## Math 231 — Hw 16

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In class, we continued to discuss how we to use matrix representations of linear maps between vector spaces. Suppose we define the horrible map you came up with in class,  $T: \mathbb{R}^4 \to \mathbb{R}^3$ 

- T(1,2,3,4) = (5,6,7)
- T(11, 10, 9, 8) = (2, 3, 1)
- T(1,5,7,2) = (7,8,6)
- T(0,0,0,1) = (9,1,1)

Our strategy for handling this is to define a map  $U: \mathbb{R}^4 \to \mathbb{R}^4$  that translates from a nice basis  $\{(1,0,0,0),(0,1,0,0),...\}$  to the basis upon which T is defined:  $\{(1,2,3,4),(11,10,9,8),...\}$ . We did this in class and defined the matrix representation for U to be

$$M(U) = \begin{pmatrix} \frac{25}{24} & \frac{-17}{6} & \frac{15}{8} & 0\\ \frac{1}{24} & \frac{1}{6} & \frac{-1}{8} & 0\\ \frac{-1}{2} & 1 & \frac{-1}{2} & 0\\ \frac{-7}{2} & 8 & \frac{-11}{2} & 1 \end{pmatrix}$$

If we define the set of mapped elements in  $\mathbb{R}^3$  to be  $\{(5,6,7),(2,3,1),(7,8,6),(9,1,1)\}$ , then the matrix representation of T is

$$M(T) = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

But this is not enough to get the full answer. Why? Suppose there is a vector v for which we apply M(U) and then M(T) and we get the result (1,0,1,1). This vector represents:  $1 \cdot (5,6,7) + 0 \cdot (2,3,1) + 1 \cdot (7,8,6) + 1 \cdot (9,1,1)$ . Ideally we'd like the result to actually be our answer directly and not have to do this extra step. So we can define a map S that goes from  $\{(5,6,7),(2,3,1),(7,8,6),(9,1,1)\}$  to  $\{(1,0,0),(0,1,0),(0,0,1)\}$ . Define M(S).