

$Obs_{\{t-2\}}$      $Obs_{\{t-1\}}$      $Obs_{\{t\}}$      $Gen_{\{t+1\}}$      $Gen_{\{t+2\}}$      $Gen_{\{t+3\}}$      $Gen_{\{t+4\}}$

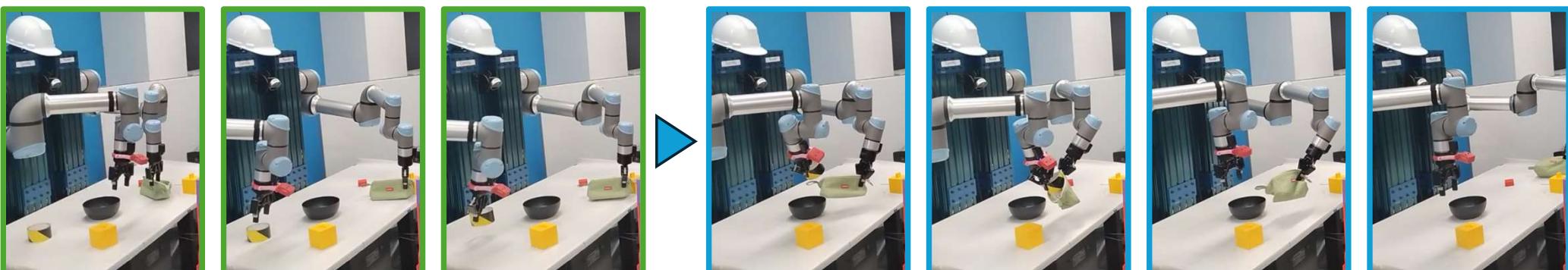


Image Encoder



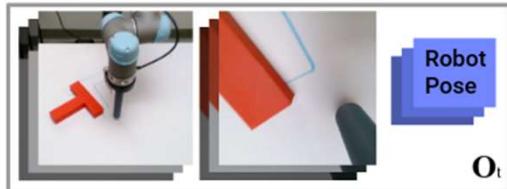
Current Observation



Goal Embedding

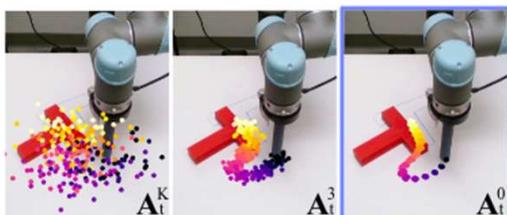
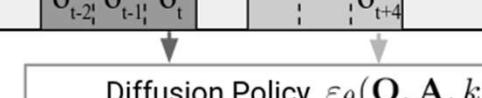


Input: Image Observation Sequence



Observation  $O_t$

$O_{t+4}$



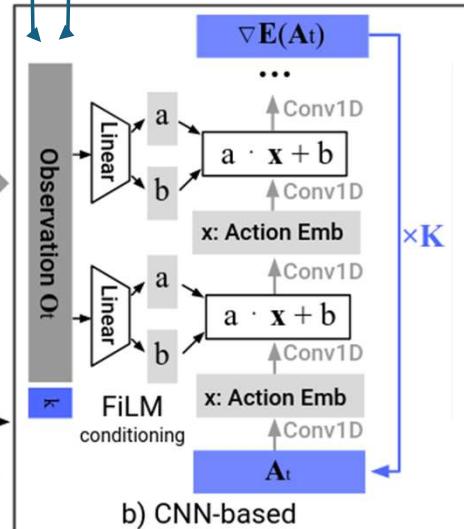
Action Sequence  $A_t$

Prediction Horizon  $T_p$

$A_{t+4}$

Output: Action Sequence

a) Diffusion Policy General Formulation



Low-Level  
Action Diffusion

Image Source:  
Diffusion Policy