

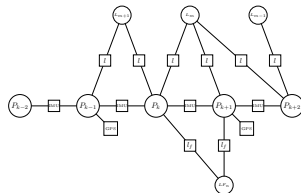
Data input

Vision

IMU

GPS

Short Term Smoother



Pose estimates

Vision

IMU

”fixed”

landmark positions

Long Term Smoother

GPS

Map

