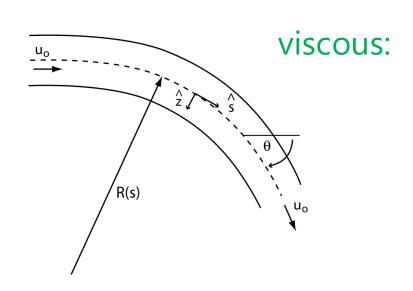
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Adding complexity: Plastic bending

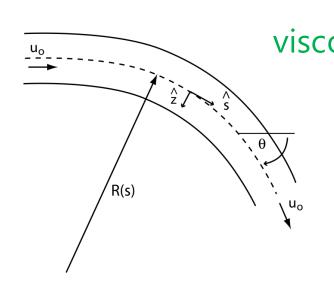


viscous:
$$N = \int_{-H/2}^{H/2} au_{ss} \, dz$$
 $M = \int_{-H/2}^{H/2} au_{ss} z \, dz$

$$\Delta N(0) = -\frac{2}{3} \left(\frac{H}{R_{\min}}\right)^3 \eta u_0$$

$$\Phi = \frac{2}{3} \left(\frac{H^3}{R_{\min}^3} \right) \eta u_0^2$$

Adding complexity: Plastic bending



VISCOUS:
$$N = \int_{-H/2}^{H/2} \tau_{ss} \, dz$$
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$$\Delta N(0) = -\frac{2}{3} \left(\frac{H}{R_{\min}}\right)^3 \eta u_0$$

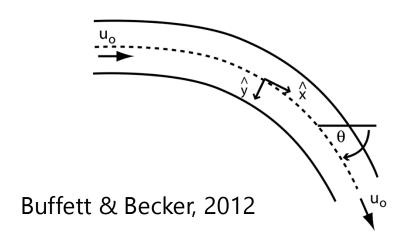
$$\Phi = \frac{2}{3} \left(\frac{H^3}{R_{\min}^3} \right) \eta u_0^2$$

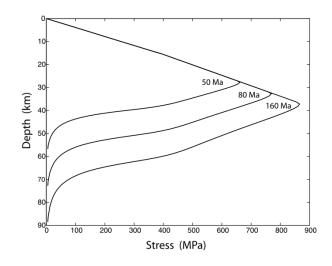
plastic:

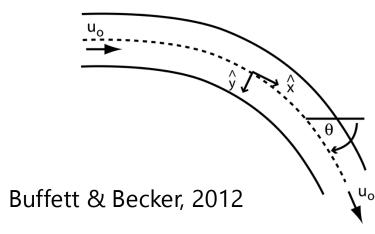
$$z < 0$$
: $\tau_y(z) = \tau_y(0)(1 + 2z/H)$

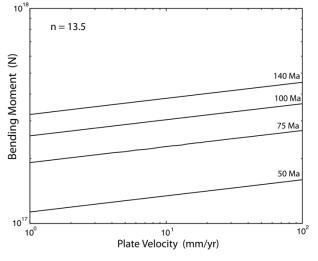
$$z > 0$$
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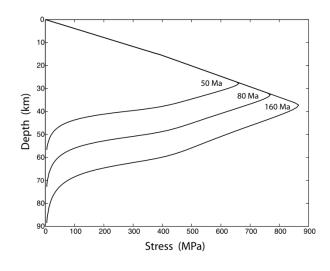
$$\Phi = rac{1}{6} \left(rac{H^2}{R_{
m min}}
ight) au_y(0) u_0 \qquad \Delta N(0) = -rac{1}{6} \left(rac{H^2}{R_{
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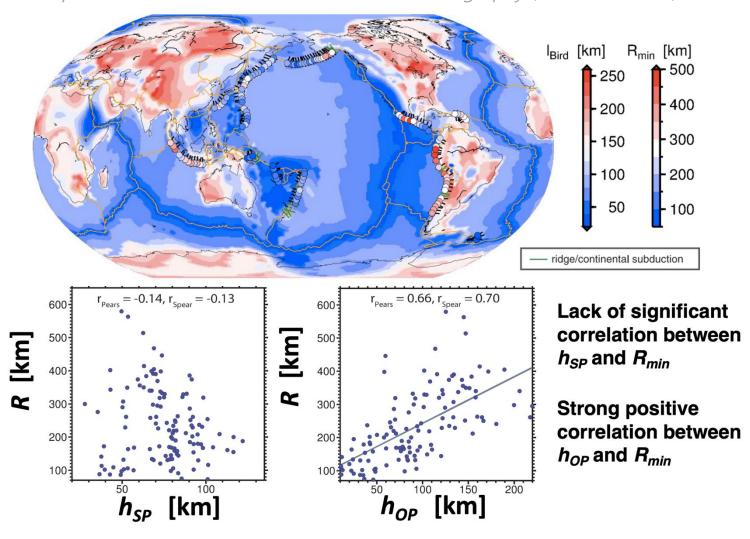


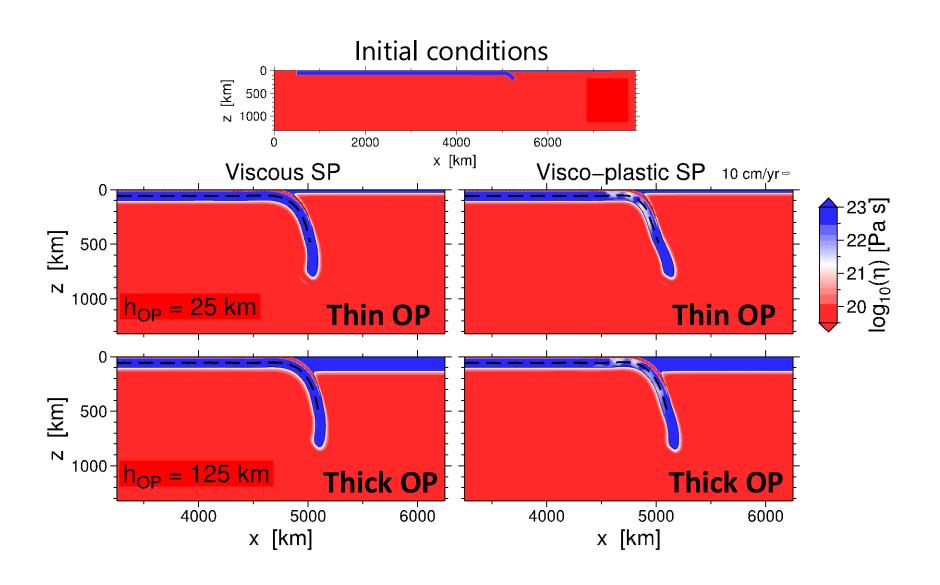


- Both bending moment (M) and bending force (N) relatively insensitive to subduction velocity.
- Moment and force can be approximated by a power-law fluid with n = 13.5 (i.e., almost perfectly plastic).

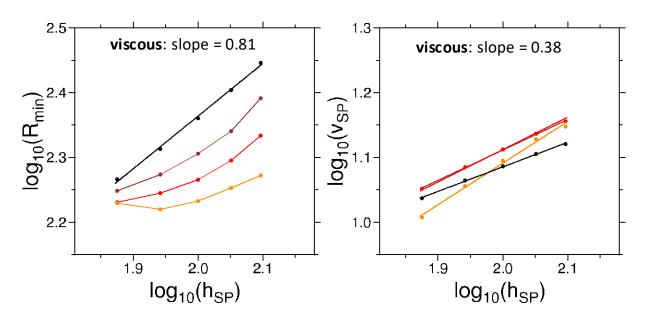
"Stresses associated with bending in a plastic plate cannot balance the torque associated with buoyancy forces. Instead, surface forces on the plate must play an important role: the conditions in the OP should contribute, and possibly control, to the evolution of curvature."

R from Benioff zone spline fits (Buffett & Heuret, 2011) Lithospheric thickness estimated from seismic tomography (Bird et al., 2008)

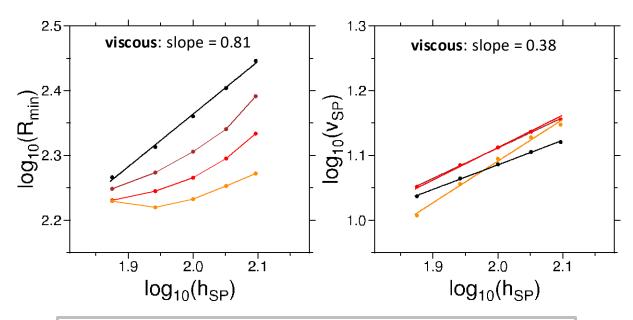




Modeled dependence on SP thickness:



Modeled dependence on SP thickness:



For viscous SP, follows from a simple scaling:

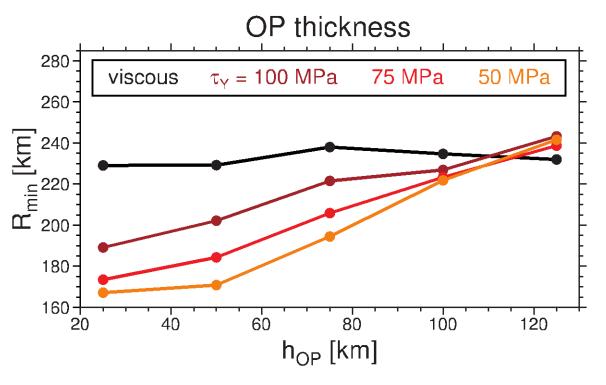
buoyancy flux
$$\propto$$
 bending dissipation
$$\Delta \rho g h_{\rm SP} D v_{\rm SP} \propto \left(\frac{h_{\rm SP}}{R_{\rm min}}\right)^3 \eta' v_{\rm SP}^2,$$

$$R_{\rm min} \propto h_{\rm SP}^{2/3} v_{\rm SP}^{1/3}$$

$$R_{\rm min} \propto h_{\rm SP}^{0.79}$$

But no positive correlation on Earth: Plasticity reduces this!

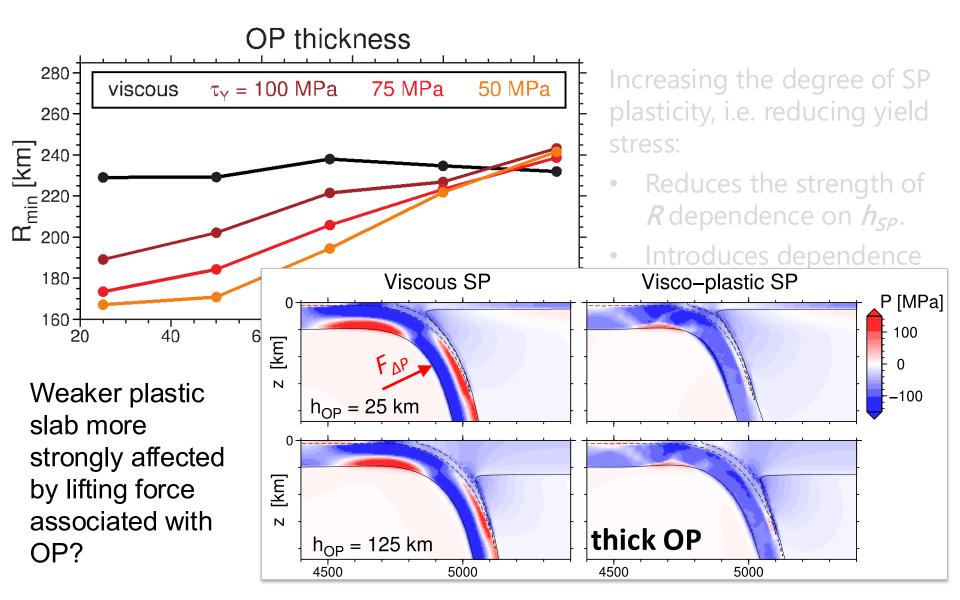
Now, **OP** thickness, h_{OP} :



Increasing the degree of SP plasticity, i.e. reducing yield stress:

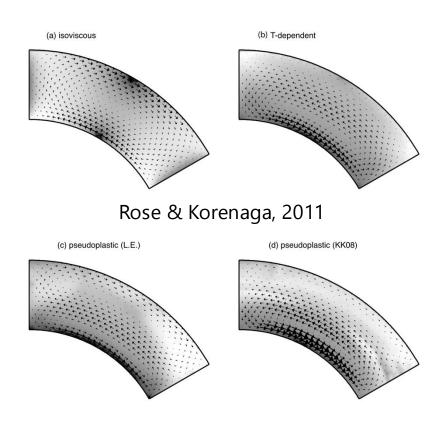
- Reduces the strength of R dependence on h_{SP} .
- Introduces dependence of R on h_{OP} .

Now, **OP thickness**, h_{OP} :



Testing variable <u>viscous</u> and <u>visco-plastic</u> rheologies

Like Conrad & Hager 1999 but with more sophisticated rheologies (including lab-derived olivine flow laws)



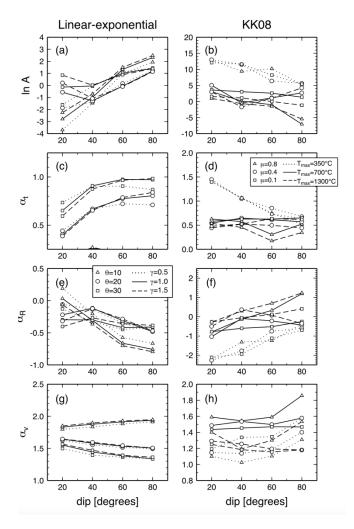
Testing variable <u>viscous</u> and <u>visco-plastic</u> rheologies

Like Conrad & Hager 1999 but with more sophisticated rheologies

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Linear regression for dissipation scaling factors points to values that are highly variable relative to is viscous case.



$$\Phi_{
m BD}(t,R,
u,\phi) = A(\phi) t^{lpha_t(\phi)} R^{lpha_R(\phi)} v^{lpha_
u(\phi)},$$

$$D_{ij} = D_{ij}^{\vee} + D_{ij}^{e} = \frac{\tau_{ij}}{2\eta} + \frac{\dot{\tau}_{ij}}{2\mu}$$

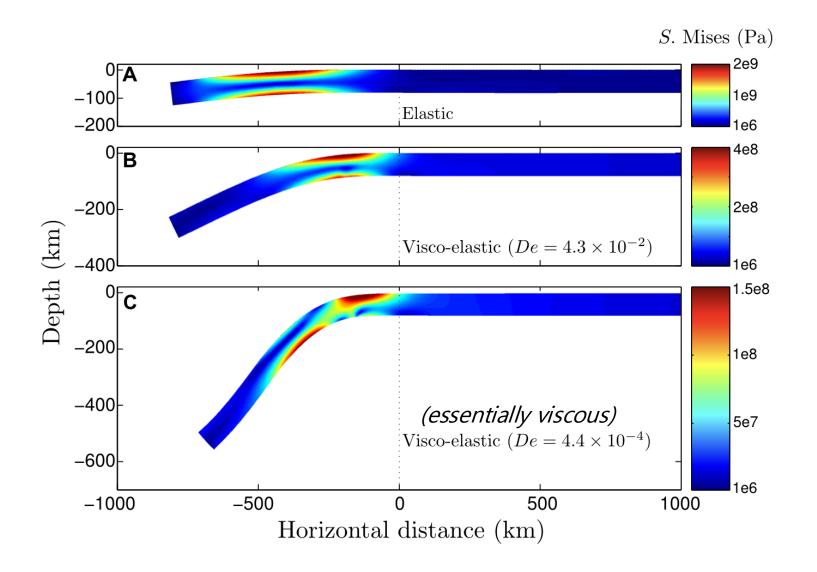
$$\dot{\tau}_{ij} = \lim_{\delta t \to 0} \frac{\tau(t, x(t)) - \tau(t - \delta t, x(t - \delta t))}{\delta t}$$

$$\tau_{ij}(t, x(t)) = 2\eta_{\text{eff}} D_{ij}(t, x(t)) + \frac{\eta_{\text{eff}}}{\mu \Delta t} \dot{\tau}(t - \Delta t, x(t))$$

$$\sigma_{ij,j} = \tau_{ij,j} - p_i = f_i$$

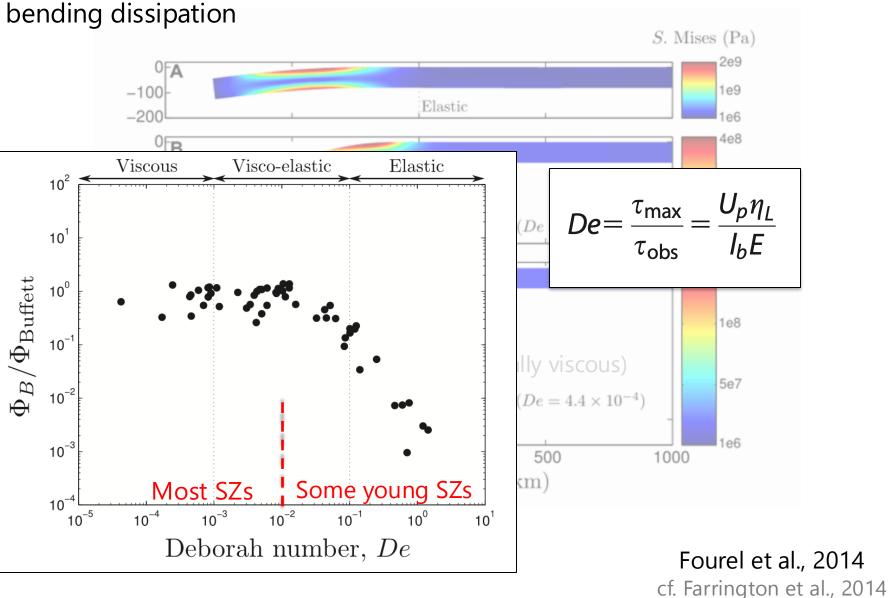
$$(2\eta_{\text{eff}} D_{ij})_{,j} - p_{,i} = f_i - \frac{\eta_{\text{eff}}}{\mu \Delta t} \tau_{ij,j}^{\vee}$$

Example implementation from Moresi et al., 2003 (and Farrington et al., 2014)

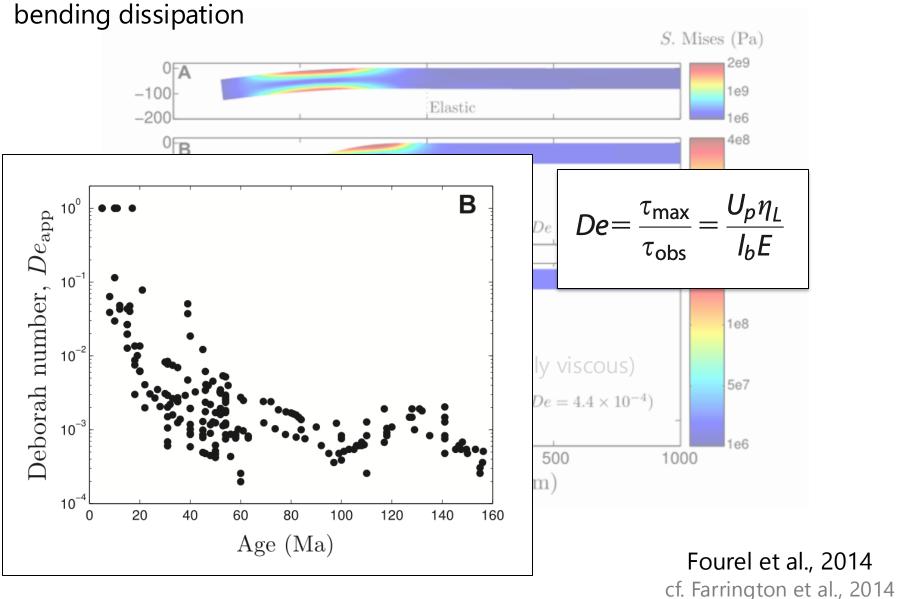


Fourel et al., 2014 cf. Farrington et al., 2014

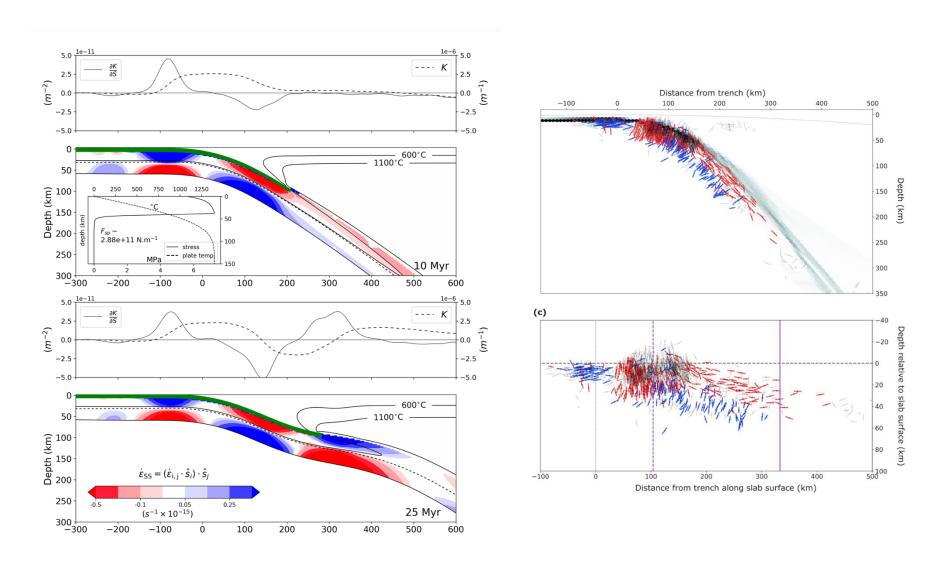
For high Deborah numbers, viscous scaling significantly overestimate



For high Deborah numbers, viscous scaling significantly overestimate



Visco-elasto-plastic



Sandiford et al., 2020 cf. Sandiford & Craig, 2023; Craig et al., 2023