CS162
Operating Systems and Systems Programming
Lecture 9

Synchronization, Readers/Writers example, Scheduling

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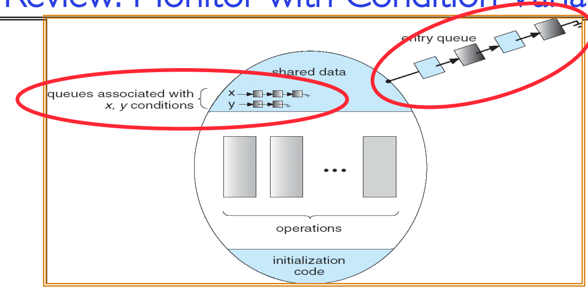
Review: Monitor with Condition Variables



- Lock: the lock provides mutual exclusion to shared data
  - Always acquire before accessing shared data structure
  - Always release after finishing with shared data
  - Lock initially free
- Condition Variable: a queue of threads waiting for something *inside* a critical section
  - Key idea: make it possible to go to sleep inside critical section by atomically releasing lock at time we go to sleep
  - Contrast to semaphores: Can't wait inside critical section

Review: Condition Variables

- How do we change the RemoveFromQueue() routine to wait until something is on the queue?
  - Could do this by keeping a count of the number of things on the queue (with semaphores), but error prone
- Condition Variable: a queue of threads waiting for something *inside* a critical section
  - Key idea: allow sleeping inside critical section by atomically releasing lock at time we go to sleep
  - Contrast to semaphores: Can't wait inside critical section
- Operations:
  - `Wait(&lock)`: Atomically release lock and go to sleep. Re-acquire lock later, before returning.
  - `Signal()`: Wake up one waiter, if any
  - `Broadcast()`: Wake up all waiters
- Rule: Must hold lock when doing condition variable ops!
  - In Birrell paper, he says can perform signal() outside of lock – IGNORE HIM (this is only an optimization)

Review: Mesa vs. Hoare Monitors

- Need to be careful about precise definition of signal and wait. Consider a piece of our dequeue code:

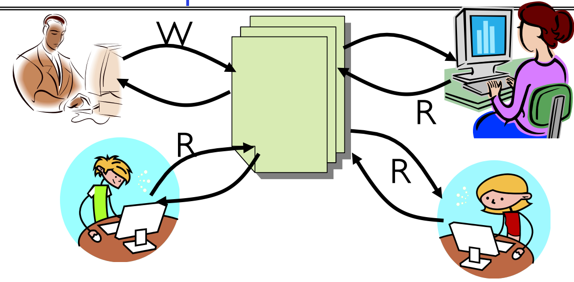
```
while (queue.isEmpty()) {
   dataready.wait(&lock); // If nothing, sleep
}
item = queue.dequeue();// Get next item
```

  - Why didn't we do this?

```
if (queue.isEmpty()) {
   dataready.wait(&lock); // If nothing, sleep
}
item = queue.dequeue();// Get next item
```

- Answer: depends on the type of scheduling
  - Hoare-style (most textbooks):
    - » Signaler gives lock, CPU to waiter; waiter runs immediately
    - » Waiter gives up lock, processor back to signaler when it exits critical section or if it waits again
  - Mesa-style (most real operating systems):
    - » Signaler keeps lock and processor
    - » Waiter placed on ready queue with no special priority
    - » Practically, need to check condition again after wait

Extended Example: Readers/Writers Problem



- Motivation: Consider a shared database
  - Two classes of users:
    - » Readers – never modify database
    - » Writers – read and modify database
  - Is using a single lock on the whole database sufficient?
    - » Like to have many readers at the same time
    - » Only one writer at a time

Basic Readers/Writers Solution

- Correctness Constraints:
  - Readers can access database when no writers
  - Writers can access database when no readers or writers
  - Only one thread manipulates state variables at a time
- Basic structure of a solution:
  - **Reader()**

```
Wait until no writers
Access data base
Check out – wake up a waiting writer
```

  - **Writer()**

```
Wait until no active readers or writers
Access database
Check out – wake up waiting readers or writer
```

  - State variables (Protected by a lock called "lock"):
    - » int AR: Number of active readers; initially = 0
    - » int WR: Number of waiting readers; initially = 0
    - » int AW: Number of active writers; initially = 0
    - » int WW: Number of waiting writers; initially = 0
    - » Condition okToRead = NIL
    - » Conditioin okToWrite = NIL

Code for a Reader

```
Reader() {
  // First check self into system
  lock.Acquire();
  while ((AW + WW) > 0) { // Is it safe to read?
    WR++;                 // No. Writers exist
    okToRead.wait(&lock); // Sleep on cond var
    WR--;                 // No longer waiting
  }
  AR++;                   // Now we are active!
  lock.release();
  // Perform actual read-only access
  AccessDatabase(ReadOnly);
  // Now, check out of system
  lock.Acquire();
  AR--;                   // No longer active
  if (AR == 0 && WW > 0)  // No other active readers
    okToWrite.signal();   // Wake up one writer
  lock.Release();
}
```


Code for a Writer

```
Writer() {
  // First check self into system
  lock.Acquire();
  while ((AW + AR) > 0) { // Is it safe to write?
    WW++;                 // No. Active users exist
    okToWrite.wait(&lock);  // Sleep on cond var
    WW--;                 // No longer waiting
  }
  AW++;                   // Now we are active!
  lock.release();
  // Perform actual read/write access
  AccessDatabase(ReadWrite);
  // Now, check out of system
  lock.Acquire();
  AW--;                   // No longer active
  if (WW > 0){            // Give priority to writers
    okToWrite.signal();   // Wake up one writer
  } else if (WR > 0) {    // Otherwise, wake reader
    okToRead.broadcast(); // Wake all readers
  }
  lock.Release();
}
```

Simulation of Readers/Writers solution

- Consider the following sequence of operators:
  - R1, R2, W1, R3
- On entry, each reader checks the following:

```
while ((AW + WW) > 0) { // Is it safe to read?
  WR++;                 // No. Writers exist
  okToRead.wait(&lock); // Sleep on cond var
  WR--;                 // No longer waiting
}
AR++;                   // Now we are active!
```

- First, R1 comes along:
  AR = 1, WR = 0, AW = 0, WW = 0
- Next, R2 comes along:
  AR = 2, WR = 0, AW = 0, WW = 0
- Now, readers make take a while to access database
  - Situation: Locks released
  - Only AR is non-zero

Simulation(2)

- Next, W1 comes along:

```
while ((AW + AR) > 0) { // Is it safe to write?
  WW++;                 // No. Active users exist
  okToWrite.wait(&lock); // Sleep on cond var
  WW--;                 // No longer waiting
}
AW++;
```

- Can't start because of readers, so go to sleep:
  AR = 2, WR = 0, AW = 0, WW = 1
- Finally, R3 comes along:
  AR = 2, WR = 1, AW = 0, WW = 1
- Now, say that R2 finishes before R1:
  AR = 1, WR = 1, AW = 0, WW = 1
- Finally, last of first two readers (R1) finishes and wakes up writer:

```
if (AR == 0 && WW > 0)  // No other active readers
  okToWrite.signal();   // Wake up one writer
```


Simulation(3)

- When writer wakes up, get:
  AR = 0, WR = 1, AW = 1, WW = 0
- Then, when writer finishes:

```
if (WW > 0){              // Give priority to writers
  okToWrite.signal();     // Wake up one writer
} else if (WR > 0) {      // Otherwise, wake reader
  okToRead.broadcast();   // Wake all readers
}
```

  - Writer wakes up reader, so get:
    AR = 1, WR = 0, AW = 0, WW = 0
- When reader completes, we are finished

Questions

- Can readers starve? Consider Reader() entry code:

```
while ((AW + WW) > 0) { // Is it safe to read?
  WR++;                 // No. Writers exist
  okToRead.wait(&lock); // Sleep on cond var
  WR--;                 // No longer waiting
}
AR++;                   // Now we are active!
```

- What if we erase the condition check in Reader exit?

```
AR--;                   // No longer active
if (AR == 0 && WW > 0)  // No other active readers
  okToWrite.signal();   // Wake up one writer
```

- Further, what if we turn the signal() into broadcast()

```
AR--;                   // No longer active
okToWrite.broadcast();  // Wake up one writer
```

- Finally, what if we use only one condition variable (call it "**okToContinue**") instead of two separate ones?
  - Both readers and writers sleep on this variable
  - Must use broadcast() instead of signal()

Administrivia

- Midterm coming up soon
  – Wednesday 3/9 6-7:30PM
  – 10 EVANS (Seats: 237); 155 DWINELLE (Seats: 481)
    » We will assign you to a room
  – Closed book, no calculators, one double-side page of handwritten notes

- No class that day, extra office hours

- Topics will include the material through lecture 12 (Wed 3/2)
  – Includes lectures, project 1, homeworks, readings, textbook

BREAK

Can we Construct Monitors from Semaphores?

- Locking aspect is easy: Just use a mutex
- Can we implement condition variables this way?

```
Wait()   { semaphore.P(); }
Signal() { semaphore.V(); }
```

- Does this work better?

```
Wait(Lock lock) {
   lock.Release();
   semaphore.P();
   lock.Acquire();
}
Signal() { semaphore.V(); }
```


Construction of Monitors from Semaphores (con't)

- Problem with previous try:
  – P and V are commutative – result is the same no matter what order they occur
  – Condition variables are NOT commutative
- Does this fix the problem?

```
Wait(Lock lock) {
   lock.Release();
   semaphore.P();
   lock.Acquire();
}
Signal() {
   if semaphore queue is not empty
      semaphore.V();
}
```

  – Not legal to look at contents of semaphore queue
  – There is a race condition – signaler can slip in after lock release and before waiter executes semaphore.P()
- It is actually possible to do this correctly
  – Complex solution for Hoare scheduling in book
  – Can you come up with simpler Mesa-scheduled solution?

Monitor Conclusion

- Monitors represent the logic of the program
  - Wait if necessary
  - Signal when change something so any waiting threads can proceed
- Basic structure of monitor-based program:

```
lock
while (need to wait) {
   condvar.wait();
}
unlock
```

Check and/or update state variables
Wait if necessary

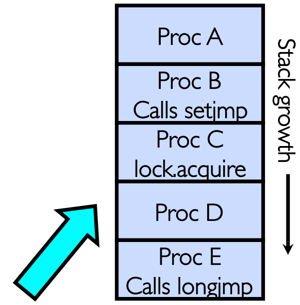
```
do something so no need to wait

lock

condvar.signal();

unlock
```

Check and/or update state variables

C-Language Support for Synchronization

- C language: Pretty straightforward synchronization
  - Just make sure you know *all* the code paths out of a critical section

```
int Rtn() {
   lock.acquire();
   …
   if (exception) {
      lock.release();
      return errReturnCode;
   }
   …
   lock.release();
   return OK;
}
```



  - Watch out for **setjmp/longjmp**!
    - » Can cause a non-local jump out of procedure
    - » In example, procedure E calls longjmp, poping stack back to procedure B
    - » If Procedure C had lock.acquire, problem!

C++ Language Support for Synchronization

- Languages with exceptions like C++
  - Languages that support exceptions are problematic (easy to make a non-local exit without releasing lock)
  - Consider:

```
void Rtn() {
   lock.acquire();
   …
   DoFoo();
   …
   lock.release();
}
void DoFoo() {
   …
   if (exception) throw errException;
   …
}
```

  - Notice that an exception in DoFoo() will exit without releasing the lock!

C++ Language Support for Synchronization (con't)

- Must catch all exceptions in critical sections
  - Catch exceptions, release lock, and re-throw exception:

```
void Rtn() {
   lock.acquire();
   try {
      …
      DoFoo();
      …
   } catch (…) {      // catch exception
      lock.release(); // release lock
      throw;          // re-throw the exception
   }
   lock.release();
}
void DoFoo() {
   …
   if (exception) throw errException;
   …
}
```

  - Even Better: auto_ptr<T> facility. See C++ Spec.
    - » Can deallocate/free lock regardless of exit method

Java Language Support for Synchronization

- Java has explicit support for threads and thread synchronization
- Bank Account example:

```
class Account {
   private int balance;
   // object constructor
   public Account (int initialBalance) {
      balance = initialBalance;
   }
   public synchronized int getBalance() {
      return balance;
   }
   public synchronized void deposit(int amount) {
      balance += amount;
   }
}
```

- Every object has an associated lock which gets automatically acquired and released on entry and exit from a *synchronized* method

Java Language Support for Synchronization (con't)

- Java also has *synchronized* statements:

```
synchronized (object) {
   …
}
```

- Since every Java object has an associated lock, this type of statement acquires and releases the object's lock on entry and exit of the body
  - Works properly even with exceptions:

```
synchronized (object) {
   …
   DoFoo();
   …
}
void DoFoo() {
   throw errException;
}
```


Java Language Support for Synchronization (con't 2)

- In addition to a lock, every object has a single condition variable associated with it
  - How to wait inside a synchronization method of block:
    - » `void wait(long timeout); // Wait for timeout`
    - » `void wait(long timeout, int nanoseconds); //variant`
    - » `void wait();`
  - How to signal in a synchronized method or block:
    - » `void notify();    // wakes up oldest waiter`
    - » `void notifyAll(); // like broadcast, wakes everyone`
  - Condition variables can wait for a bounded length of time. This is useful for handling exception cases:

```
t1 = time.now();
while (!ATMRequest()) {
   wait (CHECKPERIOD);
   t2 = time.new();
   if (t2 – t1 > LONG_TIME) checkMachine();
}
```

  - Not all Java VMs equivalent!
    - » Different scheduling policies, not necessarily preemptive!

Recall: Better Implementation of Locks by Disabling Interrupts

- Key idea: maintain a lock variable and impose mutual exclusion only during operations on that variable

`int mylock = FREE;`
`Acquire(&mylock)` – Wait until lock is free, then grab
`Release(&mylock)` – Unlock, waking up anyone waiting

```
Acquire(int *lock) {
   disable interrupts;
   if (*lock == BUSY) {
      put thread on wait queue;
      Go to sleep();
      // Enable interrupts?
   } else {
      *lock = BUSY;
   }
   enable interrupts;
}
```

```
Release(int *lock) {
   disable interrupts;
   if (anyone on wait queue) {
      take thread off wait queue
      Place on ready queue;
   } else {
      *lock = FREE;
   }
   enable interrupts;
}
```

- Really only works in kernel – why?

In-Kernel Lock: Simulation

Value: 0 | waiters | owner

READY

Running

Thread A

Thread B

```
lock.Acquire();
…
critical section;
…
lock.Release();
```

```
INIT
  int value = 0;

Acquire() {
  disable interrupts;
  if (value == 1) {
    put thread on wait-queue;
    go to sleep() //??
  } else {
    value = 1;
  }
  enable interrupts;
}

Release() {
 disable interrupts;
  if anyone on wait queue {
    take thread off wait-queue
    Place on ready queue;
  } else {
    value = 0;
  }
  enable interrupts;
}
```

```
lock.Acquire();
…
critical section;
…
lock.Release();
```


In-Kernel Lock: Simulation

Value: 1 | waiters | owner

READY

Running

Thread A

Thread B

```
lock.Acquire();
…
critical section;
…
lock.Release();
```

```
INIT
  int value = 0;

Acquire() {
  disable interrupts;
  if (value == 1) {
    put thread on wait-queue;
    go to sleep() //??
  } else {
    value = 1;
  }
  enable interrupts;
}

Release() {
 disable interrupts;
  if anyone on wait queue {
    take thread off wait-queue
    Place on ready queue;
  } else {
    value = 0;
  }
  enable interrupts;
}
```

```
lock.Acquire();
…
critical section;
…
lock.Release();
```


In-Kernel Lock: Simulation

Value: 1 | waiters | owner

READY

Running

Running

Thread A

Thread B

```
lock.Acquire();
…
critical section;
…
lock.Release();
```

```
INIT
  int value = 0;

Acquire() {
  disable interrupts;
  if (value == 1) {
    put thread on wait-queue;
    go to sleep() //??
  } else {
    value = 1;
  }
  enable interrupts;
}

Release() {
 disable interrupts;
  if anyone on wait queue {
    take thread off wait-queue
    Place on ready queue;
  } else {
    value = 0;
  }
  enable interrupts;
}
```

```
lock.Acquire();
…
critical section;
…
lock.Release();
```


In-Kernel Lock: Simulation

Value: 1 | waiters | owner

READY

Running

Running

Thread A

Thread B

```
lock.Acquire();
…
critical section;
…
lock.Release();
```

```
INIT
  int value = 0;

Acquire() {
  disable interrupts;
  if (value == 1) {
    put thread on wait-queue;
    go to sleep() //??
  } else {
    value = 1;
  }
  enable interrupts;
}

Release() {
 disable interrupts;
  if anyone on wait queue {
    take thread off wait-queue
    Place on ready queue;
  } else {
    value = 0;
  }
  enable interrupts;
}
```

```
lock.Acquire();
…
critical section;
…
lock.Release();
```

In-Kernel Lock: Simulation

Value: 1 | waiters | owner | READY

Running

Thread A

Thread B

```
INIT
  int value = 0;

lock.Acquire();          Acquire() {                          lock.Acquire();
 …                         disable interrupts;                  …
 critical section;         if (value == 1) {                    critical section;
 …                           put thread on wait-queue;          …
lock.Release();              go to sleep() //??               lock.Release();
                           } else {
                             value = 1;
                           }
                           enable interrupts;
                         }

                         Release() {
                           disable interrupts;
                           if anyone on wait queue {
                             take thread off wait-queue
                             Place on ready queue;
                           } else {
                             value = 0;
                           }
                           enable interrupts;
                         }
```


In-Kernel Lock: Simulation

Value: 1 | waiters | owner | READY

Running

Thread A

Running

Thread B

```
INIT
  int value = 0;

lock.Acquire();          Acquire() {                          lock.Acquire();
 …                         disable interrupts;                  …
 critical section;         if (value == 1) {                    critical section;
 …                           put thread on wait-queue;          …
lock.Release();              go to sleep() //??               lock.Release();
                           } else {
                             value = 1;
                           }
                           enable interrupts;
                         }

                         Release() {
                           disable interrupts;
                           if anyone on wait queue {
                             take thread off wait-queue
                             Place on ready queue;
                           } else {
                             value = 0;
                           }
                           enable interrupts;
                         }
```


Discussion

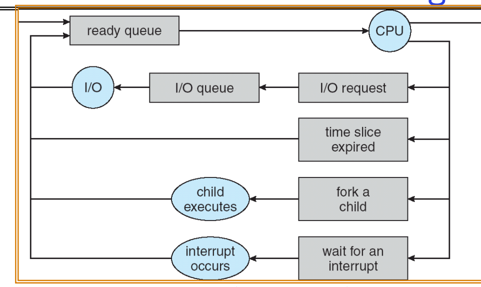
- Notice that Scheduling here involves deciding who to take off the wait queue
  - Could do by priority, etc.
- Same type of code works for in-kernel condition variables
  - The Wait queue becomes unique for each condition variable
  - Once again, transition to and from queues occurs with interrupts disabled

BREAK

Synchronization Summary

- Semaphores: Like integers with restricted interface
  - Two operations:
    - » `P()`: Wait if zero; decrement when becomes non-zero
    - » `V()`: Increment and wake a sleeping task (if exists)
    - » Can initialize value to any non-negative value
  - Use separate semaphore for each constraint
- Monitors: A lock plus zero or more condition variables
  - Always acquire lock before accessing shared data
  - Use condition variables to wait inside critical section
    - » Three Operations: `Wait()`, `Signal()`, `Broadcast()`

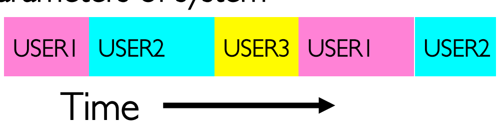
Recall: CPU Scheduling



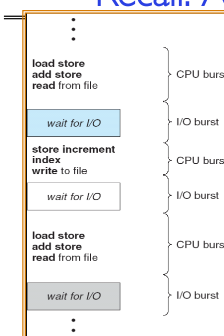
- Earlier, we talked about the life-cycle of a thread
  - Active threads work their way from Ready queue to Running to various waiting queues.
- Question: How is the OS to decide which of several tasks to take off a queue?
  - Obvious queue to worry about is ready queue
  - Others can be scheduled as well, however
- Scheduling: deciding which threads are given access to resources from moment to moment

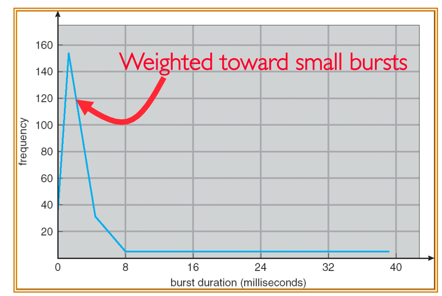
Recall: Scheduling Assumptions

- CPU scheduling big area of research in early 70's
- Many implicit assumptions for CPU scheduling:
  - One program per user
  - One thread per program
  - Programs are independent
- Clearly, these are unrealistic but they simplify the problem so it can be solved
  - For instance: is "fair" about fairness among users or programs?
    - » If I run one compilation job and you run five, you get five times as much CPU on many operating systems
- The high-level goal: Dole out CPU time to optimize some desired parameters of system



Recall: Assumption – CPU Bursts



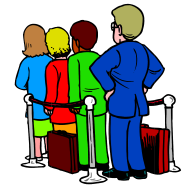


- Execution model: programs alternate between bursts of CPU and I/O
  - Program typically uses the CPU for some period of time, then does I/O, then uses CPU again
  - Each scheduling decision is about which job to give to the CPU for use by its next CPU burst
  - With timeslicing, thread may be forced to give up CPU before finishing current CPU burst

Scheduling Policy Goals/Criteria

- Minimize Response Time
  - Minimize elapsed time to do an operation (or job)
  - Response time is what the user sees:
    - » Time to echo a keystroke in editor
    - » Time to compile a program
    - » Real-time Tasks: Must meet deadlines imposed by World
- Maximize Throughput
  - Maximize operations (or jobs) per second
  - Throughput related to response time, but not identical:
    - » Minimizing response time will lead to more context switching than if you only maximized throughput
  - Two parts to maximizing throughput
    - » Minimize overhead (for example, context-switching)
    - » Efficient use of resources (CPU, disk, memory, etc)
- Fairness
  - Share CPU among users in some equitable way
  - Fairness is not minimizing average response time:
    - » Better *average* response time by making system *less* fair

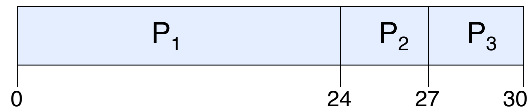
First-Come, First-Served (FCFS) Scheduling



- First-Come, First-Served (FCFS)
  - Also "First In, First Out" (FIFO) or "Run until done"
    - » In early systems, FCFS meant one program scheduled until done (including I/O)
    - » Now, means keep CPU until thread blocks
- Example:

Process	Burst Time
P_1	24
P_2	3
P_3	3

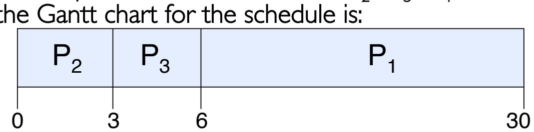
  - Suppose processes arrive in the order: P_1 , P_2 , P_3
    The Gantt Chart for the schedule is:



  - Waiting time for $P_1 = 0$; $P_2 = 24$; $P_3 = 27$
  - Average waiting time: $(0 + 24 + 27)/3 = 17$
  - Average Completion time: $(24 + 27 + 30)/3 = 27$
- *Convoy effect:* short process behind long process

FCFS Scheduling (Cont.)

- Example continued:
  - Suppose that processes arrive in order: P_2 , P_3 , P_1
    Now, the Gantt chart for the schedule is:



  - Waiting time for $P_1 = 6$; $P_2 = 0$; $P_3 = 3$
  - Average waiting time: $(6 + 0 + 3)/3 = 3$
  - Average Completion time: $(3 + 6 + 30)/3 = 13$
- In second case:
  - average waiting time is much better (before it was 17)
  - Average completion time is better (before it was 27)
- FIFO Pros and Cons:
  - Simple (+)
  - Short jobs get stuck behind long ones (-)
    - » Safeway: Getting milk, always stuck behind cart full of small items. Upside: get to read about space aliens!

Summary

- Semaphores: Like integers with restricted interface
  - Two operations:
    - » `P()`: Wait if zero; decrement when becomes non-zero
    - » `V()`: Increment and wake a sleeping task (if exists)
    - » Can initialize value to any non-negative value
  - Use separate semaphore for each constraint
- Monitors: A lock plus one or more condition variables
  - Always acquire lock before accessing shared data
  - Use condition variables to wait inside critical section
    - » Three Operations: `Wait()`, `Signal()`, and `Broadcast()`
- Scheduling: selecting a waiting process from the ready queue and allocating the CPU to it
- FCFS Scheduling:
  - Run threads to completion in order of submission
  - Pros: Simple
  - Cons: Short jobs get stuck behind long ones
- Round-Robin Scheduling:
  - Give each thread a small amount of CPU time when it executes; cycle between all ready threads
  - Pros: Better for short jobs
  - Cons: Poor when jobs are same length