



Gradient Harmonized Single-Stage Detector

AAAI 2019



- 作者介绍
- 研究背景
- 本文方法
- 实验效果
- 总结反思

作者介绍

3



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MMLab, The Chinese University
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Biography

Buyu Li is a PhD candidate at [Multimedia Lab \(MMLab\)](#), The Chinese University of Hong Kong, supervised by Prof. [Xiaogang Wang](#). He also has a close research collaboration with [Yu Liu](#), Quanquan Li, Junjie Yan and Prof. [Wanli Ouyang](#).

He used to work as a computer vision researcher in [SenseTime Research](#) (2016-2017). During this period, he was a member of the CULImage team that won the first place in ILSVRC2016 DET (ImageNet).

His research interests now include but not limit to object detection (both 2D and 3D), and 3D animation.

Yu Liu



General Manager & Senior Director, [SenseTime](#)
PI, [Shanghai AI Lab](#)
Industrial doctoral supervisor, SJTU
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[Google Scholar](#)
[Resume](#)
[GitHub](#)

News

- **Job positions and PhD program are open for talents interested in deep RL, super HUGE neural architecture, AutoML and Game AI.**
- [2022] My team have **9 papers** published on ECCV/CoRL/NeurIPS/AAAI in 2022
- [2022] We release **DI-Star**, an implementation of AlphaStar in pyTorch, beating pro players with 6000+ MMR.
- [2021] My team won the **best paper** of ICCV21 MFR workshop
- [2021] My team won **3 championships** of ICCV21 The Masked Face Recognition Challenge
- [2021] We release **OpenDILab**, an open source decision intelligence platform
- [2020] **5 papers** with **1 oral** got published on CVPR/ECCV 2020



王晓刚
港中文副教授
商汤研究院院长



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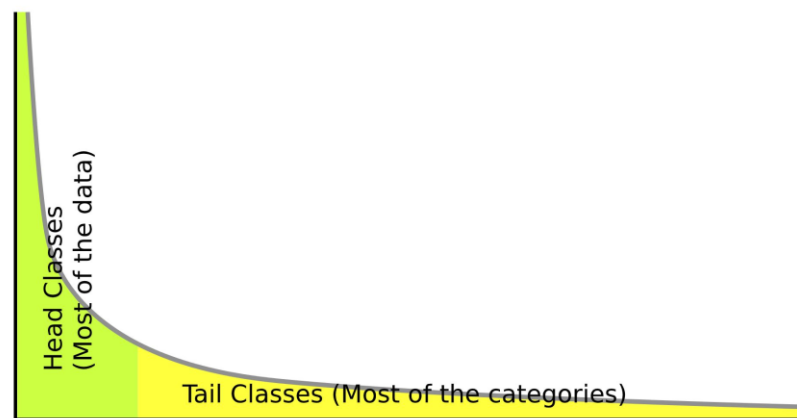
Long-Tailed Distribution

5

任务：分类、
目标检测、
实例分割

特点：少数类别样本数量庞大，
多数类别样本数量稀少

问题：数据分布先验影响分类精度
偏向头部类别的误分类
尾部类别样本量过少，难以建模

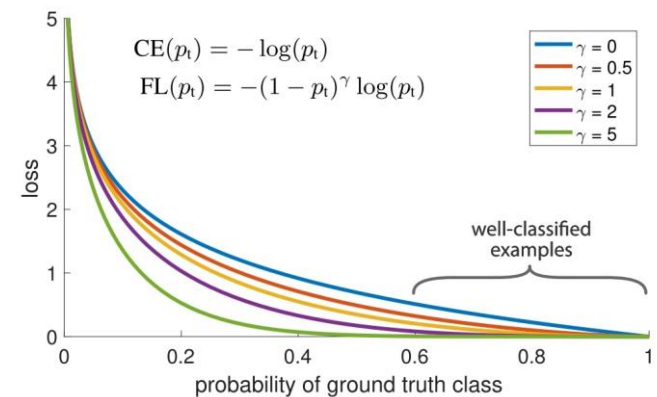
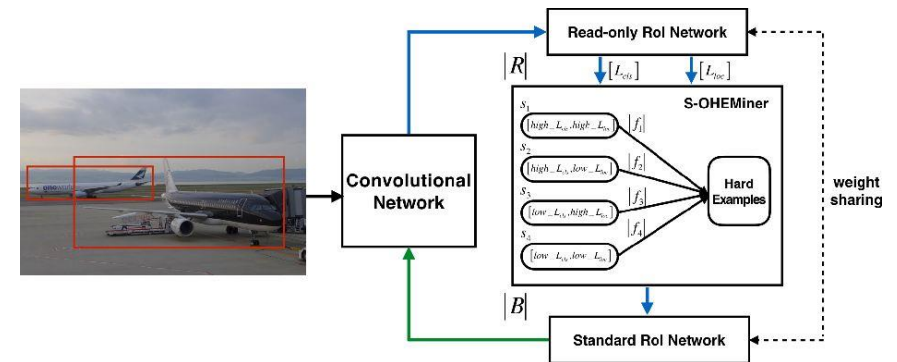
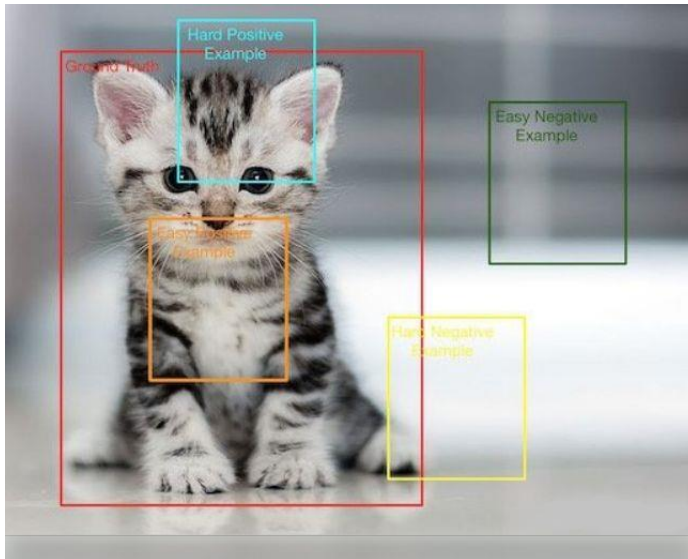


Data Imbalance in OD

6

□ Data Imbalance in OD

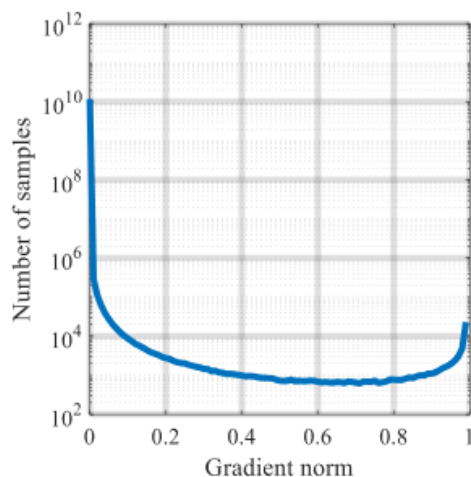
- ⊙ OHEM/S-OHEM
- ⊙ FL



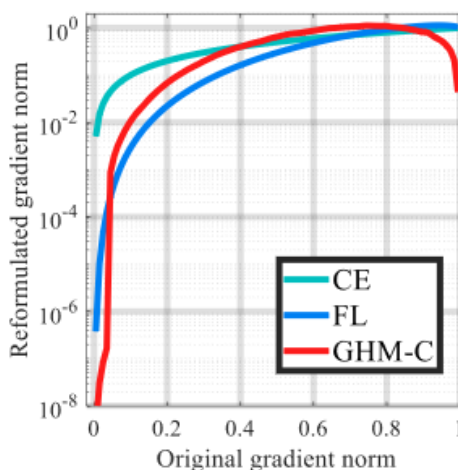
Motivation

7

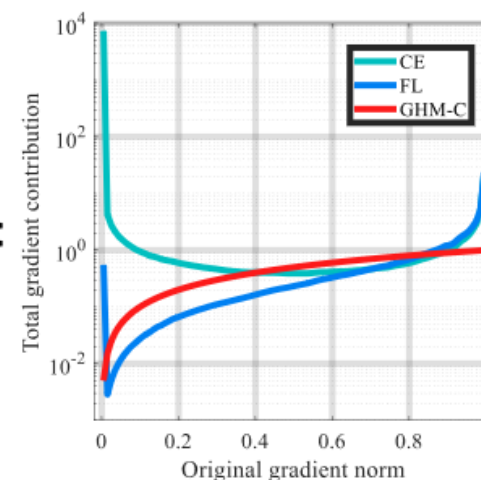
Gradient statistics



Gradient regularization



Overall gradient



梯度->样本对网络的更新作用
梯度分布极为不均衡

简单样本的梯度数值小但数量庞大
总梯度累积量，CE和FL表现均欠佳



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Gradient Harmonizing Mechanism

9

□ Overview

简单样本，没啥大用
累积效应还会影响分类结果

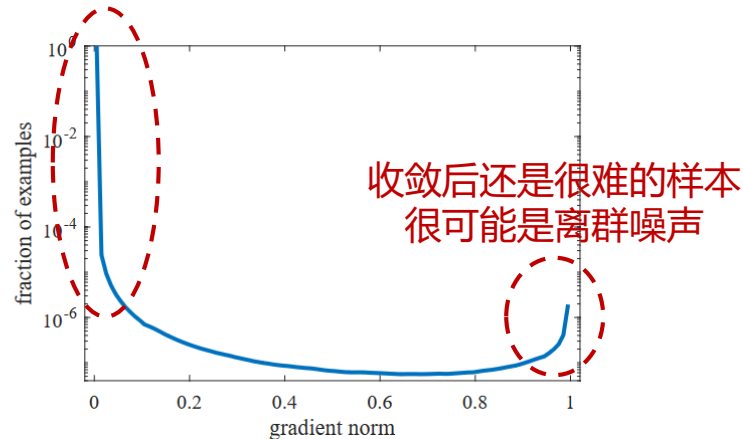


Figure 2: The distribution of the gradient norm g from a **converged** one-stage detection model. Note that the y-axis uses log scale since the number of examples with different gradient norm can differ by orders of magnitude.

按梯度分布统计 -> 重加权

$$GD(g) = \frac{1}{l_{\epsilon}(g)} \sum_{k=1}^N \delta_{\epsilon}(g_k, g)$$

小邻域指示函数 $\delta_{\epsilon}(x, y) = \begin{cases} 1 & \text{if } y - \frac{\epsilon}{2} \leq x < y + \frac{\epsilon}{2} \\ 0 & \text{otherwise} \end{cases}$

小邻域长度 $l_{\epsilon}(g) = \min(g + \frac{\epsilon}{2}, 1) - \max(g - \frac{\epsilon}{2}, 0)$

GHM权重 $\beta_i = \frac{N}{GD(g_i)}$
 $= \frac{1}{GD(g_i)/N}$

Gradient Harmonizing Mechanism

10

□ GHM-C Loss

$$L_{CE}(p, p^*) = \begin{cases} -\log(p) & \text{if } p^* = 1 \\ -\log(1-p) & \text{if } p^* = 0 \end{cases}$$

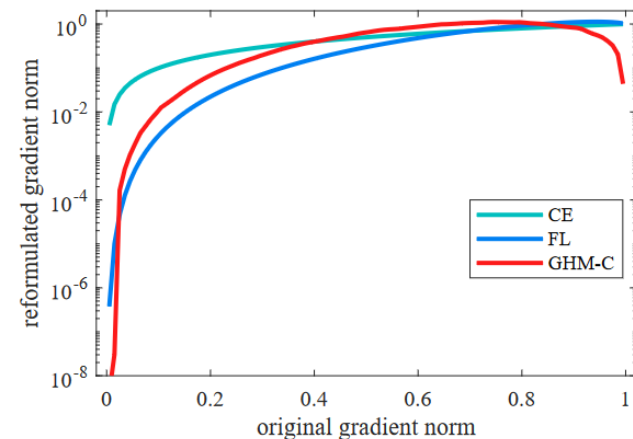
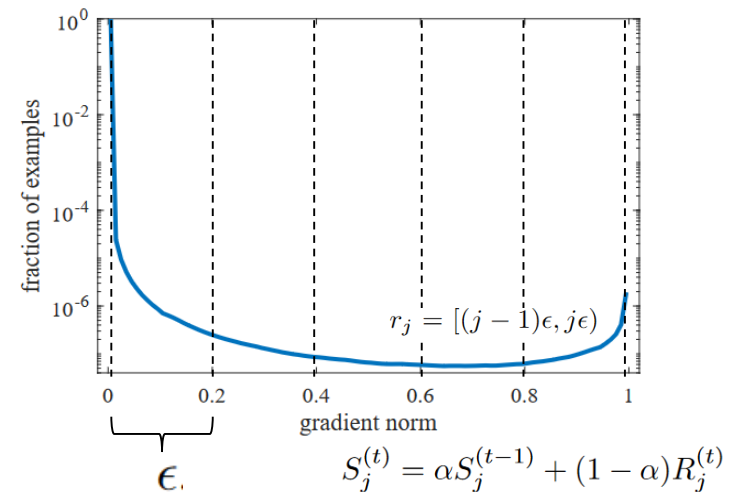
$$\frac{\partial L_{CE}}{\partial x} = \begin{cases} p-1 & \text{if } p^* = 1 \\ p & \text{if } p^* = 0 \end{cases} = p - p^*$$

$$g = |p - p^*| = \begin{cases} 1-p & \text{if } p^* = 1 \\ p & \text{if } p^* = 0 \end{cases}$$

$$\hat{GD}(g) = \frac{R_{ind}(g)}{\epsilon} = R_{ind}(g)M$$

$$\hat{\beta}_i = \frac{N}{\hat{GD}(g_i)}$$

$$\begin{aligned} \hat{L}_{GHM-C} &= \frac{1}{N} \sum_{i=1}^N \hat{\beta}_i L_{CE}(p_i, p_i^*) \\ &= \sum_{i=1}^N \frac{L_{CE}(p_i, p_i^*)}{\hat{GD}(g_i)} \end{aligned}$$



Gradient Harmonizing Mechanism

11

GHM-L Loss

$$L_{reg} = \sum_{i \in \{x, y, w, h\}} SL_1(t_i - t_i^*)$$

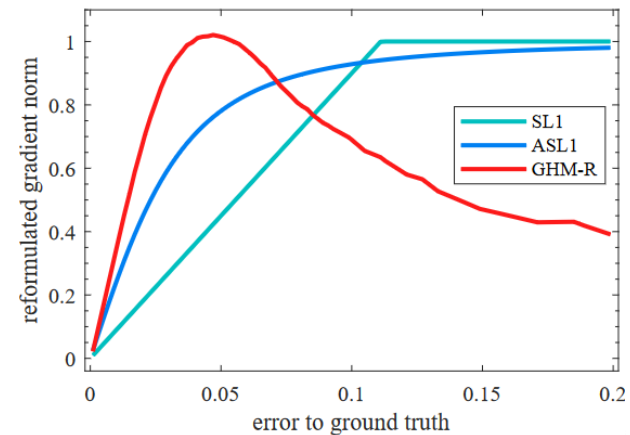
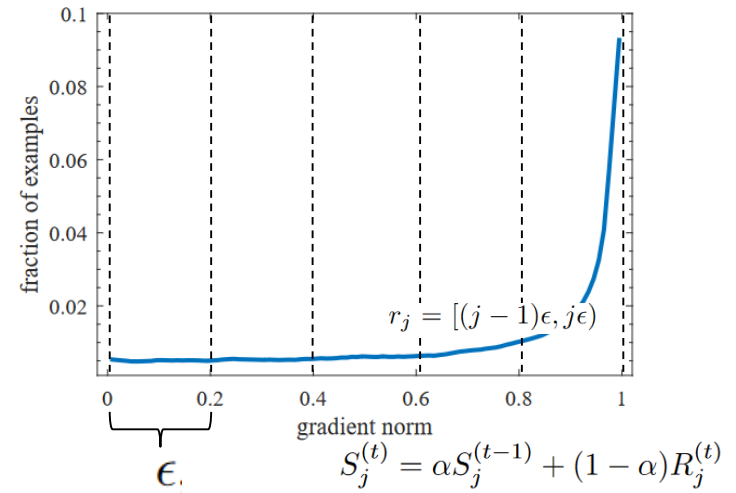
$$SL_1(d) = \begin{cases} \frac{d^2}{2\delta} & \text{if } |d| \leq \delta \\ |d| - \frac{\delta}{2} & \text{otherwise} \end{cases}$$

$$\frac{\partial SL_1}{\partial t_i} = \frac{\partial SL_1}{\partial d} = \begin{cases} \frac{d}{\delta} & \text{if } |d| \leq \delta \\ \text{sgn}(d) & \text{otherwise} \end{cases}$$

$$ASL_1(d) = \sqrt{d^2 + \mu^2} - \mu$$

$$\begin{aligned} L_{GHM-R} &= \frac{1}{N} \sum_{i=1}^N \beta_i ASL_1(d_i) \\ &= \sum_{i=1}^N \frac{ASL_1(d_i)}{GD(gr_i)} \end{aligned}$$

回归只在正样本上进行





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SOTA Comparison

13

□ COCO

method	network	AP	AP ₅₀	AP ₇₅	AP _S	AP _M	AP _L
Faster RCNN (Ren et al. 2015)	FPN-ResNet-101	36.2	59.1	39.0	18.2	39.0	48.2
Mask RCNN (He et al. 2017)	FPN-ResNet-101	38.2	60.3	41.7	20.1	41.1	50.2
Mask RCNN (He et al. 2017)	FPN-ResNeXt-101	39.8	62.3	43.4	22.1	43.2	51.2
YOLOv3 (Redmon and Farhadi 2018)	DarkNet-53	33.0	57.9	34.4	18.3	35.4	41.9
DSSD513 (Fu et al. 2017)	DSSD-ResNet-101	33.2	53.3	35.2	13.0	35.4	51.1
Focal Loss (Lin et al. 2017b)	RetinaNet-FPN-ResNet-101	39.1	59.1	42.3	21.8	42.7	50.2
Focal Loss (Lin et al. 2017b)	RetinaNet-FPN-ResNeXt-101	40.8	61.1	44.1	24.1	44.2	51.2
GHM-C + GHM-R (ours)	RetinaNet-FPN-ResNet-101	39.9	60.8	42.5	20.3	43.6	54.1
GHM-C + GHM-R (ours)	RetinaNet-FPN-ResNeXt-101	41.6	62.8	44.2	22.3	45.1	55.3

Table 3: Comparison with state-of-the-art methods (single model) on COCO *test-dev* set.

Ablation Study

14

□ 单位梯度区间 M

M	AP	AP _{.5}	AP _{.75}	AP _S	AP _M	AP _L
5	33.4	51.7	35.6	18.6	36.8	45.7
10	34.6	53.9	36.5	19.5	37.1	46.1
20	35.2	54.4	36.9	19.4	38.4	46.3
30	35.8	55.5	38.1	19.6	39.6	46.7
40	35.4	54.8	36.3	19.5	38.5	46.3

Table 1: Results of varying number of unit regions for GHM-C loss.

□ GHM-C

method	AP	AP _{.5}	AP _{.75}	AP _S	AP _M	AP _L
CE	28.6	43.3	30.7	11.4	30.7	40.7
OHEM	31.1	47.2	33.2	-	-	-
FL	35.6	55.6	38.2	19.1	39.2	46.3
GHM-C	35.8	55.5	38.1	19.6	39.6	46.7

Table 4: Comparison of other loss functions. Note that the 'OHEM' is trained with ResNet-101 while others are trained with ResNet-50.

Ablation Study

15

□ GHM-L

method	AP	AP _{.5}	AP _{.75}	AP _S	AP _M	AP _L
SL_1	35.8	55.5	38.1	19.6	39.6	46.7
ASL_1	35.7	55.0	38.1	19.7	39.7	45.9
GHM-R	36.4	54.6	38.7	20.5	40.6	47.8

Table 5: Comparison of different loss functions for regression.

method	AP	AP _{.5}	AP _{.6}	AP _{.7}	AP _{.8}	AP _{.9}
SL_1	35.8	55.5	51.2	43.4	31.4	11.9
ASL_1	35.7	55.0	51.1	43.5	31.5	12.1
GHM-R	36.4	54.6	51.4	44.0	32.2	13.1

Table 6: Comparison of AP at different IoU thresholds.

□ 两阶段

method	AP	AP _{.5}	AP _{.75}	AP _S	AP _M	AP _L
SL_1	36.4	58.7	38.8	21.1	39.6	47.0
GHM-R	37.4	58.9	39.9	21.8	40.8	48.8

Table 7: Comparison of regression loss functions on two-stage detector.



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总结反思

17

□ 总结

- ⊙ 同时解决不均衡问题和噪声样本的问题
- ⊙ 从梯度分布的统计结果进行重加权

□ 思考

- ⊙ 回归与分类问题，梯度分布有较大差别
- ⊙ 将简单类舍弃，相当于改变了输入数据的分布，是否会影响网络对简单类的建模，降低多数类的精度



Thanks for Attention!