



Closed-loop multi-sensor SLAM using factor graphs for fixed-wing UAV.

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Master Thesis

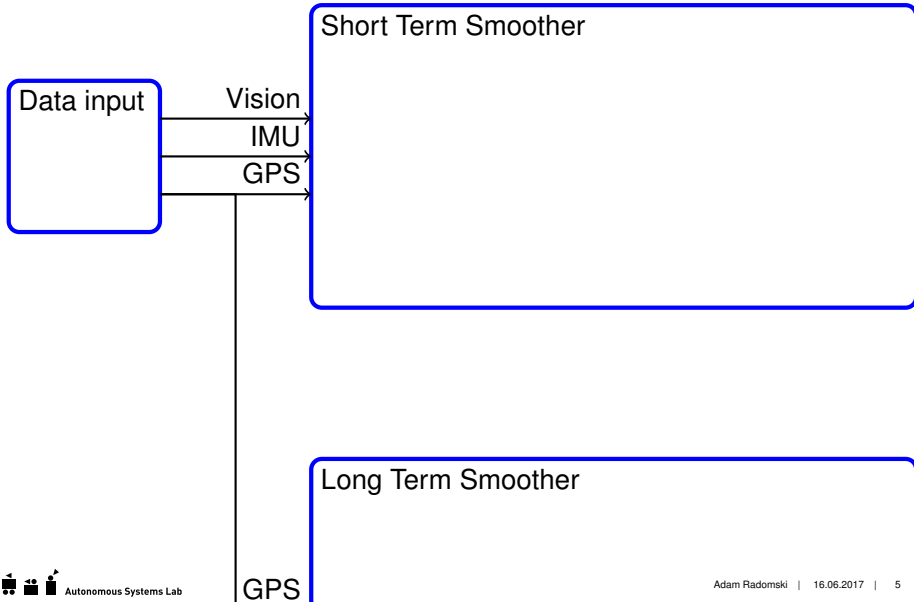
Supervised by Timo Hinzmann, Thomas Schneider

Motivation

TODO - install TexMaker from app store - `sudo apt-get install texlive-full` -
`sudo apt-get install mono-complete` - install tikzedt



Approach



Work done so far

Current challenges

Future work

Overview

Adding a video

Example Slide

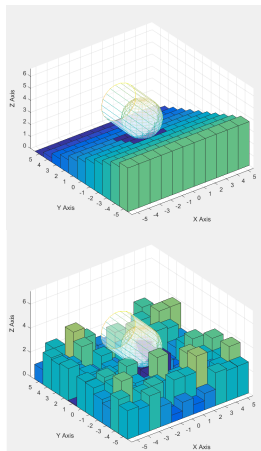
Adding a video



LittleDog walking over rough terrain (S. Schaal, “The latest version of the LittleDog Robot,” 2010. <https://www.youtube.com/watch?v=nUQsRPJ1dYw>)

Adding a video - Example Slide

- Point 1
- Point 2
 - Point 1.1
 - Point 1.2



Caption