# Crack detection Using deep learning approach

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### Problem statement

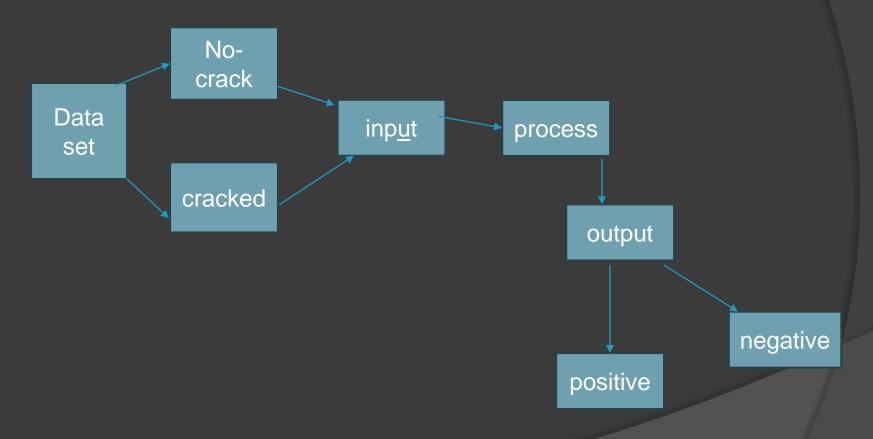
- The problem is to develop an effective and efficient system for the detection of cracks in structures, such as buildings or bridges.
- This involves creating a model capable of accurately identifying and localizing cracks in images or sensor data.
- The goal is to automate the detection process, providing a reliable tool for structural health monitoring to prevent potential failures and ensure the safety and integrity of infrastructure.
- Manual crack detection is laborious, time-consuming, and prone to subjective judgments from inspectors.
- Particularly challenging for tall buildings and bridges, manual inspection becomes impractical.

### Introduction

- Detecting cracks is a crucial aspect of monitoring the structural integrity of concrete structures and other surface structures
- The goal of this project is to develop a robust crack detection system using deep learning techniques.
- The system will analyse images of surfaces to identify and localize crack
- Automated methods offer a more efficient and objective solution to identify and analyze surface cracks in concrete structures.

### Methodology:

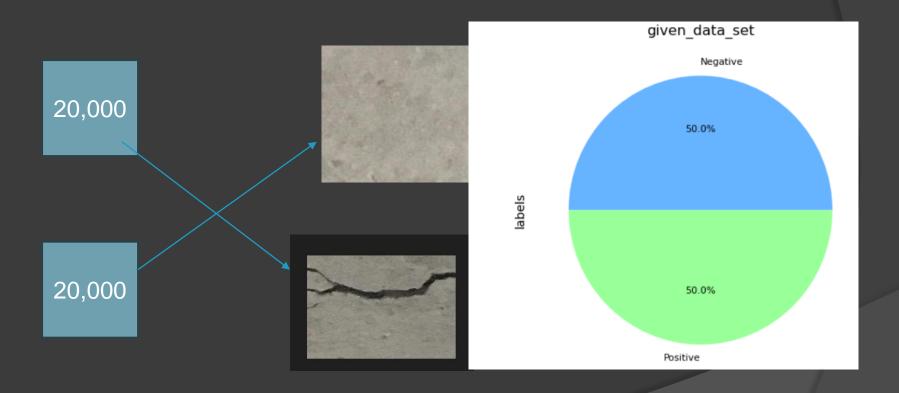
1 using deep learning approach

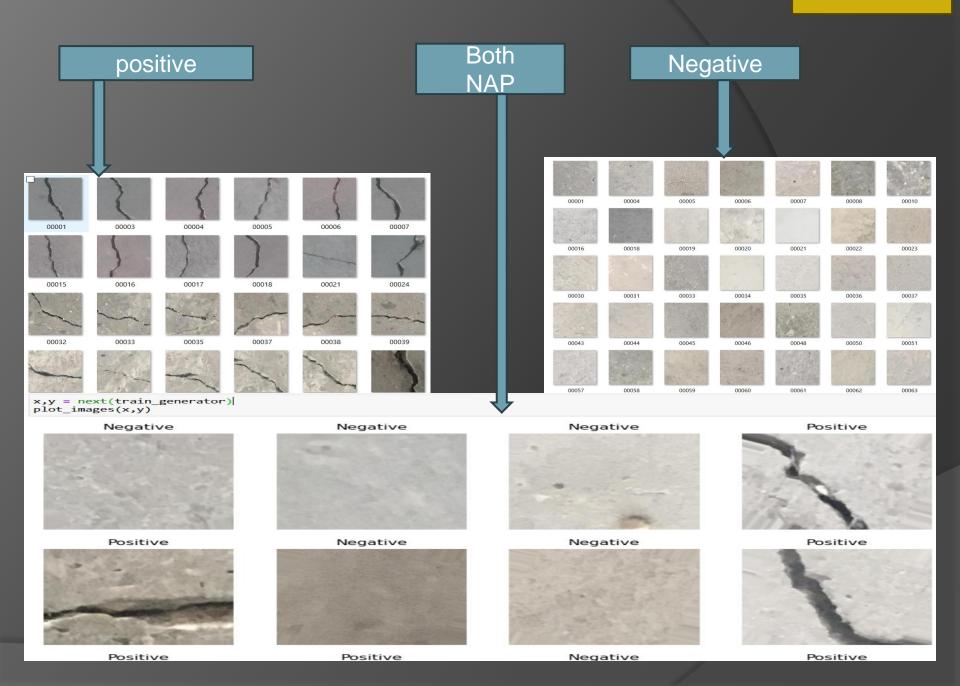


2 using non max suppression approach and edge detector

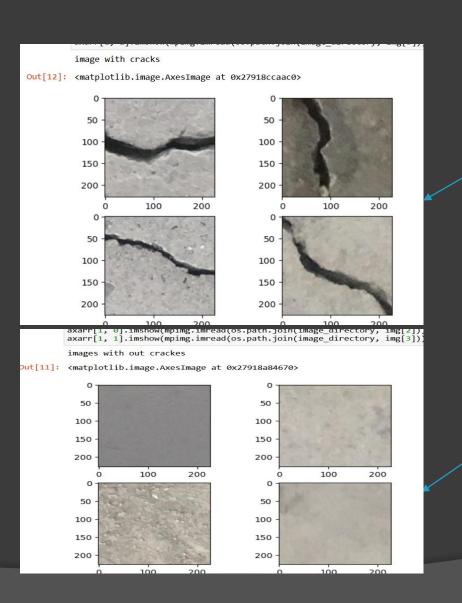
### Dataset

### Data set consist of 40000 images





## preprocessing



crack

Non crack

#### Out[14]:

Split the DataSet

	Filepath	Label
0	C:\Users\HP\Downloads\archive (4)\Positive\038	Positive
1	C:\Users\HP\Downloads\archive (4)\Positive\128	Positive
2	C:\Users\HP\Downloads\archive (4)\Positive\150	Positive
3	C:\Users\HP\Downloads\archive (4)\Negative\167	Negative
4	C:\Users\HP\Downloads\archive (4)\Positive\092	Positive
39995	C:\Users\HP\Downloads\archive (4)\Positive\078	Positive
39996	C:\Users\HP\Downloads\archive (4)\Negative\125	Negative
39997	C:\Users\HP\Downloads\archive (4)\Positive\051	Positive
39998	C:\Users\HP\Downloads\archive (4)\Positive\121	Positive
39999	C:\Users\HP\Downloads\archive (4)\Negative\130	Negative

#### 40000 rows × 2 columns

```
h train_df, test_df = train_test_split(all_df.sample(30000, random_state=1),
                  train_size=0.7,
                   shuffle=True,
                   random_state=42)
```

```
n [48]:

    ★ train_df.shape

  Out[48]: (21000, 2)

★ test_df.shape

n [49]:
  Out[49]: (9000, 2)
```

### Data augmentation and pre-processing

```
gen = ImageDataGenerator(rescale
                                         = 1./255.
                        horizontal flip = True,
                        vertical flip
                                         = True,
                                         = 0.05,
                         zoom range
                         rotation range
                                         = 25)
```

### modeling

•

- 1. Input Layer:
- tf.keras.Input(shape=(120, 120, 3))
- Defines the input layer with a shape of (120, 120, 3), indicating an input image size of 120x120 pixels with 3 color channels (RGB).
- 2. Convolutional Layers:
- x = tf.keras.layers.Conv2D(filters=16, kernel\_size=(3, 3),
   activation='relu')(inputs)
- $\odot$  x = tf.keras.layers.MaxPool2D(pool\_size=(2, 2))(x)
- x = tf.keras.layers.Conv2D(filters=32, kernel\_size=(3, 3),activation='relu')(x)
- $\bullet$  x = tf.keras.layers.MaxPool2D(pool\_size=(2, 2))(x)
- Applies two convolutional layers with 16 and 32 filters, respectively, each using a 3x3 kernel.
- Applies max pooling with a 2x2 pool size after each

## Conti.....

- 3. Global Average Pooling Layer:
- x=tf.keras.layers.GlobalAveragePooling2D()(x)
- Performs global average pooling to reduce the spatial dimensions to a single value per channel, creating a flat vector.
- 4. Output Layer:
- $\odot$  outputs = tf.keras.layers.Dense(1, activation='sigmoid')(x)
- Connects the output of the global average pooling layer to a dense layer with a single neuron (for binary classification) and a sigmoid activation function.

## Training model ¶

Training from scratch

```
In [53]: | inputs = tf.keras.Input(shape=(128,128,3))
            x = tf.keras.layers.Conv2D(filters=16, kernel_size=(3,3), activation='relu')(inputs)
             x = tf.keras.layers.MaxPool2D(pool size=(2,2))(x)
             x = tf.keras.layers.Conv2D(filters=32, kernel size=(3,3), activation='relu')(x)
             x = tf.keras.layers.MaxPool2D(pool size=(2,2))(x)
             x = tf.keras.layers.Conv2D(filters=64, kernel size=(3,3), activation='relu')(x)
             x = tf.keras.layers.MaxPool2D(pool size=(2,2))(x)
             x = tf.keras.layers.Conv2D(filters=128, kernel_size=(3,3), activation='relu')(x)
             x = tf.keras.layers.MaxPool2D(pool size=(2,2))(x)
             x = tf.keras.layers.GlobalAveragePooling2D()(x)
             outputs = tf.keras.layers.Dense(1, activation='sigmoid')(x)
```

	Layer (type)	Output Shape	Param #
	input_4 (InputLayer)	[(None, 128, 128, 3)]	0
	conv2d_11 (Conv2D)	(None, 126, 126, 16)	448
	max_pooling2d_11 (MaxPooli ng2D)	(None, 63, 63, 16)	0
	conv2d_12 (Conv2D)	(None, 61, 61, 32)	4640
Model summary of	<pre>max_pooling2d_12 (MaxPooli ng2D)</pre>	(None, 30, 30, 32)	0
training from scratch	conv2d_13 (Conv2D)	(None, 28, 28, 64)	18496
	<pre>max_pooling2d_13 (MaxPooli ng2D)</pre>	(None, 14, 14, 64)	0
	conv2d_14 (Conv2D)	(None, 12, 12, 128)	73856
	<pre>max_pooling2d_14 (MaxPooli ng2D)</pre>	(None, 6, 6, 128)	0
	global_average_pooling2d_3 (GlobalAveragePooling2D)	(None, 128)	0

# For 15000 sample

```
Epoch 1/10
280/280 [============ ] - 97s 342ms/step - loss: 0.1775 - accuracy: 0.9312 - val loss: 0.0585 - val accurac
y: 0.9790
Epoch 2/10
y: 0.9862
Epoch 3/10
y: 0.9853
Epoch 4/10
280/280 [=======================] - 33s 118ms/step - loss: 0.0539 - accuracy: 0.9839 - val_loss: 0.0475 - val accurac
y: 0.9839
Epoch 5/10
y: 0.9857
```

## Cont...

#### For 30,000 sample

```
Epoch 1/10
cy: 0.9807
Epoch 2/10
cy: 0.9705
Epoch 3/10
y: 0.9886
Epoch 4/10
y: 0.9879
Epoch 5/10
y: 0.9862
Epoch 6/10
y: 0.9924
Epoch 7/10
y: 0.9912
Epoch 8/10
y: 0.9829
Epoch 9/10
v: 0.9900
```

# Using Resnet\_v2

```
Downloading data from https://storage.googleapis.com/tensorflow/keras-applications/inception_resnet_v2/inception_resnet_v2_w eights_tf_dim_ordering_tf_kernels_notop.h5
```

Unfreezing number of layers in base model = 0

Epoch 1/3

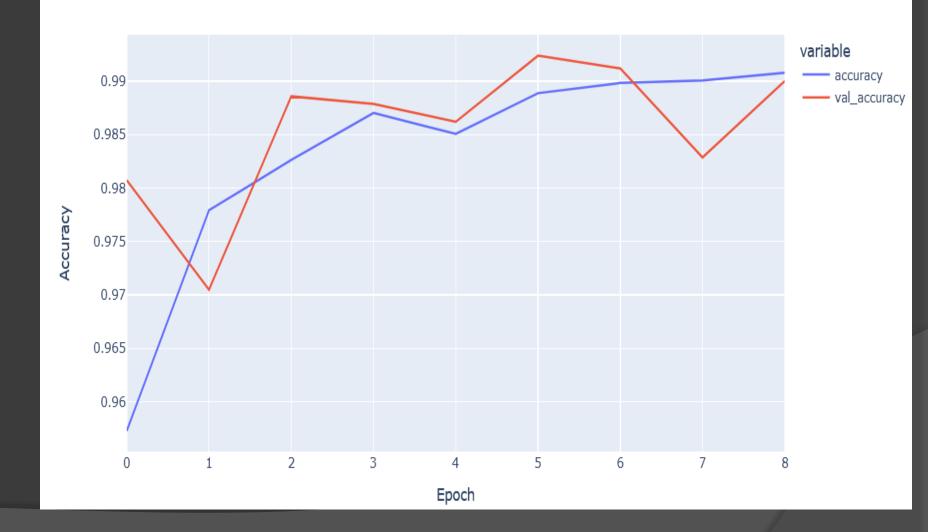
WARNING:tensorflow:From C:\Users\HP\AppData\Roaming\Python\Python39\site-packages\keras\src\utils\tf\_utils.py:492: The name tf.ragged.RaggedTensorValue is deprecated. Please use tf.compat.v1.ragged.RaggedTensorValue instead.

WARNING:tensorflow:From C:\Users\HP\AppData\Roaming\Python\Python39\site-packages\keras\src\engine\base\_layer\_utils.py:384:
The name tf.executing\_eagerly\_outside\_functions is deprecated. Please use tf.compat.v1.executing\_eagerly\_outside\_functions in nstead.

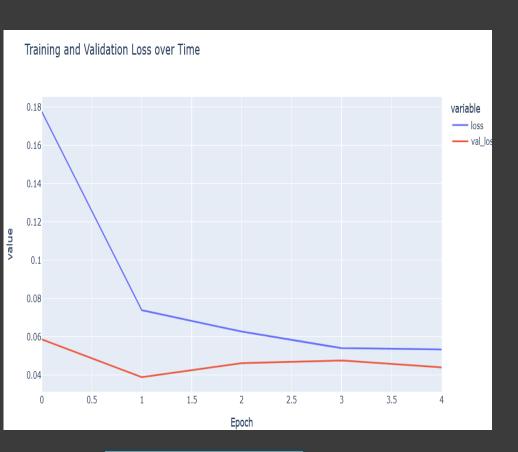
### Performance metric

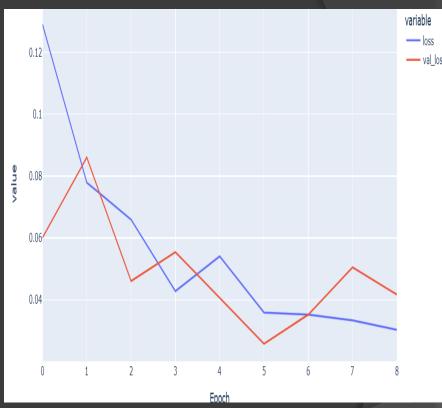
True Positive Rate (TPR) = 
$$\frac{TP}{TP + FN}$$
False Positive Rate (FPR) = 
$$\frac{FP}{FP + TN}$$
Specificity = 
$$\frac{TN}{FP + TN}$$
Accuracy = 
$$\frac{TP + TN}{TP + FN + TN + FP}$$
Precision = 
$$\frac{TP}{TP + FP}$$

### Training and Validation Accuracy Over Time



### Result

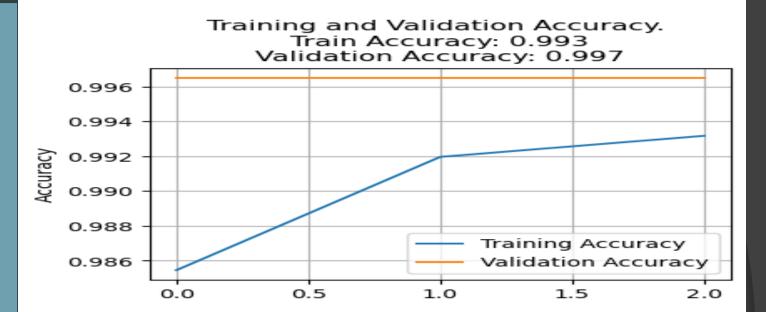


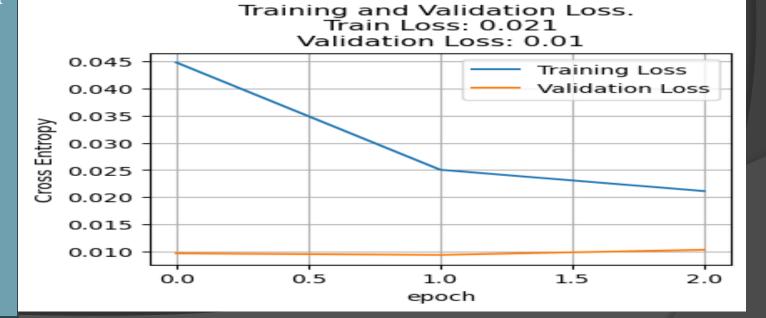


For 15000 sample

For 30000 sample

Using pretrained model





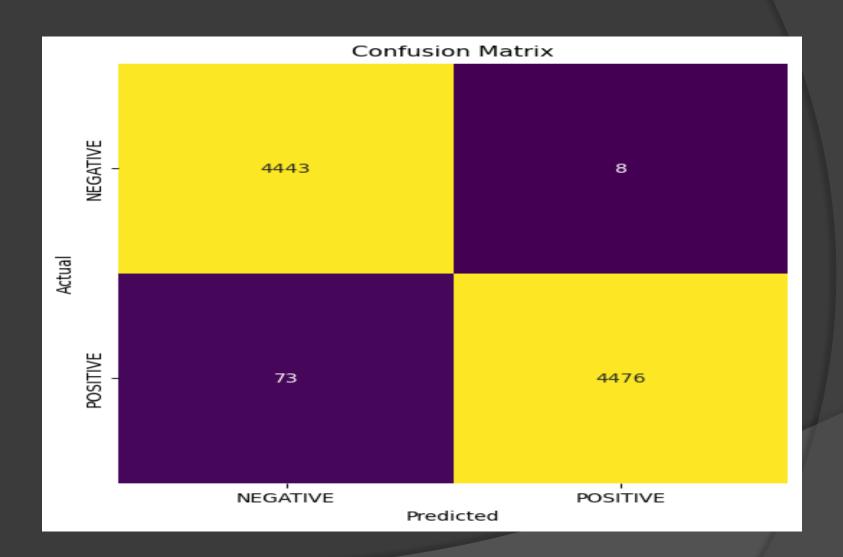
### Result

```
▶ def evaluate model(model, test data):
      results = model.evaluate(test data, verbose=0)
      loss = results[0]
      acc = results[1]
      print(" Test Loss: {:.5f}".format(loss))
      print("Test Accuracy: {:.2f}%".format(acc * 100)

► evaluate model(model, test data)

      Test Loss: 0.02858
  Test Accuracy: 99.10%
```

### Confusion matrix

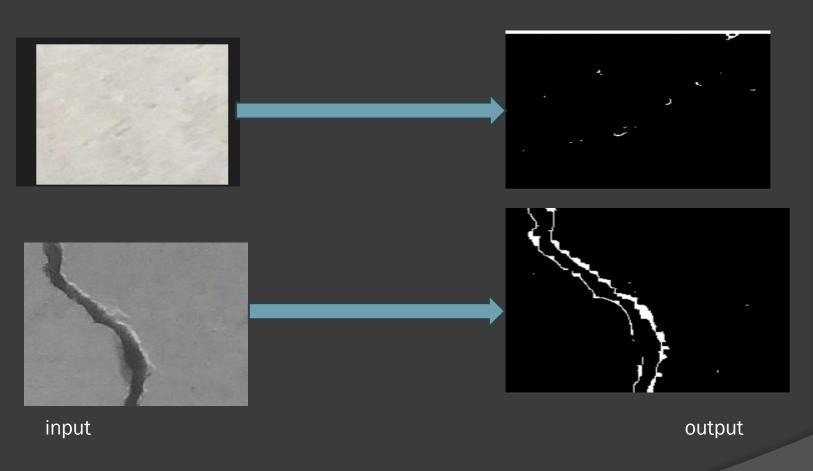


### Cont.....

Classification Report:							
	precision	recall	f1-score	support			
NEGATIVE	0.98	1.00	0.99	4451			
POSITIVE	1.00	0.98	0.99	4549			
accuracy			0.99	9000			
macro avg	0.99	0.99	0.99	9000			
weighted avg	0.99	0.99	0.99	9000			



## Using non max suppression and edge detector



## Conclusion

- By comparing result of using pretrained model and training from scratch
- Utilizing pre-trained model is better than training from scratch in term s of accuracy.



## Challenges and future work

- When I reduce the number of sample, overfitting happened
- Incorporate better accurate model to hard ware .make it more real time.
  - Applying non max suppression with deep learning

Thank you