

Faculty of Engineering & Technology Electrical & Computer Engineering Department

DIGITAL SIGNAL PROCESSING (DSP) ENCS 4310

Prepared by:

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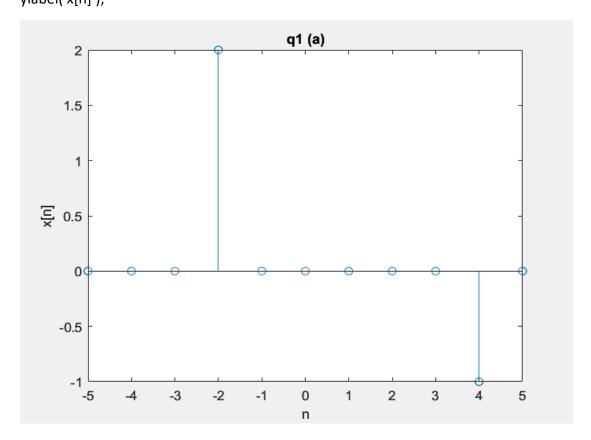
Instructor:

Dr. Qadri Mayyala

Section: 2

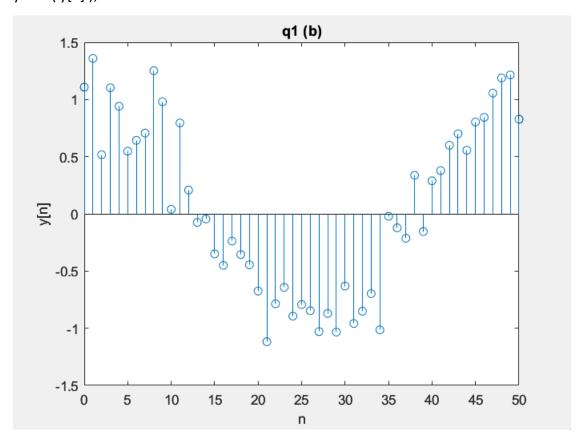
Date: 1/12/2023

```
Q1_a:
n=-5:5;
delta_n=[0,0,0,2,0,0,0,0,0,-1,0];
stem(n,delta_n);
title('q1 (a)')
xlabel('n');
ylabel('x[n]');
```



Q1_b:

```
n=linspace(0,50,51);
y_n=cos(0.04*pi*n)+0.2*randn(size(n));
stem(n,y_n)
title('q1 (b)')
xlabel('n');
ylabel('y[n]');
```



```
Q1_c:

n=-10:9;

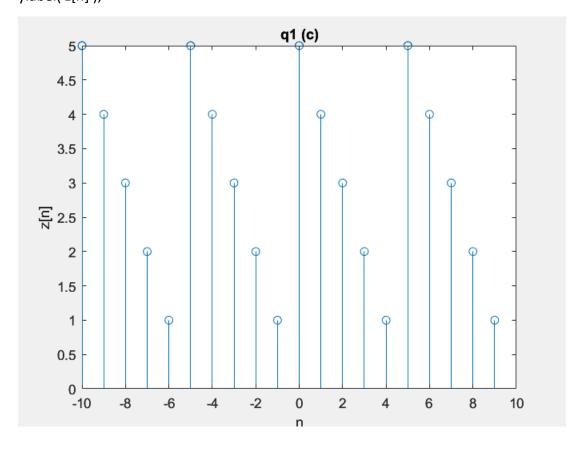
delta_n=[5,4,3,2,1,5,4,3,2,1,5,4,3,2,1,5,4,3,2,1];

stem(n,delta_n);

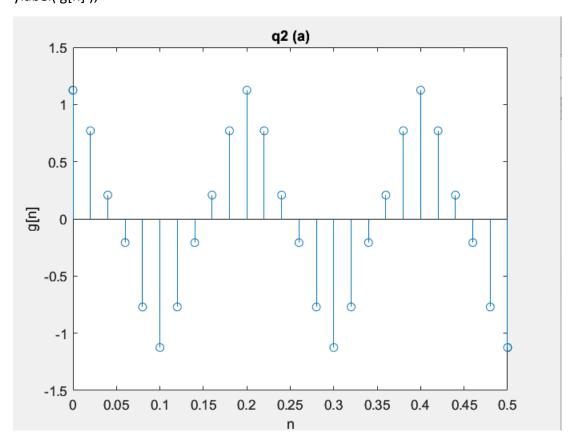
title('q1 (c)')

xlabel('n');

ylabel('z[n]');
```



```
Q2_a:  n=0:1/50:0.5; \\ F1=5; \\ F2=15; \\ g_n=cos(2*pi*F1*n)+0.125*cos(2*pi*F2*n); \\ stem(n,g_n); \\ title('q2 (a)'); \\ xlabel('n'); \\ ylabel('g[n]');
```



```
Q2_b:

n=0:1/30:0.5;

F1=5;

F2=15;

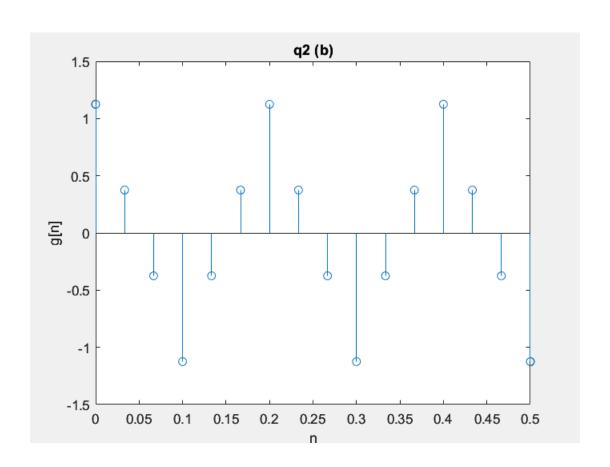
g_n=cos(2*pi*F1*n)+0.125*cos(2*pi*F2*n);

stem(n,g_n);

title('q2 (b)');

xlabel('n');

ylabel('g[n]');
```



```
Q2_c:

n=0:1/20:0.5;

F1=5;

F2=15;

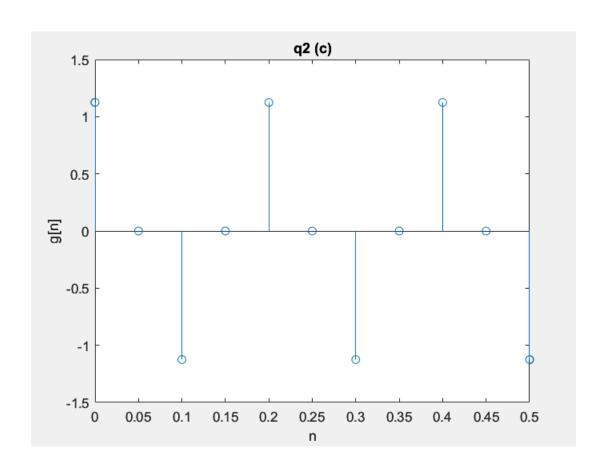
g_n=cos(2*pi*F1*n)+0.125*cos(2*pi*F2*n);

stem(n,g_n);

title('q2 (c)');

xlabel('n');

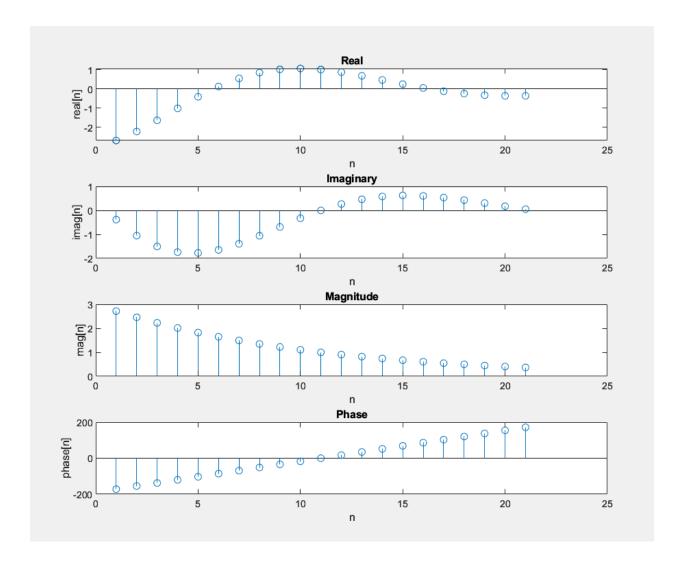
ylabel('g[n]');
```



```
Q3:
n=-10:10;
x_n = \exp((-0.1+j*0.3)*n);
subplot(4,1,1);
stem(real(x_n));
title('Real');
xlabel('n');
ylabel('real[n]');
subplot(4,1,2);
stem(imag(x_n));
title('Imaginary');
xlabel('n');
ylabel('imag[n]');
subplot(4,1,3);
stem(abs(x_n));
title('Magnitude');
xlabel('n');
ylabel('mag[n]');
subplot(4,1,4);
stem((180/pi)*angle(x_n));
title('Phase');
```

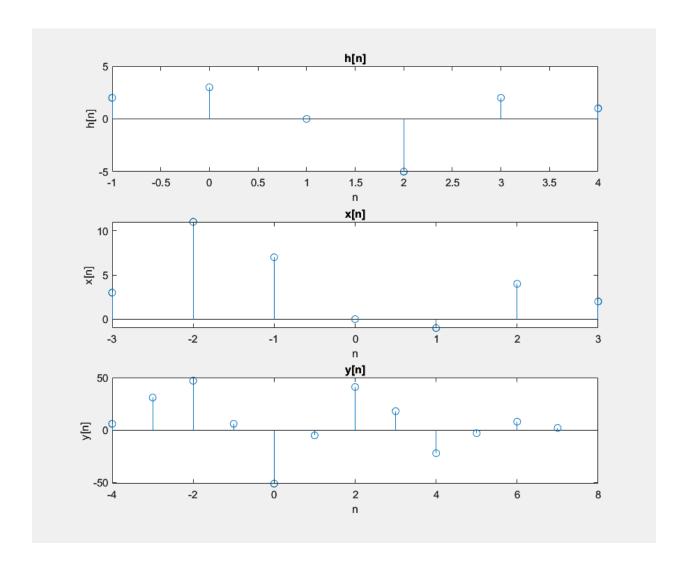
xlabel('n');

ylabel('phase[n]');



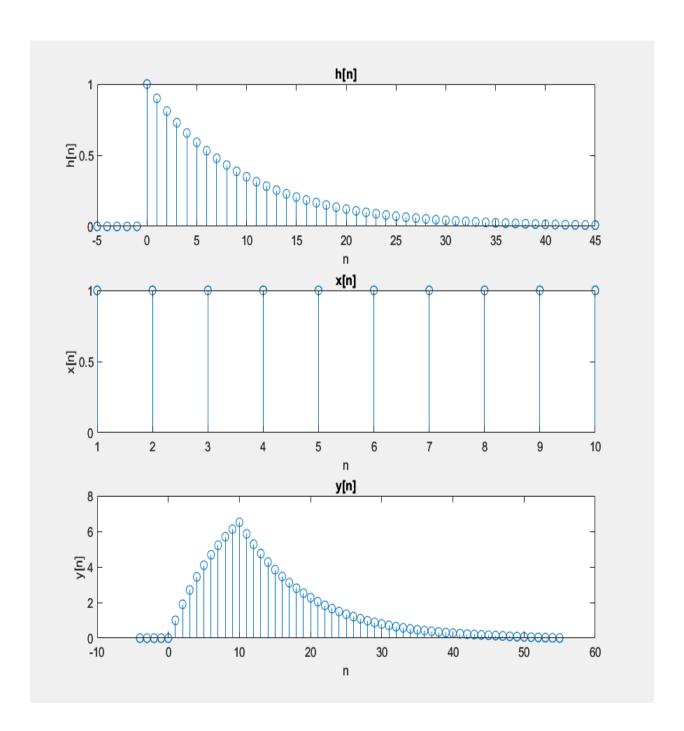
```
Q5:
m=-1:4;
n=-3:3;
c=-4:7;
x_n=[3,11,7,0,-1,4,2];
h_n=[2,3,0,-5,2,1];
y_n=conv(x_n,h_n);
subplot(3,1,1);
stem(m,h_n);
title('h[n]');
xlabel('n');
ylabel('h[n]');
subplot(3,1,2);
stem(n,x_n);
title('x[n]');
xlabel('n');
ylabel('x[n]');
subplot(3,1,3);
stem(c,y_n);
title('y[n]');
xlabel('n');
```

ylabel('y[n]');



```
Q6:
n=-5:1:45;
m=1:10;
c=-4:55
x=ones(1,10);
r=(n>=0);
h = (0.9.^{(n)}).*r;
y=conv(x,h)
subplot(3,1,1);
stem(n,h);
title('h[n]');
xlabel('n');
ylabel('h[n]');
subplot(3,1,2);
stem(m,x);
title('x[n]');
xlabel('n');
ylabel('x[n]');
subplot(3,1,3);
stem(c,y);
title('y[n]');
xlabel('n');
```

ylabel('y[n]');



```
Q7_a:

n=linspace(0,8,9);

m=0:8;

c=linspace(1,17,17);

x = [3,11,7,0,1,4,2];

B = zeros(1,9);

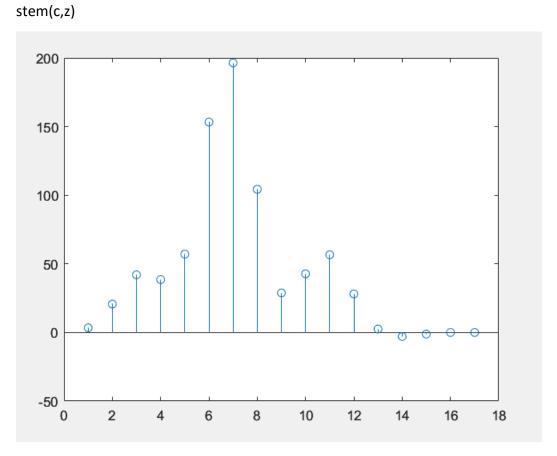
B(3:end) = x(1:7);

w=rand(size(n));

y= B + randn(size(n));

z=xcorr(x,y);

size(z)
```



```
Q7_b:

n= linspace(0,10,11);

m=0:10;

c=linspace(1,21,21);

x = [3,11,7,0,1,4,2];

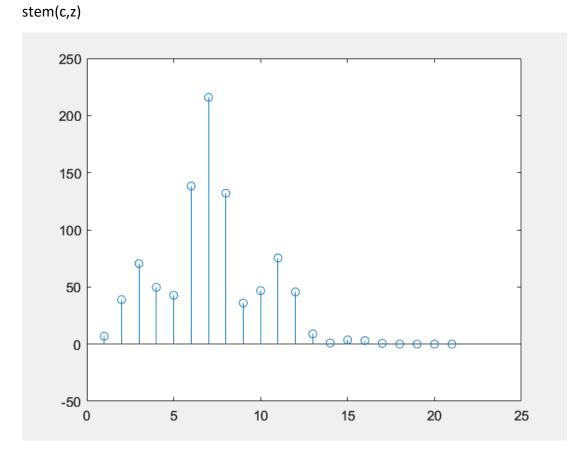
B = zeros(1,11);

B(5:end) = x(1:7);

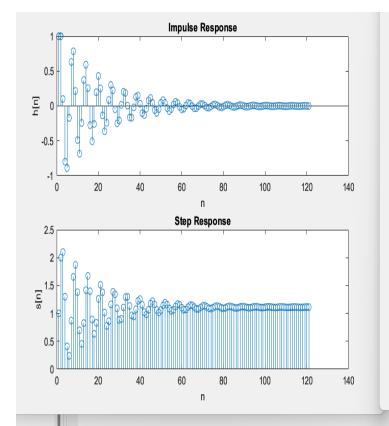
y= B + rand(size(n));

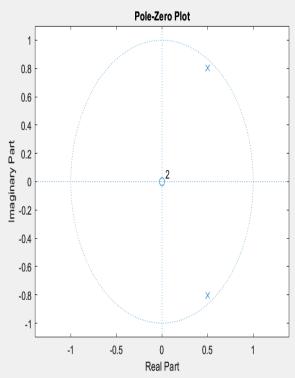
z=xcorr(x,y);

size(z)
```



```
Q8:
n=-5:1:120;
x_n = [1, zeros(1, 120)];
h=filter(1,[1,-1,0.9],x_n);
subplot(2,1,1)
stem(h);
xlabel('n');
ylabel('h[n]')
title('Impulse Response')
x_n=[1, ones(1, 120)];
s=filter(1,[1,-1,0.9],x_n);
subplot(2,1,2)
stem(s);
xlabel('n');
ylabel('s[n]')
title('Step Response')
figure;
zplane(1,[1,-1,0.9])
poles = roots([1,-1,0.9]);
if max(abs(poles)) < 1
  disp('Stable');
else
  disp('Unstable');
end
```

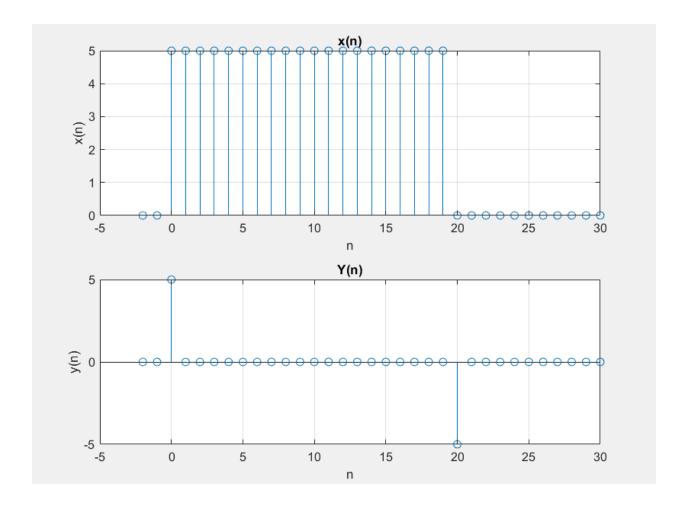




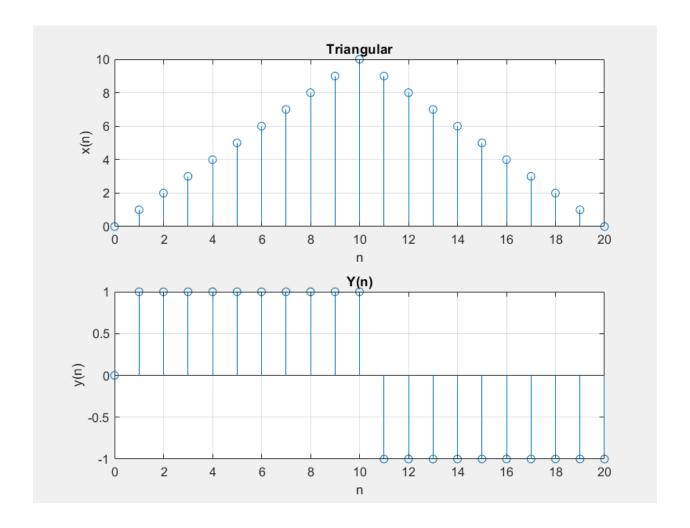
>> q8a Stable fx >>

```
Q9_a:
n=-2:1:30;
x=5*((n>=0)-(n>=20));
y=filter([1 -1],1,x);
figure;
subplot(2,1,1)
stem(n,x)
xlabel('n')
ylabel('x(n)')
grid on;
title('x(n)')
subplot(2,1,2)
stem(n,y)
xlabel('n')
ylabel('y(n)')
grid on;
```

title('Y(n)')

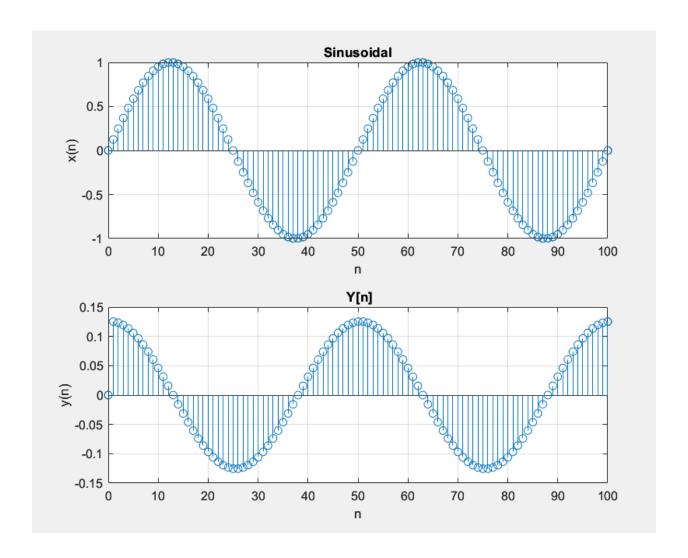


```
Q9_b:
n=0:1:20;
x=[n.*((n>=0)-(n>=10))]+[(20-n).*((n>=10)-(n>=20))]
y=filter([1 -1],1,x)
figure;
subplot(2,1,1)
stem(n,x)
xlabel('n')
ylabel('x(n)')
grid on;
title('Triangular')
subplot(2,1,2)
stem(n,y)
xlabel('n')
ylabel('y(n)')
grid on;
title('Y(n)')
```



```
Q9_c:
n=0:1:100;
x=(sin(pi*n/25)).*[(n>=0)-(n>=100)];
y=filter([1 -1],1,x)
figure;
subplot(2,1,1)
stem(n,x)
xlabel('n')
ylabel('x(n)')
grid on;
title('Sinusoidal')
subplot(2,1,2)
stem(n,y)
xlabel('n')
ylabel('y(n)')
grid on;
```

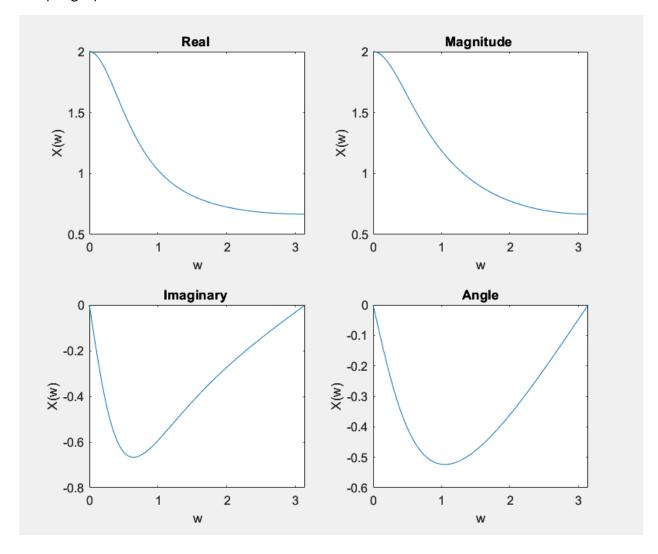
title('Y[n]')



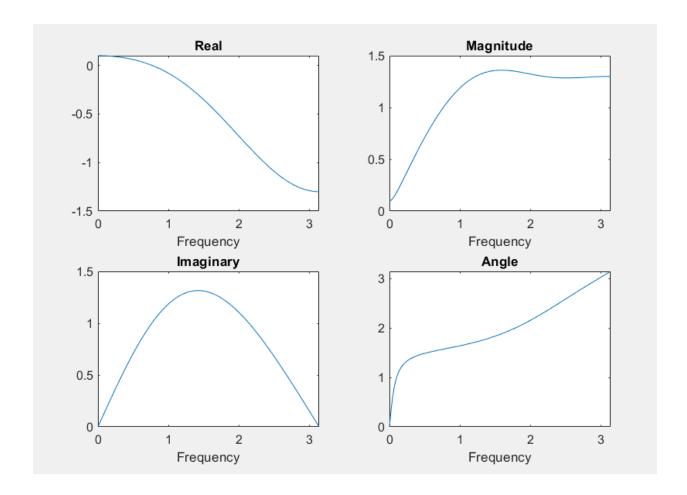
```
Q10:
k=0:500;
w = k*(pi/500);
X = \exp(j^*w) . / ((\exp(j^*w) - 0.5^*ones(1,501)));
subplot (2, 2, 1);
plot(w, real(X))
xlabel('w')
ylabel('X(w)')
title('Real')
subplot (2, 2, 3);
plot(w, imag(X))
xlabel('w')
ylabel('X(w)')
title('Imaginary')
subplot (2, 2, 2);
plot(w, abs(X))
xlabel('w')
ylabel('X(w)')
title('Magnitude ')
subplot (2, 2, 4)
plot(w, angle(X))
xlabel('w')
```

ylabel('X(w)')

title('Angle')

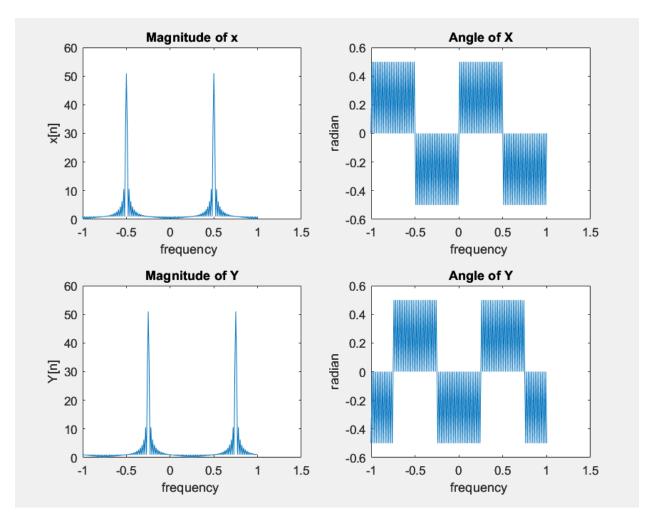


```
Q11:
n = -1:2;
x=[1,-0.5,-0.3,-0.1];
k = 0:500;
w = (pi/500)*k;
X = x*(exp(-i*pi/500)).^{(n'*k)};
subplot(2, 2, 1);
plot(w, real(X));
title('Real');
xlabel('Frequency');
subplot(2,2,3);
plot(w, imag(X));
title('Imaginary');
xlabel('Frequency');
subplot(2, 2, 2);
plot(w, abs(X));
title('Magnitude');
xlabel('Frequency');
subplot(2, 2, 4);
plot(w, angle(X));
title('Angle');
xlabel('Frequency');
```



```
Q12:
n = 0:100;
k = -100:100;
w = (pi/100)*k;
X = cos(pi*n/2) * (exp(-1j*pi/100)).^(n'*k);
Y = \exp(1j*pi*n/4).*\cos(pi*n/2)*(\exp(-1j*pi/100)).^{(n'*k)};
 subplot(2,2,1);
 plot(w/pi,abs(X));
 xlabel('frequency ');
 ylabel('x[n]')
 title('Magnitude of x')
 subplot(2,2,2);
 plot(w/pi,angle(X)/pi);
 xlabel('frequency ');
 ylabel('radian')
 title('Angle of X')
 subplot(2,2,3);
 plot(w/pi,abs(Y));
 xlabel('frequency ');
 ylabel('Y[n]')
 title('Magnitude of Y')
 subplot(2,2,4);
 plot(w/pi,angle(Y)/pi);
```

```
xlabel('frequency ');
ylabel('radian')
title('Angle of Y')
```



We notice that Y[n] is shift of x[n] by 0.25.

Done