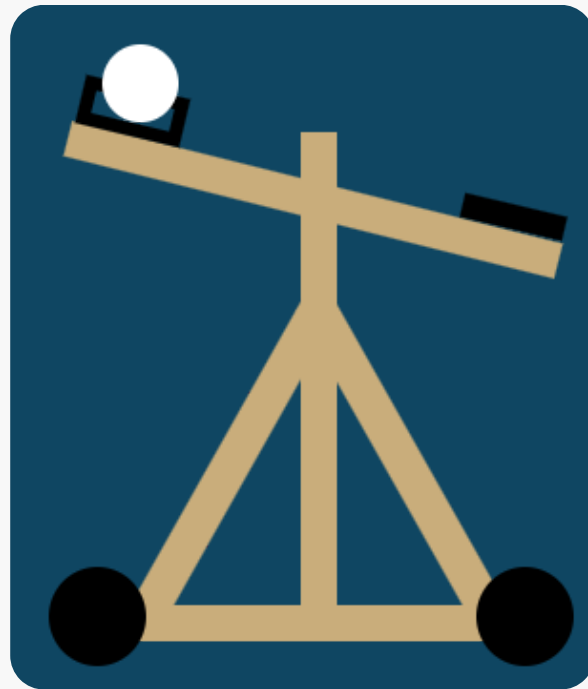


Simple Trebuchet



Equation for Total Inertia of The System

$$I_{total} = \left(\frac{1}{3} m_{arm} + m_{mass} + m_{projectile} \right) r^2$$

Equations utilized in Conservation of Energy

$$E_i = mg\Delta h$$

$$E_f = \frac{1}{2} I_{total} \left(\frac{v}{r} \right)^2$$

Relevant Equations

Equation for V (Velocity of ball)

$$v = \sqrt{\frac{\left(2mg \left(\sin(\theta_1) \right) + \left(\sin(\theta_2) \right) r \right)}{\frac{1}{12} m_2 (2r)^2 + m(r)^2 + m_b(r)^2}}$$

Equation for X (Distance covered by ball)

$$x = \left(\cos(\theta_3) v \right) \left(\frac{\sin(\theta_3) v}{g} + \sqrt{\frac{2H_g + 2 \left(\sin(\theta_3) v g \right) - \left(v \sin(\theta_3) \right)^2}{g^2}} \right)$$

How equations were derived:

Through the use of principles such as Conservation of Energy, Inertia and Torque , and Energy of Rotating Systems, these equations calculating distance, velocity, and much more were able to be derived