

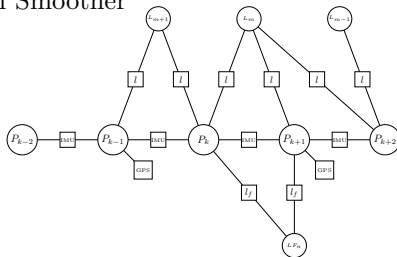
Data input

Vision

IMU

Sensors

Short Term Smoother



Pose estimates

Vision

IMU

"fixed"

landmark positions

Long Term Smoother

Sensors

