

$Obs_{\{t-2\}}$ $Obs_{\{t-1\}}$ $Obs_{\{t\}}$ $Gen_{\{t+1\}}$ $Gen_{\{t+2\}}$ $Gen_{\{t+3\}}$ $Gen_{\{t+4\}}$

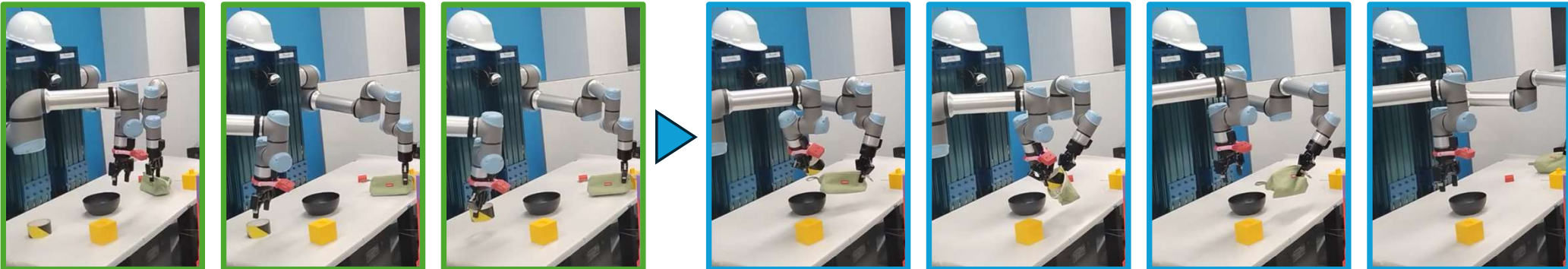


Image Encoder



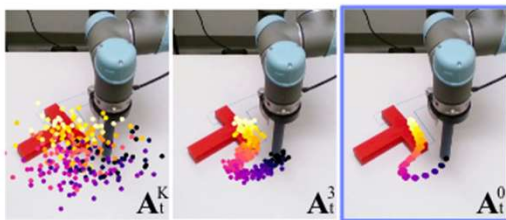
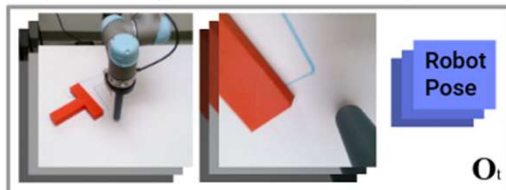
Current Observation



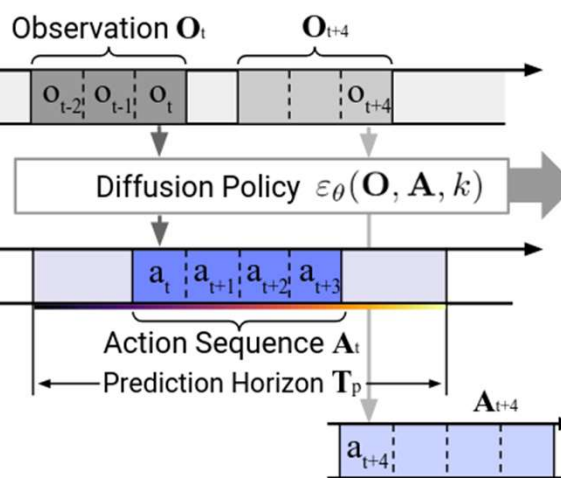
Goal Embedding



Input: Image Observation Sequence



Output: Action Sequence



a) Diffusion Policy General Formulation

