

Based on
github.com/ANYbotics/
grid_map

number of columns
`getSize()(1)`

cell value for a layer
`at(index)`
`atPosition(position)`

resolution/grid size [m/cell]
`getResolution()`

number of rows
`getSize()(0)`

grid map center

length in x-direction [m]
`getLength().x()`

position of grid map
`getPosition()`

cell index at position
`getIndex()`

position of a cell [m]
`getPosition()`

length in y-direction [m]
`getLength().y()`

grid map frame

