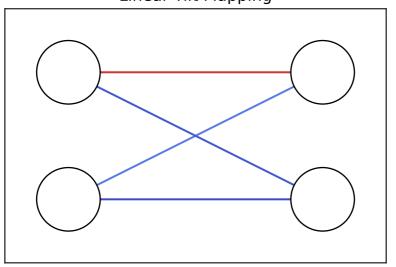
## Linear Tilt Mapping



0.3

0.2

0.1

- 0.0

- -0.1

-0.2

· **-**0.3