

LOCAL MEMORY









LEARNING OBJECTIVES

- Learn about tiling using local memory
- Learn about how to synchronize work-groups







COST OF ACCESSING GLOBAL MEMORY

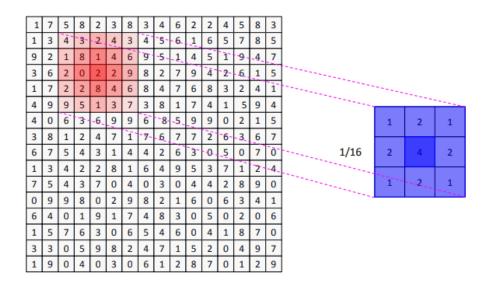
- As we covered earlier global memory is very expensive to access.
- Even with coalesced global memory access if you are accessing the same elements multiple times that can be expensive.
- Instead you want to cache those values in a lower latency memory.







WHY ARE IMAGE CONVOLUTIONS GOOD ON A GPU?



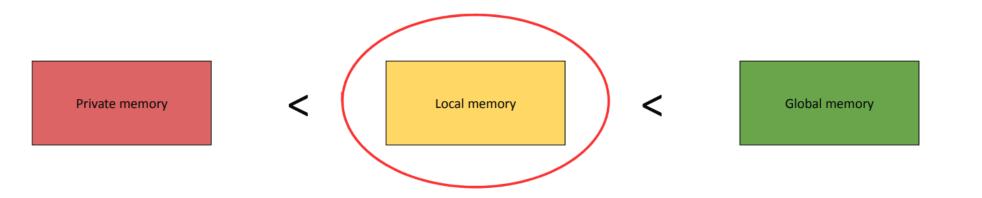
- Looking at the image convolution example.
- For each output pixel we are reading up to NxM pixels from the input image, where N and M are the dimensions of the filter.
- This means each input pixel is being read up to NxM times:
- 3x3 filter: up to 9 ops.
- 5x5 filter: up to 25 ops.
- 7x7 filter: up to 49 ops.
- If each of these operations is a separate load from global memory this becomes very expensive.





USING LOCAL MEMORY





- The solution is local memory.
- Local memory is generally on-chip and doesn't have a cache as it's managed manually so is much lower latency.
- Local memory is a smaller dedicated region of memory per work-group.
- Local memory can be used to cache, allowing us to read from global memory just once and then read from local memory instead, often referred to as a scratchpad.









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	6	7	7	2	6	3-	-6.	7

- The iteration space of the kernel function is mapped across multiple work-groups.
- Each work-group has it's own region of local memory.
- You want to split the input image data into tiles, one for each workgroup.







LOCAL ACCESSORS

```
auto scratchpad = sycl::local_accessor<int, 1>
(sycl::range{workGroupSize}, cgh);
```

- Local memory is allocated via an local_accessor.
- They allocate memory per work-group for the duration of the kernel function.
- The range provided is the number of elements of the specified type to allocate per work-group.







LOCAL ACCESSORS - COMMAND GROUPS BACKGROUND

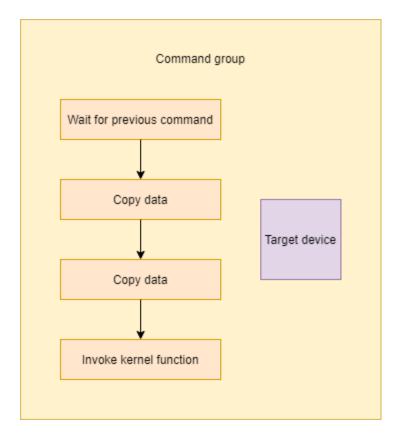
```
1 myQueue.submit([&](sycl::handler& cgh) {
2   auto scratchpad = sycl::local_accessor<int, 1>
    (sycl::range{workGroupSize}, cgh);
3   cgh.parallel_for(sycl::nd_range{globalRange, {workGroupSize}},
4   [=](nd_item<1> item) {...});
5 });
```





COMMAND GROUPS





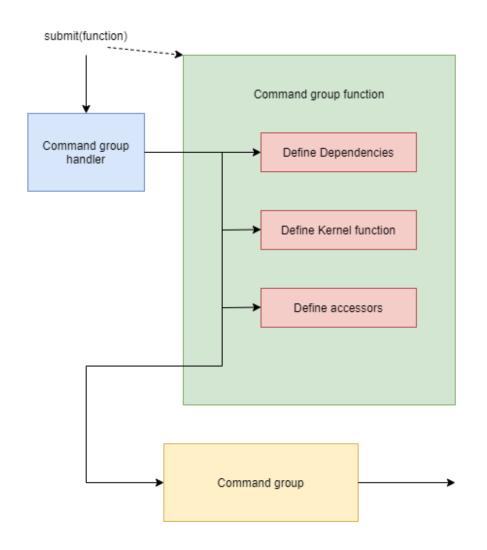
- In the buffer/accessor model or, when local memory is required, commands must be enqueued via command groups.
- A command group represents a series of commands to be executed by a device.
- These commands include:
 - Invoking kernel functions on a device.
 - Copying data to and from a device.
 - Waiting on other commands to complete.
 - Allocating local memory





SYCL

COMPOSING COMMAND GROUPS



- Command groups are composed by calling the submit member function on a queue.
- The submit function takes a command group function which acts as a factory for composing the command group.
- The submit function creates a handler and passes it into the command group function.
- The handler then composes the command group.







LOCAL ACCESSORS - IN CONTEXT

```
1 myQueue.submit([&](sycl::handler& cgh) {
2   auto scratchpad = sycl::local_accessor<int, 1>
   (sycl::range{workGroupSize}, cgh);
3   cgh.parallel_for(sycl::nd_range{globalRange, {workGroupSize}},
4   [=](nd_item<1> item) {...});
5 });
```

- The call to queue::submit gives access to the command group handler cgh
- The cgh is needed to allocate the local memory
- In this scenario parallel_for is added as the last action of this command group.
 - Caution: only one kernel can be submitted per command group
- The kernel submission mechanisms, we got to know so far, are just convenient wrappers for this.





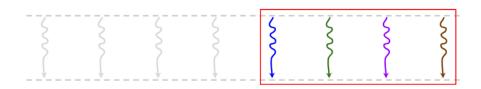


- Local memory can be used to share partial results between work-items.
- When doing so it's important to synchronize between writes and reads to memory to ensure all work-items have reached the same point in the program.







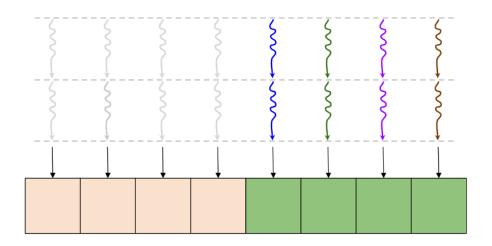


• Remember that work-items are not guaranteed to all execute at the same time (in parallel).







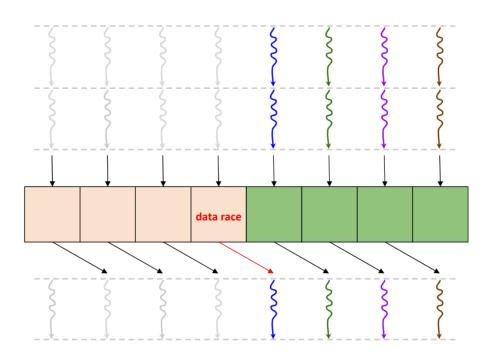


 A work-item can share results with other work-items via local (or global) memory.







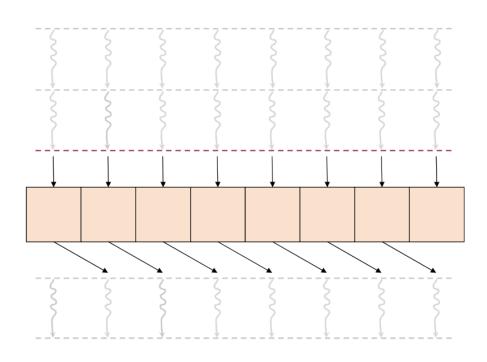


- This means it's possible for a workitem to read a result that hasn't been written to yet.
- This creates a data race.







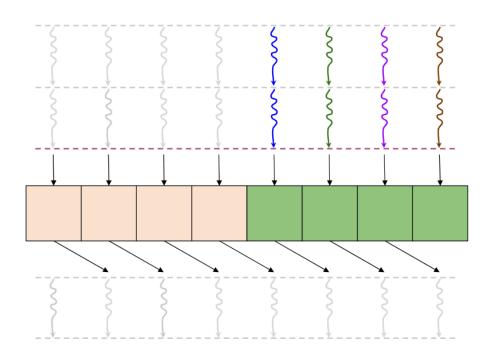


 This problem can be solved with a synchronization primitive called a work-group barrier.







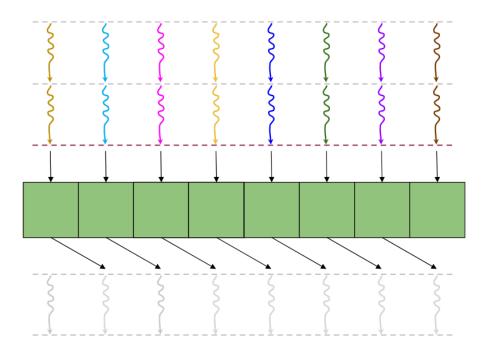


 When a work-group barrier is inserted work-items will wait until all work-items in the work-group have reached that point.







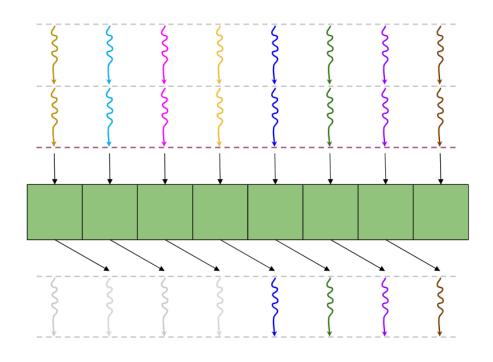


• Only then can any work-items in the work-group continue execution.







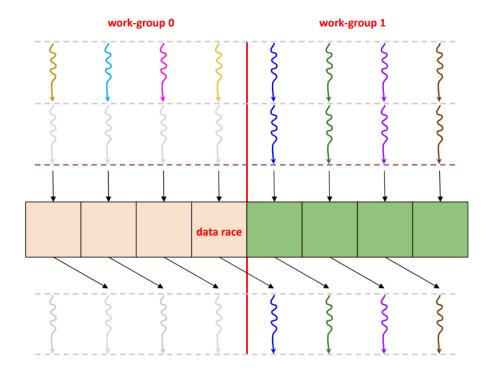


• So now you can be sure that all of the results that you want to read have been written to.









- However note that this does not apply across work-group boundaries.
- So if you write in a work-item of one work-group and then read it in a work-item of another work-group you again have a data race.
- Furthermore, remember that workitems can only access their own local memory and not that of any other work-groups.







GROUP_BARRIER

```
sycl::group_barrier(item.get_group());
```

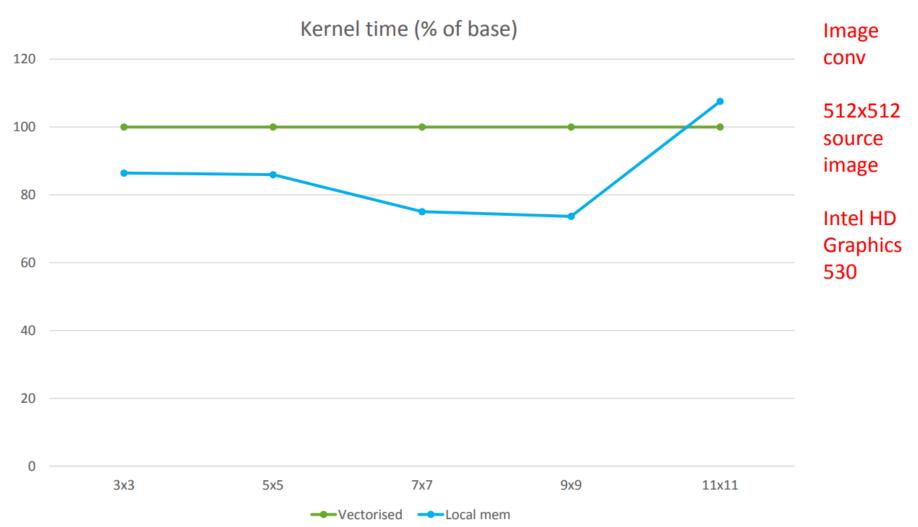
- Work-group barriers can be invoked by calling group_barrier and passing a group object.
- You can retrieve a group object representing the current work-group by calling get_group on an nd_item.
- Note this requires the nd_range variant of parallel_for.







LOCAL MEMORY IMAGE CONVOLUTION PERFORMANCE







QUESTIONS







SYCL_m

EXERCISE

Code_Exercises/Section_10_Local_Memory_Tiling/source

Use local memory to cache a tile of the input image data per work-group.

