

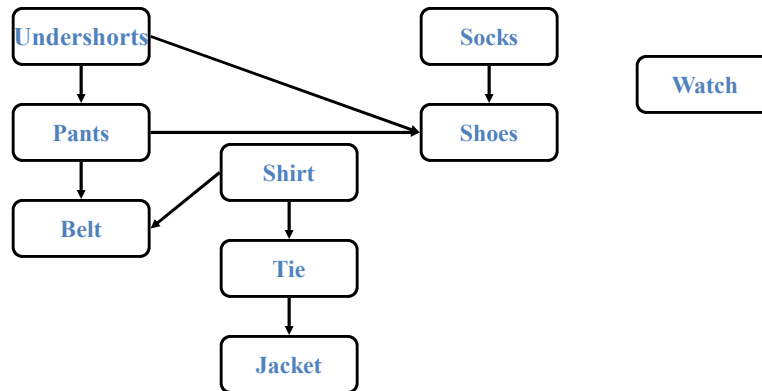
Application of DFS

- Topological Sort
- Detection of a cycles
- Strongly Connected Components
 - Component graph
 - Transpose of directed graph
 - Algorithm to compute SCC
- Biconnectivity
- Articulation Points
- Bridges

Topological Sort

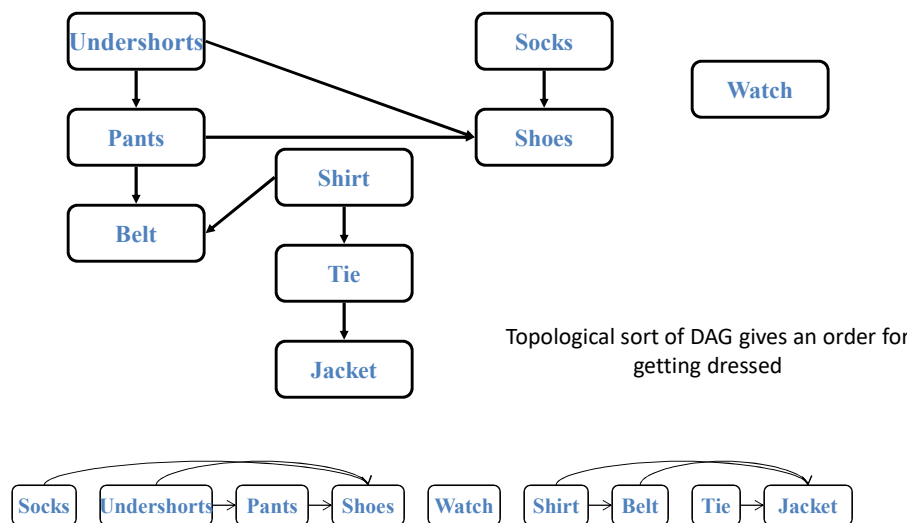
- *DFS used to perform topological sort of a DAG*
- *Topological sort* of a DAG:
 - Linear ordering of all vertices in graph G such that vertex u appears before vertex v *in the ordering* if edge $(u, v) \in G$
- Example: getting dressed

Getting Dressed



- directed edge (u,v) indicates that garment u must be put on before garment v
- certain garments put on before others
- other items may put on in any order

Getting Dressed



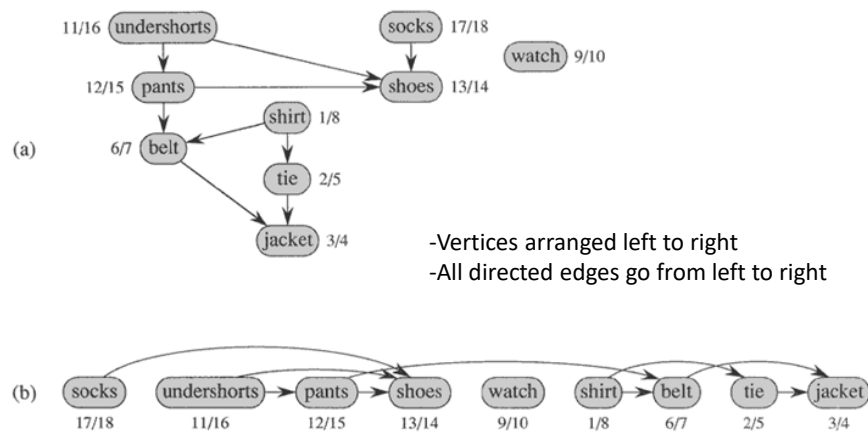
Topological Sort Algorithm

Topological-Sort(G)

```
{
1. Call DFS( $G$ ) to compute finishing times  $f(v)$ 
   for each vertex  $v$ 
2. As each vertex is finished, insert it onto
   the front of linked list
3. Return the linked list of vertices
}
```

Topological sort performed in Time: $O(V+E)$

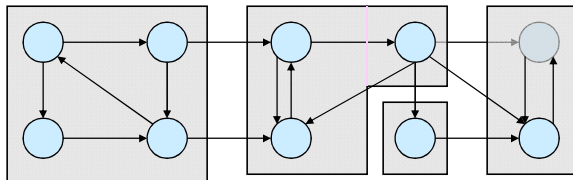
Topologically sorted graph



-topologically sorted vertices appears in reverse order of their finishing times

Strongly Connected Components

- G is strongly connected if every pair (u, v) of vertices in G is reachable from one another
- A **strongly connected component (SCC)** of G is a maximal set of vertices $C \subseteq V$ such that for all $u, v \in C$, both $u \rightsquigarrow v$ and $v \rightsquigarrow u$ exist
 - i.e. vertices u and v are reachable from each other

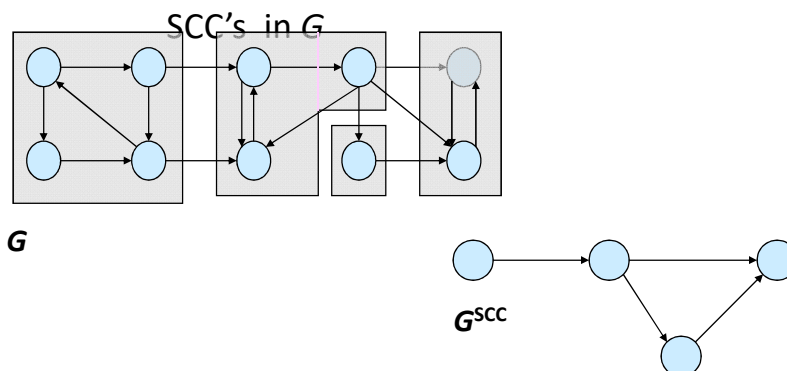


Component Graph

Component graph $G^{\text{SCC}} = (V^{\text{SCC}}, E^{\text{SCC}})$

$V^{\text{SCC}} \rightarrow$ has one vertex for each SCC in G

$E^{\text{SCC}} \rightarrow$ has an edge if there's an edge between the corresponding

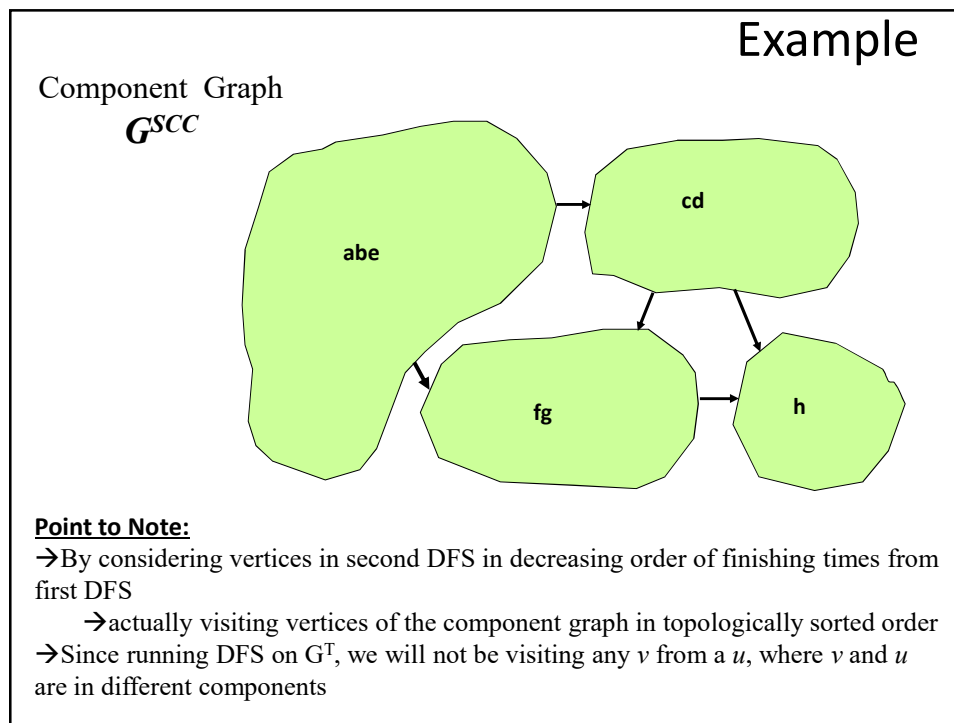
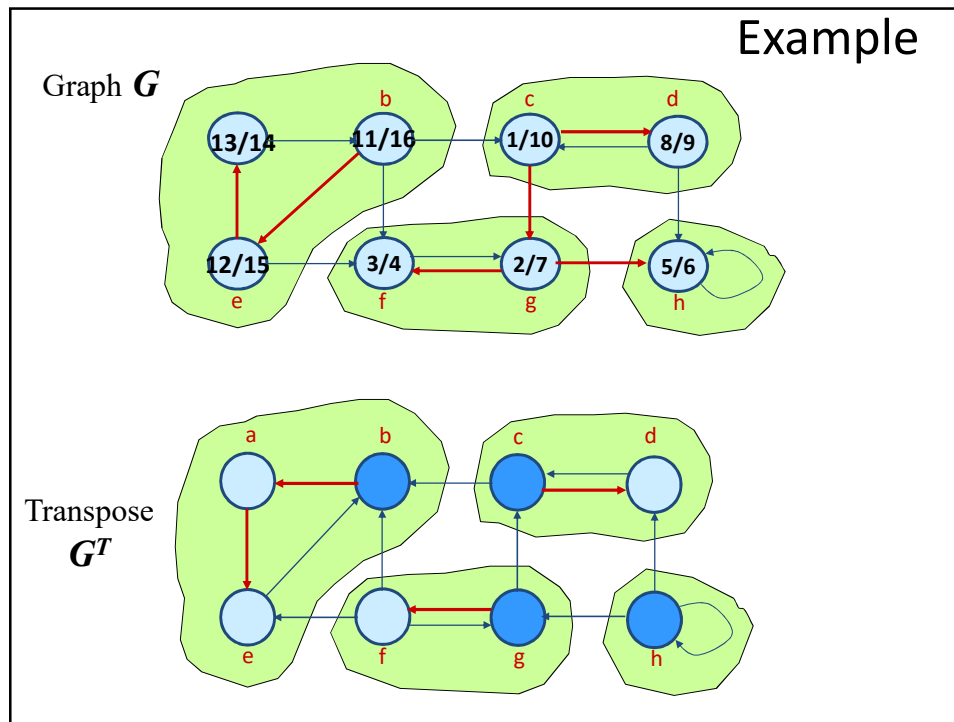


Transpose of a Directed Graph

- **Transpose** of directed $G(V, E)$ is G^T
 - $G^T = (V, E^T)$,
 - where $E^T = \{(u, v) : (v, u) \in E\}$.
 - G^T is G with all its edges reversed
- Using Adjacency list of G
 - G^T created in $\Theta(V + E)$ time
- G and G^T have the same *strongly connected components*
 - u and v are reachable from each other in G if and only if reachable from each other in G^T

Strongly_Connected_Components(G)

- Call DFS(G) to compute finishing times $f[u]$ for all u
 - Compute G^T
 - Call DFS(G^T), but in the main loop, consider vertices in order of decreasing $f[u]$ (as computed in first DFS)
 - Output the vertices in each tree of the depth-first forest formed in second DFS as a separate SCC
- Linear running Time: $\Theta(V + E)$*



Lemma

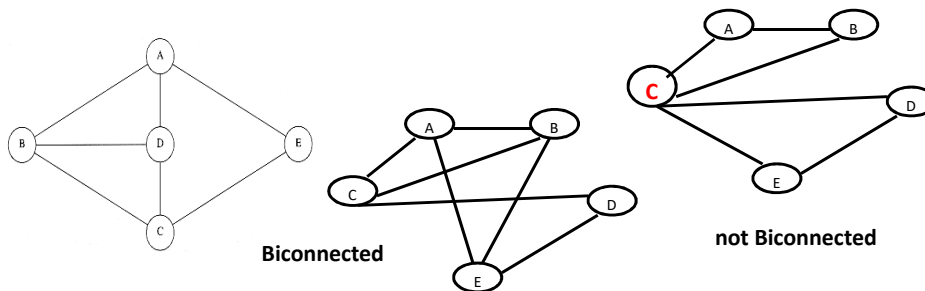
Let C and C' be distinct SCC's in $G = (V, E)$.
 Suppose there is an edge $(u, v) \in E$ such that $u \in C$ and $v \in C'$
 Then $f(C) > f(C')$.

Corollary

Let C and C' be distinct strongly connected components in $G = (V, E)$.
 Suppose there is an edge $(u, v) \in E^T$ such that $u \in C$ and $v \in C'$
 Then $f(C) < f(C')$.

Biconnectivity

- A connected undirected graph is **biconnected** if there are no vertices whose removal will disconnect the rest of the graph

**Example :**

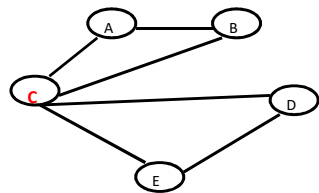
--Computer → Nodes and Links → Edges

--if any computer goes down, mailing service of network mail unaffected, except at the down computer.

Articulation Points

- **Articulation point** or cut-vertex : A vertex whose removal (along with its attached arcs) makes the graph disconnected
 → graph is not biconnected

Eg. **C** is an articulation point



- Relevant to computer networks
- Represent vulnerabilities in a network
- In many applications these nodes are critical

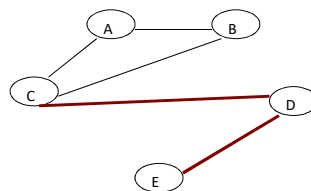
Articulation points can be computed using **depth-first search** and a special numbering of the vertices in the order of their visiting

Bridges

Bridge: An edge in a graph whose removal disconnects the graph

- a bridge is any edge in a graph, that does not lie on a cycle
- a bridge has at least one articulation point at its end
- however an articulation point is not necessarily linked in a bridge

Eg. (C,D) and (E,D)



No articulation points and No bridges → **Biconnected graph**

Binconnectivity: Articulation Points

In a connected graph all articulation points can be computed using DFS in a linear time:

1. Perform a DFS starting at any vertex
 - number the nodes as they are visited say: $dfs_num(v)$ as visiting sequence of vertices v and
2. For every vertex v in the depth-first spanning tree
 - compute $dfs_low(v)$: the lowest-numbered vertex, dfs_num that is reachable from v through a path by taking **zero or more tree edges** and then possibly followed by **zero or one back edge**
3. Vertex v is an articulation point of G if and only if either
 - v is the root of DFS tree and has at least two children
 - v is not the root of DFS tree and has a child u for which no vertex in subtree rooted with u has a back edge to one of the ancestors (in DFS tree) of v i.e. vertex v is an articulation point if and only if v has

