#### 1

# Assignment 18

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The link to the solution is

https://github.com/Adarsh1310/EE5609

Abstract—This documents solves a problem based on Linear Transformation.

### 1 Problem

Describe explicitly the linear transformation T from  $\mathbb{F}^2$  into  $\mathbb{F}^2$  such that  $T(\epsilon_1) = (a, b), T(\epsilon_2) = (c, d)$ .

## 2 Solution

We are given a linear transformation,

$$T: \mathbb{F}^2 \to \mathbb{F}^2 \tag{2.0.1}$$

The transformation for  $\in_1$  and  $\in_2$  can be written as,

$$T(\epsilon_1) = \begin{pmatrix} a \\ b \end{pmatrix} \tag{2.0.2}$$

$$T(\epsilon_2) = \begin{pmatrix} c \\ d \end{pmatrix} \tag{2.0.3}$$

Now,let's assume  $\in_1$  and  $\in_2$  as linearly independent. So the linear transformation T for any vector  $\mathbf{v}$  in two dimensional space will be,

$$T(\mathbf{v}) = \begin{pmatrix} T(\epsilon_1) & T(\epsilon_2) \end{pmatrix} \begin{pmatrix} k_1 \\ k_2 \end{pmatrix}$$
 (2.0.4)

$$= \begin{pmatrix} a & c \\ b & d \end{pmatrix} \begin{pmatrix} k_1 \\ k_2 \end{pmatrix} \tag{2.0.5}$$

$$= \mathbf{Av} \qquad (2.0.6)$$

Now, there can be two cases here, transformation of linearly independent vector can be independent or it can be dependent. Considering the first case and (2.0.5) we can say that,

$$Range(T) = \text{columnspace of} \begin{pmatrix} a & c \\ b & d \end{pmatrix}$$
 (2.0.7)

Now, considering the case when linear transformation will be linearly dependent,

$$Range(T) = \text{columnspace of} \begin{pmatrix} a \\ b \end{pmatrix}$$
 (2.0.8)

Now, considering that vectors  $\epsilon_1$  and  $\epsilon_2$  itself are linearly dependent.Let  $\mathbf{v} = \epsilon_1 + \epsilon_2$ 

$$T(\mathbf{v}) = T(\epsilon_1) + T(\epsilon_2)$$
 (2.0.9)

$$= T(\epsilon_1) + T(k \epsilon_1) \tag{2.0.10}$$

$$= (k+1)T(\epsilon_1) \tag{2.0.11}$$

$$= (k+1) \begin{pmatrix} a \\ b \end{pmatrix} \tag{2.0.12}$$

We can see from above equation that when  $\in_1$  and  $\in_2$  as linearly dependent then the transformation T will be along the line only.

<b>Vectors Independent</b>	<b>Vectors Dependent</b>
$T(v) = \begin{pmatrix} a & c \\ b & d \end{pmatrix} \begin{pmatrix} k_1 \\ k_2 \end{pmatrix}$	$T(v) = (k+1) \begin{pmatrix} a \\ b \end{pmatrix}$
Output:	Output:
On the plane	On the line