
“LEARNING ASSURANCE” FOR EMBEDDED SAFETY-CRITICAL APPLICATIONS

DSTI – [DS] PROJECT PROGRESS STATUS REPORT – JAN 2021

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PROJECT OBJECTIVES

- **Project Objective** - To “mimic” the design, development and verification phases of a safety-critical embedded machine learning software based on the preliminary guidance material issued by EASA.
- **“Mission requirements”** - To detect a “runway” (presence and coordinates), define its centre line and align the vehicle on the runway axis.
- Based on the above, **3 main sub-objectives** can be defined:
 - Develop the ML model(s) for the runway detection (presence and coordinates)
 - Transfer the model onto an inference platform (taking into account specific hardware and software constraints)
 - Demonstrate compliance to “learning assurance” requirements

PROJECT DETAILED SCOPE

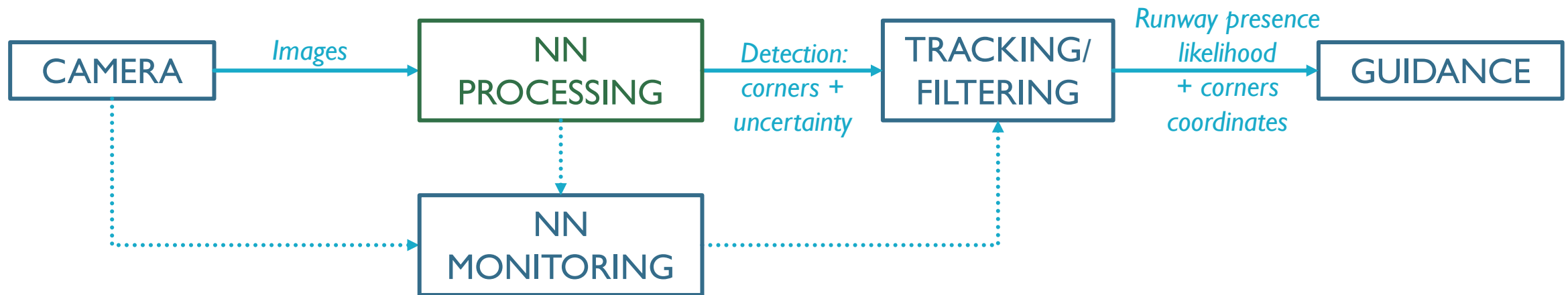
■ In-scope

- Software development
- Design assurance for Machine Learning Software
- Machine Learning for runway presence prediction and location information
- Non-adaptative deterministic system

■ Out-of-scope

- Hardware development
- Design assurance for “Classical” Software
- Machine Learning for end-to-end guidance
- Adaptative non-deterministic system
- Security concerns
- Tools and development environment (hardware and software) qualification

HIGH LEVEL ARCHITECTURE



PROGRESS STATUS

- Actions completed in December 2020-January 2021
 - Project scope and detailed outline finalised (see previous slides and [link](#)).
 - COTS Robot (Waveshare Jetbot) selected and preliminary testing performed.
 - “Learning Assurance” requirements identified (see [link](#)).
 - High-level architecture defined (see previous slide).
- Upcoming steps (February 2021)
 - Data collection
 - Preliminary model definition:
 - Key elements of the training algorithm selection
 - Verification metrics definition

REFERENCES

- “Artificial Intelligence Roadmap – A human-centric approach to Ai in Aviation”, EASA Report ([link](#))
- “Concepts of Design Assurance for Neural Networks (CoDANN)”, EASA AI Task Force and Daedalean AG ([link](#))