

# Advanced brain imaging methods: Tutorial 0

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## 1 Linear algebra: warm up

### 1.1 Adding noise to an image

Say that for some reason you want to add normally distributed noise to an image. Given an image defined by the matrix A and the matrix B containing normally distributed noise, what would be the matrix C of the image to which this noise has been added ?

$$A = \begin{pmatrix} 136 & 37 & 45 & 158 \\ 28 & 69 & 78 & 55 \\ 227 & 75 & 196 & 170 \\ 212 & 34 & 23 & 125 \end{pmatrix}; B = \begin{pmatrix} -1 & 6 & 2 & 12 \\ -14 & -6 & -4 & -1 \\ -3 & 1 & 3 & -15 \\ -13 & -4 & 5 & -6 \end{pmatrix}$$

### 1.2 Rigid body transformation: translations

The transformation matrix of an image is the matrix that allows you to say what are the coordinates [x,y,z] in world space of the voxel with indices [i,j,k] in voxel space.

What is the matrix B that will translate an image by 15 mm along the x dimension, -58 mm along the y dim and 65 mm along the z dimension?

Given the transformation matrix A below, what would be the values of the new transformation matrix once the translation performed by has been applied?

$$A = \begin{pmatrix} 5 & 0 & 0 & 125 \\ 0 & 2 & 0 & 118 \\ 0 & 0 & 1 & 10 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Given this new transformation matrix, what would be the real world coordinates of the voxel with indices [10,25,45] and for any voxel with indices [i,j,k]?

### 1.3 Rigid body transformation: rotations

What is the matrix C that will rotate an image by 90 degrees around the x axis (pitch)?

Given the transformation matrix A above, what would be the values of the new transformation matrix after this rotation has been applied?

$$A = \begin{pmatrix} 5 & 0 & 0 & 125 \\ 0 & 2 & 0 & 118 \\ 0 & 0 & 1 & 10 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

## 1.4 Rigid body transformation: order of transformation

For the point with coordinates [14,58,23], what would be its coordinates if:

1. you applied the translation defined by B then the rotation defined by C,
2. you applied the rotation defined by C and then the translation defined by B?

## 2 General linear model

In class we have seen how to find the equation that defines the ordinary least-square estimate of the  $\beta$  value of the following model:

$$y = \beta x + \varepsilon$$

For each value of  $x_i$ , the residual error ( $\varepsilon_i$ ) is given by the difference between the predicted value of the model ( $\hat{y}_i = \beta x_i$ ) and the actual empirical value ( $y_i$ ). We want to minimize the sum of the squared residual:

$$\sum_{i=1}^N \varepsilon_i^2 = \sum_{i=1}^N (y_i - \hat{y}_i)^2 = \sum_{i=1}^N (y_i - \beta x_i)^2 = \sum_{i=1}^N (y_i^2 - 2\beta x_i y_i + \beta^2 x_i^2)$$

At the value of  $\beta$  that minimize this function, we know that its derivative with respect to  $\beta$  will be equal to 0. So to find  $\beta$ , we derived this function with respect to  $\beta$ , and rearranged this derivative to have the value of  $\beta$  expressed in terms of  $x$  and  $y$ .

Let's now try to do the same with this model:

$$y = \beta_1 x + \beta_0 + \varepsilon$$

Do this by the following steps:

1. Write down the sum of the squared residual of this model.
2. Derive this function with respect to  $\beta_1$  and rearranged this derivative to have the value of  $\beta_1$  expressed in terms of  $x$ ,  $y$  and  $\beta_0$ .
3. Do the same with respect to  $\beta_0$ .
4. Substitute  $\beta_0$  in the function found in step 2 by the solution of step 3.

### 3 Design matrices

The General Linear Model described by  $Y = X\beta + \varepsilon$ . Define the design matrices ( $X$ ) of the following:

1. a two-sample t-test with 2 subjects in group A and 3 subjects in B,
2. a paired t-test with 5 subjects with two conditions a and b,
3. an ANOVA with three groups of subjects and 3 subjects in each group,
4. a repeated-measures ANOVA for 3 subjects and with three within-subject levels (a, b, c).

Here are some advices:

- Do not panic!
- For 1:
  1. write for each subject the equation that describes that subject's  $y$  in terms of:
    - the average of the group A ( $\mu_A$ ) times a certain weighting factor,
    - the average of the group B ( $\mu_B$ ) times a certain weighting factor,
    - an error term  $\varepsilon$  specific to that subject.
  2. go from the equation form to the matrix form, by putting together a) the  $y$  of all subjects, b) the weighting factors, c) the 2 averages and d) the error terms.
  3. the design matrix is the one that contains the weighting factors.
- For 2, the process will be the same as for 1 but you will have to describe each subject's  $y$  in each condition in terms of:
  - the average of the condition a ( $\mu_a$ ) times a certain weighting factor,
  - the average of the condition b ( $\mu_b$ ) times a certain weighting factor,
  - as many subject specific variable ( $\tau$ ) as there are subjects each time multiplied by a certain weighting factor,
  - an error term specific to that subject and that condition.
- For 3 and 4, you can generalize by remembering that a two sample t-test is in fact an ANOVA with only two groups and that a paired t-test is in fact a repeated-measures ANOVA with only two levels.