

# **DATA AND DEPENDENCIES**









### **LEARNING OBJECTIVES**

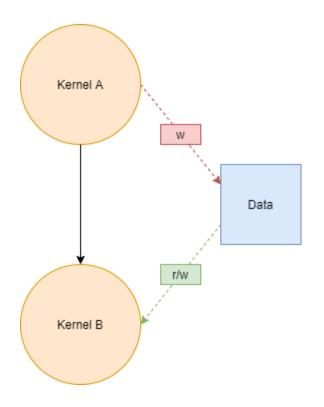
- Learn about how to create dependencies between kernel functions
- Learn about how to move data between the host and device(s)
- Learn how to represent basic data flow graphs





#### **CREATING DEPENDENCIES**





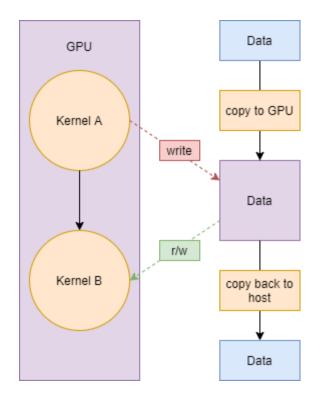
- Kernel A first writes to the data
- Kernel B then reads from and writes to the data
- This creates a read-after-write (RAW) relationship
- There must be a dependency created between Kernel A and Kernel B





#### **MOVING DATA**





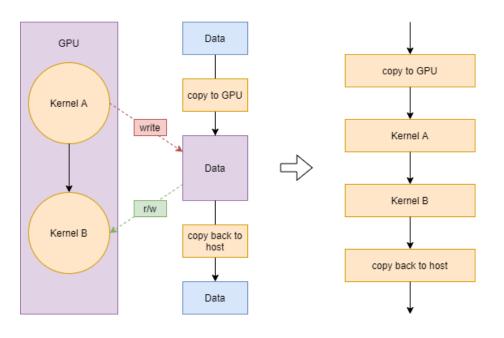
- Here both kernel functions are enqueued to the same device, in this case a GPU
- The data must be copied to the GPU before the Kernel A is executed
- The data must remain on the GPU for Kernel B to be executed
- The data must be copied back to the host after Kernel B has executed





#### **DATA FLOW**





- Combining kernel function dependencies and the data movement dependencies we have a final data flow graph
- This graph defines the order in which all commands must execute in order to maintain consistency
- In more complex data flow graphs there may be multiple orderings which can achieve the same consistency









```
auto devPtr =
   sycl::malloc device<int>(1024,
   q);
2
   auto e1 = q.memcpy(devPtr, data,
   sizeof(int));
   auto e2 =
   q.parallel_for(sycl::range{1024},
5
     e1,
     [=](sycl::id<1> idx) {
       devPtr[idx] = /* some
   computation */
8
     });
   auto e3 =
   q.parallel_for(sycl::range{1024},
11
     e2,
     [=](sycl::id<1> idx) {
       devPtr[idx] = /* some
   computation */
     });
14
15
16 auto e4 = q.memcpy(data, devPtr,
   512601(1nt), e3);
```

- The USM data management model data model is prescriptive
- Dependencies are defined explicitly by passing around event objects
- Data movement is performed explicitly by enqueuing memcpy operations
- The user is responsible for ensuring data dependencies and consistency are maintained







```
auto devPtr =
     sycl::malloc_device<int>(1024,
     q);
     auto e1 = q.memcpy(devPtr, data,
     sizeof(int));
     auto e2 =
     q.parallel_for(sycl::range{1024},
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       e1,
    [=](sycl::id<1>idx) {
         devPtr[idx] = /* some
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    auto e3 =
     q.parallel_for(sycl::range{1024},
 11
    e2,
    [=](sycl::id<<mark>1</mark>> idx) {
         devPtr[idx] = /* some
     computation */
      });
 14
 15
 16 auto e4 = q.memcpy(data, devPtr,
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 I/ C4.Wall();
```

- Each command enqueued to the queue produces an event object which can be used to synchronize with the completion of that command
- Passing those event objects when enqueueing other commands creates dependencies









```
auto devPtr =
     sycl::malloc device<int>(1024,
     q);
    auto e1 = q.memcpy(devPtr, data,
     sizeof(int));
    auto e2 =
     q.parallel_for(sycl::range{1024},
    e1,
   [=](sycl::id<1>idx) {
         devPtr[idx] = /* some
     computation */
     });
    auto e3 =
     q.parallel_for(sycl::range{1024},
 11 e2,
    [=](sycl::id<1> idx) {
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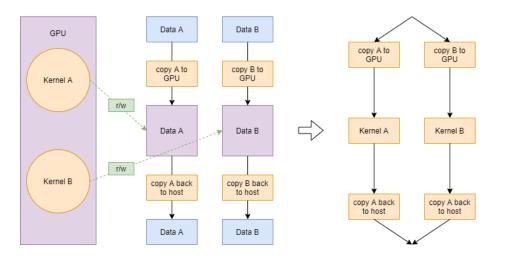
 The memcpy member functions are used to enqueue data movement commands, moving the data to the GPU and then back again





# **SYCL**<sub>M</sub>

#### **CONCURRENT DATA FLOW**



- If two kernels are accessing different buffers then there is no dependency between them
- In this case the two kernels and their respective data movement are independent
- By default queues are out-of-order which means that these commands can execute in any order
- They could also execute concurrently if the target device is able to do so







#### **CONCURRENT DATA FLOW WITH USM**

```
auto devPtrA = sycl::malloc_device<int>(1024, q);
   auto devPtrB = sycl::malloc device<int>(1024, g);
   auto e1 = q.memcpy(devPtrA, dataA, sizeof(int));
   auto e2 = q.memcpy(devPtrB, dataB, sizeof(int));
6
   auto e3 = q.parallel_for(sycl::range{1024}, e1,
       [=](sycl::id<1>idx) { devPtrA[idx] = /* some computation */
   });
9
10 auto e4 = q.parallel_for(sycl::range{1024}, e2,
       [=](sycl::id<1>idx) { devPtrB[idx] = /* some computation}
   */ });
12
13 auto e5 = q.memcpy(dataA, devPtrA, sizeof(int), e3);
14 auto e6 = q.memcpy(dataB, devPtrB, sizeof(int), e4);
15
16 e5.wait();
17 e6.wait();
18
19 sycl::free(devPtrA, q);
20 sycl::free(devPtrB, q);
```







#### CONCURRENT DATA FLOW WITH USM

```
auto devPtrA = sycl::malloc_device<int>(1024, q);
   auto devPtrB = sycl::malloc device<int>(1024, g);
   auto e1 = q.memcpy(devPtrA, dataA, sizeof(int));
5
   auto e2 = q.memcpy(devPtrB, dataB, sizeof(int));
6
   auto e3 = q.parallel_for(sycl::range{1024}, e1,
       [=](sycl::id<1>idx) { devPtrA[idx] = /* some computation */
   });
9
10 auto e4 = q.parallel_for(sycl::range{1024}, e2,
           [=](sycl::id<1>idx) { devPtrB[idx] = /* some computation}
   */ });
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13 auto e5 = q.memcpy(dataA, devPtrA, sizeof(int), e3);
14 auto e6 = q.memcpy(dataB, devPtrB, sizeof(int), e4);
15
16 e5.wait();
17 e6.wait();
18
19 sycl::free(devPtrA, q);
20 sycl::free(devPtrB, q);
```

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The dependencies of each chain of commands is independant of the other



# **QUESTIONS**



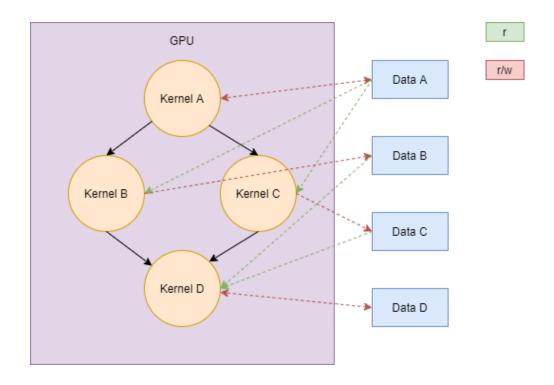








## Code\_Exercises/Data\_and\_Dependencies/source



Put together what you've seen here to create the above diamond data flow graph.

