



# Closed-loop multi-sensor SLAM using factor graphs for fixed-wing UAV.

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Master Thesis

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# Motivation

TODO - install TexMaker from app store - `sudo apt-get install texlive-full`

# Approach

# Work done so far

# Current challenges

# Future work

# Overview

## Adding a video

Example Slide

# Adding a video

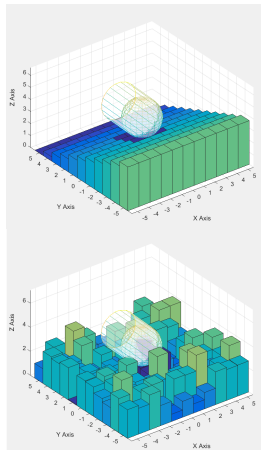


LittleDog walking over rough terrain (S. Schaal, “The latest version of the LittleDog Robot,” 2010. <https://www.youtube.com/watch?v=nUQsRPJ1dYw>)



# Adding a video - Example Slide

- Point 1
- Point 2
  - Point 1.1
  - Point 1.2



Caption