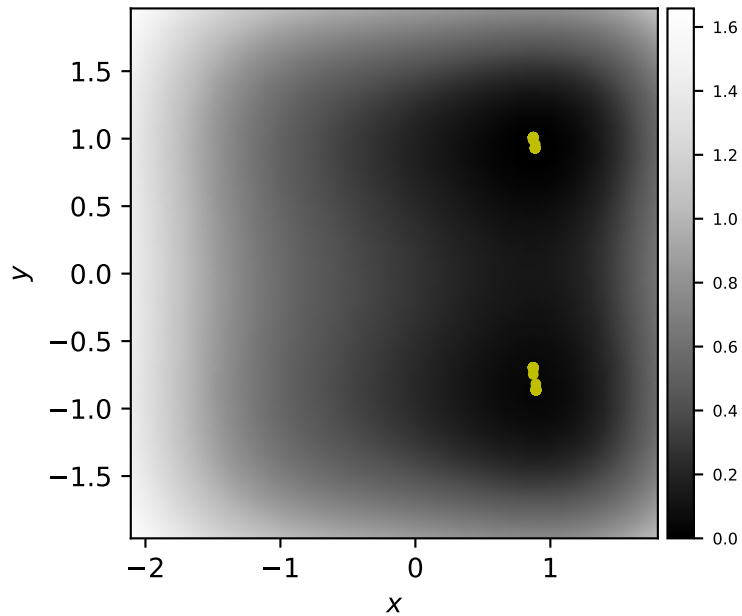


# Identifying bifurcations along tilt trajectory

$\phi(x, y)$



Tilt trajectory

