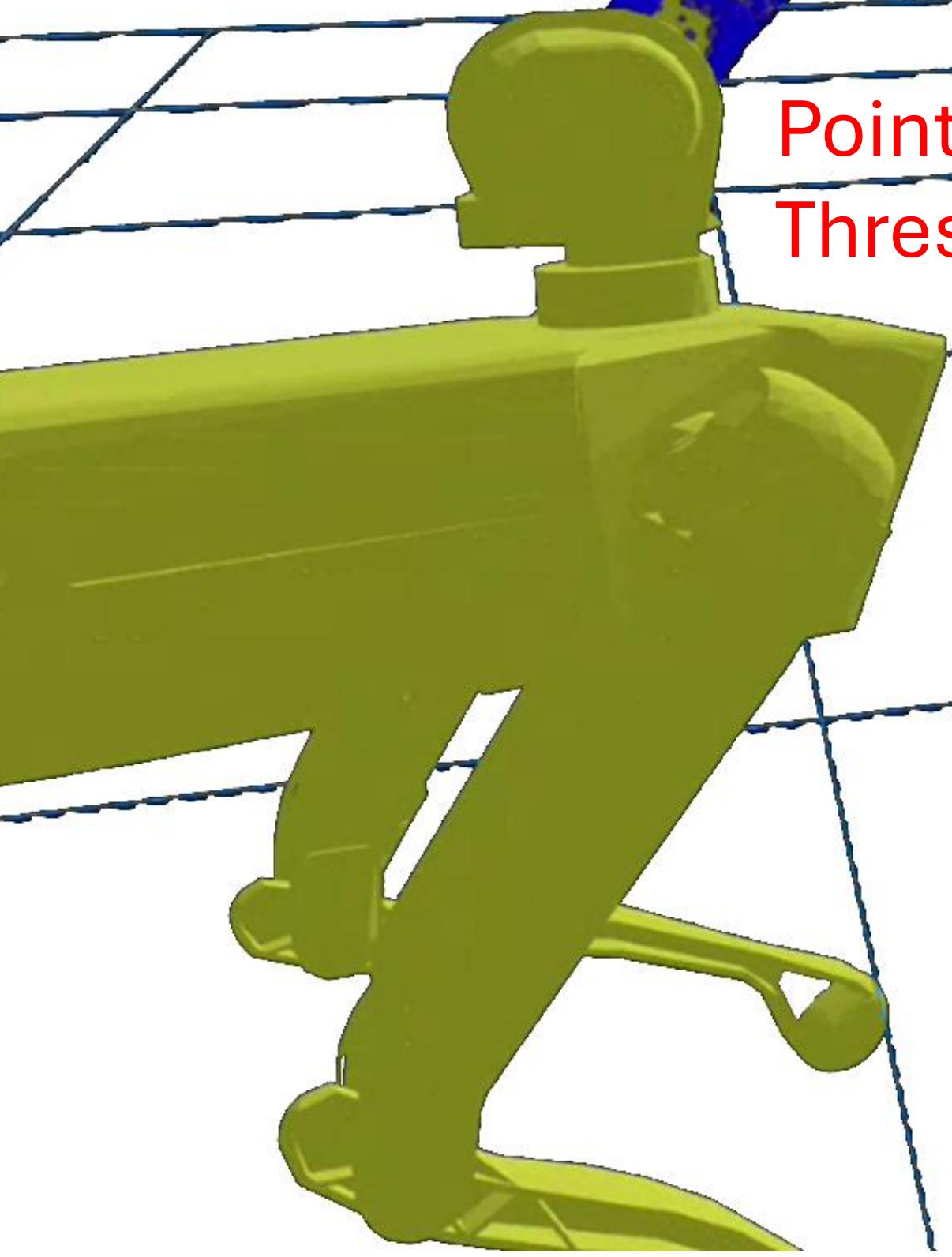


Robot Geometry
Avoidance Points



Points Within
Threshold

Contact Distance
Threshold

