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1  -----
2  -- Company:
3  -- Engineer:
4  --
5  -- Create Date:    15:57:45 05/20/2021
6  -- Design Name:
7  -- Module Name:    SyncButton - Behavioral
8  -- Project Name:
9  -- Target Devices:
10 -- Tool versions:
11 -- Description:
12 --
13 -- Dependencies:
14 --
15 -- Revision:
16 -- Revision 0.01 - File Created
17 -- Additional Comments:
18 --
19 -----
20 library IEEE;
21 use IEEE.STD_LOGIC_1164.ALL;
22
23 -- Uncomment the following library declaration if using
24 -- arithmetic functions with Signed or Unsigned values
25 --use IEEE.NUMERIC_STD.ALL;
26
27 -- Uncomment the following library declaration if instantiating
28 -- any Xilinx primitives in this code.
29 --library UNISIM;
30 --use UNISIM.VComponents.all;
31
32 entity SyncButton is
33     Port ( reset : in  STD_LOGIC;
34           clock  : in  STD_LOGIC;
35           TrainButton : in  STD_LOGIC; -- Train Button Input --
36           CarButton  : in  STD_LOGIC; -- Car Button Input --
37           PedButton  : in  STD_LOGIC; -- Pedestrian Button Input --
38           Counter    : in  STD_LOGIC_VECTOR (4 downto 0); -- Timer --
39           MotorEnabler : out STD_LOGIC; -- Enable And Disable Stepper Motor --
40           TrainAction : out STD_LOGIC; -- Train Button Output --
41           CarWaitOutput : out STD_LOGIC; -- Car Output When Train Is And Is Not
           Passing Through --
42           PedWaitOutput : out STD_LOGIC -- Pedestrian Output When Train Is And Is
           Not Passing Through --
43           );
44 end SyncButton;
45
46 architecture Behavioral of SyncButton is
47
48     type StateType is (GateClose, GateOpenCar, GateOpenPed, TrainPassed, TrainPassing, Car
49 , PedestrianPassing);
50
51     signal State, NextState : StateType;
52
53 begin
54     SyncButtonProcess:
```

```
55     process (reset, clock)
56
57     begin
58         if (reset = '1') then -- If reset is pressed --
59             State <= Car; -- Change The State To Traffic_Green --
60
61             elsif (rising_edge(clock)) then -- If Rising Clock Edge --
62                 State <= NextState; -- Change The State To The Next State --
63
64             end if;
65
66     end process;
67
68
69 InputProcess:
70     process (State, Counter, TrainButton, PedButton, CarButton)
71
72     begin
73
74         TrainAction <= '0'; -- Set Initial TrainAction Output To Be 0 --
75         CarWaitOutput <= '0'; -- Set Initial CarWaitOutput Output To Be 0 --
76         PedWaitOutput <= '0'; -- Set Initial PedWaitOutput Output To Be 0 --
77         MotorEnabler <= '0'; -- Set Initial MotorSignalDetector Output To Be 0 --
78
79         NextState <= Car; -- Set Current State To Car --
80
81         case state is
82
83             when GateClose => -- When The State Is GateClose --
84                 TrainAction <= '1'; -- Set TrainAction Output To Be 1 --
85                 CarWaitOutput <= '0'; -- Set CarWaitOutput Output To Be 0 --
86                 PedWaitOutput <= '0'; -- Set PedWaitOutput Output To Be 0 --
87                 MotorEnabler <= '1'; -- Set MotorEnabler Output To Be 1 --
88
89                 if (Counter = "00101") then -- If Counter Reached "00101" --
90                     NextState <= TrainPassing; -- Change State To TrainPassing --
91
92                 else
93                     NextState <= GateClose; -- If None Of The Above Occur, Hold State --
94
95                 end if;
96
97             when GateOpenCar => -- When The State Is GateOpenCar --
98                 TrainAction <= '0'; -- Set TrainAction Output To Be 0 --
99                 CarWaitOutput <= '1'; -- Set CarWaitOutput Output To Be 1 --
100                 PedWaitOutput <= '0'; -- Set PedWaitOutput Output To Be 0 --
101                 MotorEnabler <= '1'; -- Set MotorEnabler Output To Be 1 --
102
103                 if (Counter = "00101") then -- If Counter Reached "00101" --
104                     NextState <= Car; -- Change State To Car --
105
106                 else
107                     NextState <= GateOpenCar; -- If None Of The Above Occur, Hold State
108
109                 end if;
110
```

```
111         when GateOpenPed => -- When The State Is GateOpenPed --
112             TrainAction <= '0'; -- Set TrainAction Output To Be 0 --
113             CarWaitOutput <= '0'; -- Set CarWaitOutput Output To Be 0 --
114             PedWaitOutput <= '1'; -- Set PedWaitOutput Output To Be 1 --
115             MotorEnabler <= '1'; -- Set MotorEnabler Output To Be 1 --
116
117             if (Counter = "00101") then -- If Counter Reached "00101" --
118                 NextState <= PedestrianPassing; -- Change State To Car --
119
120             else
121                 NextState <= GateOpenPed; -- If None Of The Above Occur, Hold State
122         --
123         end if;
124
125         when TrainPassed => -- When The State Is TrainPassed --
126             TrainAction <= '0'; -- Set TrainAction Output To Be 0 --
127             CarWaitOutput <= '0'; -- Set CarWaitOutput Output To Be 0 --
128             PedWaitOutput <= '0'; -- Set PedWaitOutput Output To Be 0 --
129             MotorEnabler <= '0'; -- Set MotorEnabler Output To Be 0 --
130
131             if (TrainButton = '1') then -- If TrainButton Is Pressed --
132                 NextState <= TrainPassing; -- Change State To TrainPassing --
133
134             elsif (CarButton = '1') then -- If CarButton Is Pressed --
135                 NextState <= GateOpenCar; -- Change State To GateOpenCar --
136
137             elsif (PedButton = '1') then -- If PedButton Is Pressed --
138                 NextState <= GateOpenPed; -- Change State To GateOpenPed --
139
140             else
141                 NextState <= TrainPassed; -- If None Of The Above Occur, Hold State
142         --
143         end if;
144
145         when TrainPassing => -- When The State Is TrainPassing --
146             TrainAction <= '1'; -- Set TrainAction Output To Be 1 --
147             CarWaitOutput <= '0'; -- Set CarWaitOutput Output To Be 0 --
148             PedWaitOutput <= '0'; -- Set PedWaitOutput Output To Be 0 --
149             MotorEnabler <= '0'; -- Set MotorEnabler Output To Be 0 --
150
151             if (Counter = "11110") then -- If Counter Reached "11110" --
152                 NextState <= TrainPassed; -- Change State To TrainPassed --
153
154             else
155                 NextState <= TrainPassing; -- If None Of The Above Occur, Hold
156         State --
157         end if;
158
159         when Car => -- When The State Is Car --
160             TrainAction <= '0'; -- Set TrainAction Output To Be 0 --
161             CarWaitOutput <= '1'; -- Set CarWaitOutput Output To Be 1 --
162             PedWaitOutput <= '0'; -- Set PedWaitOutput Output To Be 0 --
163             MotorEnabler <= '0'; -- Set MotorEnabler Output To Be 0 --
164
165             if (TrainButton = '1') then -- If TrainButton Is Pressed --
166                 NextState <= GateClose; -- Change State To GateClose --
```

```
165
166         elsif (PedButton = '1') then -- If PedButton Is Pressed
167             nextState <= PedestrianPassing; -- Change State To
PedestrianPassing --
168
169         else
170             nextState <= Car; -- If None Of The Above Occur, Hold State --
171         end if;
172
173     when PedestrianPassing => -- When The State Is PedestrianPassing --
174         TrainAction <= '0'; -- Set TrainAction Output To Be 0 --
175         CarWaitOutput <= '0'; -- Set CarWaitOutput Output To Be 0 --
176         PedWaitOutput <= '1'; -- Set PedWaitOutput Output To Be 1 --
177         MotorEnabler <= '0'; -- Set MotorEnabler Output To Be 0 --
178
179         if (Counter = "10100") then -- If Counter Reached "10100" --
180             nextState <= Car; -- Change State To Car --
181
182         elsif (TrainButton = '1') then -- If TrainButton Is Pressed --
183             nextState <= GateClose; -- Change State To GateClose --
184
185         else
186             nextState <= PedestrianPassing; -- If None Of The Above Occur, Hold
State --
187         end if;
188
189     end case;
190
191 end process;
192 end Behavioral;
```