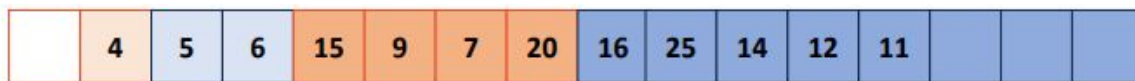
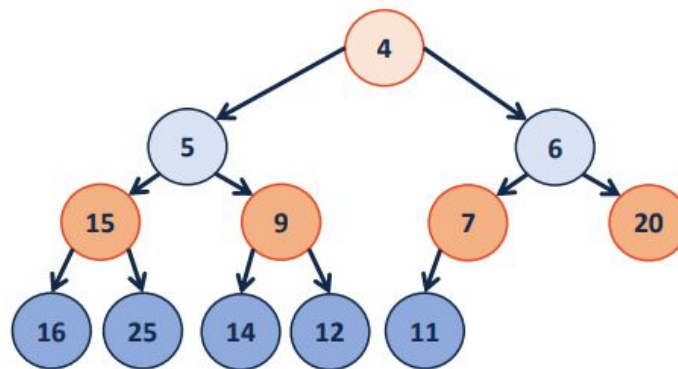


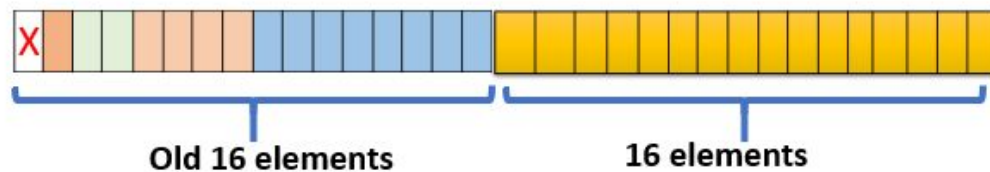
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- ADT:
 - insert()
 - remove()
 - isEmpty()



- The visualization is a tree, but the actual implementation will be an array (or vector)
 - Root is at index 1
 - For the node on index i , its
 - Left child is at index $2 * i$
 - Right child is at index $2 * i + 1$
 - Parent is at index $\lfloor i/2 \rfloor$

- Check if we still have the array capacity
 - If not, we double the size of the array

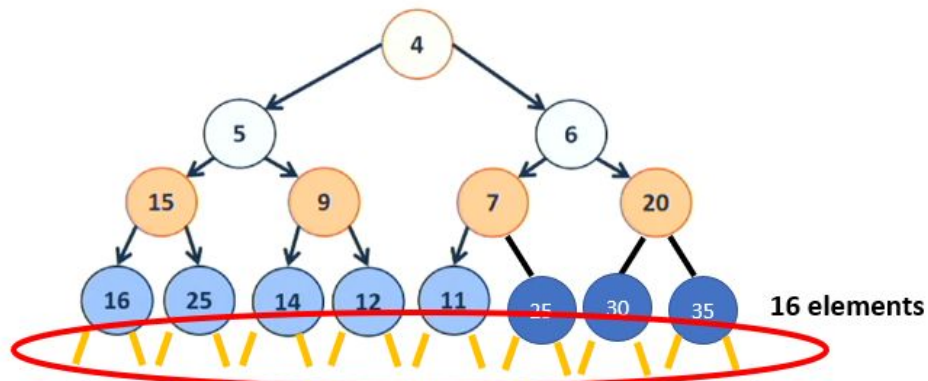


- This is just adding a new layer to the tree

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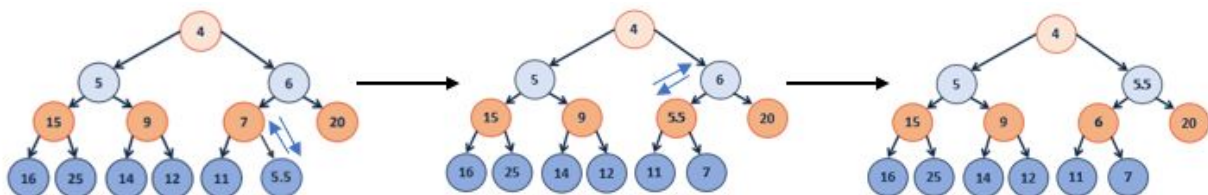
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- Insert the element at the end of the array, and make sure the resulted heap is still a heap (applying heapify-up if needed)

```
1 template <class T>
2 void Heap<T>::_insert(const T & key) {
3     // Check to ensure there's space to insert an element
4     // ...if not, grow the array
5     if ( size_ == capacity_ ) { _growArray(); }
6
7     // Insert the new element at the end of the array
8     item_[++size] = key;
9
10    // Restore the heap property
11    _heapifyUp(size);
12 }
```

Heapify-Up



- Starting from the inserted node, and also assuming the heap is valid everywhere above that inserted node
- If the current element is not the root, and smaller than its parent:
 - Swap the current element with its parent node

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- Continue to applying heapifyUp on the parent node

```
1 template <class T>
2 void Heap<T>::_heapifyUp(unsigned index) {
3     if ( index > 1 ) {
4         if ( item_[index] < item_[ parent(index) ] ) {
5             std::swap( item_[index], item_[ parent(index) ] );
6             _heapifyUp(parent(index));
7         }
8     }
9 }
```

- Runtime of Insertion operation
 - growArray() takes $O(1)$ amortized
 - insertion takes $O(1)$
 - heapify-up takes $O(h) = O(\lg n)$ since the tree is complete
 - Total runtime: $O(\lg n)$

Remove

- Swap the root with the last element
- Then remove the last element
- Heapify-Down to ensure the heap property is perserved.

```
1 template <class T>
2 void Heap<T>::_removeMin() {
3     // Swap with the last value
4     T minValue = item_[1];
5     item_[1] = item_[size_];
6     size--;
7
8     // Restore the heap property
9     heapifyDown();
10
11     // Return the minimum value
12     return minValue;
13 }
```

Heapify-Down

- Starting from the root node with the assumption that both subtrees are valid heaps
- If current is not leaf, find the minChild among the two children

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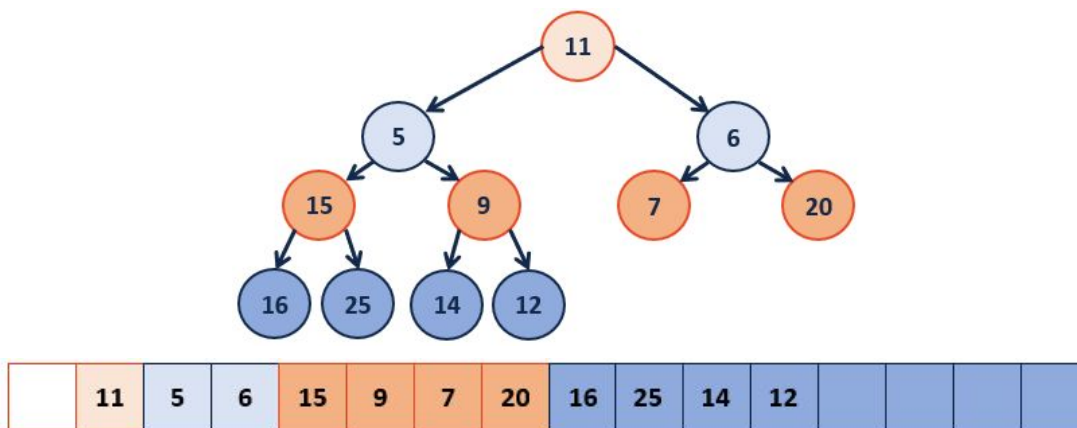
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- Swap the value of minChild and subRoot if needed
- Continue on the minChild node if swap happened

```
1 template <class T>
2 void Heap<T>::_heapifyDown(int index) {
3     if ( !_isLeaf(index) ) {
4         int minChildIndex = _minChild(index);
5         if ( item_[index] > item_[minChildIndex] ) {
6             std::swap( item_[index], item_[minChildIndex] );
7             _heapifyDown(minChildIndex);
8         }
9     }
10 }
```

- Runtime of Remove ()
 - swap takes $O(1)$
 - heapify-down takes $O(h) = O(\lg n)$ since the tree is complete
 - **Total runtime: $O(\log n)$**
- Example of HeapifyDown

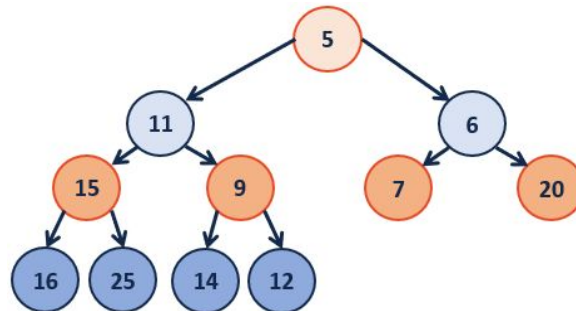


HeapifyDown(1):
minChildIndex = 2;
if(11 > 5) 😊 (true)
 swap elements;
 heapifyDown(2);

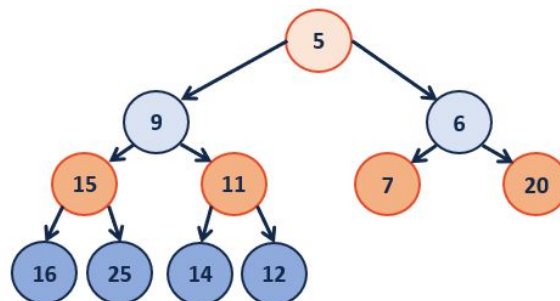
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HeapifyDown(2):
minChildIndex = 5;
if(11 > 9) 😊
swap elements;
heapifyDown(5);



HeapifyDown(5):
minChildIndex = 11;
if(11 > 12) ☹️

Done: Heap property restored!

Everything so far can be done using an AVL tree under the same runtime
But the below function, *buildHeap*, gives Heaps the edge over AVLs

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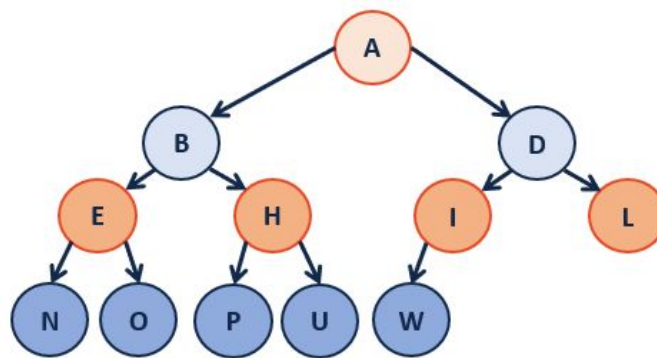
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BuildHeap

- We want to build a heap using a given array:
- **Method 1: sorting**



- A sorted array is always a heap



- Runtime: $O(n \log n)$
- **Method 2: heapify-up**
 - Call Heapify-Up on every element from the root

```
1  template <class T>
2  void Heap<T>::buildHeap() {
3      for (unsigned i = 2; i <= size_; i++) {
4          heapifyUp(i);
5      }
6  }
```

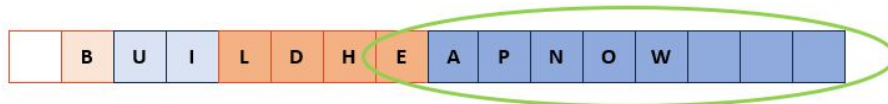
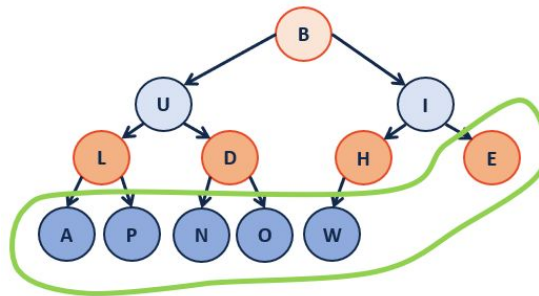
- Takes $O(\log n)$ for every element, so $O(n \log n)$ in total
- **Method 3: heapify-down**
 - Call Heapify-Down on every element from the end of the array

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- Notice that the last level already has the heap property!
- We can start from the second-last level
- In the case below, “H” is the first element that is not a heap



```
1 template <class T>
2 void Heap<T>::buildHeap() {
3     for (unsigned i = parent(size); i > 0; i--) {
4         heapifyDown(i);
5     }
6 }
```

- Since heapify-down runs in $O(h)$ time:
 - heapify on “H” takes 1 unit of work
 - heapify on “I” takes 2 units of work
 - heapify on “B” takes 3 units of work
 - In total, we have $1+1+2+2+3 = 10$ units of work, this is just linear to the number of elements
- Then we have the runtime: $O(n)$
 - Proof in next lecture