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- How to work with image data?
- What are different ways to explore and visualise image data?
- How is image clustering performed?
- · How can we perform nuclei segmentation?
- Basic image handling: reading in image files, and how to convert them into numerical arrays.
- Measurement of pixel intensity, plotting these data as histograms, and learning how to equalise these intensity values across an image.
- OpenCV to normalise pixel intensities of an image.
- Constructing and interpreting scatter plots of pixel intensities.
- Selecting and zooming in on specific parts of an image, for analyses.
- Clustering of images to identify and isolate objects.
- Counting nuclei via image segmentation, targeting cell nuclei using StarDist.

Why is Image Analysis important?

Image Analysis extracts meaningful data and can be useful in many different applications. Such as:

- 1. Analysing fluorescent digital slides, which can help to quantify the area of staining of a particular biomarker.
- 2. Image analysis tools can help to automate repetitive processes, and provide quantitative data that is accurate and reproducible: beyond the capabilities of manual microscopy.
- 3. Image analyses performed on fluorescent micrographs can help answer questions such as:
- How much area of a tissue sample is stained for a particular biomarker?
- What is the average intensity of a biomarker staining throughout the sample?
- Do multiple biomarkers co-localize in the tissue, or within individual cells? If so, to what extent?

What is an image?

Images are essentially a matrix in which each index is assigned a number, representing the value at that specific point.

These indices, more commonly called pixels, are a measure of how many photons hit that particular position on the camera sensor. As these images are matrices, we can do many of the same mathematical

operations on images as we do on matrices. However, we don't want to manually generate every image by populating a matrix. This means that we will have to have some manner of interacting with image files on our computer, programmatically.

For all scientific images, you should save them in a file format that minimizes the data lost due to compression. In the field of image analysis, the most common file format you will run into is the Tagged Image File Format (.tiff or .tif) which is a lossless compression format.

In this tutorial, we will learn how to load, manipulate and extract quantitative data from microscopy images. The data set used in this experiment has been taken from Broad Bioimage Benchmark Collection and presents *Human HT29 colon-cancer cells*.

Images in dataset

The image set consists of 12 individual images. The samples were stained with Hoechst (channel 1), pH3 (channel 2), and phalloidin (channel 3). Hoechst labels DNA, which is present in the nucleus. Phalloidin labels actin, which is present in the cytoplasm. The last stain - pH3 - is used to indicate cells in mitosis, and is irrelevant for segmentation and counting, so this channel will be omitted. In this tutorial we will be exploring channel 1 for nuclei, and channel 3 for the cytoplasm.

Packages

There are several image processing libraries available in Python, such as *Python Imaging Library*, *Sci-kit Image*, *Scipy.ndimage* and *Open CV*. While each have their own features, they all have the same (or at least very similar) utilities. In this lesson, we will be using the *Python Imaging Library* and *Sci-kit Image*, as these have everything we require, packaged together in easy-to-use functions.

The *Python Imaging Library (PIL)* has a large number of modules and submodules. Each submodule has an array of functions associated with a certain type of operation. For example, we will be using module **Image** which provides a number of factory functions, including functions to load images from files, and to create new images.

For other basic processing and plotting in Python, the scientific packages Numpy and Matplotlib are needed.

In a blank Jupyter Notebook, open a new cell, and write your own Python code to import the following packages and modules:

- Import pyplot as plt from matplotlib
- Import numpy
- · Import glob

- From PIL, we need the Image module
- From skimage, we need the exposure module

```
1  # Loading the packages
2
3  from PIL import Image # Python Image Library (Pillow)
4  from skimage import exposure
5
6  import matplotlib.pyplot as plt
7  import numpy as np
8
9  import glob
```

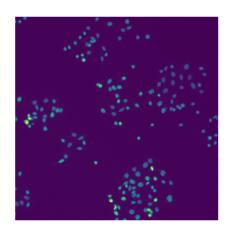
Loading images

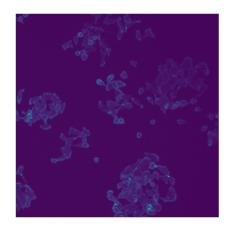
To begin, let's read in all the images from a directory, and then load an image into memory using the **open** function from the **Image** module of *Python Imaging Library*. This function opens and identifies the given image file.

```
1 ## Get image files
2
3 ch1_files = glob.glob('data/human_ht29_colon_cancer_2_images/*_channel1
      .tif') # channel 1 image - nuclei
  ch3_files = glob.glob('data/human_ht29_colon_cancer_2_images/*_channel3
      .tif') # channel 3 image - cytoplasm
5
6 ## Check they are correctly paired
7 print(ch1_files[0], ":", ch3_files[0], "\n")
8
9 ## Sort files
10
11 ch1_files.sort()
12 ch3_files.sort()
13
14 ## Check they are correctly paired
15 print("Correctly paired .... \n")
16 print(ch1_files[0], ":", ch3_files[0], "\n") # First file
  print(ch1_files[11], ":", ch3_files[11], "\n") # Last file
17
18
19 ## Load the first image
21 im1 = Image.open(ch1_files[0])
22 im3 = Image.open(ch3_files[0])
```

```
1 ## Show Data
2
3 fig, axs = plt.subplots(1,2, dpi = 300, figsize=(6, 6))
4
5 axs[0].imshow(im1);
6 axs[0].axis('off')
7
8 axs[1].imshow(im3);
9 axs[1].axis('off');
```

```
1 (-0.5, 511.5, 511.5, -0.5)
```





```
1 type(im1)
```

```
1 <class 'PIL.TiffImagePlugin.TiffImageFile'>
```

The above command shows the type of image object im1. In order to perform any analyses, we need to have the numerical information of an image, which exists as arrays. The arrays are implemented by a package called Numpy, which is foundational to the entire scientific Python ecosystem. As soon as we perform numerical computations, we use data in the form of Numpy arrays.

Below, we convert the image object into an array, as follows:

```
## Convert image to array

data1 = np.asarray(im1)

data3 = np.asarray(im3)

print('Image has', data1.shape[0], 'by', data1.shape[1], 'pixels') #
    check the shape of array

print('')

print('Total number of pixels is', data1.size) # check the size of array
```

```
1 Image has 512 by 512 pixels
2
3 Total number of pixels is 262144
```

```
1 # Check the content of the array
2
3 print(data1)
4 print('')
5 print(data1[10:20, 10:20])
6 print('')
7 print('Array type:', type(data1))
8 print('Data type: ', data1.dtype)
```

```
1 [[11 11 11 ... 9 10 10]
   [12 11 11 ... 10 9 11]
   [11 11 11 ... 10 11 10]
4
5
   [11 11 11 ... 10 10 10]
6 [12 11 11 ... 9 10 10]
7
   [11 11 11 ... 10 10 10]]
9 [[128 150 137 100 53 27 18 14 12 10]
10
  [155 177 172 136 73 38 21 15 11 11]
   [140 146 154 144 96 50 24 15 13 11]
11
   [133 144 139 122 95 55 26 15 13
12
                                     11]
13
   [114 117 122 103 78 46 22 14 11 10]
14
   [ 79 87 97 78 54 32 18 12 11 12]
   [ 48 54 53 46 27 20 14 12 10 11]
15
   [ 20 22 23 20 15 13 13 11 11 11]
16
17
   [ 17 16 15 14 13 11 11 11 10
                                     12]
18
   [ 12 14 14 13 14 12 12
                              12 11 11]]
19
20 Array type: <class 'numpy.ndarray'>
21 Data type: uint8
```

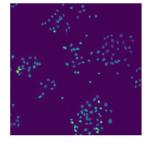
The type function has returned numpy.ndarray where nd stands for n-dimensional, as Numpy can handle data of any dimension. The above output only shows us a fraction of the image, with the . . .

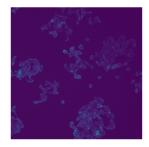
indicating non-displayed values. We can also observe dtype, which tells us the type of the pixels within the array. The variable data1 is an array, but its content can vary: we could have floating point values, integers etc. Here, uint8 tells us we have unsigned (no negative values) integers in 8 bit, i.e. up to 2^8 different possible pixel values.

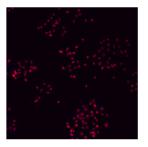
In microscopy, the fluorescent images are labelled with three colours: red, green and blue (RGB). An RGB image is simply a stack of three two-dimensional arrays. The image in the first dimension will have a red colour map, the second a green colour map, and the third a blue colour map. In this dataset, channel 1 (nuclei) is labelled red, and channel 3 (cytoplasm) is labelled blue; channel 2 is empty. We will now combine the data of these two images into a single array, and into a single image.

```
1  # Show combined data
2  fig, axs = plt.subplots(1, 3, dpi = 400)
3
4  axs[0].imshow(data1);
5  axs[0].axis('off');
6
7  axs[1].imshow(data3);
8  axs[1].axis('off');
9
10  axs[2].imshow(im); # Combined image
11  axs[2].axis('off')
```

```
1 (-0.5, 511.5, 511.5, -0.5)
```

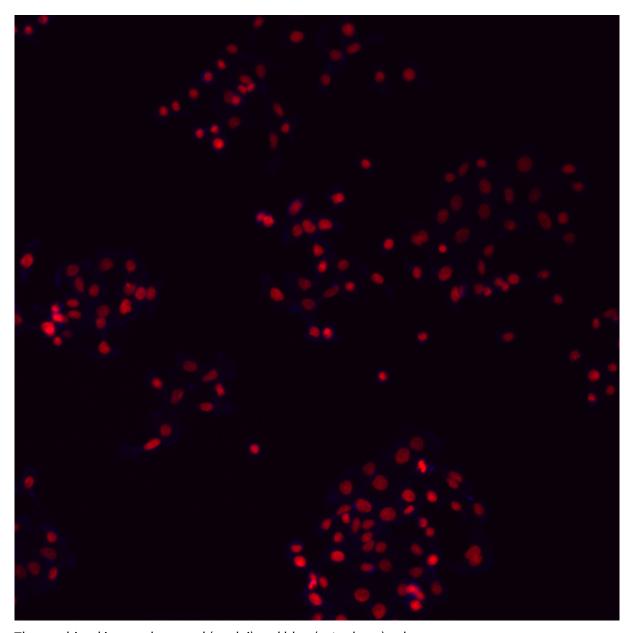






and enlarged:

```
1 im
```



The combined image shows red (nuclei) and blue (cytoplasm) colors.

Data Exploration

In image analysis, one of the most common tasks is to look at the distribution of pixel intensities, and display this as a histogram. For example: we can count how many times each pixel value (or range) appears in an image, and display this as a bar. This allows us to get a quick estimate of the intensities present in an image and to check for problems like saturation. We are going to plot the intensities of channel 1 and 3 as histograms.

We have already demonstrated that we can use Matplotlib's imshow function to display an image. Now we look at a second plotting function from that library, which generates a histogram plt.hist(). We are aiming to compute the histogram on all pixels, and for this we cannot use our 2D image as an input. The image needs to first be flattened into a single series of numbers. This can be done with the ravel() method of the array:

```
1  # Plot histogram
2  fig, axs = plt.subplots(2, sharex=True, sharey=True)
3
4  axs[0].hist(data1.ravel(), bins=100);
5  axs[0].set_title("nuclei");
6  axs[0].set_xlim(0,40)
7
8  axs[1].hist(data3.ravel(), bins=100);
9  axs[1].set_title("cytoplasm");
10  axs[1].set_xlim(0,40)
11
12  plt.show()
13
14  print(data1.max(), ":", data3.max())
```

```
1 (0.0, 40.0)
2 (0.0, 40.0)
```

```
1 255 : 122
```

The histograms show that there is a very high intensity of fluorescence for nuclei, relative to the cytoplasm, and this is the reason that red is more evident on the image, compared to blue. The intensities can be equalised by using a function *exposure.equalize_hist* from the **exposure** module in skimage library. This function returns an image which can then be used to plot a histogram.

```
# Equalize histogram
from skimage import exposure

img_eq = exposure.equalize_hist(data)

plt.figure(dpi=100)
plt.imshow(img_eq)
plt.axis('off')
plt.show()
```

```
/home/runner/.virtualenvs/carp-env/lib/python3.10/site-packages/skimage
/_shared/utils.py:326: UserWarning: This might be a color image. The
histogram will be computed on the flattened image. You can instead
apply this function to each color channel, or set channel_axis.

return func(*args, **kwargs)
(-0.5, 511.5, 511.5, -0.5)
```

Do it Yourself - Exercise 1

Plot a histogram for equalised image, and show intensities of nuclei and cytoplasm.

OpenCV

To demonstrate the vast functionality available in Python, we will take a look at **OpenCV**. OpenCV (Open Source Computer Vision Library: http://opencv.org); an open-source library that includes several hundred computer vision algorithms.

As an example, we can use functions to flexibly rescale our image data. This helps to enhance visibility of features that are limited to a narrow range of intensities. Mathematical normalisation can be performed on whole images, or with respect to a single channel. In the following example, we normalise the whole image with respect to channel 1. To do so, we calculate the mean and standard deviation of the pixel intensities of channel 1, clip the image to plus / minus the values obtained (which preserves most of the intensities) and then rescale the result to values between 0 and 255 for full image resolution.

```
import cv2
import cv2

# Calculate mean and STD of nuclei image, channel 1
mean, STD = cv2.meanStdDev(data1)

# Clip frame to lower and upper STD
data_clipped = np.clip(data, mean - STD, mean + STD).astype(np.uint8)

# Normalise to range
data_clipped_normalised = cv2.normalize(data_clipped, None, alpha=0, beta=255, norm_type=cv2.NORM_MINMAX)

# Rename the results of normalisation
result = data_clipped_normalised
```

```
fig, ax = plt.subplots(ncols=2)

ax[0].boxplot(data[:,:,0].ravel());
ax[0].set_xlabel('Original Intensities')

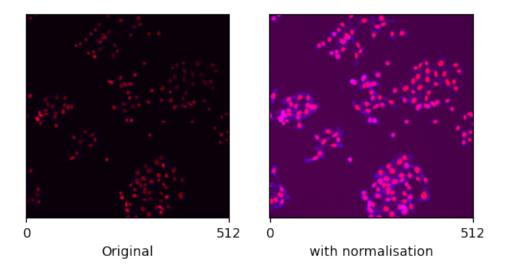
ax[1].boxplot(data_clipped[:,:,0].ravel());
ax[1].set_xlabel('Clipped Intensities');

plt.show()

#fig.savefig('clipped.png')
```

```
1 # Plot normalised image
2 fig, ax = plt.subplots(ncols=2, figsize=(6,6), dpi=200)
```

```
3
4 ax[0].imshow(im);
5 ax[0].set_xticks((0, data.shape[0]));
6 ax[0].set_yticks([]);
7 ax[0].set_xlabel('Original')
8
9 ax[1].imshow(result);
10 ax[1].set_xticks((0, data.shape[0]));
11 ax[1].set_yticks([]);
12 ax[1].set_xlabel('with normalisation');
```



Do it Yourself - Exercise 2

Normalise the combined image with respect to cytoplasm.

Tea Break

Data Visualisation

Now we can plot histograms of the normalised intensities in channel 1, channel 3, and the background.

```
1 # Plot histograms
2 fig, axs = plt.subplots(3, sharex=True, sharey=True)
3
4 axs[0].hist(result[:,:,0].ravel(), bins=30);
5 axs[0].set_title('Nuclei')
6
7 axs[1].hist(result[:,:,2].ravel(), bins=30);
```

```
8 axs[1].set_title('Cytoplasm')
9
10 axs[2].hist(result[:,:,2].ravel() - result[:,:,0].ravel(), bins=30);
11 axs[2].set_title('Cytoplasm - Nuclei')
12
13 fig.tight_layout();
14
15 plt.show()
```

The third histogram shows everything (background signal), except for nuclei and cytoplasm.

To investigate correlations between the intensities, we can look at a scatter plot (below left, once you run the cell, below). This type of plot is generally useful for exploratory data analysis.

We can see that the scatter plot is quite dense, and it is not really possible to see how many points are present, at a given location. We can display this information with the two-dimensional histogram (below centre). This clearly shows the count of points that fall into a certain square of intensities. (Note the thin, yellow area towards the right margin).

Seaborn

From a python plotting library called seaborn, we can import a function called kdeplot, which allows us to make a contour plot of the intensities. The contour plot confirms that there are at least two distinct distributions. Such a finding might inspire grouping the intensities into different categories, or clusters.

Note

This plot might take a bit longer to run, as there are a large number of data points.

```
fig, ax = plt.subplots(1, 3, figsize=(20, 6))

# Scatter plot
ax[0].scatter(result[:,:,0].flatten(), result[:,:,2].flatten());

# # 2D Histogram
ax[1].hist2d(result[:,:,0].flatten(), result[:,:,2].flatten(), bins=50, vmax=50);

# from seaborn import kdeplot

# Density Plot
kdeplot(x=result[:,:,0].flatten(), y=result[:,:,2].flatten(), ax=ax[2]);
;
```

```
14 plt.show()
```

Selecting part of an image

It is also possible to analyse a small region of an image. The image can be cropped, and then analyses can be performed on the selected region.

```
# Annotating the regions
from matplotlib.patches import Rectangle

x, y, w, h = 450, 10, 60, 50

fig, ax = plt.subplots(dpi = 100)

plt.imshow(result)

ax.add_patch(Rectangle((x,y), w, h, edgecolor="w", fill=False));

plt.show()
```

```
1 # plot what's in box
2 fig, ax = plt.subplots(dpi=100)
3 plt.imshow(result[y:y+h, x:x+w,]);
4 plt.axis('off')
5 plt.show()
```

```
1 (-0.5, 59.5, 49.5, -0.5)
```

```
1 result[y:y+h, x:x+w, 0].shape
2 result[:,:,0].shape
```

```
1 (50, 60)
2 (512, 512)
```

The region in the rectangle does not have any cells. Plotting a histogram for this region versus full image will result in the following plot.

```
1 # Plot histogram
2 fig, axs = plt.subplots(2, sharex=True)
3
4 axs[0].hist(result[:,:,0].ravel(), bins=30, label='intensity in all image');
5 axs0_2 = axs[0].twinx()
6 axs0_2.hist(result[y:y+h,x:x+w,0].ravel(), bins=3, color='r', alpha = 0.3);
7 axs[0].set_title('Nuclei')
8 axs[0].legend()
```

This plot compares the intensity of the pixels in the total image (blue) to those in the region of interest (ROI) bounded by the rectangle. If we move the ROI over cells, we can see how this intensity changes.

Do it Yourself - Exercise 3

Move the rectangle towards left so that it contains a few cells. Now plot the histogram again and see the differences.

Do it Yourself - Exercise 4

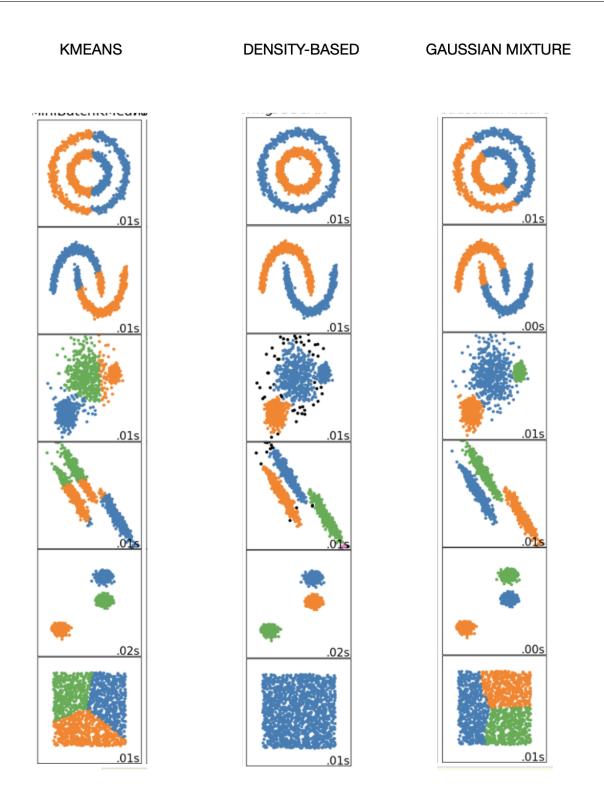
Repeat this process for other images (in the folder) and save 3-4 examples of cells with nuclei and cytoplasm marked

Lunch Break

Image clustering

Clustering Methods

Method name	Parameters	Scalability	Usecase	Geometry (metric used)
K-Means	number of clusters	Very large n samples, medium n_clusters with MiniBatch code	General-purpose, even cluster size, flat geometry, not too many clusters	Distances between points
Affinity propagation	damping, sample preference	Not scalable with n_samples	Many clusters, uneven cluster size, non-flat geometry	Graph distance (e.g. nearest-neighbor graph)
Mean-shift	bandwidth	Not scalable with n_samples	Many clusters, uneven cluster size, non-flat geometry	Distances between points
Spectral clustering	number of clusters	Medium n samples, small n_clusters	Few clusters, even cluster size, non-flat geometry	Graph distance (e.g. nearest-neighbor graph
Ward hierarchical clustering	number of clusters	Large n samples and n_clusters	Many clusters, possibly connectivity constraints	Distances between points
Agglomerative clustering	number of clusters, linkage type, distance	Large n samples and n_clusters	Many clusters, possibly connectivity constraints, non Euclidean distances	Any pairwise distance
DBSCAN	neighborhood size	Very large n samples, medium n_clusters	Non-flat geometry, uneven cluster sizes	Distances between nearest points
Gaussian mixtures	many	Not scalable	Flat geometry, good for density estimation	Mahalanobis distances to centers
Birch	branching factor, threshold, optional global clusterer.	Large n clusters and n_samples	Large dataset, outlier removal, data reduction.	Euclidean distance between points



^{1 #} Preparing the data for clustering

```
img1 = result[:,:,0].reshape(-1, 1)
img2 = result[:,:,2].reshape(-1, 1)

all_imgs = np.concatenate([img1, img2], axis=1)

all_imgs.shape
```

```
1 (262144, 2)
```

```
1 0
```

```
fig, ax = plt.subplots(figsize=(6, 6))
ax.scatter(img1[img1 > 0], img2[img2 > 0], c=all_img_labels, s=50)
ax.set_xlabel('Image 1', fontsize=16)
ax.set_ylabel('Image 2', fontsize=16);
plt.show()
```

```
from numpy import zeros

mask = (data1>0) & (data3>0)

all_img_labels_mapped = zeros(data1.shape)

all_img_labels_mapped[mask] = all_img_labels
```

```
fig, ax = plt.subplots(figsize=(6, 6))
ax.imshow(all_img_labels_mapped);
plt.show()
```

The result depends critically on the specified number of clusters.

Do it Yourself - Exercise 5

Change n_components to 2, 4, 5 and 6 and compare the results.

Do it Yourself - Exercise 6

Apply the Kmeans algorithm to the images and compare the result of the clustering for different choices of n_components.

Documentation# To import:

```
1 from sklearn.cluster import KMeans
```

Tea Break

Segmentation

Image segmentation allows us to locate objects and boundaries (lines, curves, *etc.*) within an image. Conventional methods make use of a threshold value to distinguish between different regions and/or cells. In this lesson, we will use a Python package called **StarDist**, which makes use of deep learning methods to perform nuclei segmentation. It is designed particularly for nuclei segmentation. **StarDist** comes with pretrained models, that are likely suitable for your micrograph images. However, it is also possible to train your model specifically for your dataset.

```
## Load as images - Using Raw images

data1 = Image.open(ch1_files[0])

nuclei = np.zeros(np.shape(im))
nuclei[:, :, 0] = data1

plt.figure(dpi=100)
plt.imshow(nuclei.astype(int))
plt.axis('off')

plt.show()
```

```
1 (-0.5, 511.5, 511.5, -0.5)
```

```
from stardist.models import StarDist2D
from stardist import random_label_cmap

from csbdeep.utils import Path, normalize

axis_norm = (0,1)  # normalize channels independently
img = normalize(nuclei[:,:,0], 1,99.8, axis=axis_norm)

model = StarDist2D.from_pretrained('2D_versatile_fluo')
lbl_cmap = random_label_cmap()
```

By running this Python code, you will see this message. This suggests that everything is working fine. The package **StarDist** requires the installation of a deep learning package **tensorflow**.

Output

```
1 Found model '2D_versatile_fluo' for 'StarDist2D'.
2 Loading network weights from 'weights_best.h5'.
3 Loading thresholds from 'thresholds.json'.
4 Using default values: prob_thresh=0.479071, nms_thresh=0.3.
```

In order to access pretrained models, the function *StarDist2D.from_pretrained()* provides a list from which a suitable model can be selected. There are two main types of models: one for fluorescent images, and the other for brightfield images. For our image, **StarDist** will perform nuclei prediction using *2D_versatile_fluo*.

The availability of pretrained models can be checked as follows:

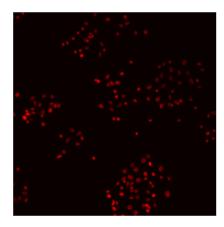
```
1 StarDist2D.from_pretrained()
```

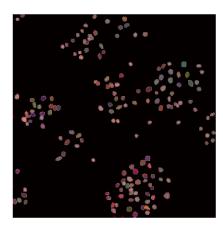
Output

```
1 # Using pre-trained network to predict nuclei
2 labels, details = model.predict_instances(img)
```

```
1 ## Show data
2
3 fig, axs = plt.subplots(1,2, dpi=200)
4 axs[0].imshow(nuclei.astype(int))
5 axs[0].axis('off')
```

```
6
7 axs[1].imshow(nuclei.astype(int))
8 axs[1].imshow(labels, cmap=lbl_cmap,alpha=0.5)
9 axs[1].axis('off')
```





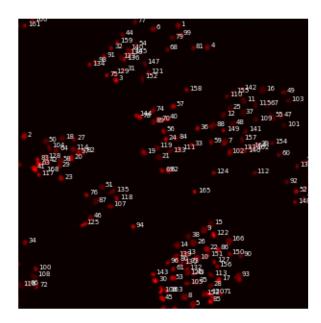
The image on the right is a segmented image, with correctly identified and predicted nuclei. This image is also referred to as a masked image. The next step will allow us to count the number of nuclei in this image, which is performed as follows:

```
# Enumerate nuclei
plt.figure(dpi=100)
plt.imshow(nuclei.astype(int))

for i, xy in enumerate(details['points']):
    plt.annotate(str(i+1), [xy[1]+5,xy[0]], color='w', size=5)
plt.axis('off')

print("The total number of nuclei in the image are: ", len(details['points']))
```

```
1 The total number of nuclei in the image are: 168
```



Do it Yourself - Exercise 7

Repeat segmentation for other images.

Do it Yourself - Exercise 8

Repeat segmentation for all 12 images and plot number of nuclei per image.

Do it Yourself - Exercise 9

Repeat segmentation for cytoplasm channel, what do you notice? Explain your observation for any pecularities.

If you have done the above exercise of using **stardist** to perform segmentation for the cytoplasm channel, then you may have noticed some peculiarities. These can be justified by StarDist being designed for accurate segmentation of nuclei. However, if you are interested in cytoplasm segmentation, then using **cellpose** is better suited for this application. This Python package is more specialised, and better applied to cell and nucleus segmentation. After completing this workshop, you will observe that **stardist** and **cellpose** both work in a similar fashion. For more information and documentation, please follow this link.

Summary and Conclusions

In undertaking this workshop, we have learned to import, explore and analyse fluorescence microscopy images, and how to perform some basic image analyses using several packages, in Python. We have also learned how to perform clustering analyses, through implementing unsupervised machine learning algorithms (GMM). Further to this, we provided an introduction into the use of deep learning algorithms for use in nuclei segmentation, which can provide a fast, accurate and powerful count of the nuclei present in an image; this can be invaluable for analysing large amounts of data. Following the guided links, you can start to explore more advanced image analysis techniques, and *Learn To Discover* how these can help you further your own work, and research.

Keypoints

- The key image processing libraries in Python include Python Imaging Library, Sci-kit Image, Scipy.ndimage and OpenCV.
- Numpy package converts an image object into a numerical array.
- ravel() method of the array flattens an image into a single series of numbers.
- The image intensities can be equalised by a function exposure.equalize_hist from the exposure module in skimage library.
- Clustering of unlabeled data can be performed by several different ways using module sklearn .cluster.
- Image segmentation allows us to locate objects and boundaries (lines, curves, etc.) within an image.
- StarDist package uses deep learning for nuclei segmentation.